Optimization for Machine Learning CS-439

Lecture 2: Gradient Descent

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EPFL - github.com/epfml/OptML_course

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Recap

Convexity

recap,

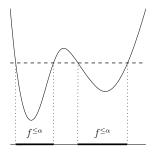
and short addition before we get to gradient descent...

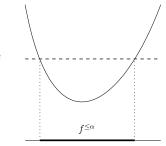
Existence of a minimizer

Sublevel sets: Let $f : \mathbf{dom}(f) \to \mathbb{R}$, $\alpha \in \mathbb{R}$. The set

$$f^{\leq \alpha} := \{\mathbf{x} \in \mathbf{dom}(f) : f(\mathbf{x}) \leq \alpha\}$$

is the α -sublevel set of f;





Weierstrass Theorem

Theorem

Let $f: \mathbf{dom}(f) \to \mathbb{R}$ be a convex function, $\mathbf{dom}(f)$ open, and suppose there is a nonempty and bounded sublevel set $f^{\leq \alpha}$. Then f has a global minimum.

Proof.

github.com/epfml/...

Chapter 2

Gradient Descent

The Algorithm

How to get near to a minimum x^* ?

(Assumptions: $f: \mathbb{R}^d o \mathbb{R}$ convex, differentiable, has a global minimum \mathbf{x}^\star)

Goal: Find $\mathbf{x} \in \mathbb{R}^d$ such that

E>0

nocuracy

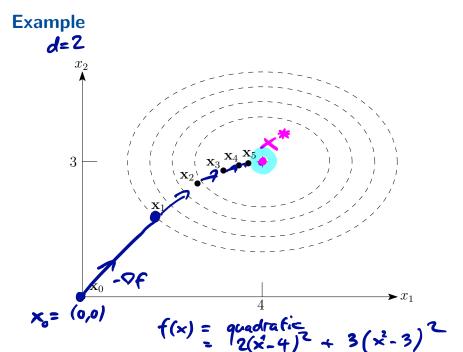
$$f(\mathbf{x}) - f(\mathbf{x}^*) \le \varepsilon.$$

Note that there can be several minima $\mathbf{x}_1^\star \neq \mathbf{x}_2^\star$ with $f(\mathbf{x}_1^\star) = f(\mathbf{x}_2^\star)$.

Iterative Algorithm:

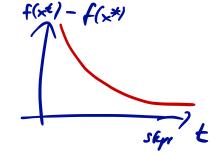
$$\mathbf{x}_{t+1} := \mathbf{x}_t - \gamma \nabla f(\mathbf{x}_t),$$

for timesteps $t = 0, 1, \ldots$, and stepsize $\gamma \ge 0$.



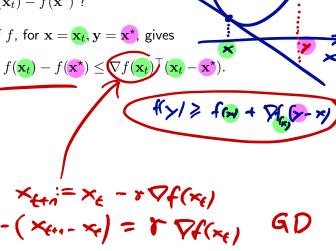
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How to bound $f(\mathbf{x}_t) - f(\mathbf{x}^{\star})$?



How to bound $f(\mathbf{x}_t) - f(\mathbf{x}^*)$?

► Convexity of f, for $\mathbf{x} = \mathbf{x}_t, \mathbf{y} = \mathbf{x}^*$, gives



How to bound $f(\mathbf{x}_t) - f(\mathbf{x}^*)$?

lacktriangle Convexity of f, for $\mathbf{x} = \mathbf{x}_t, \mathbf{y} = \mathbf{x}^{\star}$, gives

$$f(\mathbf{x}_t) - f(\mathbf{x}^*) \le \nabla f(\mathbf{x}_t)^\top (\mathbf{x}_t - \mathbf{x}^*).$$

lacktriangle Apply the definition of the iteration, $abla f(\mathbf{x}_t) = (\mathbf{x}_t - \mathbf{x}_{t+1})/\gamma$:



$$f(\mathbf{x}_t) - f(\mathbf{x}^{\star}) \leq \frac{1}{\gamma} (\mathbf{x}_t - \mathbf{x}_{t+1})^{\top} (\mathbf{x}_t - \mathbf{x}^{\star}).$$



nilla analysis
How to bound
$$f(\mathbf{x}_t) - f(\mathbf{x}^*)$$
?

• Convexity of f, for $\mathbf{x} = \mathbf{x}_t, \mathbf{y} = \mathbf{x}^*$, gives

$$f(\mathbf{x}_t) - f(\mathbf{x}^*) \le \nabla f(\mathbf{x}_t)^\top (\mathbf{x}_t - \mathbf{x}^*). \quad \text{and} \quad \mathbf{x} - \mathbf{x}^*$$

Apply the definition of the iteration, $\nabla f(\mathbf{x}_t) = (\mathbf{x}_t - \mathbf{x}_{t+1})/\gamma$:

$$f(\mathbf{x}_t) - f(\mathbf{x}^*) \le \frac{1}{\gamma} (\mathbf{x}_t - \mathbf{x}_{t+1})^\top (\mathbf{x}_t - \mathbf{x}^*).$$

Now we apply $2\mathbf{v}^{\mathsf{T}}\mathbf{w} = (|\mathbf{v}||^2) - (|\mathbf{w}||^2) - ||\mathbf{v} - \mathbf{w}||^2$

$$f(\mathbf{x}_{t}) - f(\mathbf{x}^{\star}) \leq \frac{1}{2\gamma} \left(\|\mathbf{x}_{t} - \mathbf{x}_{t+1}\|^{2} + \|\mathbf{x}_{t} - \mathbf{x}^{\star}\|^{2} - \|\mathbf{x}_{t+1} - \mathbf{x}^{\star}\|^{2} \right)$$

$$= \frac{1}{2\gamma} \left(\gamma^{2} \|\nabla f(\mathbf{x}_{t})\|^{2} + \|\mathbf{x} - \mathbf{x}^{\star}\|^{2} - \|\mathbf{x}_{t+1} - \mathbf{x}^{\star}\|^{2} \right)$$

again by the definition gradient descent

Vanilla analysis, cont.



sum this over steps $t = 0, \dots, T-1$:

$$\sum_{t=0}^{T-1} \left(f(\mathbf{x}_t) - f(\mathbf{x}^*) \right)$$

$$\leq \frac{\gamma}{2} \sum_{t=0}^{T-1} \left(\left\| \nabla f(\mathbf{x}_t) \right\|^2 + \frac{1}{2\gamma} \left(\left\| \mathbf{x}_0 - \mathbf{x}^* \right\|^2 - \left\| \mathbf{x}_T - \mathbf{x}^* \right\|^2 \right) \right)$$

$$\leq \frac{\gamma}{2} \sum_{t=0}^{T-1} \left\| \nabla f(\mathbf{x}_t) \right\|^2 + \frac{1}{\gamma\gamma} \left\| \mathbf{x}_0 - \mathbf{x}^* \right\|^2$$

an upper bound for the average error $f(\mathbf{x}_t) - f(\mathbf{x}^{\star})$, $t = 0 \dots T - 1$

- last iterate is not necessarily the best one
- stepsize is crucial

Bounded gradients: $\mathcal{O}(1/\varepsilon^2)$ **steps**

Assume that all gradients of f are bounded in norm.

Theorem

Let $f: \mathbb{R}^d \to \mathbb{R}$ be convex and differentiable with a global minimum \mathbf{x}^{\star} : furthermore, suppose that $\|\mathbf{x}_0 - \mathbf{x}^{\star}\| \leq R$ and $\|\nabla f(\mathbf{x})\| \leq L$ for all \mathbf{x} . Choosing the stepsize

$$\gamma := \frac{R}{L\sqrt{T}},$$

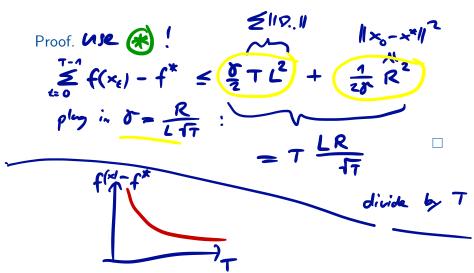
gradient descent yields

$$\frac{1}{T} \sum_{t=0}^{T-1} f(\mathbf{x}_t) - f(\mathbf{x}^*) \leq \frac{RL}{\sqrt{T}}.$$

$$\leq \frac{RL}{\sqrt{T}}$$
.

$$f(y) - f(x) \le L \cdot ||x - y||$$

Bounded gradients: $\mathcal{O}(1/\varepsilon^2)$ steps, II



Bounded gradients: $\mathcal{O}(1/\varepsilon^2)$ steps, II

Advantages:

- dimension-independent!
- ▶ holds for both average, or best iterate

d >>0

In Practice:

What if we don't know R and L?

 \rightarrow Exercise 13

$$f(x_{\ell}) - f^{**} \leq \mathcal{O}(\frac{1}{\sqrt{17}}) \leq \xi$$

Smooth functions:
$$O(1/\varepsilon)$$
 steps

Convex, but not too convex?

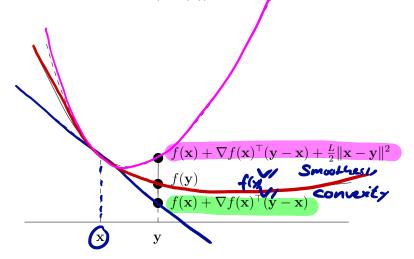
Definition

Let $f: \mathbb{R}^d \to \mathbb{R}$ be convex and differentiable, $L \in \mathbb{R}_+$. f is called smooth (with parameter L) if

$$f(\mathbf{y}) \le f(\mathbf{x}) + \nabla f(\mathbf{x})^{\mathsf{T}} (\mathbf{y} - \mathbf{x}) + \frac{L}{2} ||\mathbf{x} - \mathbf{y}||^2, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

Smooth functions: $\mathcal{O}(1/\varepsilon)$ steps

Smoothness: For any x, the graph of f is below a not-too-steep tangential paraboloid at (x, f(x)):



Smooth functions: $\mathcal{O}(1/\varepsilon)$ steps

Quadratic functions are smooth

- f(x) := ||x||2
- ▶ Operations that preserve smoothness:

Lemma (Exercise 15)

- (i) Let f_1, f_2, \ldots, f_m be convex functions that are smooth with parameters L_1, L_2, \ldots, L_m , and let $\lambda_1, \lambda_2, \ldots, \lambda_m \in \mathbb{R}_+$. Then the convex function $f := \sum_{i=1}^m \lambda_i f_i$ is smooth with parameter $\sum_{i=1}^n \lambda_i L_i$.
- (ii) Let f be convex and smooth with parameter L, and let $g(\mathbf{x}) = A\mathbf{x} + \mathbf{b}$, for $A \in \mathbb{R}^{d \times m}$ and $\mathbf{b} \in \mathbb{R}^d$. Then the convex function $f \circ g$ is smooth with parameter $L \|A\|^2$, where

$$||A|| = \max_{\max} \frac{||A\mathbf{x}||}{||\mathbf{x}||} = \max_{\max} ||A\mathbf{x}||$$

is the 2-norm (or spectral norm) of A.

Smooth functions: $\mathcal{O}(1/\varepsilon)$ steps

Convergence proof: See next lecture