

Lecture 12: Numerical Linear Algebra (UMA021): Roots of Non-Linear Equations

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Newton's method to system of non-linear equations.

Newton's method for non-linear systems:

Consider the non-linear system:

$$A X = b$$

$$X = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$f(x, y) = 0$$

$$g(x, y) = 0$$

$$\boxed{\begin{array}{l} 1x^2 + y^2 - 9 = 0 \\ x^2 + e^y = 0 \end{array}} \quad \begin{array}{l} \text{--- (1)} \\ \text{--- (2)} \end{array}$$

$$\text{Let } X^{(k)} = \begin{bmatrix} x_k \\ y_k \end{bmatrix}, \quad \checkmark F = \begin{bmatrix} f \\ g \end{bmatrix}, \quad J = \begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix}$$

$$X = (x, y)^T = \begin{bmatrix} x \\ y \end{bmatrix} = ?$$

$$F(X^{(k)}) = F(x_k, y_k) = \begin{bmatrix} f(x_k, y_k) \\ g(x_k, y_k) \end{bmatrix},$$

$$J(x_k, y_k) = \begin{bmatrix} f_x(x_k, y_k) & f_y(x_k, y_k) \\ g_x(x_k, y_k) & g_y(x_k, y_k) \end{bmatrix}$$

$$F = \begin{bmatrix} x^2 + y^2 - 9 = f \\ x^2 + e^y = g \end{bmatrix}_{2 \times 1}$$

$$X^{(0)} = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}, \quad X^{(1)} = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

$$X^{(2)} = \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}$$

$$\|X^{(n)} - X^{(n-1)}\| < \text{tol.}$$

→ norm

Newton's method to system of non-linear equations.

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

$$X^{(k+1)} = X^{(k)} - \frac{F(X^{(k)})}{F'(X^{(k)})}$$

$$\begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix}_{2 \times 2} = F' = J$$

The Newton's method for non-linear system is given by

$$X^{(k+1)} = X^{(k)} - J^{-1} F(X^{(k)})$$

$$(2 \times 2) (2 \times 1)$$

$$\text{adj}(J) = 6xy^2 + 3y^3 - 3x^3 - 6x^2y \neq 0$$

$$\text{adj}(J) = \begin{bmatrix} 3y^2 & -3x^2 \\ -(x+2y) & 2x+y \end{bmatrix}^t = \begin{bmatrix} 3y^2 & -x-2y \\ -3x^2 & 2x+y \end{bmatrix}$$

$$A_{11} = (-1)^{1+1} 3y^2$$

$$A_{12} = (-1)^{1+2} 3x^2 = -3x^2$$

$$A_{21} = (-1)^{2+1} (x+2y)$$

$$A_{22} = (-1)^{2+2} (2x+y)$$

$$J^{-1} = \frac{1}{3(y^3 - x^3) + 6xy(x+y)} \begin{bmatrix} 3y^2 & -x-2y \\ -3x^2 & 2x+y \end{bmatrix}$$

Apply Newton's method for non-linear systems

$$x^{(k+1)} = x^{(k)} - J^{-1}(x^{(k)}) f(x^{(k)})$$

Let $k=0$

$$x^{(1)} = x^{(0)} - J^{-1}(x^{(0)}) f(x^{(0)})$$

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} - \left\{ \frac{1}{3(y^3 - x^3) + 6xy(x+y)} \begin{bmatrix} 3y^2 & -x-2y \\ -3x^2 & 2x+y \end{bmatrix} \begin{bmatrix} x^2+xy \\ +y^2-7 \\ x^3+y^3 \\ -9 \end{bmatrix} \right\} \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 1.5 \\ 0.5 \end{bmatrix} - \frac{1}{2((0.5)^3 - (1.5)^3) + 6(0.5)(1.5)(1.5+0.5)}$$

$$\times \begin{bmatrix} 2(0.5)^2 & -1.5 - 2(0.5) \\ -3(1.5)^2 & 2(1.5) + 0.5 \end{bmatrix} \begin{bmatrix} (1.5)^2 + (1.5)(0.5) \\ + (0.5)^2 - 7 \\ (1.5)^3 + (0.5)^3 - 9 \end{bmatrix}$$

$$= \begin{bmatrix} 1.5 \\ 0.5 \end{bmatrix} - \frac{1}{-14.25} \begin{bmatrix} 0.75 & -0.25 \\ -6.75 & 3.5 \end{bmatrix} \begin{bmatrix} -3.75 \\ -5.50 \end{bmatrix}$$

$$= \begin{bmatrix} 2.2675 \\ 0.9254 \end{bmatrix} = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$$

let $k=1$

$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 2.2675 \\ 0.9254 \end{bmatrix} - \frac{1}{(\det(J))} J^{-1}(x^{(1)}) f(x^{(1)})$$

at $x' = (2.2675, 0.9254)$

$$= \begin{bmatrix} 2.2675 \\ 0.9254 \end{bmatrix} - \frac{1}{-49.495} \begin{bmatrix} 2.5691 & -4.1181 \\ -15.4247 & 5.7604 \end{bmatrix} \begin{bmatrix} 1.0962 \\ 3.4510 \end{bmatrix}$$

$$x^{(2)} = \begin{bmatrix} 2.0371 \\ 0.9654 \end{bmatrix}$$

$$x^{(3)} = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 2.00013 \\ 0.9987 \end{bmatrix} \quad \underline{\text{Ans.}}$$

Newton's method to system of non-linear equations.

Newton's method for nonlinear systems: Exercise

Perform 3 iterations of Newton's method to the following non-linear system:

$$x^2 - y^2 + 2y = 0$$

$$2x + y^2 - 6 = 0$$

with $x^{(0)} = (0.1, 2)^t$.