

1 Message Types

Messages can be divided into two categories. The first are standardized SBP messages which are the messages described in this document. The second category is for messages which are specific to a particular hardware platform and are implementation defined. These messages are defined to have message types in the range 0x0000 – 0x00FF.

Message	Name	Size	Description
0x0100	GPS_TIME	11	GPS Time
0x0206	DOPS	14	Dilution of Precision
0x0200	POS_ECEF	32	Position in ECEF
0x0201	POS_LLH	34	Geodetic Position
0x0202	BASELINE_ECEF	20	Baseline in ECEF
0x0203	BASELINE_NED	22	Baseline in NED
0x0204	VEL_ECEF	20	Velocity in ECEF
0x0205	VEL_NED	22	Velocity in NED

Table 1.0.1: Summary of message types

1.1 GPS_TIME (0x0100)

GPS Time.

Offset	Size	Format	Units	Name	Description
0	2	u16	weeks	wn	GPS week number
2	4	u32	ms	tow	GPS Time of Week rounded to the nearest ms
6	4	s32	ns	ns	Nanosecond remainder of rounded tow
10	1	u8		flags	Status flags (reserved)
11					

Table 1.1.1: GPS_TIME 0x0100 message structure

1.2 DOPS (0x0206)

Dilution of Precision.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	tow	GPS Time of Week
4	2	u16	0.01	gdop	Geometric Dilution of Precision
6	2	u16	0.01	pdop	Position Dilution of Precision
8	2	u16	0.01	tdop	Time Dilution of Precision
10	2	u16	0.01	hdop	Horizontal Dilution of Precision
12	2	u16	0.01	vdop	Vertical Dilution of Precision
14					

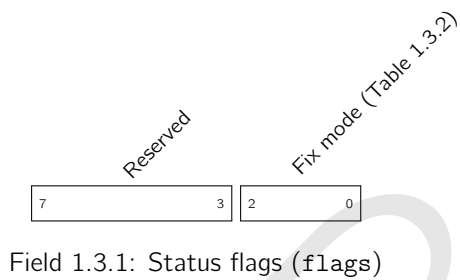
Table 1.2.1: DOPS 0x0206 message structure

1.3 POS_ECEF (0x0200)

Position solution in absolute Earth Centered Earth Fixed (ECEF) coordinates.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	<code>tow</code>	GPS Time of Week
4	8	double	m	<code>x</code>	ECEF X coordinate
12	8	double	m	<code>y</code>	ECEF Y coordinate
20	8	double	m	<code>z</code>	ECEF Z coordinate
28	2	u16	mm	<code>accuracy</code>	Position accuracy estimate
30	1	u8		<code>n_sats</code>	Number of satellites used in solution
31	1	u8		<code>flags</code>	Status flags, <i>See Field 1.3.1</i>
32					

Table 1.3.1: POS_ECEF 0x0200 message structure



Value	Description
0	Single Point Positioning (SPP)
1	RTK

Table 1.3.2: Fix mode values (`flags[0:2]`)

1.4 POS_LLH (0x0201)

Geodetic position solution.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	tow	GPS Time of Week
4	8	double	deg	lat	Latitude
12	8	double	deg	lon	Longitude
20	8	double	m	height	Height
28	2	u16	mm	h_accuracy	Horizontal position accuracy estimate
30	2	u16	mm	v_accuracy	Vertical position accuracy estimate
32	1	u8		n_sats	Number of satellites used in solution
33	1	u8		flags	Status flags, <i>See Field 1.4.1</i>
34					

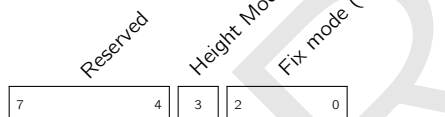
Table 1.4.1: POS_LLH 0x0201 message structure

Value	Description
0	Single Point Positioning (SPP)
1	RTK

Table 1.4.2: Fix mode values (flags[0:2])

Value	Description
0	Height above Ellipsoid
1	Height above mean sea level

Table 1.4.3: Height Mode values (flags[3])



Field 1.4.1: Status flags (flags)

1.5 BASELINE_ECEF (0x0202)

Baseline in Earth Centered Earth Fixed (ECEF) coordinates.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	<code>tow</code>	GPS Time of Week
4	4	s32	mm	<code>x</code>	Baseline ECEF X coordinate
8	4	s32	mm	<code>y</code>	Baseline ECEF Y coordinate
12	4	s32	mm	<code>z</code>	Baseline ECEF Z coordinate
16	2	u16	mm	<code>accuracy</code>	Position accuracy estimate
18	1	u8		<code>n_sats</code>	Number of satellites used in solution
19	1	u8		<code>flags</code>	Status flags (reserved)
20					

Table 1.5.1: BASELINE_ECEF 0x0202 message structure

1.6 BASELINE_NED (0x0203)

Baseline in local North East Down (NED) coordinates.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	tow	GPS Time of Week
4	4	s32	mm	n	Baseline North coordinate
8	4	s32	mm	e	Baseline East coordinate
12	4	s32	mm	d	Baseline Down coordinate
16	2	u16	mm	h_accuracy	Horizontal position accuracy estimate
18	2	u16	mm	v_accuracy	Vertical position accuracy estimate
20	1	u8		n_sats	Number of satellites used in solution
21	1	u8		flags	Status flags (reserved)
22					

Table 1.6.1: BASELINE_NED 0x0203 message structure

1.7 VEL_ECEF (0x0204)

Velocity in Earth Centered Earth Fixed (ECEF) coordinates.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	tow	GPS Time of Week
4	4	s32	mm/s	x	Velocity ECEF X coordinate
8	4	s32	mm/s	y	Velocity ECEF Y coordinate
12	4	s32	mm/s	z	Velocity ECEF Z coordinate
16	2	u16	mm/s	accuracy	Velocity accuracy estimate
18	1	u8		n_sats	Number of satellites used in solution
19	1	u8		flags	Status flags (reserved)
20					

Table 1.7.1: VEL_ECEF 0x0204 message structure

1.8 VEL_NED (0x0205)

Velocity in local North East Down (NED) coordinates.

Offset	Size	Format	Units	Name	Description
0	4	u32	ms	tow	GPS Time of Week
4	4	s32	mm/s	n	Velocity North coordinate
8	4	s32	mm/s	e	Velocity East coordinate
12	4	s32	mm/s	d	Velocity Down coordinate
16	2	u16	mm/s	h_accuracy	Horizontal velocity accuracy estimate
18	2	u16	mm/s	v_accuracy	Vertical velocity accuracy estimate
20	1	u8		n_sats	Number of satellites used in solution
21	1	u8		flags	Status flags (reserved)
22					

Table 1.8.1: VEL_NED 0x0205 message structure