

Background

◆ A Mobile Server

- ❖ Real-time inference applications
- ❖ Collect features from sensors

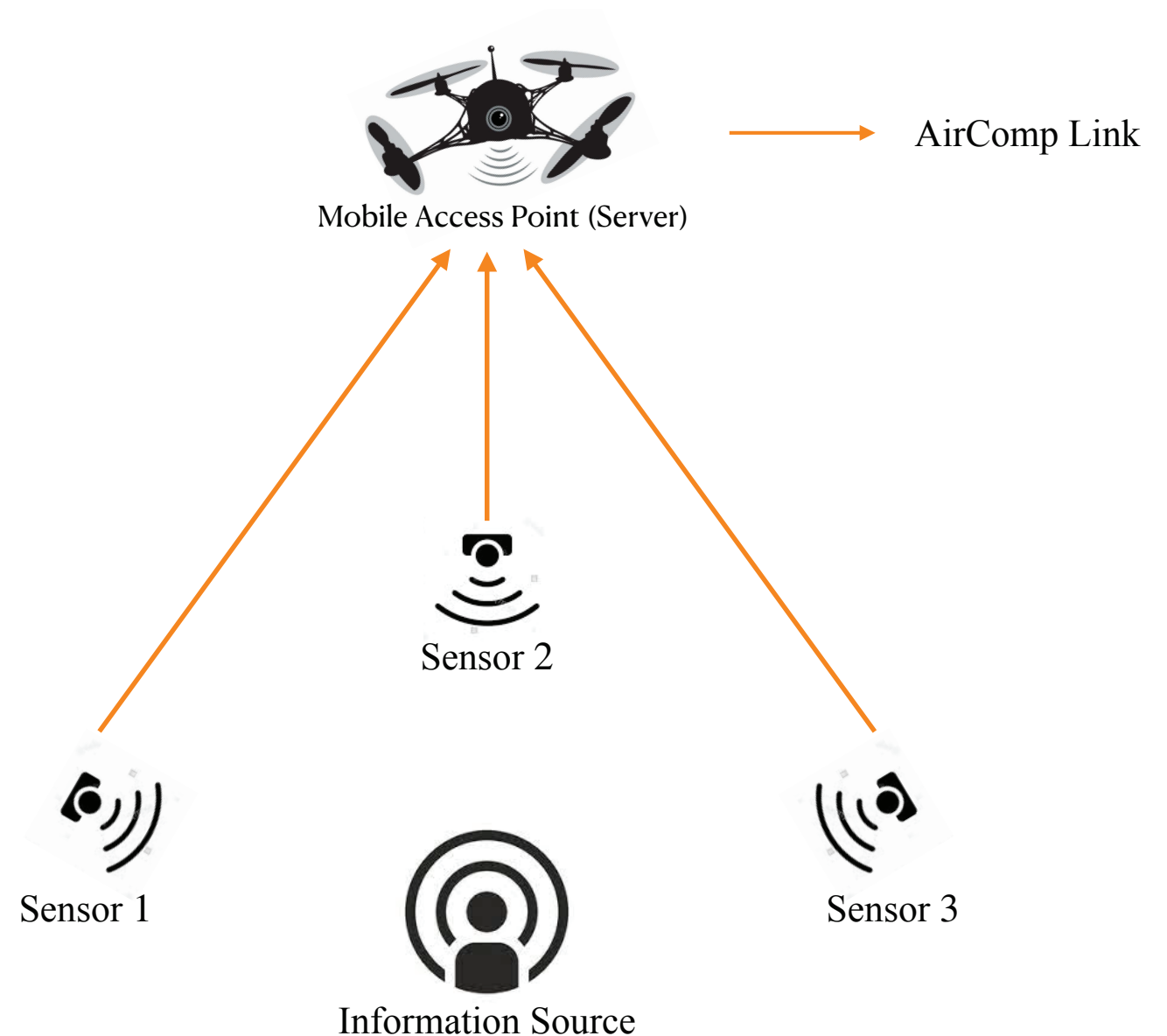
◆ Multiple Sensors

- ❖ Sensing **the same source**
- ❖ **Each observation is a corrupted version of ground-true data [1],**

◆ AirComp

- ❖ Aggregate the features to average the corruptions.

◆ Metric: Discriminant Gain



[1] J.-J. Xiao, S. Cui, Z.-Q. Luo and A. J. Goldsmith, "Power scheduling of universal decentralized estimation in sensor networks", IEEE Trans. Signal Processing, vol. 54, no. 2, pp. 413-422, Feb. 2006.

System Model

◆ Network Model

- ❖ One mobile server (access point) with N receive antennas
- ❖ K sensors with single transmit antennas

◆ Sensing Data (Features)

- ❖ The sensed data (feature) vector, denoted as \mathbf{x} , has M dimensions.
- ❖ For the k -th sensor, its observed feature vector is \mathbf{x}_k , given as

$$\mathbf{x}_k = \mathbf{x} + \mathbf{d}_k,$$

- ❖ \mathbf{x} is the ground-true data (feature).
- ❖ \mathbf{d}_k is the observation distortion with the following distribution,

$$\mathbf{d}_k \sim \mathcal{N}(\mathbf{0}, \mathbf{D}_k).$$

- $D_k = \text{diag}\{\delta_{k,1}^2, \delta_{k,2}^2, \dots, \delta_{k,M}^2\}$ is the diagonal covariance matrix.

Discriminant Gain Model

- ◆ The ground-true feature \mathbf{x} has the following distribution

$$f(\mathbf{x}) = \frac{1}{L} \sum_{\ell=1}^L \mathcal{N}(\boldsymbol{\mu}_{\ell}, \boldsymbol{\Sigma}),$$

- ♣ L is the total number of classes.

- ♣ $\boldsymbol{\mu}_{\ell} = [\mu_{\ell,1}, \mu_{\ell,2}, \dots, \mu_{\ell,M}]^T$, is the mean vector of the ℓ -th class.

- ♣ $\boldsymbol{\Sigma} = \text{diag} \{ \sigma_1^2, \sigma_2^2, \dots, \sigma_M^2 \}$, is the covariance matrix.

- ❖ $\boldsymbol{\Sigma}$ is a **diagonal matrix**, as **PCA** is used to pre-process the features and different feature elements are independent.

- ❖ All classes are assumed to have the same variance.

Discriminant Gain Model

◆ Discriminant Gain

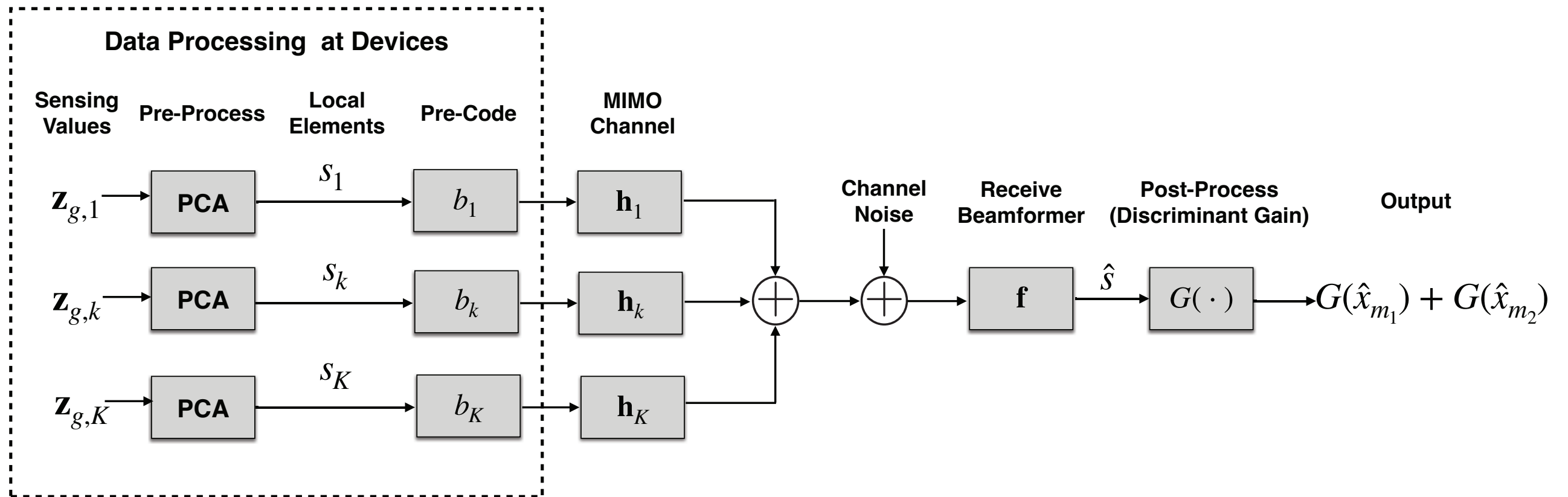
♣ Consider the m —th feature dimension, its discriminant gain is

$$G(x_m) = \frac{2}{L(L-1)} \sum_{\ell'=1}^L \sum_{\ell < \ell'} \frac{\left(\mu_{\ell,m} - \mu_{\ell',m}\right)^2}{\sigma_m^2},$$

♣ The total discriminant gain can be written as

$$G(\mathbf{x}) = \sum_{m=1}^M G(x_m).$$

AirComp Model



◆ Transmit Symbols

♣ s_k is a complex scalar:

$$s_k = x_{k,m_1} + jx_{k,m_2},$$

❖ j represents the imaginary unit.

❖ x_{k,m_1} and x_{k,m_2} are the m_1 -th and m_2 -th elements of the k -th observation.

AirComp Model

- ◆ At the server, the receive signal can be written as

$$\mathbf{y} = \sum_{k=1}^K \mathbf{h}_k b_k s_k + \mathbf{n},$$

- ♣ $\mathbf{h}_k \in \mathbb{C}^N$ is the channel vector of device k ,
- ♣ $b_k \in \mathbb{C}$ is the pre-coding scalar of sensor k ,
- ♣ \mathbf{n} is the noise with the following distribution,

$$\mathbf{n} \sim \mathcal{N}(\mathbf{0}, \delta_0^2 \mathbf{I}).$$

- ◆ Symbol estimation (receive beamforming)

$$\hat{s} = \mathbf{f}^H \mathbf{y} = \mathbf{f}^H \sum_{k=1}^K \mathbf{h}_k b_k s_k + \mathbf{f}^H \mathbf{n},$$

- ♣ $\mathbf{f} \in \mathbb{C}^N$ is the receive beamforming.

AirComp Model

◆ Estimated Elements

$$\begin{cases} \hat{x}_{m_1} = \text{Re}(\hat{s}) = \text{Re} \left(\mathbf{f}^H \sum_{k=1}^K \mathbf{h}_k b_k s_k + \mathbf{f}^H \mathbf{n} \right), \\ \hat{x}_{m_2} = \text{Im}(\hat{s}) = \text{Im} \left(\mathbf{f}^H \sum_{k=1}^K \mathbf{h}_k b_k s_k + \mathbf{f}^H \mathbf{n} \right). \end{cases}$$

Problem Formulation

- ◆ Objective: Maximize the **Receive Discriminant Gain**

$$\max_{\{b_k\}, \mathbf{f}} G = G(\hat{x}_{m_1}) + G(\hat{x}_{m_2}),$$

- ◆ Power Constraint of Each Sensor

$$b_k s_k s_k^H b_k^H \leq P_k, \quad 1 \leq k \leq K,$$

- ♣ $\{s_k\}$ have different variance, as the distortion of different devices is different.

- ♣ $s_k s_k^H$ is known to device k . Therefore,

$$b_k b_k^H \leq \hat{P}_k, \quad 1 \leq k \leq K,$$

$$\diamond \hat{P}_k = P_k / s_k s_k^H$$

Objective Simplification

◆ Zero-forcing (ZF) pre-coding

$$\mathbf{f}^H \mathbf{h}_k b_k = c_k, \quad 1 \leq k \leq K,$$

♣ c_k is a real number and represents the receive signal strength from device k .

◆ ZF pre-coders

$$b_k = \frac{c_k \mathbf{h}_k^H \mathbf{f}}{\mathbf{h}_k^H \mathbf{f} \mathbf{f}^H \mathbf{h}_k}, \quad 1 \leq k \leq K.$$

◆ Estimated Elements

$$\begin{cases} \hat{x}_{m_1} = \text{Re} \left(\sum_{k=1}^K c_k s_k + \mathbf{f}^H \mathbf{n} \right) = \sum_{k=1}^K c_k x_{k,m_1} + \text{Re}(\mathbf{f}^H \mathbf{n}), \\ \hat{x}_{m_2} = \text{Im} \left(\sum_{k=1}^K c_k s_k + \mathbf{f}^H \mathbf{n} \right) = \sum_{k=1}^K c_k x_{k,m_2} + \text{Im}(\mathbf{f}^H \mathbf{n}). \end{cases}$$

Objective Simplification

◆ Receive Elements Distribution

$$\hat{x}_{m_i} \sim \frac{1}{L} \mathcal{N} \left(\hat{\mu}_{\ell, m_i}, \hat{\sigma}_{m_i}^2 \right), \quad i = 1, 2,$$

where

$$\left\{ \begin{array}{l} \hat{\mu}_{\ell, m_1} = \sum_{k=1}^K c_k \mu_{\ell, m_1}, \\ \hat{\sigma}_{m_1}^2 = \sigma_{m_1}^2 \left(\sum_{k=1}^K c_k \right)^2 + \sum_{k=1}^K c_k^2 \delta_{k, m_1}^2 + \frac{\delta_0^2}{2} (\mathbf{f}_1^T \mathbf{f}_1 + \mathbf{f}_2^T \mathbf{f}_2), \\ \hat{\mu}_{\ell, m_2} = \sum_{k=1}^K c_k \mu_{\ell, m_2}, \\ \hat{\sigma}_{m_2}^2 = \sigma_{m_2}^2 \left(\sum_{k=1}^K c_k \right)^2 + \sum_{k=1}^K c_k^2 \delta_{k, m_2}^2 + \frac{\delta_0^2}{2} (\mathbf{f}_1^T \mathbf{f}_1 + \mathbf{f}_2^T \mathbf{f}_2). \end{array} \right.$$

$$\mathbf{f}_1 = \text{Re}(\mathbf{f})$$

$$\mathbf{f}_2 = \text{Im}(\mathbf{f})$$

Objective Simplification

◆ Receive Discriminant Gains

$$G(x_{m_i}) = \frac{2}{L(L-1)} \sum_{\ell'=1}^L \sum_{\ell < \ell'} \frac{\left(\hat{\mu}_{\ell, m_i} - \hat{\mu}_{\ell', m_i}\right)^2}{\hat{\sigma}_{m_i}^2}, \quad i = 1, 2,$$

◆ Power Constraint

$$c_k^2 \leq P_k \mathbf{h}_k^H \mathbf{f} \mathbf{f}^H \mathbf{h}_k, \quad 1 \leq k \leq K.$$

Objective Simplification

◆ Simplified Problem

$$\max_{\{c_k\}, \mathbf{f}_1, \mathbf{f}_2} G = \frac{2}{L(L-1)} \sum_{i=1}^2 \sum_{\ell'=1}^L \sum_{\ell < \ell'} \frac{\left(\hat{\mu}_{\ell, m_i} - \hat{\mu}_{\ell', m_i} \right)^2}{\hat{\sigma}_{m_i}^2},$$

$$\text{s.t. } c_k^2 \leq P_k \mathbf{h}_k^H (\mathbf{f}_1 \mathbf{f}_1^T + \mathbf{f}_2 \mathbf{f}_2^T) \mathbf{h}_k, \quad 1 \leq k \leq K,$$

$$\left\{ \begin{array}{l} \hat{\mu}_{\ell, m_1} = \sum_{k=1}^K c_k \mu_{\ell, m_1}, \\ \hat{\sigma}_{m_1}^2 = \sigma_{m_1}^2 \left(\sum_{k=1}^K c_k \right)^2 + \sum_{k=1}^K c_k^2 \delta_{k, m_1}^2 + \frac{\delta_0^2}{2} (\mathbf{f}_1^T \mathbf{f}_1 + \mathbf{f}_2^T \mathbf{f}_2), \\ \hat{\mu}_{\ell, m_2} = \sum_{k=1}^K c_k \mu_{\ell, m_2}, \\ \hat{\sigma}_{m_2}^2 = \sigma_{m_2}^2 \left(\sum_{k=1}^K c_k \right)^2 + \sum_{k=1}^K c_k^2 \delta_{k, m_2}^2 + \frac{\delta_0^2}{2} (\mathbf{f}_1^T \mathbf{f}_1 + \mathbf{f}_2^T \mathbf{f}_2). \end{array} \right.$$