## Algorithm parameters: step size $\alpha \in (0, 1]$ , small $\varepsilon > 0$ Initialize $Q_1(s, a)$ and $Q_2(s, a)$ , for all $s \in S^+$ , $a \in A(s)$ , such that $Q(terminal, \cdot) = 0$

Double Q-learning, for estimating  $Q_1 \approx Q_2 \approx q_*$ 

Loop for each episode: Initialize S

Loop for each step of episode:

Choose A from S using the policy 
$$\varepsilon$$
-greedy in  $Q_1 + Q_2$   
Take action A, observe  $R, S'$ 

With 0.5 probability:

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$$Q_1(S,A) \leftarrow Q_1(S,A) + \alpha \left(R + \gamma Q_2(S', \operatorname{arg\,max}_a Q_1(S',a)) - Q_1(S,A)\right)$$

else:

$$Q_2(S,A) \leftarrow S \leftarrow S'$$
until  $S$  is terminal

 $Q_2(S,A) \leftarrow Q_2(S,A) + \alpha \left(R + \gamma Q_1(S', \operatorname{arg\,max}_a Q_2(S',a)) - Q_2(S,A)\right)$