

Example RISC-V Assembly Programs

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Most of these instructions do not use *aliases* (aka [pseudo instructions](#)) so that you can test your ISA emulator without the assembler changing instructions on you. However, some instructions you will see use aliases, such as `la` (load address) since we need the assembler to fill in the memory address of a given symbol.

We will also discuss the choices of instructions and flow of program in class. Make sure you follow each element, and then we will discuss why I chose not to do a 1-for-1 translation of C-to-assembly in some of these programs.

When testing your emulator, test the following by assembling using the given linker script `org.ld`s.

String Length

Determine the length of a C-style string by adding 1 until we find the terminator `'\0'`.

```
int strlen(const char *str) {
int i;
for (i = 0; str[i] != '\0'; i++);
return i;
}
```

```
.section .text
```

```
.global strlen
```

```
strlen:
```

```
# a0 = const char *str
```

```
add t0, zero, zero # i = 0
```

```
1: # Start of for loop
```

```

add t1, t0, a0 # Add the byte offset for str[i]
lb t1, 0(t1) # Dereference str[i]
beq t1, zero, 1f # if str[i] == 0, break for loop
addi t0, t0, 1 # Add 1 to our iterator
jal zero, 1b # Jump back to condition (1 backwards)
1: # End of for loop
addi a0, t0, 0 # Move t0 into a0 to return
jalr zero, ra # Return back via the return address register

```

String Copy

Copy one C-style string into another. I expanded the actual implementation to make it easier to see each element in assembly.

```

void stringcopy(char *dst, const char *src) {
do {
// Copy the source's byte into the destination's byte
*dst = *src;
// We check '\0' here so that we copy the source's \0
// into the destination.
if (*src == '\0') break;
// Advance both the destination and source to the next byte.
dst++;
src++;
} while (true);
}

.section .text
.global stringcopy
stringcopy:
# a0 = destination
# a1 = source
1:
lb t0, 0(a1) # Load a char from the src
sb t0, 0(a0) # Store the value of the src
beq t0, zero, 1f # Check if it's 0
addi a0, a0, 1 # Advance destination one byte

```

```

addi a1, a1, 1 # Advance source one byte
jal zero, 1b # Go back to the start of the loop
1:
jalr zero, 0(ra) # Return back via the return address

```

String Copy (n bytes)

```

// from the strncpy man pages
char *strncpy(char *dst, const char *src, unsigned long n) {
unsigned long i;
for (i = 0; i < n && src[i] != '\0'; i++)
    dst[i] = src[i];
for ( ; i < n; i++)
    dst[i] = '\0';
return dst;
}

.section .text
.global strncpy
strncpy:
# a0 = char *dst
# a1 = const char *src
# a2 = unsigned long n
# t0 = i
addi t0, zero, 0 # i = 0
1: # first for loop
bge t0, a2, 1f # break if i >= n
add t1, a1, t0 # src + i
lb t1, 0(t1) # t1 = src[i]
beq t1, zero, 1f # break if src[i] == '\0'
add t2, a0, t0 # t2 = dst + i
sb t1, 0(t2) # dst[i] = src[i]
addi t0, t0, 1 # i++
jal zero, 1b # back to beginning of loop
1: # second for loop
bge t0, a2, 1f # break if i >= n

```

```

add t1, a0, t0 # t1 = dst + i
sb zero, 0(t1) # dst[i] = 0
addi t0, t0, 1 # i++
jal zero, 1b # back to beginning of loop
1:
# we don't have to move anything since
# a0 hasn't changed.
jalr zero, 0(ra) # return via return address register

```

Reverse a string

```

void strrev(char *str) {
    int i;
    int sz = strlen(str);
    for (i = 0; i < sz / 2; i++) {
        char c = str[i];
        str[i] = str[sz - i - 1];
        str[sz - i - 1] = c;
    }
}

.section .text
.global strrev
strrev:
    # s1 = str
    # a0 = sz
    # t0 = sz / 2
    # t1 = i
    # Enter stack frame
    addi sp, sp, -16
    sd ra, 0(sp)
    sd s1, 8(sp)
    # Get the size of the string
    mv s1, a0
    call strlen
    srai t0, a0, 1 # Divide sz by 2

```

```

li t1, 0 # i = 0
1: # for loop
bge t1, t0, 1f
add t2, s1, t1 # str + i
sub t3, a0, t1 # sz - i
addi t3, t3, -1 # sz - i - 1
add t3, t3, s1 # str + sz - i - 1
lb t4, 0(t2) # str[i]
lb t5, 0(t3) # str[sz - i - 1]
sb t4, 0(t3) # swap
sb t5, 0(t2)
addi t1, t1, 1
j 1b
1:
# Leave stack frame
ld s1, 8(sp)
ld ra, 0(sp)
addi sp, sp, 16
ret

```

Sum of an Integer Array

```

int arraysum(int a[], int size) {
int ret = 0;
int i;
for (i = 0; i < size; i++) {
ret = ret + a[i];
}
return ret;
}

.section .text
.global arraysum
arraysum:
# a0 = int a[]
# a1 = int size

```

```

# t0 = ret
# t1 = i
addi t0, zero, 0 # ret = 0
addi t1, zero, 0 # i = 0
1: # For loop
bge t1, a1, 1f # if i >= size, break
slli t2, t1, 2 # Multiply i by 4 (1 << 2 = 4)
add t2, a0, t2 # Update memory address
lw t2, 0(t2) # Dereference address to get integer
add t0, t0, t2 # Add integer value to ret
addi t1, t1, 1 # Increment the iterator
jal zero, 1b # Jump back to start of loop (1 backwards)
1:
addi a0, t0, 0 # Move t0 (ret) into a0
jalr zero, 0(ra) # Return via return address register

```

Bubble Sort

```

void bubsort(long *list, int size) {
bool swapped;
do {
    swapped = false;
    for (int i = 1; i < size; i++) {
        if (list[i-1] > list[i]) {
            swapped = true;
            long tmp = list[i-1];
            list[i-1] = list[i];
            list[i] = tmp;
        }
    }
} while (swapped);
}

.section .text
.global bubsort
bubsort:

```

```

# a0 = long *list
# a1 = size
# t0 = swapped
# t1 = i
1: # do loop
addi t0, zero, 0 # swapped = false
addi t1, zero, 1 # i = 1
2: # for loop
bge t1, a1, 2f # break if i >= size
slli t3, t1, 3 # scale i by 8 (for long)
add t3, a0, t3 # new scaled memory address
ld t4, -8(t3) # load list[i-1] into t4
ld t5, 0(t3) # load list[i] into t5
ble t4, t5, 3f # if list[i-1] < list[i], it's in position
# if we get here, we need to swap
addi t0, zero, 1 # swapped = true
sd t4, 0(t3) # list[i] = list[i-1]
sd t5, -8(t3) # list[i-1] = list[i]
3: # bottom of for loop body
addi t1, t1, 1 # i++
jal zero, 2b # loop again
2: # bottom of do loop body
bne t0, zero, 1b # loop if swapped = true
jalr zero, 0(ra) # return via return address register

```

Distance Formula w/ 64-bit Floats

```

struct Coordinate {
double x;
double y;
};

double distance(const Coordinate &from, const Coordinate &to) {
double x = to.x - from.x;
double y = to.y - from.y;
return sqrt(x*x + y*y);
}

```

```

}

.section .text
.global distance
distance:
# a0 = Coordinate &from
# a1 = Coordinate &to
# Coordinate structure
# Name Offset Size (bytes)
# x 0 8
# y 8 8
# Total size = 16 bytes
fld ft0, 0(a0) # ft0 = from.x
fld ft1, 8(a0) # ft1 = from.y
fld ft2, 0(a1) # ft2 = to.x
fld ft3, 8(a1) # ft3 = to.y
fsub.d ft0, ft2, ft0 # ft0 = to.x - from.x
fsub.d ft1, ft3, ft1 # ft1 = to.y - from.y
fmul.d ft0, ft0, ft0 # ft0 = ft0 * ft0
fmul.d ft1, ft1, ft1 # ft1 = ft1 * ft1
fadd.d ft0, ft0, ft1 # ft0 = ft0 + ft1
fsqrt.d fa0, ft0 # fa0 = sqrt(ft0)
# Return value goes in fa0
jalr zero, 0(ra) # Return

```

Min Max w/ 32-bit Floats

```

void minmax(float a, float b, float c, float &mn, float &mx) {
mn = mx = a;
if (mn > b) mn = b;
else if (mx < b) mx = b;
if (mn > c) mn = c;
else if (mx < c) mx = c;
}

.section .text
.global minmax

```


minmax:

```
# fa0 = float a
# fa1 = float b
# fa2 = float c
# ft0 = min
# ft1 = max
# a0 = float &mn
# a1 = float &mx
# Set mn = mx = a
fmv.s ft0, fa0
fmv.s ft1, fa0
fgt.s t0, ft0, fa1 # if (mn > b)
beq t0, zero, 1f # skip if false
# if we get here, then mn is > b
fmv.s ft0, fa1 # ft0 is mn, set it to b
jal zero, 2f # jump past the else if statement
1:
flt.s t0, ft1, fa1 # else if (mx < b)
beq t0, zero, 2f # skip if false
# if we get here then mx < b
fmv.s ft1, fa1 # ft1 is mx, set it to b
2:
fgt.s t0, ft0, fa2 # if (mn > c)
beq t0, zero, 1f # skip if false
# if we get here then mn > c
fmv.s ft0, fa2 # ft0 is mn, set it to c
jal zero, 2f # skip the else if statement
1:
flt.s t0, ft1, fa2 # else if (mx < c)
beq t0, zero, 2f # skip if false
# If we get here then mx < c
fmv.s ft1, fa2 # ft1 is mx, set it to c
2:
fsw ft0, 0(a0) # store minimum into &mn
fsw ft1, 0(a1) # store maximum into &mx
jalr zero, 0(ra) # return via return address register
```

Add Element to Singly Linked List

```
LL *addll(LL *list, LL *element) {
    element->next = list;
    return element;
}

.section .text
.global addll
addll:
# a0 = list
# a1 = element
# LL structure
# Name Offset Size (bytes)
# data 0 2
# next 8 8
sd a0, 8(a1) # element->next = list
addi a0, a1, 0 # set a0 to return element instead of list
jalr zero, 0(ra) # return via return address register
```

Calling a C Function from Assembly

```
.section .rodata
enter_prompt: .asciz "Enter a, b, and c: "
scan: .asciz "%d %d %d"
result_out: .asciz "Result = %d\n"

.section .text
.global main
main:
addi sp, sp, -32 # Allocate 32 bytes from the stack
sd ra, 0(sp) # Since we are making calls, we need the original ra
# Prompt the user first
la a0, enter_prompt
jal ra, printf
# We've printed the prompt, now wait for user input
```

```

la a0, scan
addi a1, sp, 8 # Address of a is sp + 8
addi a2, sp, 16 # Address of b is sp + 16
addi a3, sp, 24 # Address of c is sp + 24
jal ra, scanf
# Now all of the values are in memory, load them
# so we can jal ra, the c function.
lw a0, 8(sp)
lw a1, 16(sp)
lw a2, 24(sp)
jal ra, cfunc
# The result should be in a0, but that needs to be
# the second parameter to printf.
add a1, zero, a0
la a0, result_out
jal ra, printf
# Restore original RA and return
ld ra, 0(sp)
addi sp, sp, 32 # Always deallocate the stack!
jalr zero, 0(ra)

// extern "C" is required so we can link the name into assembly
// without knowing how C++ mangles it.
extern "C" {
int cfunc(int a, int b, int c);
}

// Simple function we're going to call from assembly.
int cfunc(int a, int b, int c) {
return a + b * c;
}

```

Binary Search

```

int binsearch(const int arr[], int needle, int size) {
int mid;
int left = 0;

```

```

int right = size - 1;
while (left <= right) {
mid = (left + right) / 2;
// Needle is bigger than what we're looking at,
// only consider the upper half of the list.
if (needle > arr[mid]) {
left = mid + 1;
}
else if (needle < arr[mid]) {
right = mid - 1;
}
else {
return mid;
}
}
// We've gone through all elements and the needle wasn't found.
return -1;
}

```

```

.section .text
.global binsearch
binsearch:
# a0 = int arr[]
# a1 = int needle
# a2 = int size
# t0 = mid
# t1 = left
# t2 = right
addi t1, zero, 0 # left = 0
addi t2, a2, -1 # right = size - 1
1: # while loop
bgt t1, t2, 1f # left > right, break
add t0, t1, t2 # mid = left + right
srai t0, t0, 1 # mid = (left + right) / 2
# Get the element at the midpoint
slli t4, t0, 2 # Scale the midpoint by 4
add t4, a0, t4 # Get the memory address of arr[mid]

```

```

lw t4, 0(t4) # Dereference arr[mid]
# See if the needle (a1) > arr[mid] (t3)
ble a1, t4, 2f # if needle <= t3, we need to check the next condition
# If we get here, then the needle is > arr[mid]
addi t1, t0, 1 # left = mid + 1
jal zero, 1b
2:
bge a1, t4, 2f # skip if needle >= arr[mid]
# If we get here, then needle < arr[mid]
addi t2, t0, -1 # right = mid - 1
jal zero, 1b
2:
# If we get here, then needle == arr[mid]
addi a0, t0, 0
1:
jalr zero, 0(ra)

```

Vector x Matrix

```

void matmul(float dst[3], float matrix[3][3], float vector[3]) {
    int r;
    int c;
    float d;
    for (r = 0; r < 3; r++) {
        d = 0;
        for (c = 0; c < 3; c++) {
            d = d + matrix[r][c] * vector[c];
        }
        dst[r] = d;
    }
}

```

We don't always have to translate 100% from C++ into assembly. We can take shortcuts if we know how the data structure is set up. `matrix[3][3]` can be calculated by using `row * width + column`, and then scaling it by the data size. However, we can take a shortcut and just advance the matrix pointer by each integer for every iteration of the loop. Since our outer and inner loops both iterate 3 times, we will iterate a total of 9 times—exactly the number of elements in our matrix.

```

.section .text
.global matmul
matmul:
# a0 = dst[3]
# a1 = matrix[3][3]
# a2 = vector[3]
# t0 = r
# t1 = c
# t3 = 3
# ft0 = d
# Row for loop
addi t0, zero, 0
addi t3, zero, 3
1:
bge t0, t3, 1f # break when we are done
fmv.s.x fa0, zero # Set d = 0
# Column for loop
addi t1, zero, 0
2:
bge t1, t3, 2f
flw ft0, 0(a1) # Load matrix value
flw ft1, 0(a2) # Load vector value
fmul.s ft0, ft0, ft1 # ft0 = matrix[r][c] * vec[c]
fadd.s fa0, fa0, ft0 # d = d + ft0
addi t1, t1, 1
addi a1, a1, 4 # Move to the next matrix value
addi a2, a2, 4 # Move to the next vector value
jal zero, 2b
2:
addi a2, a2, -12 # Move the vector back to the top
fsw fa0, 0(a0) # dst[r] = d
addi t0, t0, 1
addi a0, a0, 4 # Move to next destination
jal zero, 1b
1:
jalr zero, 0(ra)

```

