

# Chapter 5 Solutions

## Question 1

Firstly, let's rewrite  $f(x)$  as  $f(x) = 4 \log(x) \sin(x^3)$ .

Then,  $f'(x) = \frac{4}{x} \sin(x^3) + 12x^2 \log(x) \cos(x^3)$ .

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## Question 2

If we rewrite our function as  $f(x) = (1 + \exp(-x))^{-1}$ , then we have  $f'(x) = \frac{\exp(-x)}{(1+\exp(-x))^2}$ .

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## Question 3

We have  $f'(x) = \frac{\mu-x}{\sigma^2} f(x)$ .

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## Question 4

We compute the first five derivatives of our function at 0. We have  $f(0) = f'(0) = 1$ ,  $f^{(2)}(0) = f^{(3)}(0) = -1$ , and  $f^{(4)}(0) = f^{(5)}(0) = 1$ .

The Taylor polynomial  $T_5(x) = 1 + x - \frac{1}{2}x^2 - \frac{1}{6}x^3 + \frac{1}{24}x^4 + \frac{1}{120}x^5$ . The lower-order Taylor polynomials can be found by truncating this expression appropriately.

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## Question 5

### Part a

We can see below that  $\frac{\partial f_1}{\partial x}$  has dimension  $1 \times 2$ ;  $\frac{\partial f_2}{\partial x}$  has dimension  $1 \times n$ ; and  $\frac{\partial f_3}{\partial x}$  has dimension  $n^2 \times n$ .

### Part b

We have  $\frac{\partial f_1}{\partial x} = \begin{bmatrix} \cos(x_1) \cos(x_2) & -\sin(x_1) \sin(x_2) \end{bmatrix}$ ;  $\frac{\partial f_2}{\partial x} = y^\top$ . (Remember,  $y$  is a column vector!)

### Part c

Note that  $xx^T$  is the matrix  $\begin{bmatrix} x_1^2 & x_1 x_2 & \cdots & x_1 x_n \\ x_2 x_1 & x_2^2 & \cdots & x_2 x_n \\ \vdots & \vdots & \ddots & \vdots \\ x_n x_1 & x_n x_2 & \cdots & x_n^2 \end{bmatrix}$ . Thus its derivative will be a higher-order tensor.

However, if we consider the matrix to be an  $n^2$ -dimensional object in its own right, we can compute the Jacobian. Its first row consists of  $\left[ 2x_1 \quad x_2 \quad \cdots \quad x_n \mid x_2 \quad 0 \quad \cdots \quad 0 \mid \cdots \mid x_n \quad 0 \quad \cdots \quad 0 \right]$ , where I have inserted a vertical bar every  $n$  columns, to aid readability.

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## Question 6

We have  $\frac{df}{dt} = \cos(\log(t^T t)) \cdot \frac{1}{t^T t} \cdot \begin{bmatrix} 2t_1 & 2t_2 & \cdots & 2t_D \end{bmatrix} = \cos(\log(t^T t)) \cdot \frac{2t^T}{t^T t}$ .

For  $g$ , we know that the derivative of the trace is the trace of the derivative. Thus, we need to find  $\frac{d(AXB)}{dX}$ .

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## Question 7

### Part a

The chain rule tells us that  $\frac{df}{dx} = \frac{df}{dz} \frac{dz}{dx}$ , where  $\frac{df}{dz}$  has dimension  $1 \times 1$ , and  $\frac{dz}{dx}$  has dimension  $1 \times D$ . We know  $\frac{dz}{dx} = 2x^T$  from  $f$  in Question 6. Also,  $\frac{df}{dz} = \frac{1}{1+z}$ .

Therefore,  $\frac{df}{dx} = \frac{2x^T}{1+x^T x}$ .

### Part b

Here we have  $\frac{df}{dz}$  is an  $E \times E$  matrix, namely  $\begin{bmatrix} \cos z_1 & 0 & \cdots & 0 \\ 0 & \cos z_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \cos z_E \end{bmatrix}$ .

Also,  $\frac{dz}{dx}$  is an  $E \times D$ -dimensional matrix, namely  $A$  itself.

The overall derivative is obtained by multiplying these two matrices together, which will again give us an  $E \times D$ -dimensional matrix.

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## Question 8

### Part a

We have  $\frac{df}{dz}$  has dimension  $1 \times 1$ , and is simply  $-\frac{1}{2} \exp(-\frac{1}{2} z)$ .

Now,  $\frac{dz}{dy}$  has dimension  $1 \times D$ , and is given by  $y^\top (S^{-1} + (S^{-1})^\top)$ .

Finally,  $\frac{dy}{dx}$  has dimension  $D \times D$ , and is just the identity matrix.

Again, we multiply these all together to get our final derivative.

## Part b

If we explicitly write out  $xx^\top + \sigma^2 I$ , and compute its trace, we find that  $f(x) = x_1^2 + \dots + x_n^2 + n\sigma^2$ .

Hence,  $\frac{df}{dx} = 2x^\top$ .

## Part c

$$\text{Here, } \frac{df}{dz} = \begin{bmatrix} \frac{1}{\cosh^2 z_1} & 0 & \dots & 0 \\ 0 & \frac{1}{\cosh^2 z_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{1}{\cosh^2 z_M} \end{bmatrix}, \text{ while } \frac{dz}{dx} = A, \text{ as in Question 7b.}$$

Finally,  $\frac{df}{dx}$  is given by the product of these two matrices.

## Question 9

Piecing this together, replacing  $z$  with  $t(\epsilon, \nu)$  throughout, we have that  $g(\nu) = \log(p(x, t(\epsilon, \nu))) - \log(q(t(\epsilon, \nu), \nu))$ .

Therefore,  $\frac{dg}{d\nu} = \frac{p'(x, t(\epsilon, \nu)) \cdot t'(\epsilon, \nu)}{p(x, t(\epsilon, \nu))} - \frac{q'(t(\epsilon, \nu), \nu) \cdot t'(\epsilon, \nu)}{q(t(\epsilon, \nu), \nu)}$ .