

School of Mathematics, Thapar Institute of Engineering and Technology, Patiala  
Auxiliary Examination, March 2022

Name: \_\_\_\_\_ Roll No. \_\_\_\_\_

B.E. III Semester

UMA007/UMA011: Numerical Analysis

Time Limit: 02 Hours

Maximum Marks: 50

Instructor: Dr. Arvind Kumar Lal

**Instructions:** You are expected to answer **ANY FIVE** questions. Each problem has equal weight (10 marks) Arrange your work in a reasonably neat, organized and coherent way. Mysterious or unsupported answers will not receive full credit. Scientific calculator is allowed.

1. Consider the function  $f(x) = \sqrt{x+1} - \sqrt{x}$  and  $x = 12345$ . Show that this function is well-conditioned but not stable (use six decimal digit rounding arithmetic). (10.0)
2. Find a positive root, between 0 and 1, of the equation  $x e^x = 1$  correct to two decimal places using bisection method. (10.0)
3. Using Gauss elimination method, determine the LU factorization for matrix A in the linear system  $Ax = b$ , where  $A = \begin{bmatrix} 1 & 1 & 1 \\ 4 & 3 & -1 \\ 3 & 5 & 3 \end{bmatrix}$  and  $b = \begin{bmatrix} 1 \\ 6 \\ 2 \end{bmatrix}$ . (10.0)
4. Let  $f \in C^n[a, b]$  and  $x_0, x_1, \dots, x_n$  are distinct numbers in  $[a, b]$ . Let  $P_n(x)$  be the interpolating polynomial in Newton's form. Then prove that there exists a point  $\xi \in (a, b)$  such that  $f[x_0, x_1, \dots, x_n] = \frac{f^{(n)}(\xi)}{n!}$ . (10.0)
5. Use the method of least squares to fit a curve of the form  $y = a b^x$  to the following data. (10.0)

$x$	0		1	2	3
$y$	10		21	35	59

- 6 (a) Determine the constants  $x_0, x_1$  and  $c_1$  that will produce a quadrature formula 
$$\int_0^1 f(x) dx = \frac{1}{2} f(x_0) + c_1 f(x_1)$$
 that has the highest possible degree of precision. (5.0)
- (b) Evaluate the integral  $\int_0^1 \frac{dx}{1+x^2}$  using Gauss quadrature two point formula and compare your answer with exact value of given integral. (5.0)
7. Apply the fourth-order Runge-Kutta method for the system to find the approximate solution at  $x = 0.1$  with step-size  $h = 0.1$ .
$$\frac{dy}{dx} = y - z + 2, \quad y(0) = -1; \quad \frac{dz}{dx} = -y + z + 4x, \quad z(0) = 0$$
 (10.0)

END

Name: \_\_\_\_\_ Roll No.: \_\_\_\_\_ Tutorial Group: \_\_\_\_\_

**SCHOOL OF MATHEMATICS, THAPAR INSTITUTE OF ENGINEERING AND TECHNOLOGY, PATIALA**

**U – Grade Exam. Numerical Analysis (UMA007/011) March 12, 2022**

**Max. Mark: 35**

**Time: 35 Minutes**

**Note: (i) Tick the appropriate answer. (ii) Each question carries 1.4 marks.**

Q. 1	<p>If <math>f(x)</math> is <math>(k+1)</math> times differentiable on the interval <math>[a, b]</math> and <math>x_0, x_1, \dots, x_k, x_{k+1}</math> are <math>(k+2)</math> distinct points in <math>[a, b]</math>, then for some <math>\xi \in (a, b)</math>, <math>f[x_0, x_1, \dots, x_{k+1}]</math> equals</p> <p>(A) <math>\frac{f^{(k)}(\xi)}{k!}</math>      (B) <math>\frac{f^{(k+1)}(\xi)}{k!}</math>      (C) <math>\frac{f^{(k+1)}(\xi)}{k+1!}</math>      (D) None of these</p>
Q. 2	<p>For certain function <math>f(x)</math>, divided differences are given as <math>f[-1] = 2</math>, <math>f[-1, 1] = 1</math>. The Lagrange's interpolating polynomial based on the nodal points <math>-1</math> and <math>1</math> is</p> <p>(A) <math>x + 3</math>      (B) <math>2x - 1</math>      (C) <math>x^2 + x + 1</math>      (D) <math>x^2 - 3</math></p>
Q. 3	<p>For which type of polynomials does the Simpson's integration rule give an exact result?</p> <p>(A) Polynomial with degree greater than three.          (B) All trigonometric functions.          (C) All transcendental functions.          (D) All polynomials with degree three or less.</p>
Q. 4	<p>Compute the <math>\infty</math>-norm of a matrix, <math>\ A\ _\infty</math>. Consider <math>A = \begin{pmatrix} 1 &amp; 1 &amp; 0 \\ 1 &amp; 2 &amp; 1 \\ -1 &amp; 1 &amp; 2 \end{pmatrix}</math>.</p> <p>(A) <math>\sqrt{7 + \sqrt{7}}</math>      (B) <math>\sqrt{7 - \sqrt{7}}</math>      (C) 4      (D) None of these</p>
Q. 5	<p>While solving systems of linear equations using an iteration scheme of the form <math>\mathbf{x}^{(k)} = T\mathbf{x}^{(k-1)} + \mathbf{c}</math>, <math>\forall k \geq 1</math>, the iterates converge to a unique solution if and only if the following condition holds:</p> <p>(A) <math>\rho(T) &lt; 1</math>      (B) the induced norm <math>\ T\  \rightarrow \infty</math>          (C) <math>T</math> is invertible      (D) <math>T</math> has at least one zero eigenvalue</p>

Q.6	<p>The dominant eigenvalue of the matrix <math>A = \begin{pmatrix} 3 &amp; 0 &amp; 0 \\ 0 &amp; -1 &amp; 0 \\ 0 &amp; 0 &amp; 5 \end{pmatrix}</math> is</p> <p>(A) 5            (B) 0            (C) 3            (D) does not exist.</p>
Q. 7	<p>The Trapezoidal rule and Simpson's one - third rule give the value 4 and 2, respectively on applying to <math>\int_0^2 f(x) dx</math>. What is <math>f(1)</math> ?</p> <p>(A) <math>\frac{1}{4}</math>            (B) <math>\frac{1}{5}</math>            (C) 1            (D) <math>\frac{1}{2}</math></p>
Q. 8	<p>Let <math>p(x)</math> be an interpolating polynomial of degree atmost 3 that passes through the points <math>(-2,12)</math>, <math>(-1,1)</math>, <math>(0,2)</math> and <math>(2,-8)</math>. Then, the coefficient of <math>x^3</math> in the <math>p(x)</math> is equal to</p> <p>(A) -2            (B) 1            (C) -1            (D) None of these</p>
Q. 9	<p>The value of <math>y(0.1)</math> obtained by solving initial value problem: <math>\frac{dy}{dx} = x + y</math>, <math>y(0) = 1</math> by modified Euler's method is equal to</p> <p>(A) 0.20            (B) 0.21            (C) 2.38            (D) 1.64</p>
Q. 10	<p>Let <math>(x_0, f(x_0)) = (0, -1)</math>, <math>(x_1, f(x_1)) = (1, \alpha)</math> and <math>(x_2, f(x_2)) = (2, \beta)</math>. If the first-order divided differences are <math>f[x_0, x_1] = 5</math> and <math>f[x_1, x_2] = \gamma</math> and the second-order divided difference is <math>f[x_0, x_1, x_2] = -\frac{3}{2}</math>, then the values of <math>\alpha, \beta</math> and <math>\gamma</math> are, respectively</p> <p>(A) 4, 2, 4            (B) 2, 4, 6            (C) 4, 6, 2            (D) 6, 2, 4</p>
Q. 11	<p>Let <math>x_0, x_1, \dots, x_n</math> be <math>n+1</math> distinct points. If the Lagrange polynomial for <math>(n+1)</math> points takes the form <math>l_k(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \frac{x-x_i}{x_k-x_i}</math>, <math>k = 0, 1, \dots, n</math>, then <math>\sum_{k=0}^n l_k(x)</math> equals to</p> <p>(A) 0            (B) 1            (C) 2            (D) None of these</p>
Q.12	<p>Using Euler method, the value of <math>y</math> at <math>t = 0.1</math> for initial value problem: <math>\frac{dy}{dt} = y</math>, <math>y(0) = 1</math>, is</p> <p>(A) 1.1            (B) 1.2            (C) 0.1            (D) 1</p>



Q. 13	Which one of the integration method is used to correct the value in modified Euler's method?  (A) Trapezoidal rule. (B) Simpson 1/3 rule. (C) Simpson 3/8 rule (D) Gauss quadrature two-point rule.
Q. 14	For solving the integral $\int_1^2 \frac{dx}{\sqrt{4-x^2}}$ , which of the following method is the most appropriate (A) Trapezoidal Rule (B) Simpson (1/3 <sup>rd</sup> ) Rule (C) Gauss – two point formula (D) None of these
Q. 15	Runge - Kutta fourth order method to solve initial value problem: $\frac{dy}{dx} = f(x, y)$ , $y(x_0) = y_0$ with step size $h$ is given by  $K_1 = hf(x_i, y_i); \quad K_2 = hf\left(x_i + \frac{h}{2}, y_i + \frac{K_1}{2}\right);$ $K_3 = hf\left(x_i + \frac{h}{2}, y_i + \frac{K_2}{2}\right) \text{ and } K_4 = hf(x_i + h, y_i + K_3)$ $y_{i+1} = y_i + \frac{1}{6}(K_1 + aK_2 + bK_3 + cK_4); \quad x_{i+1} = x_i + h, \quad i = 0, 1, 2, \dots$ The value of $a$ , $b$ , and $c$ in the above formula are respectively  (A) 2, 1, and 2 (B) 1, 2, and 2 (C) 2, 2, and 1 (D) 2, 2, and 2
Q. 16	The two - point Gauss quadrature formula for $\int_{-1}^1 f(x)dx$ is equal to  (A) $f(-0.774) + f(0.5774)$ (B) $f(-0.5774) + f(0) + f(0.5774)$ (C) $0.8889f(-0.7746) + 0.5556f(0) + 0.8889f(0.7746)$ (D) $0.5556f(-0.7746) + 0.8889f(0) + 0.5556f(0.7746)$
Q. 17	Value of all $\alpha > 0$ and $\beta > 0$ so that matrix $A = \begin{bmatrix} 3 & 2 & \beta \\ \alpha & 5 & \beta \\ 2 & 1 & \alpha \end{bmatrix}$ is strictly diagonally dominant, are  (A) $0 < \beta < 1$ and $3 < \alpha < 5 - \beta$ (B) $1 < \beta < 2$ and $3 < \alpha < 5 + \beta$ (C) $0 < \beta < 1$ and $4 < \alpha < 6 - \beta$ (D) $1 < \beta < 2$ and $3 < \alpha < 5 - \beta$
Q. 18	Applying Trapezoidal rule to $\int_0^2 e^x dx$ gives  (A) 8.999 (B) 8.909 (C) 8.363 (D) 8.389

Q. 19	Suppose $f(0)=1, f(0.5)=2.5, f(1)=2$ , and $f(0.25)=f(0.75)=\alpha$ . The value of $\alpha$ , for which the composite Trapezoidal rule with $N=4$ gives $\int_0^1 f(x) dx=1.75$ , is (A) 4 (B) 5 (C) 6 (D) None of these
Q. 20	Suppose that $\bar{X}$ is an approximation to the solution of $AX=b$ , $A$ is nonsingular matrix and $r$ is the residual vector for $\bar{X}$ . Then for any natural norm, which one of the following is correct? (i) $\ X - \bar{X}\  \leq \ A\  \ r\ $ (ii) $\frac{\ X - \bar{X}\ }{\ X\ } \leq \frac{\ A^{-1}\ }{\ b\ } \ r\ $ (A) Only (i) (B) only (ii) (C) both (i) and (ii) (D) None of these
Q.21	Consider a sequence of vectors $X^{(k)} = \left(1, 2 + \frac{1}{k}, \frac{3}{k^2}, e^{-k} \sin k\right)$ . For $l_\infty$ norm, this sequence converges to the vector (A) $X = (1, 2, 1, 0)$ (B) $X = (1, 0, 2, 0)$ (C) $X = (1, 3, 3, 0)$ (D) $X = (1, 2, 0, 0)$
Q.22	If a matrix $A$ has eigenvalue 5, 3, 1 then $(A - 2I)^{-1}$ has eigenvalues (A) $\frac{1}{3}, 1, -1$ (B) $-\frac{1}{3}, 1, -1$ (C) $\frac{1}{3}, 1, 1$ (D) $\frac{1}{3}, 1, 0$
Q.23	Which of the method of order two cannot be used to solve the IVP : $y' = y^{1/3}, y(0) = 0$ on $[0,1]$ with $h = 0.2$ ? (A) Taylor Series Method of order two (B) Euler method (C) Runge - Kutta second order method (D) Runge - Kutta fourth order method
Q.24	The normal equation obtained for fitting the curve $y = a\sqrt{x} + \frac{b}{x}$ to some data $(x_i, y_i), i = 1, 2, \dots, N$ , is $a \sum_{i=1}^N x_i + b \sum_{i=1}^N \frac{1}{\sqrt{x_i}} = \sum_{i=1}^N y_i \sqrt{x_i}; a \sum_{i=1}^N \frac{1}{\sqrt{x_i}} + b P = Q$ , where $P$ and $Q$ are given as (A) $P = \sum_{i=1}^N \frac{1}{x_i^2}, Q = \sum_{i=1}^N \frac{y_i}{x_i^2}$ (B) $P = \sum_{i=1}^N \frac{y_i}{x_i^2}, Q = \sum_{i=1}^N \frac{y_i}{x_i}$ (C) $P = \sum_{i=1}^N \frac{1}{x_i^2}, Q = \sum_{i=1}^N \frac{y_i}{x_i}$ (D) $P = \sum_{i=1}^N \frac{1}{x_i^2}, Q = \sum_{i=1}^N \frac{\sqrt{y_i}}{x_i^2}$
Q.25	The condition number $\kappa(A)$ of a matrix $A$ of order $n$ is (A) Exactly equal to one (B) At least one (C) At most one (D) None of these.