## Jeremy C. Kanovsky

EDUCATION TUFTS UNIVERSITY, Medford, MA

Bachelor of Science in Mechanical Engineering Expected May 2021
Bachelor of Science in Computer Science Expected May 2021

GPA: 3.55/4.00, Dean's List

NEW HOPE SOLEBURY HIGH SCHOOL, New Hope, PA Graduated 2017

GPA: 96.5/100, National Honor Society

RELEVANT COURSES **ENGINEERING:** Data Structures, Simple Robotics, Intro Electrical Systems, Intro

Computer Science, Web Programming, Intro to Algorithms

**SCIENCE AND MATHEMATICS:** Discrete Mathematics, Physics – Electricity and Magnetism, Chemical Fundamentals, Calculus III, Differential Equations

WORK EXPERIENCE **SPECIALTY PAPERS AND FILMS, INC.,** New Hope, PA, August 2016 – June 2017 *Lab Assistant, Lab Technician* 

- Developed printed circuitry, performed product testing and experimental method development
- Operated a differential scanning calorimeter and thermal transfer printers **CANNONVILLE BEACH ASSOCIATION, Mattapoisett, MA, Summers 2014** 2017
  - Managed beach cleanup and admission

RESEARCH EXPERIENCE

## TUFTS UNIVERSITY, DEPARTMENT OF MECHANICAL ENGINEERING,

Undergraduate Research Project, May 2018 - Present

- Developed code infrastructure to control multiple quadcopter UAVs
- Implemented UAV three-dimensional positioning system and feedback control

**SKILLS** 

**Computer:** C++, Java, HTML, CSS, JavaScript, Node.js, Git, Python

**Design:** Adobe Illustrator, Adobe Photoshop

**Hardware:** Arduino, Raspberry Pi, Computer Assembly

**Lab:** Differential Scanning Calorimeter, Transfer Thermal Printing

**ACTIVITIES** 

Tufts Engineering Student Council, Treasurer, January 2017 – Present

**Tufts Robotics Team**, *Treasurer*, September 2017 – Present **Tufts MAKE Club**, *Project Leader*, September 2017 – Present **Tufts Rocketry Team**, *Co-Founder*, November 2017 – Present **Vex Robotics Team**, *Founder*, September 2016 – June 2017

**PROJECTS** 

## **Autonomous Quadcopter UAV,** January 2018 – May 2018

• Lead a project team designing, building, and programming a semi-autonomous quadcopter UAV for open-ended applications

Trinity Firefighting Robot, December 2017 – May 2018

• Designed, fabricated, and programmed a robot entered in the Trinity College International Robot Contest

Motorized Skateboard, September 2017 – December 2017

• Designed and assembled an electric motorized longboard

Expo<sup>®</sup> Marker Digitizer, October 2017 (Tufts Hackathon)

• Designed and assembled a removable pen digitizer for a whiteboard marker to generate PDF files of handwriting