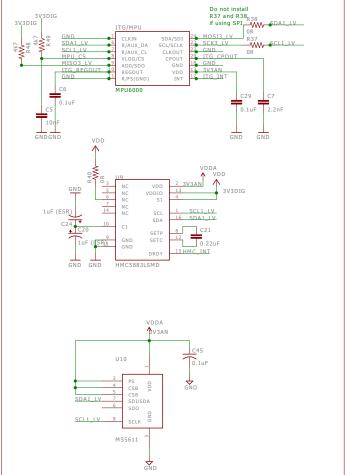


Sensors



Receiver: TIM1, TIM4

Motor: TIM8, TIM2, TIM3

Servo: TIM5

