# Dl4j学习率衰减策略

```
package org.deeplearning4j.nn.conf;
/**
 * Learning Rate Policy
 * How to decay learning rate during training.
 * <b>None</b> = do not apply decay policy aka fixed in Caffe <br>
 * <b>Exponential</b> = applies decay rate to the power of the # batc
 * <b>Inverse</b> = divide learning rate by negative (1 + decay rate
* # batches) ^power <br>
 * <b>Poly</b> = polynomial decay that hits 0 when iterations are com
plete <br>
 * <b>Sigmoid</b> = sigmoid decay rate <br>
 * <b>Step</b> = decay rate to the power of the floor (nearest
integer) of # of batches by # of steps <br>
 * <b>Schedule</b> = rate to use at a specific iteration <br>
 * <b>Score</b> = apply decay when score stops improving <br>
 * /
// TODO provide options using epochs in addition to iterations
public enum LearningRatePolicy {
    None, Exponential, Inverse, Poly, Sigmoid, Step, TorchStep, Schedule,
Score
```

dl4j的学习率衰减策略应用部分是在反向传播计算完地图之后,调用Updater.update()方法对梯度进行更新并且进行梯度的衰减。

```
调用学习率衰减的为 package org.deeplearning4j.optimize.solvers 包下的 BaseOptimizer 抽象类中的 updateGradientAccordingToParams(Gradient gradient, Model model, int batchSize)方法中的 updater.update(layer, gradient, getIterationCount(model), batchSize);语句。
```

- 后面衰减策略所使用的iteration为Model的总迭代次数
- 衰减率由 NeuralNetConfiguration.Builder() 的 1rPolicyDecayRate() 方法进行配置,衰减率通常为0~1中间的一个值。

### **Exponential**

```
1. newLr = lr * Math.pow(decayRate, iteration);
```

$$newLr = lr imes decayRate^{iteration}$$

#### Inverse

```
newLr = lr / Math.pow((1 + decayRate * iteration), conf.getLrPolicyPower(
));
```

$$newLr = rac{lr}{1 + (decayRate imes iteration)^{conf.getLrPolicyPower()}}$$

注: LrPolicyPower由用户自定义设置。默认值为0。

### Step

```
newLr = lr * Math.pow(decayRate, Math.floor(iteration / conf.getLrPolicyS
teps()));
```

$$newLr = lr imes decayRate^{\lfloor rac{iteration}{conf.getLrPolicySteps()} 
floor}$$

注: IrPolicySteps 由用户自定义, 默认值为0。

## TorchStep

```
1. //<mark>当模型的总迭代次数>1次且设置的</mark>lrPolicySteps 正好是当前总迭代次数的倍数的时候调用
2. if (iteration > 1 && conf.getLrPolicySteps() % iteration == 0) {
```

#### $newLr = lr \times decayRate$

## Poly

```
newLr = lr * Math.pow((1 - ((double) iteration) / conf.getNumIterations()
), conf.getLrPolicyPower());
```

$$newLr = lr*(1 - rac{iteration}{conf. getNumIterations()})^{conf. getLrPolicyPower()}$$

注: conf.getNumIterations(),是对于每一个miniBatch的数据中的迭代次数。

## Sigmoid

```
newLr = lr / (1 + Math.exp(-decayRate * (iteration -
conf.getLrPolicySteps())));
```

$$newLr = rac{lr}{1 + e^{-decayRate imes (iteration-conf.getLrPolicySteps())}}$$

### Schedule

```
if (baseLayer.getLearningRateSchedule().containsKey(iteration)) {
    newLr = baseLayer.getLearningRateSchedule().get(iteration);
} else {
    newLr = lr;
}
```

根据前面设置的Schedule来更改对应的学习率,例如设置的Schedule为:

```
1. // Map为<iterations, learningRate>的key-value对
```

```
2. Map<Integer, Double> schedule = new HashMap<>();
3. schedule.put(200, 0.01);
4. schedule.put(60000, 0.001);
5. schedule.put(80000, 0.0001);
```

就是在模型迭代第200次的时候,学习率变更为0.01;在第60000次的时候变更为0.001...依次类推

#### Score

Score的触发条件和前面几个都并不一样,触发的代码为:

```
@Override
public boolean checkTerminalConditions (INDArray gradient, double
oldScore, double score, int i) {
    for (TerminationCondition condition : terminationConditions) {
        //log.info("terminations: {}", condition);
        if (condition.terminate(score, oldScore, new Object[] {gradient})
) {
            log.debug("Hit termination condition on iteration {}: score={
}, oldScore={}, condition={}", i, score,
                            oldScore, condition);
            //触发EpsTermination, 且当前网络层不为空且衰减策略为Score的时候调用
            if (condition instanceof EpsTermination && conf.getLayer() !=
null
                            && conf.getLearningRatePolicy() == LearningRat
ePolicy.Score) {
                model.applyLearningRateScoreDecay();
            return true;
   return false;
```

#### 其中策略的实现方式基本为:

```
1. @Override
2. public void applyLearningRateScoreDecay() {
3. for (Map.Entry<String, Double> lrPair : conf.getLearningRateByParam()
```

 $newLr = lr \times (conf.\ getLrPolicyDecayRate() + Nd4j.\ EPS\_THRESHOLD)$ 

#### 注:

- 1. Nd4j.EPS\_THRESHOLD的默认值为  $1e^{-5}$
- 2. 使用这个策略的时候,网络模型损失函数得分容易进入 ZeroDirectionTermination 使得模型学习率不再衰减,使得模型停止更新。

更多文档可以查看 https://github.com/sjsdfg/deeplearning4j-issues。 欢迎star