

Lecture 11: Numerical Linear Algebra (UMA021): Roots of Non-Linear Equations

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Modified Newton's method

$f(x) = 0$ has a root p

with multiplicity m

$$f(x) = (x-p)^m q(x)$$

$q(p) \neq 0$

m. n. m. formula when (m is given)

$$p_{n+1} = p_n - m \frac{f(p_n)}{f'(p_n)}$$

$$p_{n+1} = g(p_n)$$

$$g(x) = x - m \frac{f(x)}{f'(x)}$$

Multiple roots

Order of convergence of modified Newton's method:

$$g(x) = x - m \frac{f(x)}{f'(x)}$$

$$g(x) = x - m \frac{(x-p)^m g(x)}{(x-p)^m g'(x) + g(x) m (x-p)^{m-1}}$$

$$g(x) = x - m \frac{(x-p)^1 g(x)}{(x-p) g'(x) + m g(x)}, \quad x \neq p$$

let $x=p$

$$g(p) = p - m \frac{0}{m g(p)} = p - \frac{m}{m} \frac{0}{g(p)} = p$$

$$\begin{aligned}
 \downarrow g'(x) &= 1 - m \left[\frac{(x-p) q'(x)}{(x-p) q'(x) + m q(x)} \right. \\
 &\quad + \frac{q(x) \cdot 1}{(x-p) q'(x) + m q(x)} + \\
 &\quad \left. + (x-p) q(x) \frac{d}{dx} \frac{1}{(x-p) q'(x) + m q(x)} \right]
 \end{aligned}$$

but $x=p$

$$\begin{aligned}
 g'(p) &= 1 - m \left[\frac{0 \cdot q'(p)}{0 + m q(p)} + \frac{q(p)}{0 + m q(p)} + \frac{(0)}{\text{nonzero}} \right] \\
 &= 1 - m \left[0 + \frac{1}{m} + 0 \right] = 1 - \frac{m}{m} = 1 - 1 = 0
 \end{aligned}$$

Multiple roots

Modified Newton's method (if multiplicity is not given)

let $f(x) = 0$ be an equation which has a root at p with multiplicity m i.e.

$$f(x) = (x-p)^m q(x), \quad q(p) \neq 0$$

Define
$$u(x) = \frac{f(x)}{f'(x)} = \frac{(x-p)^m q(x)}{(x-p)^m q'(x) + q(x)m(x-p)^{m-1}}$$

$$= (x-p) \frac{q(x)}{(x-p) q'(x) + m q(x)}$$

$$u(x) = (x-p) Q(x) \quad \leftarrow$$

$$Q(p) \neq 0$$

$$= (x-p) Q(x)$$

$\Rightarrow u(x)$ has a simple root at $x=p$

where $Q(x) = \frac{q(x)}{(x-p)q'(x) + m q(x)}$

So, Apply N. m. on $u(x)$

$$Q(p) = \frac{q(p)}{0 + m q(p)} = \frac{1}{m} \neq 0$$

$$p_{n+1} = p_n - \frac{u(p_n)}{u'(p_n)}$$

$$= p_n - \frac{\left(\frac{f(p_n)}{f'(p_n)} \right)}{\left(\frac{f(p_n)}{f'(p_n)} \right)'}$$

$$= p_n - \frac{\frac{f(p_n)}{f'(p_n)}}{\frac{f'(p_n) f'(p_n) - f(p_n) f''(p_n)}{(f'(p_n))^2}}$$

$$= p_n - \frac{f(p_n) f'(p_n)}{(f'(p_n))^2 - f(p_n) f''(p_n)}$$

Multiple roots

Example:

Show that the modification of Newton's method improves the rate of convergence for $f(x) = e^x - x - 1$ at $x = 0$ with $p_0 = 1$.

Apply M·N·M. (when multiplicity is not given)

$$\begin{aligned}
 p_{n+1} &= p_n - \frac{f(p_n) f'(p_n)}{(f'(p_n))^2 - f(p_n) f''(p_n)} \\
 &= p_n - \frac{(e^{p_n} - p_n - 1)(e^{p_n} - 1)}{(e^{p_n} - 1)^2 - (e^{p_n} - p_n - 1)(e^{p_n})}
 \end{aligned}$$

let $n=0$, $p_0 = 1$

$$p_1 = 1 - \frac{(e^1 - 2)(e^1 - 1)}{(e^1 - 1)^2 - (e^1 - 2)(e^1)}$$

$$(e-1)^2 - (e'-2)(e')$$

$$= -0.23421$$

$$p_2 = \frac{-0.23421 - \left(e^{-0.23421} + 0.23421 - 1 \right) \left(e^{-0.23421} - 1 \right)}{\left(e^{-0.23421} - 1 \right)^2 - \left(e^{-0.23421} + 0.23421 - 1 \right) * e^{-0.23421}}$$

$$= -0.0084575$$

$$p_3 = - \dots$$

To check order
of error

$$\frac{|p_{n+1} - p|}{|p_n - p|^2}$$

$p=0$

$$\rightarrow \frac{|p_{n+1}|}{|p_n|^2}$$

Newton's method to system of non-linear equations.

Newton's method for non-linear systems:

Consider the non-linear system:

$$x^2 + 2x + 3 = 0$$

$$\begin{aligned} f(x, y) &= 0 \\ g(x, y) &= 0 \end{aligned}$$

$$\begin{aligned} x^2 + y^2 - 9 &= 0 \\ x^2 + e^y - 3 &= 0 \end{aligned}$$

$$X = \begin{bmatrix} x \\ y \end{bmatrix} \text{ vector}$$

$$\text{Let } X^{(k)} = \begin{bmatrix} x_k \\ y_k \end{bmatrix}, \quad F = \begin{bmatrix} f \\ g \end{bmatrix}, \quad J = \begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix}$$

$$F(X^{(k)}) = F(x_k, y_k) = \begin{bmatrix} f(x_k, y_k) \\ g(x_k, y_k) \end{bmatrix},$$

$$J(x_k, y_k) = \begin{bmatrix} f_x(x_k, y_k) & f_y(x_k, y_k) \\ g_x(x_k, y_k) & g_y(x_k, y_k) \end{bmatrix}$$

$$F = \begin{bmatrix} x^2 + y^2 - 9 \\ x^2 + e^y - 3 \end{bmatrix}$$

$$X^{(0)} = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} \rightarrow \text{initial guess}$$

$$X^{(1)}, X^{(2)}, \dots$$

Newton's method for non-linear eqⁿ is given by

$$f(x) = 0$$

$$\begin{cases} f(x, y) = 0 \\ g(x, y) = 0 \end{cases}$$

$$F = \begin{bmatrix} f \\ g \end{bmatrix}_{2 \times 1}$$

$$X = \begin{bmatrix} x \\ y \end{bmatrix}_{2 \times 1}$$

$$f' = \begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix}_{2 \times 2} = J$$

$$\boxed{x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}}$$

vector
vector
Matrix

$$X^{(k+1)} = X^{(k)} - \frac{F(X^{(k)})}{F'(X^{(k)})}$$

→ 2x1

Convert Newton's method for system i.e. In Matrix form

$$\boxed{X^{(k+1)} = X^{(k)} - J_{(X^k)}^{-1} F(X^k)}$$

2x2

Newton's method to system of non-linear equations.

The Newton's method for non-linear system is given by

$$X^{(k+1)} = X^{(k)} - J^{-1}F(X^{(k)})$$
