ARCOS Group

uc3m Universidad Carlos III de Madrid

Lesson 4 (III) The processor

Computer Structure
Bachelor in Computer Science and Engineering



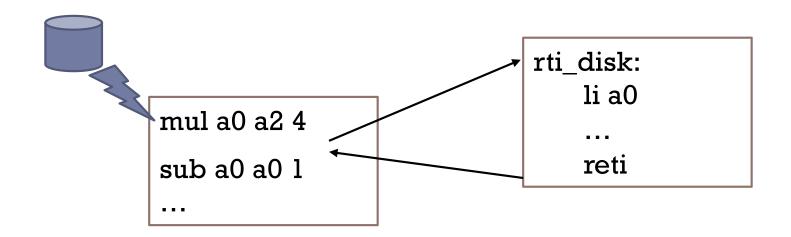
Contents

- Computer elements
- 2. Processor organization
- 3. Control unit
- 4. Execution of instructions
- 5. Control unit design
- 6. Execution modes
- 7. Interrupts
- 8. Computer startup
- 9. Performance and parallelism

Modes of execution

- ▶ It is indicated by a bit in the status register (U)
- At least 2 modes:
 - User Mode
 - The processor cannot execute privileged instructions (e.g.: I/O instructions, interrupt enable instructions, ...)
 - If a user process executes a privileged instruction, an interruption (exception) occurs
 - Kernel Mode
 - Reserved to the operating system
 - The processor can execute the entire repertoire of instructions

Interrupts



- ▶ Signal that arrives to the control unit (CU) and breaks the normal execution sequence:
 - The current program is stopped and the execution is transferred to another program that attend the interruption (ISR)
 - When the ISR ends, the execution of the interrupted program is resumed.
- Example of causes:
 - When a peripheral requests the attention of the processor,
 - When an error occurs in the execution of the instruction,
 - Etc.

Classification of interruptions

Synchronous hardware exceptions

When an error occurs in the execution of the instruction: Division by zero, access to an illegal memory position, illegal instruction, etc.

Asynchronous hardware exceptions

Faults or errors in hardware not related to current instruction: printer without paper, power failure, etc.

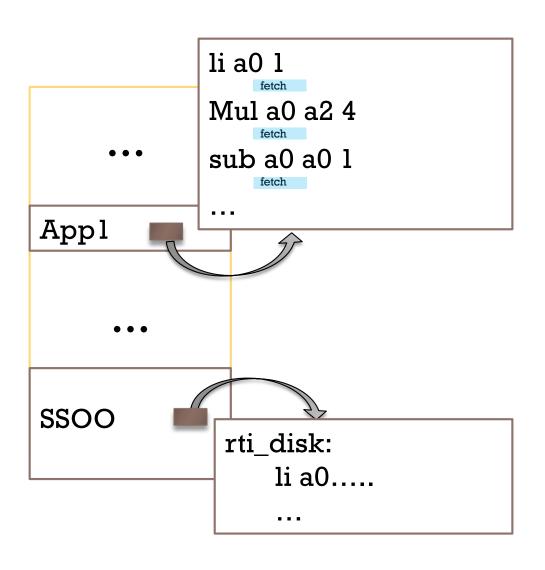
External interruptions

When a peripheral (or CPU) requests the attention of the CPU: Peripherals, clock interruption

System calls

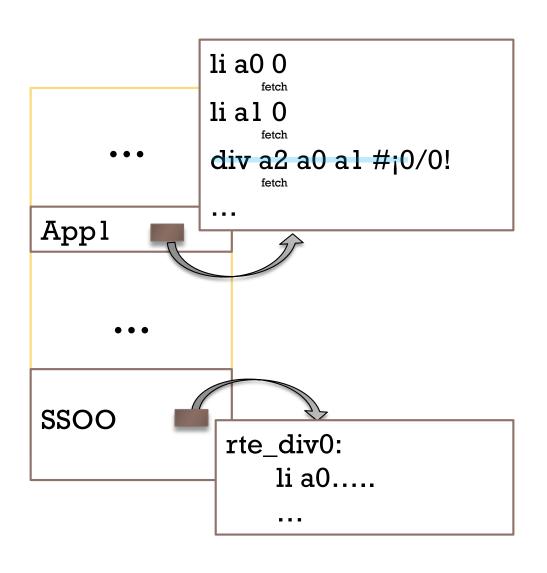
- Request an operating system service
 - Special machine instructions that generate an interruption to activate the operating system

Asynchronous Hardware Exceptions and External Interrupts



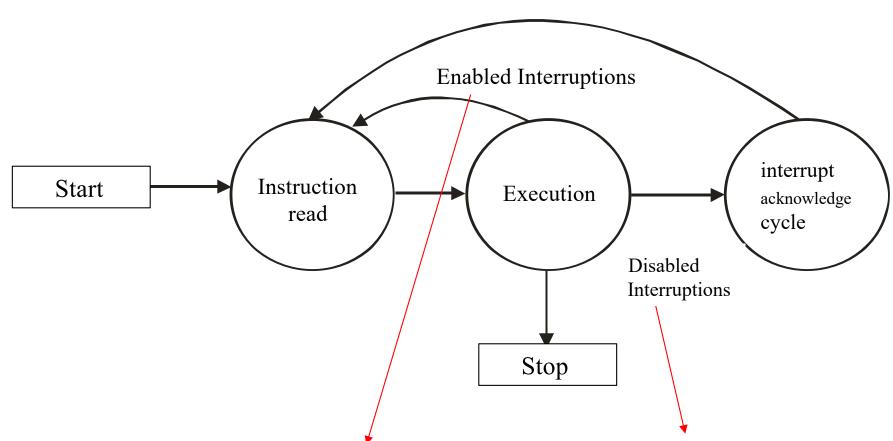
- They cause an unscheduled sequence break
 - Before doing the fetch cycle, first see if there is any pending interruption, and if so...
 - ...Bifurcation to subroutine of the O.S. that treats it
- It then restores the status and returns control to the interrupted program.
- Asynchronous cause to the execution of the current program
 - Peripheral care
 - Etc.

Synchronous hardware exceptions



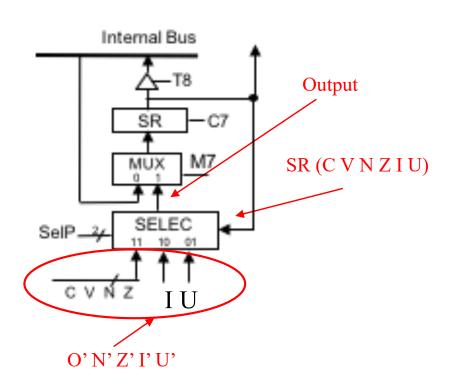
- They cause an unscheduled sequence break
 - Within the microprogram of the ongoing instruction...
 - ...Bifurcation to subroutine of the O.S. that treats it
- It restores the status and returns control to the interrupted program or ends its execution
- Synchronous cause to the execution of the current program
 - Division between zero
 - Etc.

Activation of the status register



It is indicated by a bit located in the status register (I)

Activation of the status register



SELEC operation:

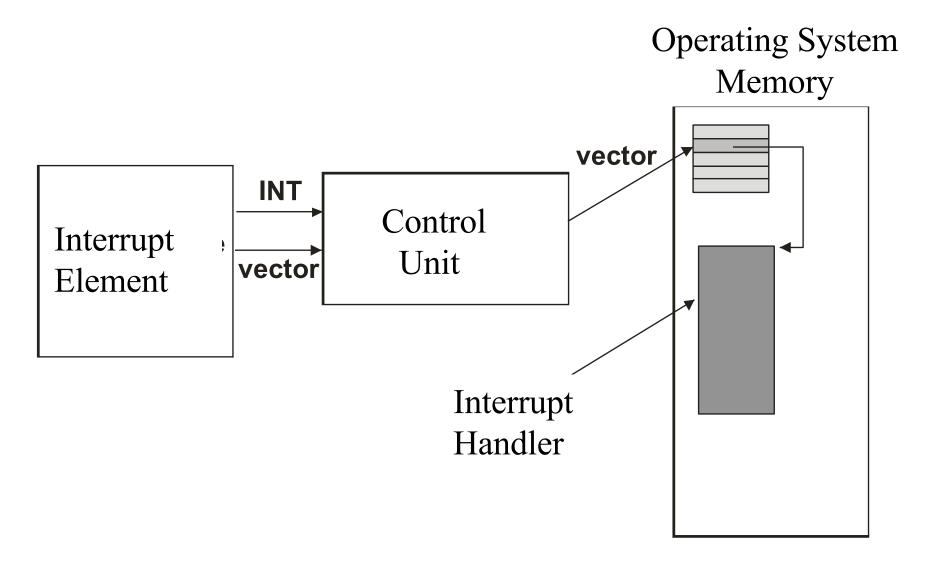
Interrupt Acknowledge Cycle (IAC)

- It is a microcode before the fetch cycle
 - It handles the asynchronous interrupts
- General structure of the IAC:
 - L. Checks if an interruption signal is activated.
 - 2. If it is activated:
 - 1. Saves the program counter and status register
 - ☐ Equivalent to "push pc, push sr"
 - 2. Switches from user mode to kernel mode
 - ☐ Equivalent to "SR.U = 0"
 - 3. Obtains the address of the Interrupt Service Routine (ISR)
 - □ Equivalent to "isr_addr = Vector_interrupts[id_interrupt]"
 - 4. Store the address obtained in the program counter (this way the following instruction will be the first one for the treatment routine)
 - ☐ Equivalent to "PC = isr_addr"

Interrupt service routine (ISR)

- It is part of the operating system code
 - There is one ISR for each interruption that may occur
- General structure of the ISR:
 - I. Saves the rest of the processor registers (if required)
 - 2. Service the interrupt
 - 3. Restores processor registers saved in (2)
 - 4. Executes a special machine instruction: RETI
 - Resets the status register of the interrupted program (by setting the processor mode back to user mode).
 - Resets the program counter (so that the next instruction is that of the interrupted program).

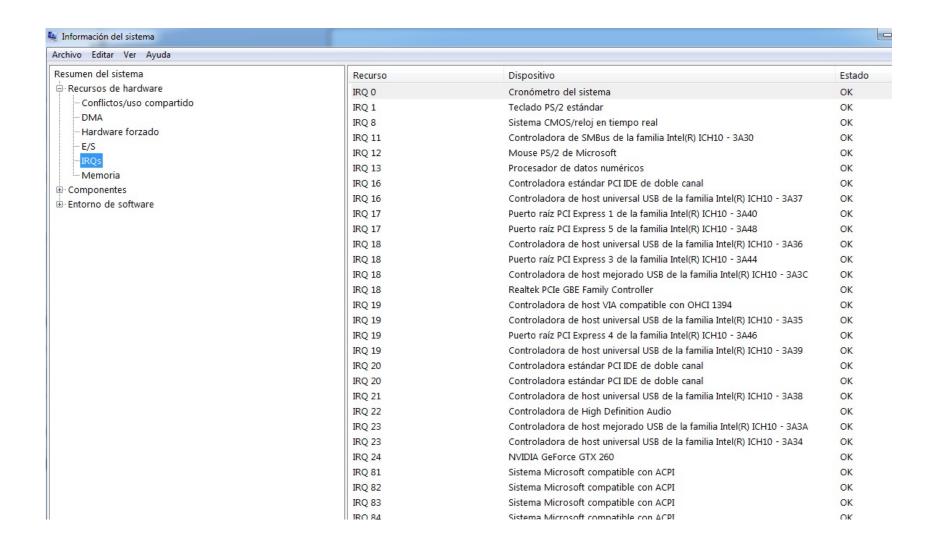
Vector interrupts



Vector interrupts

- ▶ The interrupting element supplies the interrupt vector
- This vector is an index in a table containing the address of the interrupt handdler routine.
- The Control Unit reads the content of this entry and loads the value into the PC
- Each operating system fills this table with the addresses of each of the treatment routines, which are dependent on each operating system.

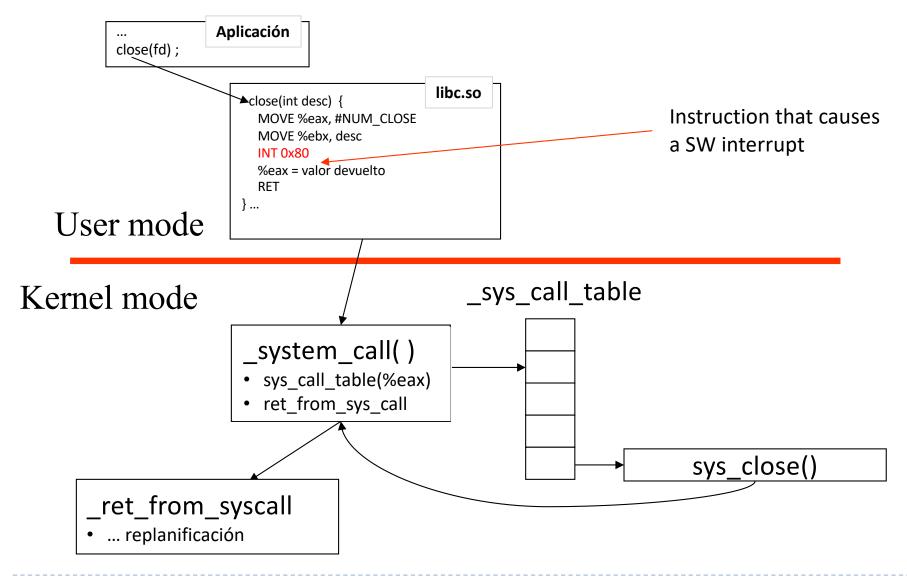
Interrupts in Windows



Software Interrupts. System calls and operating systems

- The system call mechanism is the one that allows user programs to request the services offered by the operating system
 - Load programs into memory for execution
 - Access to peripheral devices
 - Etc.
- Similar to the system calls offered by the CREATOR simulator
 - WepSIM examples show how system calls are internally implemented.

Software interrupts System calls (example: Linux)



Clock interrupts and operating system

- The signal that governs the execution of machine instructions is divided by a frequency divider to generate an external interruption every certain time interval (a few milliseconds)
- These clock interruptions or ticks are periodic interruptions that allow the operating system to come in and run periodically, preventing a user program from monopolizing the CPU
 - Allows to alternate the execution of various programs on a system given the appearance of simultaneous execution
 - Each time a clock interruption arrives, the program is suspended and the operating system that runs the scheduler is skipped to decide the next program to run

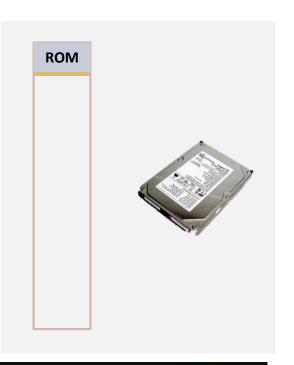
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- ▶ The Reset loads the predefined values in registers:
 - PC ← initial address of the initialization program (in ROM memory)

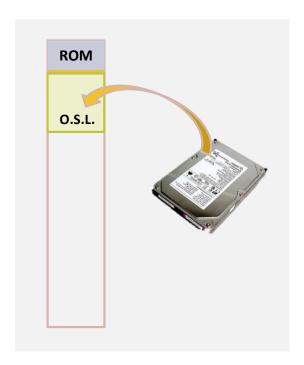


- The Reset loads the predefined values in registers:
 - ▶ PC ← initial address of the initialization program (in ROM memory)
- ▶ The initialization program is executed:
 - System test (POST)



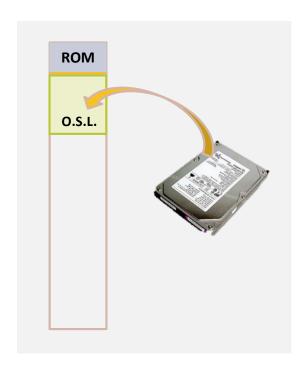
```
Award Modular BIOS v6.00PG, An Energy Star Ally
  Copyright (C) 1984-2007, Award Software, Inc.
Intel X38 BIOS for X38-DQ6 F4
Main Processor : Intel(R) Core(TM)2 Extreme CPU X9650 @ 4.00GHz(333x12
<CPUID:0676 Patch ID:0000>
Memory Testing : 2096064K OK
Memory Runs at Dual Channel Interleaved
IDE Channel 0 Slave ; WDC WD3200AAJS-00RYA0 12.01801
IDE Channel 1 Slave : WDC WD3290AAJS-00RYA0 12.01801
Detecting IDE drives ....
IDE Channel 4 Master : Mone
IDE Channel 4 Slave : Mone
IDE Channel 5 Master : None
IDE Channel 5 Slave : None
<DEL>:BIOS Setup <F9>:XpressRecovery2 <F12>:Boot Menu <End>:Qflash
09/19/2007-X38-ICH9-6A790G0QC-00
```

- ▶ The Reset loads the predefined values in registers:
 - PC ← initial address of the initialization program (in ROM memory)
- ▶ The initialization program is executed:
 - System test (POST)
 - Load into memory the operating system loader (MBR)



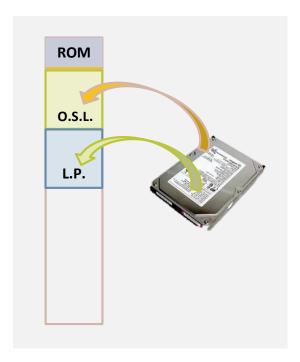
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 - ▶ PC ← initial address of the initialization program (in ROM memory)
- The initialization program is executed:
 - System test (POST)
 - Load into memory the operating system loader (MBR)
- ▶ The Operating System Loader is executed:
 - Sets boot options



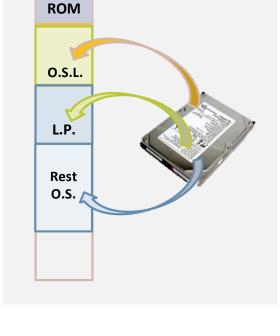




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 - PC ← initial address of the initialization program (in ROM memory)
- ▶ The initialization program is executed:
 - System test (POST)
 - Load into memory the operating system loader (MBR)
- ▶ The Operating System Loader is executed:
 - Sets boot options
 - Loads the loading program



- The Reset loads the predefined values in registers:
 - PC ← initial address of the initialization program (in ROM memory)
- ▶ The initialization program is executed:
 - System test (POST)
 - Load into memory the operating system loader
- The Operating System Load
 - Sets boot options
 - Loads the loading progra
- The Loading Program is executed:
 - Sets the initial state of the O.S.
 - Loads the O.S. and executed it.



```
Configuring ISA PNP
Setting system time from the hardware clock (localtime).

Ising /etc/random-seed to initialize /dev/urandom.

Initializing basic system settings ...

Updating shared libraries

Setting hostname: engpc23.murdoch.edu.au

INIT: Entering runlevel: 4

rc.M => Going multiuser...

Starting system logger ...

Initializing advanced hardware

Setting up modules ...

I OK 1

Initializing metwork

Setting up localhost ...

Setting up localhost ...

Setting up fancy console and GUI

Loading fc-cache ...

Setting up fancy console and GUI

Loading fc-cache ...

Setting up services of runlevel 4

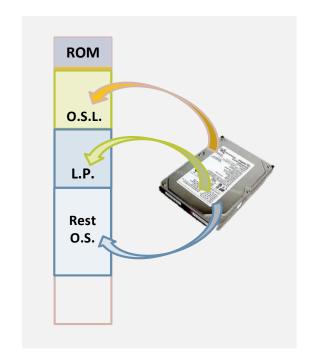
Starting services of multiuser GUI mode ...

KPree86 Display Manager

Framebuffer /dev/fb0 is 307200 bytes.

Grabbing 640x480 ...
```

- The Reset loads the predefined values in registers:
 - PC ← initial address of the initialization program (in ROM memory)
- ▶ The initialization program is executed:
 - System test (POST)
 - Load into memory the operating system loader (MBR)
- ▶ The Operating System Loader is executed:
 - Sets boot options
 - Loads the loading program
- ▶ The Loading Program is executed:
 - Sets the initial state of the O.S.
 - Loads the O.S. and executed it.



Program execution time

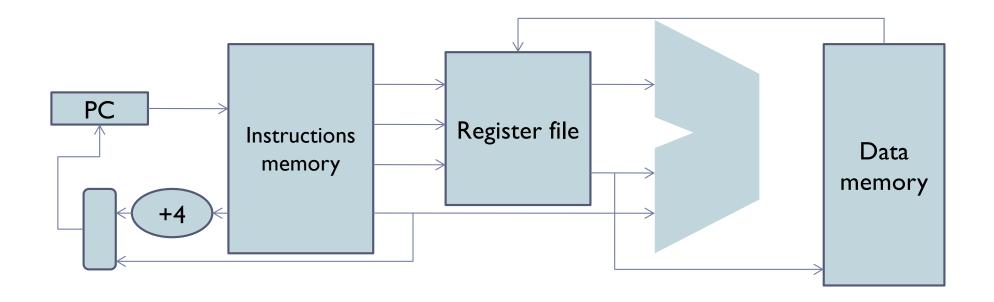
$$Time_{execution} = IN \times CPI \times t_{cycle_CPU} + IN \times AMI \times t_{cycle_mem}$$

- IN is the number of instructions of the program
- is the average number of clock cycles to execute an instruction
- ▶ t_{cycle_CPI} is the cycle clock duration
- is the average number of memory access per instruction
- ▶ t_{cycle mem} is the time needed for a memory access

Factors affecting execution time

	IN	CPI	t _{cycle_CPI}	AMI	t _{cycle_mem}
Program	√			√	
Compiler	✓	√		✓	
Instruction set	>	√	✓	>	
Organization		√	✓		✓
Technology			✓		✓

Model of processor based on datapath (without internal bus)



Instruction level parallelism

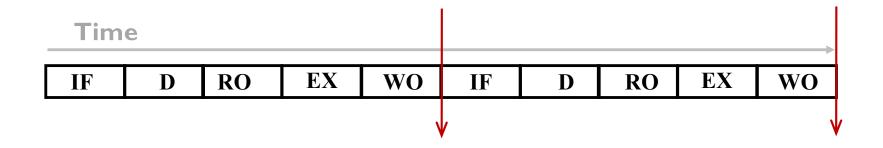
- Concurrent execution of several machine instructions
- Combination of elements working in parallel:
 - Pipelined processor: use pipelines in which multiple instructions are overlapped in execution
 - Superscalar processor: multiple independent instruction pipelines are used. Each pipeline can handle multiple instructions at a time
 - Multicore processor: several processors or cores in the same chip

Segmentation of instructions



- Stages in the execution of instructions:
 - ▶ IF: Instruction fetch
 - Decoding
 - RO: Read operands
 - **EX**: Execution
 - WO: Write operands

Segmentation of instructions without pipeline



Stages in the execution of instructions:

▶ IF: Instruction fetch

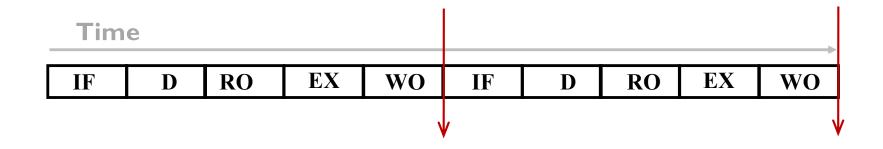
Decoding

RO: Read operands

EX: Execution

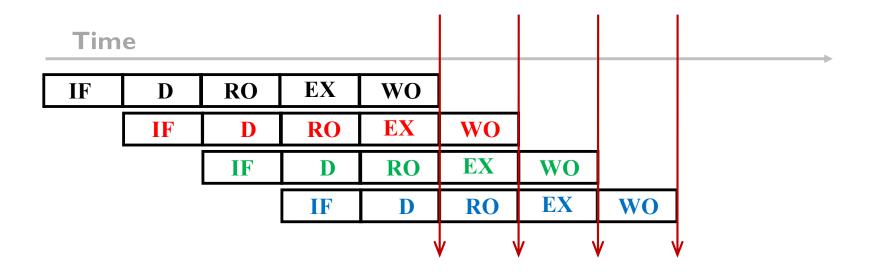
WO: Write operands

Segmentation of instructions without pipeline



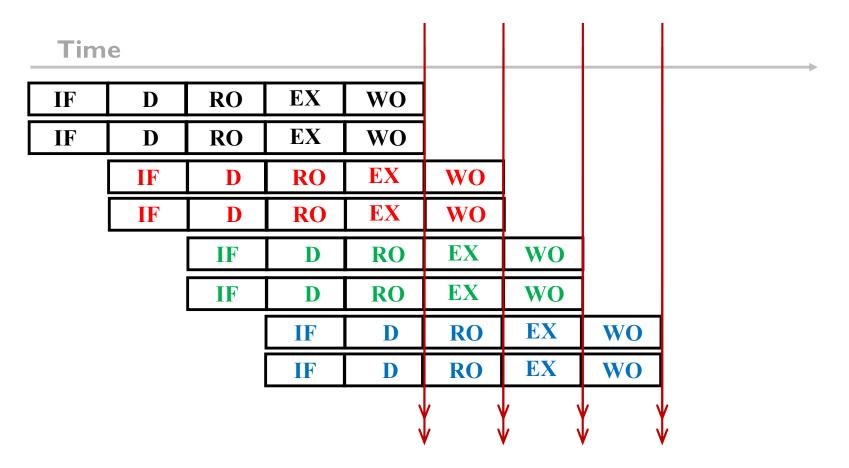
- If each phase takes N clock cycles, then:
 - ▶ One instruction takes 5*N clock cycles to be executed
 - ▶ 1/5 of instruction is issued every N clock cycles

Segmentation of instructions with pipeline



- If each phase takes N clock cycles, then:
 - One instruction takes 5*N clock cycles to be executed
 - One instruction is issued every N clock cycles

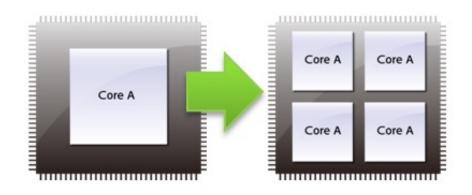
Superscalar

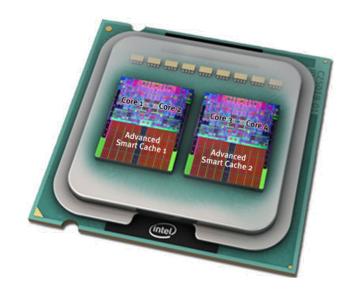


Pipeline with several functional units in parallel

Multicore

Multiples processors in the same chip

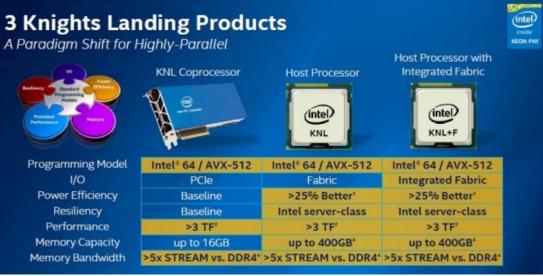




Multicore

Multiples processors in the same chip





http://wccftech.com/intel-knights-landing-detailed-16-gb-highbandwidth-ondie-memory-384-gb-ddr4-system-memory-support-8-billion-transistors/