Jeremy C. Kanovsky

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EDUCATION TUFTS UNIVERSITY, Medford, MA

Bachelor of Science in Mechanical Engineering, Expected May 2021 Bachelor of Science in Computer Science, Expected May 2021

GPA: 3.55/4.00, Dean's List

NEW HOPE SOLEBURY HIGH SCHOOL, New Hope, PA, Graduated 2017

GPA: 96.5/100, National Honor Society

RELEVANT COURSES **MECHANICAL ENGINEERING:** Mechanical Statics and Dynamics, Thermodynamics, Simple Robotics, Intro Electrical Systems

COMPUTER SCIENCE: Machine Structure and Assembly, Artificial Intelligence,

Data Structures, Algorithms, Web Programming, Graphical User Interfaces
SCIENCE AND MATHEMATICS: Discrete Mathematics, Physics – Electricity and

Magnetism, Chemical Fundamentals, Differential Equations

WORK EXPERIENCE **SPECIALTY PAPERS AND FILMS, INC.,** New Hope, PA, August 2016 – June 2017 *Lab Assistant, Lab Technician*

- Developed printed circuitry, performed product testing and experimental method development
- Operated a differential scanning calorimeter and thermal transfer printers **CANNONVILLE BEACH ASSOCIATION, Mattapoisett, MA, Summers 2014 2017**
 - Managed beach cleanup and admission

RESEARCH EXPERIENCE TUFTS UNIVERSITY, DEPARTMENT OF MECHANICAL ENGINEERING,

Undergraduate Research Project, May 2018 – Present

- Developed code infrastructure to control multiple quadcopter UAVs
- Implemented UAV three-dimensional positioning system and feedback control

SKILLS

Computer: C/C++, Java, HTML, CSS, JavaScript, Git, Python

Design: Adobe Illustrator, Adobe Photoshop

Hardware: Arduino, Raspberry Pi, Computer Assembly

Lab: Differential Scanning Calorimeter, Transfer Thermal Printing

ACTIVITIES

Tufts Engineering Student Council, Treasurer, January 2018 – Present

Tufts Robotics Team, *Treasurer*, September 2017 – Present **Tufts MAKE Club**, *Project Leader*, September 2017 – Present **Tufts Rocketry Team**, *Co-Founder*, November 2017 – Present **NHS Vex Robotics Team**, *Founder*, September 2016 – June 2017

PROJECTS

Autonomous Quadcopter UAV, January 2018 – May 2018

• Lead a project team designing, building, and programming a semi-autonomous quadcopter UAV for open-ended applications

Trinity Firefighting Robot, December 2017 – May 2018

• Designed, fabricated, and programmed a robot entered in the Trinity College International Robot Contest

Motorized Longboard, September 2017 – December 2017

• Designed and assembled an electric motorized longboard

Expo® Marker Digitizer, October 2017 (Tufts Hackathon)

• Designed and assembled a removable pen digitizer for a whiteboard marker to generate PDF files of handwriting