## Thapar Institute of Engineering & Technology, Patiala Department of Mathematics

UMA021: Numerical Linear Algebra Assignment 3

 $\underline{\text{Matrix Algebra}}$ 

1. Use Gaussian elimination with backward substitution and two-digit rounding arithmetic to solve the following linear systems (do not reorder the equations). The exact solution to each system is  $x_1 = -1$ ,  $x_2 = 1$ ,  $x_3 = 3$ .

(a)

$$-x_1 + 4x_2 + x_3 = 8$$

$$\frac{5}{3}x_1 + \frac{2}{3}x_2 + \frac{2}{3}x_3 = 1$$

$$2x_1 + x_2 + 4x_3 = 11$$

(b)

$$4x_1 + 2x_2 - x_3 = -5$$

$$\frac{1}{9}x_1 + \frac{1}{9}x_2 - \frac{1}{3}x_3 = -1$$

$$x_1 + 4x_2 + 2x_3 = 9$$

2. Using four-digit arithmetic, solve the following system of equations by Gaussian elimination with partial pivoting:

$$0.729x_1 + 0.81x_2 + 0.9x_3 = 0.6867$$
  
 $x_1 + x_2 + x_3 = 0.8338$   
 $1.331x_1 + 1.21x_2 + 1.1x_3 = 1.000$ 

3. Use Gaussian elimination to solve the following systems and determine if row interchanges are necessary:

(a)

$$x_1 - x_2 + 3x_3 = 2$$
$$3x_1 - 3x_2 + x_3 = -1$$
$$x_1 + x_2 = 3$$

(b)

$$2x_{1} - x_{2} + x_{3} - x_{4} = 6$$

$$x_{2} - x_{3} + x_{4} = 5$$

$$x_{4} = 5$$

$$x_{3} - x_{4} = 3$$

4. Use LU factorization to solve the following systems:

(a)

$$2x_1 - x_2 + x_3 = -1$$
$$3x_1 + 3x_2 + 9x_3 = 0$$
$$3x_1 + 3x_2 + 5x_3 = 4$$

(b)

$$x_1 + x_2 - x_3 = 3$$
$$x_1 + 2x_2 - 2x_3 = 2$$
$$-2x_1 + x_2 + x_3 = 1$$

- **5.** Find  $l_{\infty}$  and  $l_2$  norms of the vectors.
  - (a)  $x = (3, -4, 0, 32)^t$ .
  - (b)  $x = (\sin k, \cos k, 2^k)^t$  for a fixed positive integer k.
- **6.** Find the  $l_{\infty}$  and  $l_2$  norm of the matrix:

$$A = \begin{pmatrix} 4 & -1 & 7 \\ -1 & 4 & 0 \\ -7 & 0 & 4 \end{pmatrix}$$

7. The following linear system Ax = b has x as the actual solution and  $\tilde{x}$  as an approximate solution. Compute  $||x - \tilde{x}||_{\infty}$  and  $||A\tilde{x} - b||_{\infty}$ . Also compute  $||A||_{\infty}$ .

$$x_1 + 2x_2 + 3x_3 = 1$$
  
 $2x_1 + 3x_2 + 4x_3 = -1$   
 $3x_1 + 4x_2 + 6x_3 = 2$ 

Here, actual solution:  $x = (0, -7, 5)^t$ , approximate solution:  $\tilde{x} = (-0.2, -7.5, 5.4)^t$ .

**8.** Find the first two iterations of Jacobi and Gauss-Seidel using  $\vec{x}^{(0)} = (0,0,0)^t$ :

$$4.63x_1 - 1.21x_2 + 3.22x_3 = 2.22,$$
  
$$-3.07x_1 + 5.48x_2 + 2.11x_3 = -3.17,$$
  
$$1.26x_1 + 3.11x_2 + 4.57x_3 = 5.11.$$

9. The linear system:

$$x_1 - x_3 = 0.2$$

$$-\frac{1}{2}x_1 + x_2 - \frac{1}{4}x_3 = -1.425$$

$$x_1 - \frac{1}{2}x_2 + x_3 = 2$$

has the solution  $(0.9, -0.8, 0.7)^t$ .

- (a) Is the coefficient matrix strictly diagonally dominant?
- (b) Compute the spectral radius of the Gauss-Seidel iteration matrix.
- (c) Perform four iterations of the Gauss-Seidel iterative method to approximate the solution.
- (d) What happens in part (c) when the first equation in the system is changed to  $x_1 2x_3 = 0.2$ ?
- 10. Comment whether the Gauss-Seidel method can be applied for the following system of equations. If applicable, perform two iterations, assuming the initial guess as  $\vec{x}^{(0)} = (0,0,0)^t$ .

$$12x_1 + 3x_2 - 5x_3 = 1$$
$$x_1 + 5x_2 + 3x_3 = 28$$
$$3x_1 + 7x_2 + 13x_3 = 76$$

11. Compute the condition numbers of the following matrices relative to  $\|\cdot\|_{\infty}$ :

(a) 
$$\begin{bmatrix} 0.03 & 58.9 \\ 5.31 & -6.10 \end{bmatrix}$$

(b) 
$$\begin{bmatrix} 0.04 & 0.01 & -0.01 \\ 0.2 & 0.5 & -0.2 \\ 1 & 2 & 4 \end{bmatrix}$$

Answers: 1(a)  $\vec{x} = (-0.7, 1.1, 2.9)^t$ ; 1(b)  $\vec{x} = (0.38, -2, 2.5)^t$ ; (2)  $\vec{x} = (0.2246, 0.2812, 0.3280)^t$ ; (3) do it your self; 4(a)  $\vec{x} = (1, 2, -1)^t$ ; 4(b)  $\vec{x} = (4, 4, 5)^t$ ; 5(a) 4, 5.2202; 5(b)  $2^k$ ,  $\sqrt{1 + 4k^2}$ ; (6) 12, 8.2394; (7) 0.5, 0.3, 13; (8) Jacobi:  $\vec{x}^{(1)} = (0.47948, -0.57847, 1.11816)^t$ ,  $\vec{x}^{(2)} = (-0.44934, -0.74039, 1.37962)^t$ , Gauss-Seidel:  $\vec{x}^{(1)} = (0.47948, -0.30985, 1.19683)^t$ ,  $\vec{x}^{(2)} = (-0.43384, -1:28234, 2.11044)^t$ ; 9. (a) No (b)  $\rho(T_g) = 0.625$  (c)  $\vec{x}^{(4)} = (1.07090, -0.67183, 0.59319)^t$  (d) Gauss-Seidel method will not converge  $(\rho(T_g) = 1.375 > 1)$  (10) method will work  $(\rho(T_g) = 0.18605 < 1)$ ,  $\vec{x}^{(2)} = (-0.13729, 3.93515, 3.75891)^t$  (11) (a) 12.24, (b) 198.17.