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## 1 Basic

### 1.1 vimrc

```
se is nu rnu bs=2 ru mouse=a encoding=utf-8
se cin et ts=4 sw=4 sts=4 t_Co=256
syn on
colorscheme ron
filetype indent on
map <F8> <ESC>:w<CR>:!clear && g++ "%" -o "%<" -
fsanitize=address -fsanitize=undefined -g && echo
success<CR>
map <F9> <ESC>:w<CR>:!clear && g++ "%" -o "%<" -O2 &&
echo success<CR>
map <F10> <ESC>:!. / "%<" <CR>
```

### 1.2 Pragma optimization

```
#pragma GCC optimize("Ofast,no-stack-protector")
#pragma GCC optimize("no-math-errno,unroll-loops")
#pragma GCC target("sse,sse2,sse3,ssse3,sse4")
#pragma GCC target("popcnt,abm,mmx,avx,tune=native")
```

### 1.3 IO Optimization

```
static inline int gc() {
    static char buf[ 1 << 20 ], *p = buf, *end = buf;
    if ( p == end ) {
        end = buf + fread( buf, 1, 1 << 20, stdin );
        if ( end == buf ) return EOF;
        p = buf;
    }
    return *p++;
}

template < typename T >
static inline bool gn( T &_ ) {
    register int c = gc(); register T __ = 1; _ = 0;
    while(( '0' > c || c > '9' ) && c != EOF && c != '-') c = gc();
    if(c == '-') { __ = -1; c = gc(); }
    if(c == EOF) return false;
    while( '0' <= c && c <= '9' ) _ = _ * 10 + c - '0', c = gc();
    _ *= __;
    return true;
}

template < typename T, typename ...Args >
static inline bool gn( T &x, Args &...args )
{ return gn(x) && gn(args...); }
```

## 2 Data Structure

### 2.1 BigInt

```
class BigInt{
private:
    using lld = int_fast64_t;
    #define PRINTF_ARG PRIuFAST64
    #define LOG_BASE_STR "9"
    static constexpr lld BASE = 1000000000;
    static constexpr int LOG_BASE = 9;
    vector<lld> dig;
```

```

bool neg;
inline int len() const { return (int) dig.size(); }
inline int cmp_minus(const BigInt& a) const {
    if(len() == 0 && a.len() == 0) return 0;
    if(neg ^ a.neg) return (int)a.neg*2 - 1;
    if(len() != a.len())
        return neg?a.len()-len():len()-a.len();
    for(int i=len()-1; i>=0; i--) if(dig[i] != a.dig[i])
        return neg?a.dig[i]-dig[i]:dig[i]-a.dig[i];
    return 0;
}
inline void trim(){
    while(!dig.empty() && !dig.back()) dig.pop_back();
    if(dig.empty()) neg = false;
}
public:
BigInt(): dig(vector<lld>()), neg(false){}
BigInt(lld a): dig(vector<lld>()){
    neg = a<0; dig.push_back(abs(a));
    trim();
}
BigInt(const string& a): dig(vector<lld>()){
    assert(!a.empty()); neg = (a[0]=='-');
    for(int i=((int)a.size())-1; i>=neg; i-=LOG_BASE){
        lld cur = 0;
        for(int j=min(LOG_BASE-1, i-neg); j>=0; j--){
            cur = cur*10+a[i-j]-'0';
        }
        dig.push_back(cur);
    }
    trim();
}
inline bool operator<(const BigInt& a) const {
    return cmp_minus(a)<0;
}
inline bool operator<=(const BigInt& a) const {
    return cmp_minus(a)<=0;
}
inline bool operator==(const BigInt& a) const {
    return cmp_minus(a)==0;
}
inline bool operator!=(const BigInt& a) const {
    return cmp_minus(a)!=0;
}
inline bool operator>(const BigInt& a) const {
    return cmp_minus(a)>0;
}
inline bool operator>=(const BigInt& a) const {
    return cmp_minus(a)>=0;
}
BigInt operator-() const {
    BigInt ret = *this;
    ret.neg ^= 1;
    return ret;
}
BigInt operator+(const BigInt& a) const {
    if(neg) return -(*this)+(-a);
    if(a.neg) return (*this)-(-a);
    int n = max(a.len(), len());
    BigInt ret; ret.dig.resize(n);
    lld pro = 0;
    for(int i=0; i<n; i++) {
        ret.dig[i] = pro;
        if(i < a.len()) ret.dig[i] += a.dig[i];
        if(i < len()) ret.dig[i] += dig[i];
        pro = 0;
        if(ret.dig[i] >= BASE) pro = ret.dig[i]/BASE;
        ret.dig[i] -= BASE*pro;
    }
    if(pro != 0) ret.dig.push_back(pro);
    return ret;
}
BigInt operator-(const BigInt& a) const {
    if(neg) return -(-(*this) - (-a));
    if(a.neg) return (*this) + (-a);
    int diff = cmp_minus(a);
    if(diff < 0) return -(a - (*this));
    if(diff == 0) return 0;
    BigInt ret; ret.dig.resize(len(), 0);
    for(int i=0; i<len(); i++) {
        ret.dig[i] += dig[i];
        if(i < a.len()) ret.dig[i] -= a.dig[i];
        if(ret.dig[i] < 0){
            ret.dig[i] += BASE;
            ret.dig[i+1]--;
        }
    }
    ret.trim();
    return ret;
}

```

```

BigInt operator*(const BigInt& a) const {
    if(!len() || !a.len()) return 0;
    BigInt ret; ret.dig.resize(len()+a.len()+1);
    ret.neg = neg ^ a.neg;
    for(int i=0; i<len(); i++){
        for(int j=0; j<a.len(); j++){
            ret.dig[i+j] += dig[i] * a.dig[j];
            if(ret.dig[i+j] >= BASE) {
                lld x = ret.dig[i+j] / BASE;
                ret.dig[i+j+1] += x;
                ret.dig[i+j] -= x * BASE;
            }
        }
    }
    ret.trim();
    return ret;
}
BigInt operator/(const BigInt& a) const {
    assert(a.len());
    if(len() < a.len()) return 0;
    BigInt ret; ret.dig.resize(len()-a.len()+1);
    ret.neg = a.neg;
    for(int i=len()-a.len(); i>=0; i--){
        lld l = 0, r = BASE;
        while(r-l > 1){
            lld mid = (l+r)>>1;
            ret.dig[i] = mid;
            if(ret*a<=(neg?-(*this):(*this))) l = mid;
            else r = mid;
        }
        ret.dig[i] = l;
    }
    ret.neg ^= neg; ret.trim();
    return ret;
}
BigInt operator%(const BigInt& a) const {
    return (*this) - (*this) / a * a;
}
friend BigInt abs(BigInt a){
    a.neg = 1; return a;
}
friend void swap(BigInt& a, BigInt& b){
    swap(a.dig, b.dig); swap(a.neg, b.neg);
}
friend istream& operator>>(istream& ss, BigInt& a){
    string s; ss >> s; a = s;
    return ss;
}
friend ostream& operator<<(ostream& o, const BigInt& a){
    if(a.len() == 0) return o << '0';
    if(a.neg) o << '-';
    ss << o.dig.back();
    for(int i=a.len()-2; i>=0; i--){
        o << setw(LOG_BASE) << setfill('0') << a.dig[i];
    }
    return o;
}
inline void print() const {
    if(len() == 0){ putchar('0'); return; }
    if(neg) putchar('-');
    printf("%" PRINTF_ARG, dig.back());
    for(int i=len()-2; i>=0; i--){
        printf("%0" LOG_BASE_STR PRINTF_ARG, dig[i]);
    }
}
#undef PRINTF_ARG
#undef LOG_BASE_STR
};

```

## 2.2 Dark Magic

```

#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/priority_queue.hpp>
using __gnu_pbds::pairing_heap_tag;
using __gnu_pbds::binary_heap_tag;
using __gnu_pbds::binomial_heap_tag;
using __gnu_pbds::rc_binomial_heap_tag;
using __gnu_pbds::thin_heap_tag;
template<typename T>
using pbds_heap = __gnu_pbds::priority_queue<T, less<T>, \
    pairing_heap_tag>;

// a.join(b), pq.modify(pq.push(10), 87)
using __gnu_pbds::rb_tree_tag;
using __gnu_pbds::ov_tree_tag;

```

```
using __gnu_pbds::splay_tree_tag;
template<typename T>
using ordered_set = __gnu_pbds::tree<T,\
__gnu_pbds::null_type,less<T>,rb_tree_tag,\
__gnu_pbds::tree_order_statistics_node_update>;
// find_by_order, order_of_key
template<typename A,typename B>
using hTable1=__gnu_pbds::cc_hash_table<A,B>;
template<typename A,typename B>
using hTable2=__gnu_pbds::gp_hash_table<A,B>;
```

## 2.3 Disjoint Set

```
class DJS {
private:
    vector< int > fa, sz, sv;
    vector< pair< int*, int > > opt;
    void assign( int *k, int v ) {
        opt.emplace_back( k, *k );
        *k = v;
    }
public:
    void init( int n ) {
        fa.resize( n ); iota( fa.begin(), fa.end(), 0 );
        sz.resize( n ); fill( sz.begin(), sz.end(), 1 );
        opt.clear();
    }
    int query( int x ) {return fa[x] == x?x:query(fa[x]);}
    void merge( int a, int b ) {
        int af = query( a ), bf = query( b );
        if( af == bf ) return;
        if( sz[ af ] < sz[ bf ] ) swap( af, bf );
        assign( &fa[ bf ], fa[ af ] );
        assign( &sz[ af ], sz[ af ] + sz[ bf ] );
    }
    void save() { sv.push_back( (int) opt.size() ); }
    void undo() {
        int ls = sv.back(); sv.pop_back();
        while ( ( int ) opt.size() > ls ) {
            pair< int*, int > cur = opt.back();
            *cur.first = cur.second;
            opt.pop_back();
        }
    }
};
```

## 2.4 Link-Cut Tree

```
struct Node{
    Node *par,*ch[2];
    int xor_sum,v;
    bool is_rev;
    Node(int _v){
        v=xor_sum=_v;is_rev=false;
        par=ch[0]=ch[1]=nullptr;
    }
    inline void set_rev(){is_rev^=1;swap(ch[0],ch[1]);}
    inline void down(){
        if(is_rev){
            if(ch[0]!=nullptr) ch[0]->set_rev();
            if(ch[1]!=nullptr) ch[1]->set_rev();
            is_rev=false;
        }
    }
    inline void up(){
        xor_sum=v;
        if(ch[0]!=nullptr){
            xor_sum^=ch[0]->xor_sum;
            ch[0]->par=this;
        }
        if(ch[1]!=nullptr){
            xor_sum^=ch[1]->xor_sum;
            ch[1]->par=this;
        }
    }
    inline bool is_root(){
        return par==nullptr ||\
            (par->ch[0]!=this && par->ch[1]!=this);
    }
    bool is_rch(){return !is_root() && par->ch[1]==this;}
    *node[maxn],*stk[maxn];
```

```
int top;
void to_child(Node* p,Node* c,bool dir){
    p->ch[dir]=c;
    p->up();
}
inline void rotate(Node* node){
    Node* par=node->par;
    Node* par_par=par->par;
    bool dir=node->is_rch();
    bool par_dir=par->is_rch();
    to_child(par,node->ch[!dir],dir);
    to_child(node,par,!dir);
    if(par_par!=nullptr && par_par->ch[par_dir]==par)
        to_child(par_par,node,par_dir);
    else node->par=par_par;
}
inline void splay(Node* node){
    Node* tmp=node;
    stk[top++]=node;
    while(!tmp->is_root()){
        tmp=tmp->par;
        stk[top++]=tmp;
    }
    while(top) stk[--top]->down();
    for(Node *fa=node->par;
        !node->is_root();
        rotate(node),fa=node->par)
        if(!fa->is_root())
            rotate(fa->is_rch()==node->is_rch()?fa:node);
}
inline void access(Node* node){
    Node* last=nullptr;
    while(node!=nullptr){
        splay(node);
        to_child(node,last,true);
        last=node;
        node=node->par;
    }
}
inline void change_root(Node* node){
    access(node);splay(node);node->set_rev();
}
inline void link(Node* x,Node* y){
    change_root(x);splay(x);x->par=y;
}
inline void split(Node* x,Node* y){
    change_root(x);access(y);splay(x);
    to_child(x,nullptr,true);y->par=nullptr;
}
inline void change_val(Node* node,int v){
    access(node);splay(node);node->v=v;node->up();
}
inline int query(Node* x,Node* y){
    change_root(x);access(y);splay(y);
    return y->xor_sum;
}
inline Node* find_root(Node* node){
    access(node);splay(node);
    Node* last=nullptr;
    while(node!=nullptr){
        node->down();last=node;node=node->ch[0];
    }
    return last;
}
set<pii> dic;
inline void add_edge(int u,int v){
    if(u>v) swap(u,v);
    if(find_root(node[u])==find_root(node[v])) return;
    dic.insert(pii(u,v));
    link(node[u],node[v]);
}
inline void del_edge(int u,int v){
    if(u>v) swap(u,v);
    if(dic.find(pii(u,v))==dic.end()) return;
    dic.erase(pii(u,v));
    split(node[u],node[v]);
}
```

## 2.5 LiChao Segment Tree

```
struct Line{
```

```

int m, k, id;
Line() : id( -1 ) {}
Line( int a, int b, int c )
    : m( a ), k( b ), id( c ) {}
int at( int x ) { return m * x + k; }
};

class LiChao {
private:
    int n; vector< Line > nodes;
    inline int lc( int x ) { return 2 * x + 1; }
    inline int rc( int x ) { return 2 * x + 2; }
    void insert( int l, int r, int id, Line ln ) {
        int m = ( l + r ) >> 1;
        if ( nodes[ id ].id == -1 ) {
            nodes[ id ] = ln;
            return;
        }
        bool atLeft = nodes[ id ].at( l ) < ln.at( l );
        if ( nodes[ id ].at( m ) < ln.at( m ) ) {
            atLeft ^= 1; swap( nodes[ id ], ln );
        }
        if ( r - l == 1 ) return;
        if ( atLeft ) insert( l, m, lc( id ), ln );
        else insert( m, r, rc( id ), ln );
    }
    int query( int l, int r, int id, int x ) {
        int ret = 0;
        if ( nodes[ id ].id != -1 )
            ret = nodes[ id ].at( x );
        int m = ( l + r ) >> 1;
        if ( r - l == 1 ) return ret;
        else if ( x < m )
            return max( ret, query( l, m, lc( id ), x ) );
        else
            return max( ret, query( m, r, rc( id ), x ) );
    }
public:
    void build( int n_ ) {
        n = n_; nodes.clear();
        nodes.resize( n << 2, Line() );
    }
    void insert( Line ln ) { insert( 0, n, 0, ln ); }
    int query( int x ) { return query( 0, n, 0, x ); }
} lichao;

```

## 2.6 Treap

```

namespace Treap{
#define sz( x ) ( ( x ) ? ( ( x )->size ) : 0 )
struct node{
    int size;
    uint32_t pri;
    node *lc, *rc;
    node() : size(0), pri(rand()), lc( 0 ), rc( 0 ) {}
    void pull() {
        size = 1;
        if ( lc ) size += lc->size;
        if ( rc ) size += rc->size;
    }
};

node* merge( node* L, node* R ) {
    if ( not L or not R ) return L ? L : R;
    if ( L->pri > R->pri ) {
        L->rc = merge( L->rc, R ); L->pull();
        return L;
    } else {
        R->lc = merge( L, R->lc ); R->pull();
        return R;
    }
}

void split_by_size( node*rt, int k, node*&L, node*&R ) {
    if ( not rt ) L = R = nullptr;
    else if( sz( rt->lc ) + 1 <= k ) {
        L = rt;
        split_by_size( rt->rc, k-sz(rt->lc)-1, L->rc, R );
        L->pull();
    } else {
        R = rt;
        split_by_size( rt->lc, k, L, R->lc );
        R->pull();
    }
}

```

```

}
#undef sz
}

```

## 2.7 SparseTable

```

template < typename T, typename Cmp_ = less< T > >
class SparseTable {
private:
    vector< vector< T > > tbl;
    vector< int > lg;
    T cv( T a, T b ) {
        return Cmp_()( a, b ) ? a : b;
    }
public:
    void init( T arr[], int n ) {
        // 0-base
        lg.resize( n + 1 );
        lg[ 0 ] = -1;
        for( int i=1; i<=n; ++i ) lg[i] = lg[i>>1] + 1;
        tbl.resize( lg[n] + 1 );
        tbl[ 0 ].resize( n );
        copy( arr, arr + n, tbl[ 0 ].begin() );
        for ( int i = 1; i <= lg[ n ]; ++ i ) {
            int len = 1 << ( i - 1 ), sz = 1 << i;
            tbl[ i ].resize( n - sz + 1 );
            for ( int j = 0; j <= n - sz; ++ j )
                tbl[i][j] = cv(tbl[i-1][j], tbl[i-1][j+len]);
        }
    }
    T query( int l, int r ) {
        // 0-base [l, r)
        int wh = lg[ r - l ], len = 1 << wh;
        return cv( tbl[ wh ][ l ], tbl[ wh ][ r - len ] );
    }
};

```

## 2.8 Linear Basis

```

struct LinearBasis {
private:
    int n, sz;
    vector< ll_u > B;
    inline ll_u two( int x ){ return ( ( ll_u ) 1 ) << x; }
public:
    void init( int n_ ) {
        n = n_; B.clear(); B.resize( n ); sz = 0;
    }
    void insert( ll_u x ) {
        // add x into B
        for ( int i = n-1; i >= 0; --i ) if( two(i) & x ){
            if ( B[ i ] ) x ^= B[ i ];
            else {
                B[ i ] = x; sz++;
                for ( int j = i - 1; j >= 0; -- j )
                    if( B[ j ] && ( two( j ) & B[ i ] ) )
                        B[ i ] ^= B[ j ];
                for (int j = i + 1; j < n; ++ j )
                    if ( two( i ) & B[ j ] )
                        B[ j ] ^= B[ i ];
                break;
            }
        }
    }
    inline int size() { return sz; }
    bool check( ll_u x ) {
        // is x in span(B) ?
        for ( int i = n-1; i >= 0; --i ) if( two(i) & x )
            if ( B[ i ] ) x ^= B[ i ];
        else return false;
        return true;
    }
    ll_u kth_small(ll_u k) {
        /** 1-base would always > 0 **/
        /** should check it **/
        /* if we choose at least one element
        but size(B)(vectors in B)==N(original elements)
        then we can't get 0 */
        ll_u ret = 0;
        for ( int i = 0; i < n; ++ i ) if( B[ i ] ) {
            if( k & 1 ) ret ^= B[ i ];
        }
    }
}

```

```

    k >>= 1;
}
return ret;
}
} base;

```

### 3 Graph

#### 3.1 Euler Circuit

```

bool vis[ N ]; size_t la[ K ];
void dfs( int u, vector< int >& vec ) {
    while ( la[ u ] < G[ u ].size() ) {
        if ( vis[ G[ u ][ la[ u ] ].second ] ) {
            ++ la[ u ];
            continue;
        }
        int v = G[ u ][ la[ u ] ].first;
        vis[ G[ u ][ la[ u ] ].second ] = true;
        ++ la[ u ]; dfs( v, vec );
        vec.push_back( v );
    }
}

```

#### 3.2 BCC Edge

```

class BCC{
private:
    vector< int > low, dfn;
    int cnt;
    vector< bool > bridge;
    vector< vector< PII > > G;
    void dfs( int w, int f ) {
        low[ w ] = dfn[ w ] = cnt++;
        for ( auto [ u, t ] : G[ w ] ) {
            if ( u == f ) continue;
            if ( dfn[ u ] != 0 ) {
                low[ w ] = min( low[ w ], dfn[ u ] );
            } else {
                dfs( u, w );
                low[ w ] = min( low[ w ], low[ u ] );
                if ( low[ u ] > dfn[ w ] ) bridge[ t ] = true;
            }
        }
    }
public:
    void init( int n, int m ) {
        G.resize( n ); cnt = 0;
        fill( G.begin(), G.end(), vector< PII >() );
        bridge.clear(); bridge.resize( m );
        low.clear(); low.resize( n );
        dfn.clear(); dfn.resize( n );
    }
    void add_edge( int u, int v ) {
        // should check for multiple edge
        G[ u ].emplace_back( v, cnt );
        G[ v ].emplace_back( u, cnt ++ );
    }
    void solve(){
        cnt = 1;
        for ( int i = 0; i < n; ++i )
            if ( not vis[ i ] ) dfs( i, i );
        // the id will be same as insert order, 0-base
        bool is_bridge( int x ) { return bridge[ x ]; }
    }
} bcc;

```

#### 3.3 BCC Vertex

```

class BCC{
private:
    int n, ecnt;
    vector< vector< pair< int, int > > > G;
    vector< int > low, dfn, id;
    vector< bool > vis, ap;
    void dfs( int u, int f, int d ) {
        int child = 0;
        dfn[ u ] = low[ u ] = d; vis[ u ] = true;
        for ( auto e : G[ u ] ) if ( e.first != f ) {

```

```

            if ( vis[ e.first ] ) {
                low[ u ] = min( low[ u ], dfn[ e.first ] );
            } else {
                dfs( e.first, u, d + 1 ); child ++;
                low[ u ] = min( low[ u ], low[ e.first ] );
                if ( low[ e.first ] >= d ) ap[ u ] = true;
            }
        }
        if ( u == f and child <= 1 ) ap[ u ] = false;
    }
    void mark( int u, int idd ) {
        // really?????????
        if ( ap[ u ] ) return;
        for ( auto e : G[ u ] )
            if ( id[ e.second ] != -1 ) {
                id[ e.second ] = idd;
                mark( e.first, idd );
            }
    }
public:
    void init( int n_ ) {
        ecnt = 0, n = n_;
        G.clear(); G.resize( n );
        low.resize( n ); dfn.resize( n );
        ap.clear(); ap.resize( n );
        vis.clear(); vis.resize( n );
    }
    void add_edge( int u, int v ) {
        G[ u ].emplace_back( v, ecnt );
        G[ v ].emplace_back( u, ecnt ++ );
    }
    void solve() {
        for ( int i = 0; i < n; ++ i )
            if ( not vis[ i ] ) dfs( i, i, 0 );
        id.resize( ecnt );
        fill( id.begin(), id.end(), -1 );
        ecnt = 0;
        for ( int i = 0; i < n; ++ i )
            if ( ap[ i ] ) for ( auto e : G[ i ] )
                if ( id[ e.second ] != -1 ) {
                    id[ e.second ] = ecnt;
                    mark( e.first, ecnt ++ );
                }
    }
    int get_id( int x ) { return id[ x ]; }
    int count() { return ecnt; }
    bool is_ap( int u ) { return ap[ u ]; }
} bcc;

```

#### 3.4 2-SAT (SCC)

```

class TwoSat{
private:
    int n;
    vector<vector<int>>> rG,G,sccs;
    vector<int> ord,idx;
    vector<bool> vis,result;
    void dfs(int u){
        vis[u]=true;
        for(int v:G[u])
            if(!vis[v]) dfs(v);
        ord.push_back(u);
    }
    void rdfs(int u){
        vis[u]=false;idx[u]=sccs.size()-1;
        sccs.back().push_back(u);
        for(int v:rG[u])
            if(vis[v])rdfs(v);
    }
public:
    void init(int n_){
        n=n_;G.clear();G.resize(n);
        rG.clear();rG.resize(n);
        sccs.clear();ord.clear();
        idx.resize(n);result.resize(n);
    }
    void add_edge(int u,int v){
        G[u].push_back(v);rG[v].push_back(u);
    }
    void orr(int x,int y){
        if ((x^y)==1)return;

```



```

    add_edge(x^1,y); add_edge(y^1,x);
}
bool solve(){
    vis.clear();vis.resize(n);
    for(int i=0;i<n;++i)
        if(not vis[i])dfs(i);
    reverse(ord.begin(),ord.end());
    for (int u:ord){
        if(!vis[u])continue;
        sccs.push_back(vector<int>());
        rdfs(u);
    }
    for(int i=0;i<n;i+=2)
        if(idx[i]==idx[i+1])
            return false;
    vector<bool> c(sccs.size());
    for(size_t i=0;i<sccs.size();++i){
        for(size_t j=0;j<sccs[i].size();++j){
            result[sccs[i][j]]=c[i];
            c[idx[sccs[i][j]^1]]=!c[i];
        }
    }
    return true;
}
bool get(int x){return result[x];}
inline int get_id(int x){return idx[x];}
inline int count(){return sccs.size();}
} sat2;

```

### 3.5 Lowbit Decomposition

```

class LowbitDecomp{
private:
    int time_, chain_, LOG_N;
    vector< vector< int > > G, fa;
    vector< int > tl, tr, chain, chain_st;
    // chain_ : number of chain
    // tl, tr[ u ] : subtree interval in the seq. of u
    // chain_st[ u ] : head of the chain contains u
    // chain[ u ] : chain id of the chain u is on
    inline int lowbit( int x ) {
        return x & ( -x );
    }
    void predfs( int u, int f ) {
        chain[ u ] = 0;
        for ( int v : G[ u ] ) {
            if ( v == f ) continue;
            predfs( v, u );
            if( lowbit( chain[ u ] ) < lowbit( chain[ v ] ) )
                chain[ u ] = chain[ v ];
        }
        if ( not chain[ u ] )
            chain[ u ] = chain_ ++;
    }
    void dfschain( int u, int f ) {
        fa[ u ][ 0 ] = f;
        for ( int i = 1 ; i < LOG_N ; ++ i )
            fa[ u ][ i ] = fa[ fa[ u ][ i - 1 ] ][ i - 1 ];
        tl[ u ] = time_++;
        if ( not chain_st[ chain[ u ] ] )
            chain_st[ chain[ u ] ] = u;
        for ( int v : G[ u ] )
            if ( v != f and chain[ v ] == chain[ u ] )
                dfschain( v, u );
        for ( int v : G[ u ] )
            if ( v != f and chain[ v ] != chain[ u ] )
                dfschain( v, u );
        tr[ u ] = time_;
    }
    inline bool anc( int u, int v ) {
        return tl[ u ] <= tl[ v ] \
            and tr[ v ] <= tr[ u ];
    }
public:
    inline int lca( int u, int v ) {
        if ( anc( u, v ) ) return u;
        for ( int i = LOG_N - 1 ; i >= 0 ; -- i )
            if ( not anc( fa[ u ][ i ], v ) )
                u = fa[ u ][ i ];
        return fa[ u ][ 0 ];
    }
}

```

```

void init( int n ) {
    n ++;
    for ( LOG_N = 0 ; ( 1 << LOG_N ) < n ; ++ LOG_N );
    fa.clear();
    fa.resize( n, vector< int >( LOG_N ) );
    G.clear(); G.resize( n );
    tl.clear(); tl.resize( n );
    tr.clear(); tr.resize( n );
    chain.clear(); chain.resize( n );
    chain_st.clear(); chain_st.resize( n );
}
void add_edge( int u , int v ) {
    // 1-base
    G[ u ].push_back( v );
    G[ v ].push_back( u );
}
void decompose(){
    chain_ = 1;
    predfs( 1, 1 );
    time_ = 0;
    dfschain( 1, 1 );
}
PII get_inter( int u ) { return {tl[ u ], tr[ u ]}; }
vector< PII > get_path( int u , int v ){
    vector< PII > res;
    int g = lca( u, v );
    while ( chain[ u ] != chain[ g ] ) {
        int s = chain_st[ chain[ u ] ];
        res.emplace_back( tl[ s ], tl[ u ] + 1 );
        u = fa[ s ][ 0 ];
    }
    res.emplace_back( tl[ g ], tl[ u ] + 1 );
    while ( chain[ v ] != chain[ g ] ) {
        int s = chain_st[ chain[ v ] ];
        res.emplace_back( tl[ s ], tl[ v ] + 1 );
        v = fa[ s ][ 0 ];
    }
    res.emplace_back( tl[ g ] + 1, tl[ v ] + 1 );
    return res;
}
/* res : list of intervals from u to v
 * ( note only nodes work, not edge )
 * usage :
 * vector< PII >& path = tree.get_path( u , v )
 * for( auto [ l, r ] : path ) {
 *     0-base [ l, r )
 * }
 */
} tree;

```

### 3.6 MaxClique

```

// contain a self loop u to u, than u won't in clique
template < size_t MAXN >
class MaxClique{
private:
    using bits = bitset< MAXN >;
    bits popped, G[ MAXN ], ans;
    size_t deg[ MAXN ], deo[ MAXN ], n;
    void sort_by_degree() {
        popped.reset();
        for ( size_t i = 0 ; i < n ; ++ i )
            deg[ i ] = G[ i ].count();
        for ( size_t i = 0 ; i < n ; ++ i ) {
            size_t mi = MAXN, id = 0;
            for ( size_t j = 0 ; j < n ; ++ j )
                if ( not popped[ j ] and deg[ j ] < mi )
                    mi = deg[ id = j ];
            popped[ deo[ i ] = id ] = 1;
            for( size_t u = G[ i ]._Find_first() ;
                u < n ; u = G[ i ]._Find_next( u ) )
                -- deg[ u ];
        }
    }
    void BK( bits R, bits P, bits X ) {
        if ( R.count()+P.count() <= ans.count() ) return;
        if ( not P.count() and not X.count() ) {
            if ( R.count() > ans.count() ) ans = R;
            return;
        }
        /* greedily choose max degree as pivot

```

```

bits cur = P | X; size_t pivot = 0, sz = 0;
for ( size_t u = cur._Find_first() ;
      u < n ; u = cur._Find_next( u ) )
    if ( deg[ u ] > sz ) sz = deg[ pivot = u ];
cur = P & ( ~G[ pivot ] );
/* // or simply choose first
bits cur = P & ( ~G[ ( P | X )._Find_first() ] );
for ( size_t u = cur._Find_first() ;
      u < n ; u = cur._Find_next( u ) ) {
    if ( R[ u ] ) continue;
    R[ u ] = 1;
    BK( R, P & G[ u ], X & G[ u ] );
    R[ u ] = P[ u ] = 0, X[ u ] = 1;
}
}
public:
void init( size_t n_ ) {
    n = n_;
    for ( size_t i = 0 ; i < n ; ++ i )
        G[ i ].reset();
    ans.reset();
}
void add_edges( int u, bits S ) { G[ u ] = S; }
void add_edge( int u, int v ) {
    G[ u ][ v ] = G[ v ][ u ] = 1;
}
int solve() {
    sort_by_degree(); // or simply iota( deo... )
    for ( size_t i = 0 ; i < n ; ++ i )
        deg[ i ] = G[ i ].count();
    bits pob, nob = 0; pob.set();
    for ( size_t i=n; i<MAXN; ++i ) pob[i] = 0;
    for ( size_t i = 0 ; i < n ; ++ i ) {
        size_t v = deo[ i ];
        bits tmp; tmp[ v ] = 1;
        BK( tmp, pob & G[ v ], nob & G[ v ] );
        pob[ v ] = 0, nob[ v ] = 1;
    }
    return static_cast< int >( ans.count() );
}
};

```

### 3.7 Virtual Tree

```

inline bool cmp(const int &i, const int &j) {
    return dfn[i] < dfn[j];
}
void build(int vectrices[], int k) {
    static int stk[MAX_N];
    sort(vectrices, vectrices + k, cmp);
    stk[sz++] = 0;
    for ( int i = 0; i < k; ++i ) {
        int u = vectrices[i], lca = LCA(u, stk[sz - 1]);
        if (lca == stk[sz - 1]) stk[sz++] = u;
        else {
            while (sz >= 2 && dep[stk[sz - 2]] >= dep[lca]) {
                addEdge(stk[sz - 2], stk[sz - 1]);
                sz--;
            }
            if (stk[sz - 1] != lca) {
                addEdge(lca, stk[sz - 1]);
                stk[sz++] = lca, vectrices[cnt++] = lca;
            }
            stk[sz++] = u;
        }
    }
    for ( int i = 0; i < sz - 1; ++i )
        addEdge(stk[i], stk[i + 1]);
}

```

### 3.8 Tree Hashing

```

uint64_t hsah( int u, int f ) {
    uint64_t r = 127;
    for ( int v : G[ u ] ) {
        if ( v == f ) continue;
        uint64_t hh = hsah( v, u );
        r = r + ( hh * hh ) % mod;
    }
    return r;
}

```

### 3.9 Minimum Mean Cycle

```

/* minimum mean cycle O(VE) */
struct MMC{
#define FZ(n) memset((n),0,sizeof(n))
#define E 101010
#define V 1021
#define inf 1e9
    struct Edge { int v,u; double c; };
    int n, m, prv[V][V], prve[V][V], vst[V];
    Edge e[E];
    vector<int> edgeID, cycle, rho;
    double d[V][V];
    void init( int _n ) { n = _n; m = 0; }
    // WARNING: TYPE matters
    void add_edge( int vi, int ui, double ci )
    { e[ m ++ ] = { vi, ui, ci }; }
    void bellman_ford() {
        for(int i=0; i<n; i++) d[0][i]=0;
        for(int i=0; i<n; i++) {
            fill(d[i+1], d[i+1]+n, inf);
            for(int j=0; j<m; j++) {
                int v = e[j].v, u = e[j].u;
                if(d[i][v]<inf && d[i+1][u]>d[i][v]+e[j].c) {
                    d[i+1][u] = d[i][v]+e[j].c;
                    prv[i+1][u] = v;
                    prve[i+1][u] = j;
                }
            }
        }
    }
    double solve(){
        // returns inf if no cycle, mmc otherwise
        double mmc=inf;
        int st = -1;
        bellman_ford();
        for(int i=0; i<n; i++) {
            double avg=-inf;
            for(int k=0; k<n; k++) {
                if(d[n][i]<inf-eps)
                    avg=max(avg, (d[n][i]-d[k][i])/(n-k));
                else avg=max(avg, inf);
            }
            if (avg < mmc) tie(mmc, st) = tie(avg, i);
        }
        FZ(vst); edgeID.clear(); cycle.clear(); rho.clear();
        for ( int i=n; !vst[st]; st=prv[i--][st] ) {
            vst[st]++;
            edgeID.PB(prve[i][st]);
            rho.PB(st);
        }
        while (vst[st] != 2) {
            int v = rho.back(); rho.pop_back();
            cycle.PB(v);
            vst[v]++;
        }
        reverse(ALL(edgeID));
        edgeID.resize(SZ(cycle));
        return mmc;
    }
} mmc;

```

### 3.10 Mo's Algorithm on Tree

```

int n, q, nxt[ N ], to[ N ], hd[ N ];
struct Que{
    int u, v, id;
} que[ N ];
void init() {
    cin >> n >> q;
    for ( int i = 1 ; i < n ; ++ i ) {
        int u, v; cin >> u >> v;
        nxt[ i << 1 | 0 ] = hd[ u ];
        to[ i << 1 | 0 ] = v;
        hd[ u ] = i << 1 | 0;
        nxt[ i << 1 | 1 ] = hd[ v ];
        to[ i << 1 | 1 ] = u;
        hd[ v ] = i << 1 | 1;
    }
    for ( int i = 0 ; i < q ; ++ i ) {
        cin >> que[ i ].u >> que[ i ].v; que[ i ].id = i;
    }
}

```

```

}
}
int dfn[N], dfn_, block_id[N], block_, stk[N], stk_;
void dfs( int u, int f ) {
    dfn[ u ] = dfn_++; int saved_rbp = stk_;
    for ( int v_ = hd[ u ] ; v_ ; v_ = nxt[ v_ ] ) {
        if ( to[ v_ ] == f ) continue;
        dfs( to[ v_ ], u );
        if ( stk_ - saved_rbp < SQRT_N ) continue;
        for ( ++ block_ ; stk_ != saved_rbp ; )
            block_id[ stk[ -- stk_ ] ] = block_;
    }
    stk[ stk_ ++ ] = u;
}
bool inPath[ N ];
void Diff( int u ) {
    if ( inPath[ u ] ^ 1 )
        // remove this edge
    else
        // add this edge
}
void traverse( int& origin_u, int u ) {
    for ( int g = lca( origin_u, u ) ;
        origin_u != g ; origin_u = parent_of[ origin_u ] )
        Diff( origin_u );
    for ( int v = u ; v != origin_u ; v = parent_of[v] )
        Diff( v );
    origin_u = u;
}
void solve() {
    dfs( 1, 1 );
    while ( stk_ ) block_id[ stk[ -- stk_ ] ] = block_;
    sort( que, que + q, [](const Que& x, const Que& y) {
        return tie( block_id[ x.u ], dfn[ x.v ] )
            < tie( block_id[ y.u ], dfn[ y.v ] );
    } );
    int U = 1, V = 1;
    for ( int i = 0 ; i < q ; ++ i ) {
        pass( U, que[ i ].u );
        pass( V, que[ i ].v );
        // we could get our answer of que[ i ].id
    }
}
/*
Method 2:
dfs u:
    push u
    iterate subtree
    push u
Let P = LCA(u, v), and St(u) <= St(v)
if ( P == u ) query[St(u), St(v)]
else query[Ed(u), St(v)], query[St(P), St(P)]
*/

```

### 3.11 Minimum Steiner Tree

```

// Minimum Steiner Tree
// O(V^3 T + V^2 2^T)
struct SteinerTree {
#define V 33
#define T 8
#define INF 1023456789
    int n, dst[V][V], dp[1 << T][V], tdst[V];
    void init( int _n ) {
        n = _n;
        for( int i = 0 ; i < n ; i ++ ) {
            for( int j = 0 ; j < n ; j ++ )
                dst[ i ][ j ] = INF;
            dst[ i ][ i ] = 0;
        }
    }
    void add_edge( int ui, int vi, int wi ) {
        dst[ ui ][ vi ] = min( dst[ ui ][ vi ], wi );
        dst[ vi ][ ui ] = min( dst[ vi ][ ui ], wi );
    }
    void shortest_path() {
        for( int k = 0 ; k < n ; k ++ )
            for( int i = 0 ; i < n ; i ++ )
                for( int j = 0 ; j < n ; j ++ )
                    dst[ i ][ j ] = min( dst[ i ][ j ],
                        dst[ i ][ k ] + dst[ k ][ j ] );
    }
}

```

```

}
int solve( const vector<int>& ter ) {
    int t = (int)ter.size();
    for( int i = 0 ; i < ( 1 << t ) ; i ++ )
        for( int j = 0 ; j < n ; j ++ )
            dp[ i ][ j ] = INF;
    for( int i = 0 ; i < n ; i ++ )
        dp[ 0 ][ i ] = 0;
    for( int msk = 1 ; msk < ( 1 << t ) ; msk ++ ) {
        if( msk == ( msk & (-msk) ) ) {
            int who = __lg( msk );
            for( int i = 0 ; i < n ; i ++ )
                dp[ msk ][ i ] = dst[ ter[ who ] ][ i ];
            continue;
        }
        for( int i = 0 ; i < n ; i ++ )
            for( int submsk = ( msk - 1 ) & msk ; submsk ;
                submsk = ( submsk - 1 ) & msk )
                dp[ msk ][ i ] = min( dp[ msk ][ i ],
                    dp[ submsk ][ i ] +
                    dp[ msk ^ submsk ][ i ] );
        for( int i = 0 ; i < n ; i ++ ) {
            tdst[ i ] = INF;
            for( int j = 0 ; j < n ; j ++ )
                tdst[ i ] = min( tdst[ i ],
                    dp[ msk ][ j ] + dst[ j ][ i ] );
        }
        for( int i = 0 ; i < n ; i ++ )
            dp[ msk ][ i ] = tdst[ i ];
    }
    int ans = INF;
    for( int i = 0 ; i < n ; i ++ )
        ans = min( ans, dp[ ( 1 << t ) - 1 ][ i ] );
    return ans;
}
} solver;

```

### 3.12 Directed Minimum Spanning Tree

```

template <typename T> struct DMST {
    T g[maxn][maxn], fw[maxn];
    int n, fr[maxn];
    bool vis[maxn], inc[maxn];
    void clear() {
        for(int i = 0; i < maxn; ++i) {
            for(int j = 0; j < maxn; ++j) g[i][j] = inf;
            vis[i] = inc[i] = false;
        }
    }
    void addEdge(int u, int v, T w) { g[u][v] = min(g[u][v], w); }
    T operator()(int root, int _n) {
        n = _n; T ans = 0;
        if (dfs(root) != n) return -1;
        while (true) {
            for(int i = 1; i <= n; ++i) fw[i] = inf, fr[i] = i;
            for (int i = 1; i <= n; ++i) if (!inc[i]) {
                for (int j = 1; j <= n; ++j) {
                    if (!inc[j] && i != j && g[j][i] < fw[i]) {
                        fw[i] = g[j][i]; fr[i] = j;
                    }
                }
            }
            int x = -1;
            for(int i = 1; i <= n; ++i) if(i != root && !inc[i]) {
                int j = i, c = 0;
                while(j != root && fr[j] != i && c <= n) ++c, j = fr[j];
                if (j == root || c > n) continue;
                else { x = i; break; }
            }
            if (!~x) {
                for (int i = 1; i <= n; ++i)
                    if (i != root && !inc[i]) ans += fw[i];
                return ans;
            }
            int y = x;
            for (int i = 1; i <= n; ++i) vis[i] = false;
            do {

```



```

    ans += fw[y]; y = fr[y]; vis[y] = inc[y] = true;
    ;
    } while (y != x);
    inc[x] = false;
    for (int k = 1; k <= n; ++k) if (vis[k]) {
        for (int j = 1; j <= n; ++j) if (!vis[j]) {
            if (g[x][j] > g[k][j]) g[x][j] = g[k][j];
            if (g[j][k] < inf && g[j][k] - fw[k] < g[j][x])
                g[j][x] = g[j][k] - fw[k];
        }
    }
    return ans;
}
int dfs(int now) {
    int r = 1; vis[now] = true;
    for (int i = 1; i <= n; ++i)
        if (g[now][i] < inf && !vis[i]) r += dfs(i);
    return r;
}
};

```

### 3.13 Dominator Tree

```

namespace dominator {
vector<int> g[maxn], r[maxn], rdom[maxn];
int dfn[maxn], rev[maxn], fa[maxn], sdom[maxn];
int dom[maxn], val[maxn], rp[maxn], tk;
void init(int n) {
    // vertices are numbered from 0 to n - 1
    fill(dfn, dfn + n, -1); fill(rev, rev + n, -1);
    fill(fa, fa + n, -1); fill(val, val + n, -1);
    fill(sdom, sdom + n, -1); fill(rp, rp + n, -1);
    fill(dom, dom + n, -1); tk = 0;
    for (int i = 0; i < n; ++i) {
        g[i].clear(); r[i].clear(); rdom[i].clear();
    }
}
void add_edge(int x, int y) { g[x].push_back(y); }
void dfs(int x) {
    rev[dfn[x]] = tk; fa[x] = val[x] = tk; tk++;
    for (int u : g[x]) {
        if (dfn[u] == -1) dfs(u), rp[dfn[u]] = dfn[x];
        r[dfn[u]].push_back(dfn[x]);
    }
}
void merge(int x, int y) { fa[x] = y; }
int find(int x, int c = 0) {
    if (fa[x] == x) return c ? -1 : x;
    int p = find(fa[x], 1);
    if (p == -1) return c ? fa[x] : val[x];
    if (sdom[val[x]] > sdom[val[fa[x]]]) val[x] = val[fa[x]];
    fa[x] = p;
    return c ? p : val[x];
}
vector<int> build(int s, int n) {
    // return the father of each node in the dominator tree
    // p[i] = -2 if i is unreachable from s
    dfs(s);
    for (int i = tk - 1; i >= 0; --i) {
        for (int u : r[i]) sdom[i] = min(sdom[i], sdom[find(u)]);
        if (i) rdom[sdom[i]].push_back(i);
        for (int &u : rdom[i]) {
            int p = find(u);
            if (sdom[p] == i) dom[u] = i;
            else dom[u] = p;
        }
        if (i) merge(i, rp[i]);
    }
    vector<int> p(n, -2); p[s] = -1;
    for (int i = 1; i < tk; ++i)
        if (sdom[i] != dom[i]) dom[i] = dom[dom[i]];
    for (int i = 1; i < tk; ++i) p[rev[i]] = rev[dom[i]];
    return p;
}
}

```

## 4 Matching & Flow

### 4.1 Kuhn Munkres

```

class KM {
private:
    static constexpr lld INF = 1LL << 60;
    vector<lld> h1, hr, slk;
    vector<int> f1, fr, pre, qu;
    vector<vector<lld>> w;
    vector<bool> v1, vr;
    int n, q1, qr;
    bool check(int x) {
        if (v1[x] = true, f1[x] != -1)
            return vr[qu[qr++] = f1[x]] = true;
        while (x != -1) swap(x, fr[f1[x] = pre[x]]);
        return false;
    }
    void bfs(int s) {
        fill(slk.begin(), slk.end(), INF);
        fill(v1.begin(), v1.end(), false);
        fill(vr.begin(), vr.end(), false);
        q1 = qr = 0;
        qu[qr++] = s;
        vr[s] = true;
        while (true) {
            lld d;
            while (q1 < qr) {
                for (int x = 0, y = qu[q1++]; x < n; ++x) {
                    if (!v1[x] && slk[x] >= (d = h1[x] + hr[y] - w[x][y])) {
                        if (pre[x] = y, d) slk[x] = d;
                        else if (!check(x)) return;
                    }
                }
            }
            d = INF;
            for (int x = 0; x < n; ++x)
                if (!v1[x] && d > slk[x]) d = slk[x];
            for (int x = 0; x < n; ++x) {
                if (v1[x]) h1[x] += d;
                else slk[x] -= d;
                if (vr[x]) hr[x] -= d;
            }
            for (int x = 0; x < n; ++x)
                if (!v1[x] && !slk[x] && !check(x)) return;
        }
    }
public:
    void init(int n_) {
        n = n_; qu.resize(n);
        f1.clear(); f1.resize(n, -1);
        fr.clear(); fr.resize(n, -1);
        hr.clear(); hr.resize(n); h1.resize(n);
        w.clear(); w.resize(n, vector<lld>(n));
        slk.resize(n); pre.resize(n);
        v1.resize(n); vr.resize(n);
    }
    void set_edge(int u, int v, lld x) { w[u][v] = x; }
    lld solve() {
        for (int i = 0; i < n; ++i)
            h1[i] = *max_element(w[i].begin(), w[i].end());
        for (int i = 0; i < n; ++i) bfs(i);
        lld res = 0;
        for (int i = 0; i < n; ++i) res += w[i][f1[i]];
        return res;
    }
} km;

```

### 4.2 Bipartite Matching

```

class BipartiteMatching {
private:
    vector<int> X[N], Y[N];
    int fX[N], fY[N], n;
    bitset<N> walked;
    bool dfs(int x) {
        for (auto i : X[x]) {
            if (walked[i]) continue;
            walked[i] = 1;
            if (fY[i] == -1 || dfs(fY[i])) {
                fY[i] = x; fX[x] = i;
            }
        }
    }
}

```

```

        return 1;
    }
    return 0;
}
public:
void init(int _n){
    n=_n; walked.reset();
    for(int i=0;i<n;i++){
        X[i].clear();Y[i].clear();
        fX[i]=fY[i]=-1;
    }
}
void add_edge(int x, int y){
    X[x].push_back(y); Y[y].push_back(x);
}
int solve(){
    int cnt = 0;
    for(int i=0;i<n;i++){
        walked.reset();
        if(dfs(i)) cnt++;
    }
    // return how many pair matched
    return cnt;
}
};

```

### 4.3 General Graph Matching

```

const int N = 514, E = (2e5) * 2;
struct Graph{
    int to[E],bro[E],head[N],e;
    int lnk[N],vis[N],stp,n;
    void init( int _n ){
        stp = 0; e = 1; n = _n;
        for( int i = 0 ; i <= n ; i ++ )
            head[i] = lnk[i] = vis[i] = 0;
    }
    void add_edge(int u,int v){
        // 1-base
        to[e]=v,bro[e]=head[u],head[u]=e++;
        to[e]=u,bro[e]=head[v],head[v]=e++;
    }
    bool dfs(int x){
        vis[x]=stp;
        for(int i=head[x];i;i=bro[i]){
            int v=to[i];
            if(!lnk[v]){
                lnk[x]=v,lnk[v]=x;
                return true;
            }else if(vis[lnk[v]]<stp){
                int w=lnk[v];
                lnk[x]=v,lnk[v]=x,lnk[w]=0;
                if(dfs(w)) return true;
                lnk[w]=v,lnk[v]=w,lnk[x]=0;
            }
        }
        return false;
    }
    int solve(){
        int ans = 0;
        for(int i=1;i<=n;i++){
            if(not lnk[i]){
                stp++; ans += dfs(i);
            }
        }
        return ans;
    }
} graph;

```

### 4.4 Minimum Weight Matching (Clique version)

```

struct Graph {
    // 0-base (Perfect Match)
    int n, edge[MXN][MXN];
    int match[MXN],dis[MXN],onstk[MXN];
    vector<int> stk;
    void init(int _n) {
        n = _n;
        for (int i=0; i<n; i++)

```

```

        for (int j=0; j<n; j++)
            edge[i][j] = 0;
    }
    void set_edge(int u, int v, int w) {
        edge[u][v] = edge[v][u] = w;
    }
    bool SPFA(int u){
        if (onstk[u]) return true;
        stk.PB(u);
        onstk[u] = 1;
        for (int v=0; v<n; v++){
            if (u != v && match[u] != v && !onstk[v]){
                int m = match[v];
                if (dis[m] > dis[u] - edge[v][m] + edge[u][v]){
                    dis[m] = dis[u] - edge[v][m] + edge[u][v];
                    onstk[v] = 1;
                    stk.PB(v);
                    if (SPFA(m)) return true;
                    stk.pop_back();
                    onstk[v] = 0;
                }
            }
        }
        onstk[u] = 0;
        stk.pop_back();
        return false;
    }

    int solve() {
        // find a match
        for (int i=0; i<n; i+=2){
            match[i] = i+1;
            match[i+1] = i;
        }
        while (true){
            int found = 0;
            for (int i=0; i<n; i++){
                dis[i] = onstk[i] = 0;
            }
            for (int i=0; i<n; i++){
                stk.clear();
                if (!onstk[i] && SPFA(i)){
                    found = 1;
                    while (SZ(stk)>=2){
                        int u = stk.back(); stk.pop_back();
                        int v = stk.back(); stk.pop_back();
                        match[u] = v;
                        match[v] = u;
                    }
                }
            }
            if (!found) break;
        }
        int ret = 0;
        for (int i=0; i<n; i++){
            ret += edge[i][match[i]];
        }
        return ret>>1;
    }
} graph;

```

### 4.5 Flow Models

- Maximum/Minimum flow with lower bound / Circulation problem

- Construct super source  $S$  and sink  $T$ .
- For each edge  $(x, y, l, u)$ , connect  $x \rightarrow y$  with capacity  $u - l$ .
- For each vertex  $v$ , denote by  $in(v)$  the difference between the sum of incoming lower bounds and the sum of outgoing lower bounds.
- If  $in(v) > 0$ , connect  $S \rightarrow v$  with capacity  $in(v)$ , otherwise, connect  $v \rightarrow T$  with capacity  $-in(v)$ .
  - To maximize, connect  $t \rightarrow s$  with capacity  $\infty$  (skip this in circulation problem), and let  $f$  be the maximum flow from  $S$  to  $T$ . If  $f \neq \sum_{v \in V, in(v) > 0} in(v)$ , there's no solution. Otherwise, the maximum flow from  $s$  to  $t$  is the answer.
  - To minimize, let  $f$  be the maximum flow from  $S$  to  $T$ . Connect  $t \rightarrow s$  with capacity  $\infty$  and let the flow from  $S$  to  $T$  be  $f'$ . If  $f + f' \neq \sum_{v \in V, in(v) > 0} in(v)$ , there's no solution. Otherwise,  $f'$  is the answer.
- The solution of each edge  $e$  is  $l_e + f_e$ , where  $f_e$  corresponds to the flow of edge  $e$  on the graph.

- Construct minimum vertex cover from maximum matching  $M$  on bipartite graph  $(X, Y)$

1. Redirect every edge:  $y \rightarrow x$  if  $(x, y) \in M$ ,  $x \rightarrow y$  otherwise.
  2. DFS from unmatched vertices in  $X$ .
  3.  $x \in X$  is chosen iff  $x$  is unvisited.
  4.  $y \in Y$  is chosen iff  $y$  is visited.
- Minimum cost cyclic flow
    1. Construct super source  $S$  and sink  $T$
    2. For each edge  $(x, y, c)$ , connect  $x \rightarrow y$  with  $(cost, cap) = (c, 1)$  if  $c > 0$ , otherwise connect  $y \rightarrow x$  with  $(cost, cap) = (-c, 1)$
    3. For each edge with  $c < 0$ , sum these cost as  $K$ , then increase  $d(y)$  by 1, decrease  $d(x)$  by 1
    4. For each vertex  $v$  with  $d(v) > 0$ , connect  $S \rightarrow v$  with  $(cost, cap) = (0, d(v))$
    5. For each vertex  $v$  with  $d(v) < 0$ , connect  $v \rightarrow T$  with  $(cost, cap) = (0, -d(v))$
    6. Flow from  $S$  to  $T$ , the answer is the cost of the flow  $C + K$
  - Maximum density induced subgraph
    1. Binary search on answer, suppose we're checking answer  $T$
    2. Construct a max flow model, let  $K$  be the sum of all weights
    3. Connect source  $s \rightarrow v$ ,  $v \in G$  with capacity  $K$
    4. For each edge  $(u, v, w)$  in  $G$ , connect  $u \rightarrow v$  and  $v \rightarrow u$  with capacity  $w$
    5. For  $v \in G$ , connect it with sink  $v \rightarrow t$  with capacity  $K + 2T - (\sum_{e \in E(v)} w(e)) - 2w(v)$
    6.  $T$  is a valid answer if the maximum flow  $f < K|V|$
  - Minimum weight edge cover
    1. For each  $v \in V$  create a copy  $v'$ , and connect  $u' \rightarrow v'$  with weight  $w(u, v)$ .
    2. Connect  $v \rightarrow v'$  with weight  $2\mu(v)$ , where  $\mu(v)$  is the cost of the cheapest edge incident to  $v$ .
    3. Find the minimum weight perfect matching on  $G'$ .
  - Project selection problem
    1. If  $p_v > 0$ , create edge  $(s, v)$  with capacity  $p_v$ ; otherwise, create edge  $(v, t)$  with capacity  $-p_v$ .
    2. Create edge  $(u, v)$  with capacity  $w$  with  $w$  being the cost of choosing  $u$  without choosing  $v$ .
    3. The mincut is equivalent to the maximum profit of a subset of projects.

#### • 0/1 quadratic programming

$$\sum_x c_x x + \sum_y c_y \bar{y} + \sum_{xy} c_{xy} x \bar{y} + \sum_{xyx'y'} c_{xyx'y'} (x \bar{y} + x' \bar{y}')$$

can be minimized by the mincut of the following graph:

1. Create edge  $(x, t)$  with capacity  $c_x$  and create edge  $(s, y)$  with capacity  $c_y$ .
2. Create edge  $(x, y)$  with capacity  $c_{xy}$ .
3. Create edge  $(x, y)$  and edge  $(x', y')$  with capacity  $c_{xyx'y'}$ .

## 4.6 Dinic

```
class Dinic{
private:
    using CapT = int64_t;
    struct Edge{
        int to, rev;
        CapT cap;
    };
    int n, st, ed;
    vector<vector<Edge>> G;
    vector<int> lv, idx;
    bool BFS(){
        fill(lv.begin(), lv.end(), -1);
        queue<int> bfs;
        bfs.push(st);
        lv[st] = 0;
        while(!bfs.empty()){
            int u = bfs.front(); bfs.pop();
            for(auto e: G[u]){
                if(e.cap <= 0 or lv[e.to] != -1) continue;
                lv[e.to] = lv[u] + 1;
                bfs.push(e.to);
            }
        }
        return (lv[ed] != -1);
    }
    CapT DFS(int u, CapT f){
        if(u == ed) return f;
        CapT ret = 0;
        for(int& i = idx[u]; i < (int)G[u].size(); ++i){
            auto& e = G[u][i];
            if(e.cap <= 0 or lv[e.to] != lv[u]+1) continue;
```

```
        CapT nf = DFS(e.to, min(f, e.cap));
        ret += nf; e.cap -= nf; f -= nf;
        G[e.to][e.rev].cap += nf;
        if(f == 0) return ret;
    }
    if(ret == 0) lv[u] = -1;
    return ret;
}
public:
    void init(int n_, int st_, int ed_){
        n = n_, st = st_, ed = ed_;
        G.resize(n); lv.resize(n);
        fill(G.begin(), G.end(), vector<Edge>());
    }
    void add_edge(int u, int v, CapT c){
        G[u].push_back({v, (int)G[v].size(), c});
        G[v].push_back({u, ((int)G[u].size()-1), 0});
    }
    CapT max_flow(){
        CapT ret = 0;
        while(BFS()){
            idx.assign(n, 0);
            CapT f = DFS(st, numeric_limits<CapT>::max());
            ret += f;
            if(f == 0) break;
        }
        return ret;
    }
} flow;
```

## 4.7 Minimum Cost Maximum Flow

```
class MiniCostMaxiFlow{
    using CapT = int;
    using WeiT = int64_t;
    using PCW = pair<CapT, WeiT>;
    static constexpr CapT INF_CAP = 1 << 30;
    static constexpr WeiT INF_WEI = 1LL << 60;
private:
    struct Edge{
        int to, back;
        WeiT wei;
        CapT cap;
        Edge() {}
        Edge(int a, int b, WeiT c, CapT d):
            to(a), back(b), wei(c), cap(d) {}
    };
    int ori, edd;
    vector<vector<Edge>> G;
    vector<int> fa, wh;
    vector<bool> inq;
    vector<WeiT> dis;
    PCW SPFA(){
        fill(inq.begin(), inq.end(), false);
        fill(dis.begin(), dis.end(), INF_WEI);
        queue<int> qq; qq.push(ori);
        dis[ori] = 0;
        while(!qq.empty()){
            int u = qq.front(); qq.pop();
            inq[u] = 0;
            for(int i = 0; i < SZ(G[u]); ++i){
                Edge e = G[u][i];
                int v = e.to;
                WeiT d = e.wei;
                if(e.cap <= 0 || dis[v] <= dis[u] + d) continue;
                dis[v] = dis[u] + d;
                fa[v] = u, wh[v] = i;
                if(inq[v]) continue;
                qq.push(v);
                inq[v] = 1;
            }
        }
        if(dis[edd] == INF_WEI)
            return {-1, -1};
        CapT mw = INF_CAP;
        for(int i = edd; i != ori; i = fa[i])
            mw = min(mw, G[fa[i]][wh[i]].cap);
        for(int i = edd; i != ori; i = fa[i]){
            auto &eg = G[fa[i]][wh[i]];
```

```

    eg.cap-=mw;
    G[eg.to][eg.back].cap+=mw;
}
return {mw,dis[edd]};
}
public:
void init(int a,int b,int n){
    ori=a,edd=b;
    G.clear();G.resize(n);
    fa.resize(n);wh.resize(n);
    inq.resize(n); dis.resize(n);
}
void add_edge(int st,int ed,WeiT w,CapT c){
    G[st].emplace_back(ed,SZ(G[ed]),w,c);
    G[ed].emplace_back(st,SZ(G[st])-1,-w,0);
}
PCW solve(){
    /* might modify to
    cc += ret.first * ret.second
    or
    ww += ret.first * ret.second
    */
    CapT cc=0; WeiT ww=0;
    while(true){
        PCW ret=SPFA();
        if(ret.first==-1) break;
        cc+=ret.first;
        ww+=ret.second;
    }
    return {cc,ww};
}
} mcmf;

```

## 4.8 Global Min-Cut

```

const int maxn = 500 + 5;
int w[maxn][maxn], g[maxn];
bool v[maxn], del[maxn];

void add_edge(int x, int y, int c) {
    w[x][y] += c;
    w[y][x] += c;
}

pair<int, int> phase(int n) {
    memset(v, false, sizeof(v));
    memset(g, 0, sizeof(g));
    int s = -1, t = -1;
    while (true) {
        int c = -1;
        for (int i = 0; i < n; ++i) {
            if (del[i] || v[i]) continue;
            if (c == -1 || g[i] > g[c]) c = i;
        }
        if (c == -1) break;
        v[c] = true;
        s = t, t = c;
        for (int i = 0; i < n; ++i) {
            if (del[i] || v[i]) continue;
            g[i] += w[c][i];
        }
    }
    return make_pair(s, t);
}

int mincut(int n) {
    int cut = 1e9;
    memset(del, false, sizeof(del));
    for (int i = 0; i < n - 1; ++i) {
        int s, t; tie(s, t) = phase(n);
        del[t] = true;
        cut = min(cut, g[t]);
        for (int j = 0; j < n; ++j) {
            w[s][j] += w[t][j];
            w[j][s] += w[j][t];
        }
    }
    return cut;
}

```

## 5 Math

### 5.1 Prime Table

```

1002939109, 1020288887, 1028798297, 1038684299,
1041211027, 1051762951, 1058585963, 1063020809,
1147930723, 1172520109, 1183835981, 1187659051,
1241251303, 1247184097, 1255940849, 1272759031,
1287027493, 1288511629, 1294632499, 1312650799,
1868732623, 1884198443, 1884616807, 1885059541,
1909942399, 1914471137, 1923951707, 1925453197,
1979612177, 1980446837, 1989761941, 2007826547,
2008033571, 2011186739, 2039465081, 2039728567,
2093735719, 2116097521, 2123852629, 2140170259,
3148478261, 3153064147, 3176351071, 3187523093,
3196772239, 3201312913, 3203063977, 3204840059,
3210224309, 3213032591, 3217689851, 3218469083,
3219857533, 3231880427, 3235951699, 3273767923,
3276188869, 3277183181, 3282463507, 3285553889,
3319309027, 3327005333, 3327574903, 3341387953,
3373293941, 3380077549, 3380892997, 3381118801

```

### 5.2 $\lfloor \frac{n}{i} \rfloor$ Enumeration

$T_0 = 1, T_{i+1} = \lfloor \frac{n}{T_i + 1} \rfloor$

### 5.3 ax+by=gcd

```

// ax+ny = 1, ax+ny == ax == 1 (mod n)
void exgcd(lld x, lld y, lld &g, lld &a, lld &b) {
    if (y == 0) g=x, a=1, b=0;
    else exgcd(y, x%y, g, b, a), b-= (x/y)*a;
}

```

### 5.4 Pollard Rho

```

// does not work when n is prime
// return any non-trivial factor
llu pollard_rho(llu n){
    static auto f=[](llu x,llu k,llu m){
        return add(k,mul(x,x,m),m);
    };
    if (!(n&1)) return 2;
    mt19937 rnd(120821011);
    while(true){
        llu y=2, yy=y, x=rnd()%n, t=1;
        for(llu sz=2;t==1;sz<=1) {
            for(llu i=0;i<sz;++i){
                if(t!=1)break;
                yy=f(yy,x,n);
                t=gcd(yy>y?yy-y:y-yy,n);
            }
            y=yy;
        }
        if(t!=1&&t!=n) return t;
    }
}

```

### 5.5 Pi Count (Linear Sieve)

```

static constexpr int N = 1000000 + 5;
lld pi[N];
vector<int> primes;
bool sieved[N];
lld cube_root(lld x){
    lld s=cbrt(x-static_cast<long double>(0.1));
    while(s*s*s <= x) ++s;
    return s-1;
}
lld square_root(lld x){
    lld s=sqrt(x-static_cast<long double>(0.1));
    while(s*s <= x) ++s;
    return s-1;
}
void init(){
    primes.reserve(N);
    primes.push_back(1);
    for(int i=2;i<N;i++){
        if(!sieved[i]) primes.push_back(i);
        pi[i] = !sieved[i] + pi[i-1];
        for(int p: primes) if(p > 1) {
            if(p * i >= N) break;
            sieved[p * i] = true;
            if(p % i == 0) break;
        }
    }
}

```

```

    }
}
}
lld phi(lld m, lld n) {
    static constexpr int MM = 80000, NN = 500;
    static lld val[MM][NN];
    if(m<MM&&n<NN&&val[m][n])return val[m][n]-1;
    if(n == 0) return m;
    if(primes[n] >= m) return 1;
    lld ret = phi(m,n-1)-phi(m/primes[n],n-1);
    if(m<MM&&n<NN) val[m][n] = ret+1;
    return ret;
}
lld pi_count(lld);
lld P2(lld m, lld n) {
    lld sm = square_root(m), ret = 0;
    for(lld i = n+1;primes[i]<=sm;i++)
        ret+=pi_count(m/primes[i])-pi_count(primes[i])+1;
    return ret;
}
lld pi_count(lld m) {
    if(m < N) return pi[m];
    lld n = pi_count(cube_root(m));
    return phi(m, n) + n - 1 - P2(m, n);
}

```

## 5.6 Range Sieve

```

const int MAX_SQRT_B = 50000;
const int MAX_L = 200000 + 5;

bool is_prime_small[MAX_SQRT_B];
bool is_prime[MAX_L];

void sieve(lld l, lld r){
    // [1, r)
    for(lld i=2;i<r;i++) is_prime_small[i] = true;
    for(lld i=1;i<r;i++) is_prime[i-1] = true;
    if(l==1) is_prime[0] = false;
    for(lld i=2;i<r;i++){
        if(!is_prime_small[i]) continue;
        for(lld j=i*i;j<r;j+=i) is_prime_small[j]=false;
        for(lld j=std::max(2LL, (l+i-1)/i)*i;j<r;j+=i)
            is_prime[j-1]=false;
    }
}

```

## 5.7 Miller Rabin

```

bool isprime(llu x){
    static llu magic[]={2,325,9375,28178,\
        450775,9780504,1795265022};
    static auto witn=[](llu a,llu u,llu n,int t){
        a = mpow(a,u,n);
        if (!a)return 0;
        while(t--){
            llu a2=mul(a,a,n);
            if(a2==1 && a!=1 && a!=n-1)
                return 1;
            a = a2;
        }
        return a!=1;
    };
    if(x<2)return 0;
    if(!(x&1))return x==2;
    ll u=x-1;int t=0;
    while(!(x1&1))x1>>=1,t++;
    for(llu m:magic)if(witn(m,x1,x,t))return 0;
    return 1;
}

```

## 5.8 Inverse Element

```

// x's inverse mod k
long long GetInv(long long x, long long k){
    // k is prime: euler(k)=k-1
    return qPow(x, euler_phi(k)-1);
}
// if you need [1, x] (most use: [1, k-1])
void solve(int x, long long k){

```

```

    inv[1] = 1;
    for(int i=2;i<x;i++)
        inv[i] = ((long long)(k - k/i) * inv[k % i]) % k;
}

```

## 5.9 Euler Phi Function

```

/*
    extended euler:
    a^b mod p
    if gcd(a, p)==1: a^(b%phi(p))
    elif b < phi(p): a^b mod p
    else a^(b%phi(p) + phi(p))
*/
lld euler_phi(int x){
    lld r=1;
    for(int i=2;i*i<=x;i++){
        if(x%i==0){
            x/=i; r*=(i-1);
            while(x%i==0){
                x/=i; r*=i;
            }
        }
    }
    if(x>1) r*=x-1;
    return r;
}
vector<int> primes;
bool notprime[N];
lld phi[N];
void euler_sieve(int n){
    for(int i=2;i<n;i++){
        if(!notprime[i]){
            primes.push_back(i); phi[i] = i-1;
        }
        for(auto j: primes){
            if(i*j >= n) break;
            notprime[i*j] = true;
            phi[i*j] = phi[i] * phi[j];
            if(i % j == 0){
                phi[i*j] = phi[i] * j;
                break;
            }
        }
    }
}

```

## 5.10 Gauss Elimination

```

void gauss(vector<vector<double>> &d) {
    int n = d.size(), m = d[0].size();
    for (int i = 0; i < m; ++i) {
        int p = -1;
        for (int j = i; j < n; ++j) {
            if (fabs(d[j][i]) < eps) continue;
            if (p == -1 || fabs(d[j][i]) > fabs(d[p][i])) p=j;
        }
        if (p == -1) continue;
        for (int j = 0; j < m; ++j) swap(d[p][j], d[i][j]);
        for (int j = 0; j < n; ++j) {
            if (i == j) continue;
            double z = d[j][i] / d[i][i];
            for (int k = 0; k < m; ++k) d[j][k] -= z*d[i][k];
        }
    }
}

```

## 5.11 Fast Fourier Transform

```

/*
    polynomial multiply:
    DFT(a, len); DFT(b, len);
    for(int i=0;i<len;i++) c[i] = a[i]*b[i];
    iDFT(c, len);
    (len must be 2^k and >= 2*(max(a, b)))
    Hand written Cplx would be 2x faster
*/
Cplx omega[2][N];
void init_omega(int n) {
    static constexpr llf PI=acos(-1);

```

```

const llf arg=(PI+PI)/n;
for(int i=0;i<n;++i)
    omega[0][i]={cos(arg*i),sin(arg*i)};
for(int i=0;i<n;++i)
    omega[1][i]=conj(omega[0][i]);
}
void tran(Cplx arr[],int n,Cplx omg[]) {
    for(int i=0,j=0;i<n;++i){
        if(i>j)swap(arr[i],arr[j]);
        for(int l=n>>1;(j^=1)<l;l>=>1);
    }
    for (int l=2;l<=n;l<=>1){
        int m=l>>1;
        for(auto p=arr;p!=arr+n;p+=l){
            for(int i=0;i<m;++i){
                Cplx t=omg[n/l*i]*p[m+i];
                p[m+i]=p[i]-t; p[i]+=t;
            }
        }
    }
}
void DFT(Cplx arr[],int n){tran(arr,n,omega[0]);}
void idFT(Cplx arr[],int n){
    tran(arr,n,omega[1]);
    for(int i=0;i<n;++i) arr[i]/=n;
}

```

## 5.12 High Speed Linear Recurrence

```

#define mod 998244353
const int N=1000010;
int n,k,m,f[N],h[N],a[N],b[N],ib[N];
int pw(int x,int y){
    int re=1;
    if(y<0)y+=mod-1;
    while(y){
        if(y&1)re=(ll)re*x%mod;
        y>>=1;x=(ll)x*x%mod;
    }
    return re;
}
void inc(int&x,int y){x+=y;if(x>=mod)x-=mod;}
namespace poly{
    const int G=3;
    int rev[N],L;
    void ntt(int*A,int len,int f){
        for(L=0;(1<L)<len;L+=L);
        for(int i=0;i<len;++i){
            rev[i]=(rev[i>>1]>>1)|((i&1)<<(L-1));
            if(i<rev[i])swap(A[i],A[rev[i]]);
        }
        for(int i=1;i<len;i<=>1){
            int wn=pw(G,f*(mod-1)/(i<<1));
            for(int j=0;j<len;j+=i<<1){
                int w=1;
                for(int k=0;k<i;++k,w=(ll)w*wn%mod){
                    int x=A[j+k],y=(ll)w*A[j+k+i]%mod;
                    A[j+k]=(x+y)%mod,A[j+k+i]=(x-y+mod)%mod;
                }
            }
        }
        if(!f){
            int iv=pw(len,mod-2);
            for(int i=0;i<len;++i)A[i]=(ll)A[i]*iv%mod;
        }
    }
    void cls(int*A,int l,int r){
        for(int i=l;i<r;++i)A[i]=0;
    }
    void cpy(int*A,int*B,int l){
        for(int i=0;i<l;++i)A[i]=B[i];
    }
    void inv(int*A,int*B,int l){
        if(l==1){B[0]=pw(A[0],mod-2);return;}
        static int t[N];
        int len=l<<1;
        inv(A,B,l>>1);
        cpy(t,A,l);cls(t,l,len);
        ntt(t,len,1);ntt(B,len,1);
        for(int i=0;i<len;++i)
            B[i]=(ll)B[i]*(2-(ll)t[i]*B[i]%mod+mod)%mod;
        ntt(B,len,-1);cls(B,l,len);
    }
}

```

```

void pmod(int*A){
    static int t[N];
    int l=k+1,len=1;while(len<=(k<<1))len<=>1;
    cpy(t,A,(k<<1)+1);
    reverse(t,t+(k<<1)+1);
    cls(t,l,len);
    ntt(t,len,1);
    for(int i=0;i<len;++i)t[i]=(ll)t[i]*ib[i]%mod;
    ntt(t,len,-1);
    cls(t,l,len);
    reverse(t,t+1);
    ntt(t,len,1);
    for(int i=0;i<len;++i)t[i]=(ll)t[i]*b[i]%mod;
    ntt(t,len,-1);
    cls(t,l,len);
    for(int i=0;i<k;++i)A[i]=(A[i]-t[i]+mod)%mod;
    cls(A,k,len);
}
void pow(int*A,int n){
    if(n==1){cls(A,0,k+1);A[1]=1;return;}
    pow(A,n>>1);
    int len=1;while(len<=(k<<1))len<=>1;
    ntt(A,len,1);
    for(int i=0;i<len;++i)A[i]=(ll)A[i]*A[i]%mod;
    ntt(A,len,-1);
    pmod(A);
    if(n&1){
        for(int i=k;i;--i)A[i]=A[i-1];A[0]=0;
        pmod(A);
    }
}
int main(){
    n=rd();k=rd();
    for(int i=1;i<=k;++i)f[i]=(mod+rd())%mod;
    for(int i=0;i<k;++i)h[i]=(mod+rd())%mod;
    for(int i=a[k]=b[k]=1;i<=k;++i)
        a[k-i]=b[k-i]=(mod-f[i])%mod;
    int len=1;while(len<=(k<<1))len<=>1;
    reverse(a,a+k+1);
    poly::inv(a,ib,len);
    poly::cls(ib,k+1,len);
    poly::ntt(b,len,1);
    poly::ntt(ib,len,1);
    poly::pow(a,n);
    int ans=0;
    for(int i=0;i<k;++i)inc(ans,(ll)a[i]*h[i]%mod);
    printf("%d\n",ans);
    return 0;
}

```

## 5.13 Chinese Remainder

```

lld crt(lld ans[], lld pri[], int n){
    lld M = 1, ret = 0;
    for(int i=0;i<n;i++) M *= pri[i];
    for(int i=0;i<n;i++){
        lld iv = gcd(M/pri[i],pri[i]).FF+pri[i])%pri[i];
        ret += (ans[i]*(M/pri[i])%M * iv)%M;
        ret %= M;
    }
    return ret;
}
/*
Another:
x = a1 % m1
x = a2 % m2
g = gcd(m1, m2)
assert((a1-a2)%g==0)
[p, q] = exgcd(m2/g, m1/g)
return a2+m2*(p*(a1-a2)/g)
0 <= x < lcm(m1, m2)
*/

```

## 5.14 Berlekamp Massey

```

// x: 1-base, p[]: 0-base
template<size_t N>
vector<llf> BM(llf x[N],size_t n){
    size_t f[N]={0},t=0;llf d[N];
    vector<llf> p[N];
}

```



```

for(size_t i=1,b=0;i<=n;++i) {
    for(size_t j=0;j<p[t].size();++j)
        d[i]+=x[i-j-1]*p[t][j];
    if(abs(d[i]-x[i])<=EPS)continue;
    f[t]=i;if(!t){p[++t].resize(i);continue;}
    vector<llf> cur(i-f[b]-1);
    llf k=-d[i]/d[f[b]];cur.PB(-k);
    for(size_t j=0;j<p[b].size();++j)
        cur.PB(p[b][j]*k);
    if(cur.size()<p[t].size())cur.resize(p[t].size());
    for(size_t j=0;j<p[t].size();++j)cur[j]+=p[t][j];
    if(i-f[b]+p[b].size()>=p[t].size()) b=t;
    p[++t]=cur;
}
return p[t];
}

```

## 5.15 NTT

```

// Remember coefficient are mod P
/* p=a*2^n+1
n    2^n    p    a    root
16   65536   65537   1    3
20   1048576 7340033   7    3 */
// (must be 2^k)
template<LL P, LL root, int MAXN>
struct NTT{
    static LL bigmod(LL a, LL b) {
        LL res = 1;
        for (LL bs = a; b; b >>= 1, bs = (bs * bs) % P)
            if(b&1) res=(res*bs)%P;
        return res;
    }
    static LL inv(LL a, LL b) {
        if(a==1)return 1;
        return (((LL)(a-inv(b*a,a))*b+1)/a)%b;
    }
    LL omega[MAXN+1];
    NTT() {
        omega[0] = 1;
        LL r = bigmod(root, (P-1)/MAXN);
        for (int i=1; i<=MAXN; i++)
            omega[i] = (omega[i-1]*r)%P;
    }
    // n must be 2^k
    void tran(int n, LL a[], bool inv_ntt=false){
        int basic = MAXN / n, theta = basic;
        for (int m = n; m >= 2; m >>= 1) {
            int mh = m >> 1;
            for (int i = 0; i < mh; i++) {
                LL w = omega[i*theta*MAXN];
                for (int j = i; j < n; j += m) {
                    int k = j + mh;
                    LL x = a[j] - a[k];
                    if (x < 0) x += P;
                    a[j] += a[k];
                    if (a[j] > P) a[j] -= P;
                    a[k] = (w * x) % P;
                }
            }
            theta = (theta * 2) % MAXN;
        }
        int i = 0;
        for (int j = 1; j < n - 1; j++) {
            for (int k = n >> 1; k > (i ^ k); k >>= 1);
            if (j < i) swap(a[i], a[j]);
        }
        if (inv_ntt) {
            LL ni = inv(n,P);
            reverse(a+1, a+n);
            for (i = 0; i < n; i++)
                a[i] = (a[i] * ni) % P;
        }
    }
};
const LL P=2013265921,root=31;
const int MAXN=4194304;
NTT<P, root, MAXN> ntt;

```

## 5.16 Polynomial Operations

```

using VI = vector<int>;
Poly Inverse(Poly f) {
    int n = f.size();
    Poly q(1, fpow(f[0], kMod - 2));
    for (int s = 2;; s <= 1) {
        if (f.size() < s) f.resize(s);
        Poly fv(f.begin(), f.begin() + s);
        Poly fq(q.begin(), q.end());
        fv.resize(s + s); fq.resize(s + s);
        ntt::Transform(fv, s + s);
        ntt::Transform(fq, s + s);
        for (int i = 0; i < s + s; ++i)
            fv[i] = 1LL * fv[i] * fq[i]%kMod * fq[i]%kMod;
        ntt::InverseTransform(fv, s + s);
        Poly res(s);
        for (int i = 0; i < s; ++i) {
            res[i] = kMod - fv[i];
            if (i < (s >> 1)) {
                int v = 2 * q[i] % kMod;
                (res[i] += v) >= kMod ? res[i] -= kMod : 0;
            }
        }
        q = res;
        if (s >= n) break;
    }
    q.resize(n);
    return q;
}

Poly Divide(const Poly &a, const Poly &b) {
    int n = a.size(), m = b.size(), k = 2;
    while (k < n - m + 1) k <= 1;
    Poly ra(k), rb(k);
    for (int i = 0; i < min(n, k); ++i) ra[i] = a[n-1-i];
    for (int i = 0; i < min(m, k); ++i) rb[i] = b[m-1-i];
    auto rbi = Inverse(rb);
    auto res = Multiply(rbi, ra);
    res.resize(n - m + 1);
    reverse(res.begin(), res.end());
    return res;
}

Poly Modulo(const Poly &a, const Poly &b) {
    if (a.size() < b.size()) return a;
    auto dv = Multiply(Divide(a, b), b);
    assert(dv.size() == a.size());
    for (int i = 0; i < dv.size(); ++i)
        dv[i] = (a[i] + kMod - dv[i]) % kMod;
    while (!dv.empty() && dv.back() == 0) dv.pop_back();
    return dv;
}

Poly Integral(const Poly &f) {
    int n = f.size();
    VI res(n + 1);
    for (int i = 0; i < n; ++i)
        res[i+1] = 1LL * f[i] * fpow(i + 1, kMod - 2)%kMod;
    return res;
}

Poly Evaluate(const Poly &f, const VI &x) {
    if (x.empty()) return Poly();
    int n = x.size();
    vector<Poly> up(n * 2);
    for (int i = 0; i < n; ++i) up[i+n] = {kMod-x[i], 1};
    for (int i = n - 1; i > 0; --i)
        up[i] = Multiply(up[i * 2], up[i * 2 + 1]);
    vector<Poly> down(n * 2);
    down[1] = Modulo(f, up[1]);
    for (int i = 2; i < n * 2; ++i)
        down[i] = Modulo(down[i >> 1], up[i]);
    VI y(n);
    for (int i = 0; i < n; ++i) y[i] = down[i + n][0];
    return y;
}

Poly Interpolate(const VI &x, const VI &y) {
    int n = x.size();
    vector<Poly> up(n * 2);
    for (int i = 0; i < n; ++i) up[i+n] = {kMod-x[i], 1};
    for (int i = n - 1; i > 0; --i)
        up[i] = Multiply(up[i * 2], up[i * 2 + 1]);
    VI a = Evaluate(Derivative(up[1]), x);
    for (int i = 0; i < n; ++i)
        a[i] = 1LL * y[i] * fpow(a[i], kMod - 2) % kMod;
    vector<Poly> down(n * 2);
    for (int i = 0; i < n; ++i) down[i + n] = {a[i]};
}

```

```

for (int i = n - 1; i > 0; --i) {
    auto lhs = Multiply(down[i * 2], up[i * 2 + 1]);
    auto rhs = Multiply(down[i * 2 + 1], up[i * 2]);
    assert(lhs.size() == rhs.size());
    down[i].resize(lhs.size());
    for (int j = 0; j < lhs.size(); ++j)
        down[i][j] = (lhs[j] + rhs[j]) % kMod;
}
return down[1];
}
Poly Log(Poly f) {
    int n = f.size();
    if (n == 1) return {0};
    auto d = Derivative(f);
    f.resize(n - 1);
    d = Multiply(d, Inverse(f));
    d.resize(n - 1);
    return Integral(d);
}
Poly Exp(Poly f) {
    int n = f.size();
    Poly q(1, 1); f[0] += 1;
    for (int s = 1; s < n; s <= 1) {
        if (f.size() < s + s) f.resize(s + s);
        Poly g(f.begin(), f.begin() + s + s);
        Poly h(q.begin(), q.end());
        h.resize(s + s); h = Log(h);
        for (int i = 0; i < s + s; ++i)
            g[i] = (g[i] + kMod - h[i]) % kMod;
        g = Multiply(g, q);
        g.resize(s + s); q = g;
    }
    assert(q.size() >= n);
    q.resize(n);
    return q;
}
Poly SquareRootImpl(Poly f) {
    if (f.empty()) return {0};
    int z = QuadraticResidue(f[0], kMod), n = f.size();
    constexpr int kInv2 = (kMod + 1) >> 1;
    if (z == -1) return {-1};
    VI q(1, z);
    for (int s = 1; s < n; s <= 1) {
        if (f.size() < s + s) f.resize(s + s);
        VI fq(q.begin(), q.end());
        fq.resize(s + s);
        VI f2 = Multiply(fq, fq);
        f2.resize(s + s);
        for (int i = 0; i < s + s; ++i)
            f2[i] = (f2[i] + kMod - f[i]) % kMod;
        f2 = Multiply(f2, Inverse(fq));
        f2.resize(s + s);
        for (int i = 0; i < s + s; ++i)
            fq[i] = (fq[i] + kMod - 1LL * f2[i] * kInv2 % kMod) % kMod;
        q = fq;
    }
    q.resize(n);
    return q;
}
Poly SquareRoot(Poly f) {
    int n = f.size(), m = 0;
    while (m < n && f[m] == 0) m++;
    if (m == n) return VI(n);
    if (m & 1) return {-1};
    auto s = SquareRootImpl(VI(f.begin() + m, f.end()));
    if (s[0] == -1) return {-1};
    VI res(n);
    for (int i = 0; i < s.size(); ++i) res[i + m/2] = s[i];
    return res;
}

```

## 5.17 FWT

```

/* xor convolution:
* x = (x0,x1), y = (y0,y1)
* z = ( x0y0 + x1y1, x0y1 + x1y0 )
* =>
* x' = ( x0+x1, x0-x1 ), y' = ( y0+y1, y0-y1 )
* z' = ( ( x0+x1 )( y0+y1 ), ( x0-x1 )( y0-y1 ) )
* z = (1/2) * z'
* or convolution:

```

```

* x = (x0, x0+x1), inv = (x0, x1-x0) w/o final div
* and convolution:
* x = (x0+x1, x1), inv = (x0-x1, x1) w/o final div */
const LL MOD = 1e9+7;
inline void fwt( LL x[ MAXN ], int N, bool inv=0 ) {
    for( int d = 1 ; d < N ; d <= 1 ) {
        int d2 = d<<1;
        for( int s = 0 ; s < N ; s += d2 )
            for( int i = s, j = s+d ; i < s+d ; i++, j++ ){
                LL ta = x[ i ], tb = x[ j ];
                x[ i ] = ta+tb;
                x[ j ] = ta-tb;
                if( x[ i ] >= MOD ) x[ i ] -= MOD;
                if( x[ j ] < 0 ) x[ j ] += MOD;
            }
    }
    if( inv )
        for( int i = 0 ; i < N ; i++ ) {
            x[ i ] *= inv( N, MOD );
            x[ i ] %= MOD;
        }
}

```

## 5.18 DiscreteLog

```

// Baby-step Giant-step Algorithm
lld BSGS(lld P, lld B, lld N) {
    // find B^L = N mod P
    unordered_map<lld, int> R;
    lld sq = (lld)sqrt(P);
    lld t = 1;
    for (int i = 0; i < sq; i++) {
        if (t == N) return i;
        if (!R.count(t)) R[t] = i;
        t = (t * B) % P;
    }
    lld f = inverse(t, P);
    for(int i=0;i<=sq+1;i++) {
        if (R.count(N))
            return i * sq + R[N];
        N = (N * f) % P;
    }
    return -1;
}

```

## 5.19 Quadratic residue

```

struct Status{
    ll x,y;
};
ll w;
Status mult(const Status& a,const Status& b,ll mod){
    Status res;
    res.x=(a.x*b.x+a.y*b.y%mod*w)%mod;
    res.y=(a.x*b.y+a.y*b.x)%mod;
    return res;
}
inline Status qpow(Status _base,ll _pow,ll _mod){
    Status res = {1, 0};
    while(_pow>0){
        if(_pow&1) res=mult(res,_base,_mod);
        _base=mult(_base,_base,_mod);
        _pow>>=1;
    }
    return res;
}
inline ll check(ll x,ll p){
    return qpow_mod(x,(p-1)>>1,p);
}
inline ll get_root(ll n,ll p){
    if(p==2) return 1;
    if(check(n,p)==p-1) return -1;
    ll a;
    while(true){
        a=rand()%p;
        w=((a*a-n)%p+p)%p;
        if(check(w,p)==p-1) break;
    }
    Status res = {a, 1}
    res=qpow(res,(p+1)>>1,p);
    return res.x;
}

```

```
} }
```

## 5.20 De-Bruijn

```
int res[maxn], aux[maxn], sz;
void db(int t, int p, int n, int k) {
    if (t > n) {
        if (n % p == 0)
            for (int i = 1; i <= p; ++i)
                res[sz++] = aux[i];
    } else {
        aux[t] = aux[t - p];
        db(t + 1, p, n, k);
        for (int i = aux[t - p] + 1; i < k; ++i) {
            aux[t] = i;
            db(t + 1, t, n, k);
        }
    }
}
int de_bruijn(int k, int n) {
    // return cyclic string of len k^n s.t. every string
    // of len n using k char appears as a substring.
    if (k == 1) {
        res[0] = 0;
        return 1;
    }
    for (int i = 0; i < k * n; i++) aux[i] = 0;
    sz = 0;
    db(1, 1, n, k);
    return sz;
}
```

## 5.21 Simplex Construction

Standard form: maximize  $\sum_{1 \leq i \leq n} c_i x_i$  such that for all  $1 \leq j \leq m$ ,  $\sum_{1 \leq i \leq n} A_{ji} x_i \leq b_j$  and  $x_i \geq 0$  for all  $1 \leq i \leq n$ .

1. In case of minimization, let  $c'_i = -c_i$
2.  $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j \rightarrow \sum_{1 \leq i \leq n} -A_{ji} x_i \leq -b_j$
3.  $\sum_{1 \leq i \leq n} A_{ji} x_i = b_j$ 
  - $\sum_{1 \leq i \leq n} A_{ji} x_i \leq b_j$
  - $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j$
4. If  $x_i$  has no lower bound, replace  $x_i$  with  $x_i - x'_i$

## 5.22 Simplex

```
namespace simplex {
    // maximize c^T x under Ax <= B
    // return vector<double>(n, -inf) if the solution doesn't exist
    // return vector<double>(n, +inf) if the solution is unbounded
    using VD = vector<double>;
    using VVD = vector<vector<double>>;
    const double eps = 1e-9;
    const double inf = 1e+9;
    int n, m;
    VVD d;
    vector<int> p, q;
    void pivot(int r, int s) {
        double inv = 1.0 / d[r][s];
        for (int i = 0; i < m + 2; ++i) {
            for (int j = 0; j < n + 2; ++j) {
                if (i != r && j != s)
                    d[i][j] -= d[r][j] * d[i][s] * inv;
            }
        }
        for (int i = 0; i < m + 2; ++i) if (i != r) d[i][s] *= -inv;
        for (int j = 0; j < n + 2; ++j) if (j != s) d[r][j] *= +inv;
        d[r][s] = inv;
        swap(p[r], q[s]);
    }
    bool phase(int z) {
        int x = m + z;
        while (true) {
            int s = -1;
            for (int i = 0; i <= n; ++i) {
```

```
                if (!z && q[i] == -1) continue;
                if (s == -1 || d[x][i] < d[x][s]) s = i;
            }
            if (d[x][s] > -eps) return true;
            int r = -1;
            for (int i = 0; i < m; ++i) {
                if (d[i][s] < eps) continue;
                if (r == -1 || \
                    d[i][n+1]/d[i][s] < d[r][n+1]/d[r][s]) r = i;
            }
            if (r == -1) return false;
            pivot(r, s);
        }
    }
    VD solve(const VVD &a, const VD &b, const VD &c) {
        m = b.size(), n = c.size();
        d = VVD(m + 2, VD(n + 2));
        for (int i = 0; i < m; ++i) {
            for (int j = 0; j < n; ++j) d[i][j] = a[i][j];
        }
        p.resize(m), q.resize(n + 1);
        for (int i = 0; i < m; ++i)
            p[i] = n + i, d[i][n] = -1, d[i][n + 1] = b[i];
        for (int i = 0; i < n; ++i) q[i] = i, d[m][i] = -c[i];
        q[n] = -1, d[m + 1][n] = 1;
        int r = 0;
        for (int i = 1; i < m; ++i)
            if (d[i][n + 1] < d[r][n + 1]) r = i;
        if (d[r][n + 1] < -eps) {
            pivot(r, n);
            if (!phase(1) || d[m + 1][n + 1] < -eps)
                return VD(n, -inf);
        }
        for (int i = 0; i < m; ++i) if (p[i] == -1) {
            int s = min_element(d[i].begin(), d[i].end() - 1)
                - d[i].begin();
            pivot(i, s);
        }
    }
    if (!phase(0)) return VD(n, inf);
    VD x(n);
    for (int i = 0; i < m; ++i)
        if (p[i] < n) x[p[i]] = d[i][n + 1];
    return x;
}
```

## 6 Geometry

### 6.1 Point Class

```
template<typename T>
struct Point {
    typedef long double llf;
    static constexpr llf EPS = 1e-8;
    T x, y;
    Point(T _x=0, T _y=0): x(_x), y(_y){}
    template<typename T2>
        Point(const Point<T2>& a): x(a.x), y(a.y){}
    inline llf theta() const {
        return atan2((llf)y, (llf)x);
    }
    inline llf dis() const {
        return hypot((llf)x, (llf)y);
    }
    inline llf dis(const Point& o) const {
        return hypot((llf)(x-o.x), (llf)(y-o.y));
    }
    Point operator-(const Point& o) const {
        return Point(x-o.x, y-o.y);
    }
    Point operator+(const Point& o) const {
        return Point(x+o.x, y+o.y);
    }
    Point operator*(const T& k) const {
        return Point(x*k, y*k);
    }
    Point operator/(const T& k) const {
        return Point(x/k, y/k);
    }
    Point operator-() const {return Point(-x, -y);}
    Point rot90() const {return Point(-y, x);}
    template<typename T2>
        bool in(const Circle<T2>& a) const {
            /* Add struct Circle at top */
            return a.o.dis(*this)+EPS <= a.r;
        }
    bool equal(const Point& o, true_type) const {
        return fabs(x-o.x) < EPS && fabs(y-o.y) < EPS;
    }
    bool equal(const Point& o, false_type) const {
        return tie(x, y) == tie(o.x, o.y);
    }
}
```

```

bool operator==(const Point& o) const {
    return equal(o, is_floating_point<T>()); }
bool operator!=(const Point& o) const {
    return !(*this == o); }
bool operator<(const Point& o) const {
    return theta() < o.theta();
    // sort like what pairs did
    // if (is_floating_point<T>())
    //     return fabs(x-o.x)<EPS?y<o.y:x<o.x;
    // else return tie(x, y) < tie(o.x, o.y);
}
friend inline T cross(const Point&a, const Point&b){
    return a.x*b.y - b.x*a.y; }
friend inline T dot(const Point& a, const Point &b){
    return a.x*b.x + a.y*b.y; }
friend ostream&operator<<(ostream&ss, const Point&o){
    ss<<"("<<o.x<<"", "<<o.y<<""); return ss; }
};

```

## 6.2 Circle Class

```

template<typename T>
struct Circle{
    static constexpr llf EPS = 1e-8;
    Point<T> o; T r;
    vector<Point<llf>> operator&(const Circle& aa) const{
        //https://www.cnblogs.com/wangzming/p/8338142.html
        llf d=o.dis(aa.o);
        if(d>r+aa.r+EPS || d<fabs(r-aa.r)-EPS) return {};
        llf dt = (r*r - aa.r*aa.r)/d, d1 = (d+dt)/2;
        Point<llf> dir = (aa.o-o); dir /= d;
        Point<llf> pcrs = dir*d1 + o;
        dt=sqrt(max(0.0L, r*r - d1*d1)), dir=dir.rot90();
        return {pcrs + dir*dt, pcrs - dir*dt};
    }
};

```

## 6.3 Segment Class

```

const long double EPS = 1e-8;
template<typename T>
struct Segment{
    // p1.x < p2.x
    Line<T> base;
    Point<T> p1, p2;
    Segment(): base(Line<T>()), p1(Point<T>()), p2(Point<T>()){}
    Segment(Line<T> base, Point<T> p1, Point<T> p2): base(base), p1(p1), p2(p2){
        assert(on_line(p1, base) and on_line(p2, base));
    }
    Segment(Line<T> _, Point<T> __, Point<T> ___): base(_), p1(__), p2(___){
        assert(on_line(p1, base) and on_line(p2, base));
    }
    template<typename T2>
    Segment(const Segment<T2>& _): base(_.base), p1(_.p1), p2(_.p2) {}
    typedef Point<long double> Pt;
    friend bool on_segment(const Point<T>& p, const Segment& l){
        if(on_line(p, l.base))
            return (l.p1.x-p.x)*(p.x-l.p2.x)>=0 and (l.p1.y-p.y)*(p.y-l.p2.y)>=0;
        return false;
    }
    friend bool have_inter(const Segment& a, const Segment& b){
        if(is_parallel(a.base, b.base)){
            return on_segment(a.p1, b) or on_segment(a.p2, b)
                or on_segment(b.p1, a) or on_segment(b.p2, a);
        }
        Pt inter = get_inter(a.base, b.base);
        return on_segment(inter, a) and on_segment(inter, b);
    }
    friend inline Pt get_inter(const Segment& a, const Segment& b){
        if(!have_inter(a, b)){
            return NOT_EXIST;
        }else if(is_parallel(a.base, b.base)){
            if(a.p1 == b.p1){

```

```

                if(on_segment(a.p2, b) or on_segment(b.p2, a))
                    return INF_P;
                else return a.p1;
            }else if(a.p1 == b.p2){
                if(on_segment(a.p2, b) or on_segment(b.p1, a))
                    return INF_P;
                else return a.p1;
            }else if(a.p2 == b.p1){
                if(on_segment(a.p1, b) or on_segment(b.p2, a))
                    return INF_P;
                else return a.p2;
            }else if(a.p2 == b.p2){
                if(on_segment(a.p1, b) or on_segment(b.p1, a))
                    return INF_P;
                else return a.p2;
            }
        }
        return INF_P;
    }
    return get_inter(a.base, b.base);
}
friend ostream& operator<<(ostream& ss, const Segment & o){
    ss<<o.base<<"", "<<o.p1<<" ~ "<<o.p2;
    return ss;
}
};
template<typename T>
inline Segment<T> get_segment(const Point<T>& a, const Point<T>& b){
    return Segment<T>(get_line(a, b), a, b);
}

```

## 6.4 Line Class

```

const Point<long double> INF_P(-1e20, 1e20);
const Point<long double> NOT_EXIST(1e20, 1e-20);
template<typename T>
struct Line{
    static constexpr long double EPS = 1e-8;
    // ax+by+c = 0
    T a, b, c;
    Line(T _=0, T __=1, T ___=0): a(_), b(__), c(___){
        assert(fabs(a)>EPS or fabs(b)>EPS);
    }
    template<typename T2>
    Line(const Line<T2>& x): a(x.a), b(x.b), c(x.c){}
    typedef Point<long double> Pt;
    bool equal(const Line& o, true_type) const {
        return fabs(a-o.a)<EPS &&
            fabs(b-o.b)<EPS && fabs(c-o.c)<EPS;
    }
    bool equal(const Line& o, false_type) const {
        return a==o.a and b==o.b and c==o.c;
    }
    bool operator==(const Line& o) const {
        return equal(o, is_floating_point<T>());
    }
    bool operator!=(const Line& o) const {
        return !(*this == o);
    }
    friend inline bool on_line__(const Point<T>& p, const Line& l, true_type){
        return fabs(l.a*p.x + l.b*p.y + l.c) < EPS;
    }
    friend inline bool on_line__(const Point<T>& p, const Line& l, false_type){
        return l.a*p.x + l.b*p.y + l.c == 0;
    }
    friend inline bool on_line(const Point<T>&p, const Line& l){
        return on_line__(p, l, is_floating_point<T>());
    }
    friend inline bool is_parallel__(const Line& x, const Line& y, true_type){
        return fabs(x.a*y.b - x.b*y.a) < EPS;
    }
    friend inline bool is_parallel__(const Line& x, const Line& y, false_type){
        return x.a*y.b == x.b*y.a;
    }
    friend inline bool is_parallel(const Line& x, const Line& y){
        return is_parallel__(x, y, is_floating_point<T>());
    }
    friend inline Pt get_inter(const Line& x, const Line& y){

```

```

typedef long double llf;
if(x==y) return INF_P;
if(is_parallel(x, y)) return NOT_EXIST;
llf delta = x.a*y.b - x.b*y.a;
llf delta_x = x.b*y.c - x.c*y.b;
llf delta_y = x.c*y.a - x.a*y.c;
return Pt(delta_x / delta, delta_y / delta);
}
friend ostream&operator<<(ostream&ss, const Line&o){
    ss<<o.a<<"x"<<o.b<<"y"<<o.c<<"=0";
    return ss;
}
};
template<typename T>
inline Line<T> get_line(const Point<T>& a, const Point<
T>& b){
    return Line<T>(a.y-b.y, b.x-a.x, (b.y-a.y)*a.x-(b.x-a
.x)*a.y);
}

```

## 6.5 Triangle Circumcentre

```

template<typename T>
Circle<llf> get_circum(const Point<T>& a, const Point<T>
>& b, const Point<T>& c){
    llf a1 = a.x-b.x, b1 = a.y-b.y;
    llf c1 = (a.x+b.x)/2 * a1 + (a.y+b.y)/2 * b1;
    llf a2 = a.x-c.x, b2 = a.y-c.y;
    llf c2 = (a.x+c.x)/2 * a2 + (a.y+c.y)/2 * b2;
    Circle<llf> cc;
    cc.o.x = (c1*b2-b1*c2)/(a1*b2-b1*a2);
    cc.o.y = (a1*c2-c1*a2)/(a1*b2-b1*a2);
    cc.r = hypot(cc.o.x-a.x, cc.o.y-a.y);
    return cc;
}

```

## 6.6 2D Convex Hull

```

template<typename T>
class ConvexHull_2D{
private:
    typedef Point<T> PT;
    vector<PT> d;
    struct myhash{
        uint64_t operator()(const PT& a) const {
            uint64_t xx=0, yy=0;
            memcpy(&xx, &a.x, sizeof(a.x));
            memcpy(&yy, &a.y, sizeof(a.y));
            uint64_t ret = xx*17+yy*31;
            ret = (ret ^ (ret >> 16))*0x9E3779B1;
            ret = (ret ^ (ret >> 13))*0xC2B2AE35;
            ret = ret ^ xx;
            return (ret ^ (ret << 3)) * yy;
        }
    };
    unordered_set<PT, myhash> in_hull;
public:
    void init(){in_hull.clear();d.clear();}
    void insert(const PT& x){d.PB(x);}
    void solve(){
        sort(ALL(d), [](const PT& a, const PT& b){
            return tie(a.x, a.y) < tie(b.x, b.y);});
        vector<PT> s(SZ(d)<<1); int o = 0;
        for(auto p: d) {
            while(o>=2 && cross(p-s[o-2],s[o-1]-s[o-2])<=0)
                o--;
            s[o++] = p;
        }
        for(int i=SZ(d)-2, t = o+1;i>=0;i--){
            while(o==t&&cross(d[i]-s[o-2],s[o-1]-s[o-2])<=0)
                o--;
            s[o++] = d[i];
        }
        s.resize(o-1); swap(s, d);
        for(auto i: s) in_hull.insert(i);
    }
    vector<PT> get(){return d;}
    bool in_it(const PT& x){
        return in_hull.find(x)!=in_hull.end();}
};

```

## 6.7 2D Farthest Pair

```

// stk is from convex hull
n = (int)(stk.size());
int pos = 1, ans = 0; stk.push_back(stk[0]);
for(int i=0;i<n;i++) {
    while(abs(cross(stk[i+1]-stk[i],
        stk[(pos+1)%n]-stk[i])) >
        abs(cross(stk[i+1]-stk[i],
        stk[pos]-stk[i]))) pos = (pos+1)%n;
    ans = max({ans, dis(stk[i], stk[pos]),
        dis(stk[i+1], stk[pos])});
}

```

## 6.8 2D Closest Pair

```

struct cmp_y {
    bool operator()(const P& p, const P& q) const {
        return p.y < q.y;
    }
};
multiset<P, cmp_y> s;
void solve(P a[], int n) {
    sort(a, a + n, [](const P& p, const P& q) {
        return tie(p.x, p.y) < tie(q.x, q.y);
    });
    llf d = INF; int pt = 0;
    for (int i = 0; i < n; ++i) {
        while (pt < i and a[i].x - a[pt].x >= d)
            s.erase(s.find(a[pt++]));
        auto it = s.lower_bound(P(a[i].x, a[i].y - d));
        while (it != s.end() and it->y - a[i].y < d)
            d = min(d, dis(*(it++), a[i]));
        s.insert(a[i]);
    }
}

```

## 6.9 Simulated Annealing

```

llf anneal() {
    mt19937 rnd_engine( seed );
    uniform_real_distribution< llf > rnd( 0, 1 );
    const llf dT = 0.001;
    // Argument p
    llf S_cur = calc( p ), S_best = S_cur;
    for ( llf T = 2000 ; T > EPS ; T -= dT ) {
        // Modify p to p_prime
        const llf S_prime = calc( p_prime );
        const llf delta_c = S_prime - S_cur;
        llf prob = min( ( llf ) 1, exp( -delta_c / T ) );
        if ( rnd( rnd_engine ) <= prob )
            S_cur = S_prime, p = p_prime;
        if ( S_prime < S_best )
            S_best = S_prime, p_best = p_prime;
    }
    return S_best;
}

```

## 6.10 Half Plane Intersection

```

inline int dcmp ( double x ) {
    if( fabs( x ) < eps ) return 0;
    return x > 0 ? 1 : -1;
}
struct Line {
    Point st, ed;
    double ang;
    Line(Point _s=Point(), Point _e=Point()):
        st(_s),ed(_e),ang(atan2(_e.y-_s.y,_e.x-_s.x)){}
    inline bool operator< ( const Line& rhs ) const {
        if(dcmp(ang - rhs.ang) != 0) return ang < rhs.ang;
        return dcmp( cross( st, ed, rhs.st ) ) < 0;
    }
};
// cross(pt, line.ed-line.st)>=0 <=> pt in half plane
vector< Line > lns;
deque< Line > que;
deque< Point > pt;
double HPI() {
    sort( lns.begin(), lns.end() );
}

```



```

que.clear(); pt.clear();
que.push_back( lns[ 0 ] );
for ( int i = 1 ; i < (int)lns.size() ; i ++ ) {
    if(!dcmp(lns[i].ang - lns[i-1].ang)) continue;
    while ( pt.size() > 0 &&
        dcmp( cross(lns[i].st, lns[i].ed, pt.back()) ) < 0 ) {
        pt.pop_back(); que.pop_back();
    }
    while ( pt.size() > 0 &&
        dcmp( cross(lns[i].st, lns[i].ed, pt.front()) ) < 0 ) {
        pt.pop_front(); que.pop_front();
    }
    pt.push_back( get_point( que.back(), lns[ i ] ) );
    que.push_back( lns[ i ] );
}
while ( pt.size() > 0 &&
    dcmp( cross(que[0].st, que[0].ed, pt.back()) ) < 0 ) {
    que.pop_back();
    pt.pop_back();
}
while ( pt.size() > 0 &&
    dcmp( cross(que.back().st, que.back().ed, pt[0]) ) < 0 ) {
    que.pop_front();
    pt.pop_front();
}
pt.push_back( get_point( que.front(), que.back() ) );
vector< Point > conv;
for ( int i = 0 ; i < (int)pt.size() ; i ++ )
    conv.push_back( pt[ i ] );
double ret = 0;
for ( int i = 1 ; i + 1 < (int)conv.size() ; i ++ )
    ret += abs( cross( conv[0], conv[i], conv[i + 1] ) );
return ret / 2.0;
}

```

## 6.11 Ternary Search on Integer

```

int TernarySearch(int l, int r) {
    // max value @ (l, r]
    while (r - l > 1) {
        int m = (l + r) >> 1;
        if (f(m) > f(m + 1)) r = m;
        else l = m;
    }
    return l + 1;
}

```

## 6.12 Minimum Covering Circle

```

template<typename T>
Circle<llf> MinCircleCover(const vector<PT>& pts) {
    random_shuffle(ALL(pts));
    Circle<llf> c = {pts[0], 0};
    for(int i=0; i<SZ(pts); i++) {
        if(pts[i].in(c)) continue;
        c = {pts[i], 0};
        for(int j=0; j<i; j++) {
            if(pts[j].in(c)) continue;
            c.o = (pts[i] + pts[j]) / 2;
            c.r = pts[i].dis(c.o);
            for(int k=0; k<j; k++) {
                if(pts[k].in(c)) continue;
                c = get_circum(pts[i], pts[j], pts[k]);
            }
        }
    }
    return c;
}

```

## 6.13 KDTree (Nearest Point)

```

const int MXN = 100005;
struct KDTree {
    struct Node {
        int x, y, x1, y1, x2, y2;
        int id, f;
        Node *L, *R;
    } tree[MXN], *root;
    int n;
    LL dis2(int x1, int y1, int x2, int y2) {

```

```

        LL dx = x1-x2, dy = y1-y2;
        return dx*dx+dy*dy;
    }
    static bool cmpx(Node& a, Node& b) {return a.x<b.x;}
    static bool cmpy(Node& a, Node& b) {return a.y<b.y;}
    void init(vector<pair<int, int>> ip) {
        n = ip.size();
        for (int i=0; i<n; i++) {
            tree[i].id = i;
            tree[i].x = ip[i].first;
            tree[i].y = ip[i].second;
        }
        root = build_tree(0, n-1, 0);
    }
    Node* build_tree(int L, int R, int d) {
        if (L>R) return nullptr;
        int M = (L+R)/2; tree[M].f = d%2;
        nth_element(tree+L, tree+M, tree+R+1, d%2?cmpy:cmpx);
        tree[M].x1 = tree[M].x2 = tree[M].x;
        tree[M].y1 = tree[M].y2 = tree[M].y;
        tree[M].L = build_tree(L, M-1, d+1);
        if (tree[M].L) {
            tree[M].x1 = min(tree[M].x1, tree[M].L->x1);
            tree[M].x2 = max(tree[M].x2, tree[M].L->x2);
            tree[M].y1 = min(tree[M].y1, tree[M].L->y1);
            tree[M].y2 = max(tree[M].y2, tree[M].L->y2);
        }
        tree[M].R = build_tree(M+1, R, d+1);
        if (tree[M].R) {
            tree[M].x1 = min(tree[M].x1, tree[M].R->x1);
            tree[M].x2 = max(tree[M].x2, tree[M].R->x2);
            tree[M].y1 = min(tree[M].y1, tree[M].R->y1);
            tree[M].y2 = max(tree[M].y2, tree[M].R->y2);
        }
        return tree+M;
    }
    int touch(Node* r, int x, int y, LL d2) {
        LL dis = sqrt(d2)+1;
        if (x<r->x1-dis || x>r->x2+dis ||
            y<r->y1-dis || y>r->y2+dis)
            return 0;
        return 1;
    }
    void nearest(Node* r, int x, int y, int &mID, LL &md2) {
        if (!r || !touch(r, x, y, md2)) return;
        LL d2 = dis2(r->x, r->y, x, y);
        if (d2 < md2 || (d2 == md2 && mID < r->id)) {
            mID = r->id;
            md2 = d2;
        }
        // search order depends on split dim
        if ((r->f == 0 && x < r->x) ||
            (r->f == 1 && y < r->y)) {
            nearest(r->L, x, y, mID, md2);
            nearest(r->R, x, y, mID, md2);
        } else {
            nearest(r->R, x, y, mID, md2);
            nearest(r->L, x, y, mID, md2);
        }
    }
    int query(int x, int y) {
        int id = 1029384756;
        LL d2 = 102938475612345678LL;
        nearest(root, x, y, id, d2);
        return id;
    }
} tree;

```

# 7 Stringology

## 7.1 Hash

```

class Hash {
private:
    const int p = 127, q = 1051762951;
    int sz, prefix[N], power[N];
    int add(int x, int y) {return x+y==q?x+y-q:x+y;}
    int sub(int x, int y) {return x-y<0?x-y+q:x-y;}
    int mul(int x, int y) {return 1LL*x*y%q;}
public:
    void init(const string &x) {

```



```

    sz = x.size(); prefix[0]=0; power[0]=1;
    for(int i=1; i<=sz; i++)
        prefix[i]=add(mul(prefix[i-1], p), x[i-1]);
    for(int i=1; i<=sz; i++) power[i]=mul(power[i-1], p);
}
int query(int l, int r){
    // 1-base (l, r)
    return sub(prefix[r], mul(prefix[l], power[r-l]));
}
};

```

## 7.2 Suffix Array

```

namespace sfxarray {
bool t[maxn * 2];
int hi[maxn], rev[maxn];
int _s[maxn * 2], sa[maxn * 2], c[maxn * 2];
int x[maxn], p[maxn], q[maxn * 2];
// sa[i]: sa[i]-th suffix is the \
// i-th lexicographically smallest suffix.
// hi[i]: longest common prefix \
// of suffix sa[i] and suffix sa[i - 1].
void pre(int *sa, int *c, int n, int z) {
    memset(sa, 0, sizeof(int) * n);
    memcpy(x, c, sizeof(int) * z);
}
void induce(int *sa, int *c, int *s, bool *t, int n, int z) {
    memcpy(x + 1, c, sizeof(int) * (z - 1));
    for (int i = 0; i < n; ++i)
        if (sa[i] && !t[sa[i] - 1])
            sa[x[s[sa[i] - 1]]++] = sa[i] - 1;
    memcpy(x, c, sizeof(int) * z);
    for (int i = n - 1; i >= 0; --i)
        if (sa[i] && t[sa[i] - 1])
            sa[--x[s[sa[i] - 1]]] = sa[i] - 1;
}
void sais(int *s, int *sa, int *p, int *q,
bool *t, int *c, int n, int z) {
    bool uniq = t[n - 1] = true;
    int nn=0, nmzx=-1, *nsa = sa+n, *ns=s+n, last=-1;
    memset(c, 0, sizeof(int) * z);
    for (int i = 0; i < n; ++i) uniq &= ++c[s[i]] < 2;
    for (int i = 0; i < z - 1; ++i) c[i + 1] += c[i];
    if (uniq) {
        for (int i = 0; i < n; ++i) sa[--c[s[i]]] = i;
        return;
    }
    for (int i = n - 2; i >= 0; --i)
        t[i] = (s[i]==s[i + 1] ? t[i + 1] : s[i]<s[i + 1]);
    pre(sa, c, n, z);
    for (int i = 1; i <= n - 1; ++i)
        if (t[i] && !t[i - 1])
            sa[--x[s[i]]] = p[q[i] = nn++] = i;
    induce(sa, c, s, t, n, z);
    for (int i = 0; i < n; ++i) {
        if (sa[i] && t[sa[i]] && !t[sa[i] - 1]) {
            bool neq = last < 0 || \
                memcmp(s + sa[i], s + last,
                    (p[q[sa[i]] + 1] - sa[i]) * sizeof(int));
            ns[q[last = sa[i]]] = nmzx += neq;
        }
    }
    sais(ns, nsa, p+nn, q+n, t+n, c+z, nn, nmzx+1);
    pre(sa, c, n, z);
    for (int i = nn - 1; i >= 0; --i)
        sa[--x[s[p[nsa[i]]]]] = p[nsa[i]];
    induce(sa, c, s, t, n, z);
}
void build(const string &s) {
    for (int i = 0; i < (int)s.size(); ++i) _s[i] = s[i];
    _s[(int)s.size()] = 0; // s shouldn't contain 0
    sais(_s, sa, p, q, t, c, (int)s.size() + 1, 256);
    for (int i = 0; i < (int)s.size(); ++i) sa[i]=sa[i+1];
    for (int i = 0; i < (int)s.size(); ++i) rev[sa[i]]=i;
    int ind = 0; hi[0] = 0;
    for (int i = 0; i < (int)s.size(); ++i) {
        if (!rev[i]) {
            ind = 0;
            continue;
        }
        while (i + ind < (int)s.size() && \
            s[i + ind]==s[sa[rev[i] - 1] + ind]) ++ind;
    }
}

```

```

        hi[rev[i]] = ind ? ind-- : 0;
    }
}

```

## 7.3 Aho-Corasick Algorithm

```

class AhoCorasick{
private:
    static constexpr int Z = 26;
    struct node{
        node *nxt[ Z ], *fail;
        vector< int > data;
        node(): fail( nullptr ) {
            memset( nxt, 0, sizeof( nxt ) );
            data.clear();
        }
    } *rt;
    inline int Idx( char c ) { return c - 'a'; }
public:
    void init() { rt = new node(); }
    void add( const string& s, int d ) {
        node* cur = rt;
        for ( auto c : s ) {
            if ( not cur->nxt[ Idx( c ) ] )
                cur->nxt[ Idx( c ) ] = new node();
            cur = cur->nxt[ Idx( c ) ];
        }
        cur->data.push_back( d );
    }
    void compile() {
        vector< node* > bfs;
        size_t ptr = 0;
        for ( int i = 0; i < Z; ++i ) {
            if ( not rt->nxt[ i ] ) {
                // uncomment 2 lines to make it DFA
                // rt->nxt[i] = rt;
                continue;
            }
            rt->nxt[ i ]->fail = rt;
            bfs.push_back( rt->nxt[ i ] );
        }
        while ( ptr < bfs.size() ) {
            node* u = bfs[ ptr++ ];
            for ( int i = 0; i < Z; ++i ) {
                if ( not u->nxt[ i ] ) {
                    // u->nxt[i] = u->fail->nxt[i];
                    continue;
                }
                node* u_f = u->fail;
                while ( u_f ) {
                    if ( not u_f->nxt[ i ] ) {
                        u_f = u_f->fail; continue;
                    }
                    u->nxt[ i ]->fail = u_f->nxt[ i ];
                    break;
                }
                if ( not u_f ) u->nxt[ i ]->fail = rt;
                bfs.push_back( u->nxt[ i ] );
            }
        }
    }
    void match( const string& s, vector< int >& ret ) {
        node* u = rt;
        for ( auto c : s ) {
            while ( u != rt and not u->nxt[ Idx( c ) ] )
                u = u->fail;
            u = u->nxt[ Idx( c ) ];
            if ( not u ) u = rt;
            node* tmp = u;
            while ( tmp != rt ) {
                for ( auto d : tmp->data )
                    ret.push_back( d );
                tmp = tmp->fail;
            }
        }
    }
} ac;

```

## 7.4 Suffix Automaton

```

struct Node{
    Node *green, *edge[26];
    int max_len;
    Node(const int _max_len)
        : green(NULL), max_len(_max_len){
        memset(edge,0,sizeof(edge));
    }
} *ROOT, *LAST;
void Extend(const int c) {
    Node *cursor = LAST;
    LAST = new Node((LAST->max_len) + 1);
    for(;cursor&&!cursor->edge[c]; cursor=cursor->green)
        cursor->edge[c] = LAST;
    if (!cursor)
        LAST->green = ROOT;
    else {
        Node *potential_green = cursor->edge[c];
        if((potential_green->max_len)==(cursor->max_len+1))
            LAST->green = potential_green;
        else {
            //assert(potential_green->max_len>(cursor->max_len+1));
            Node *wish = new Node((cursor->max_len) + 1);
            for(;cursor && cursor->edge[c]==potential_green;
                cursor = cursor->green)
                cursor->edge[c] = wish;
            for (int i = 0; i < 26; i++)
                wish->edge[i] = potential_green->edge[i];
            wish->green = potential_green->green;
            potential_green->green = wish;
            LAST->green = wish;
        }
    }
}
char S[10000001], A[10000001];
int N;
int main(){
    scanf("%d%s", &N, S);
    ROOT = LAST = new Node(0);
    for (int i = 0; S[i]; i++)
        Extend(S[i] - 'a');
    while (N--){
        scanf("%s", A);
        Node *cursor = ROOT;
        bool ans = true;
        for (int i = 0; A[i]; i++){
            cursor = cursor->edge[A[i] - 'a'];
            if (!cursor) {
                ans = false;
                break;
            }
        }
        puts(ans ? "Yes" : "No");
    }
    return 0;
}

```

## 7.5 KMP

```

vector<int> kmp(const string &s) {
    vector<int> f(s.size(), 0);
    /* f[i] = length of the longest prefix
       (excluding s[0:i]) such that it coincides
       with the suffix of s[0:i] of the same length */
    /* i + 1 - f[i] is the length of the
       smallest recurring period of s[0:i] */
    int k = 0;
    for (int i = 1; i < (int)s.size(); ++i) {
        while (k > 0 && s[i] != s[k]) k = f[k - 1];
        if (s[i] == s[k]) ++k;
        f[i] = k;
    }
    return f;
}
vector<int> search(const string &s, const string &t) {
    // return 0-indexed occurrence of t in s
    vector<int> f = kmp(t), r;
    for (int i = 0, k = 0; i < (int)s.size(); ++i) {
        while(k > 0 && (k==(int)t.size() || s[i]!=t[k]))
            k = f[k - 1];
        if (s[i] == t[k]) ++k;
        if (k == (int)t.size()) r.push_back(i-t.size()+1);
    }
}

```

```

}
return res;
}

```

## 7.6 Z value

```

char s[MAXN];
int len,z[MAXN];
void Z_value() {
    int i,j,left,right;
    left=right=0; z[0]=len;
    for(i=1;i<len;i++) {
        j=max(min(z[i-left],right-i),0);
        for(;i+j<len&&s[i+j]==s[j];j++);
        z[i]=j;
        if(i+z[i]>right) {
            right=i+z[i];
            left=i;
        }
    }
}

```

## 7.7 Manacher

```

int z[maxn];
int manacher(const string& s) {
    string t = ".";
    for(char c:s) t += c, t += '.';
    int l = 0, r = 0, ans = 0;
    for (int i = 1; i < t.length(); ++i) {
        z[i] = (r > i ? min(z[2 * l - i], r - i) : 1);
        while (i - z[i] >= 0 && i + z[i] < t.length()) {
            if(t[i - z[i]] == t[i + z[i]]) ++z[i];
            else break;
        }
        if (i + z[i] > r) r = i + z[i], l = i;
    }
    for(int i=1;i<t.length();++i) ans = max(ans, z[i]-1);
    return ans;
}

```

## 7.8 Lexico Smallest Rotation

```

string mcp(string s){
    int n = s.length();
    s += s;
    int i=0, j=1;
    while (i<n && j<n){
        int k = 0;
        while (k < n && s[i+k] == s[j+k]) k++;
        if (s[i+k] <= s[j+k]) j += k+1;
        else i += k+1;
        if (i == j) j++;
    }
    int ans = i < n ? i : j;
    return s.substr(ans, n);
}

```

## 7.9 BWT

```

struct BurrowsWheeler{
#define SIGMA 26
#define BASE 'a'
    vector<int> v[ SIGMA ];
    void BWT(char* ori, char* res){
        // make ori -> ori + ori
        // then build suffix array
    }
    void iBWT(char* ori, char* res){
        for( int i = 0 ; i < SIGMA ; i ++ )
            v[ i ].clear();
        int len = strlen( ori );
        for( int i = 0 ; i < len ; i ++ )
            v[ ori[i] - BASE ].push_back( i );
        vector<int> a;
        for( int i = 0 , ptr = 0 ; i < SIGMA ; i ++ )
            for( auto j : v[ i ] ){
                a.push_back( j );
                ori[ ptr ++ ] = BASE + i;
            }
    }
}

```

```

    }
    for( int i = 0 , ptr = 0 ; i < len ; i ++ ){
        res[ i ] = ori[ a[ ptr ] ];
        ptr = a[ ptr ];
    }
    res[ len ] = 0;
}
} bwt;

```

## 7.10 Palindromic Tree

```

struct palindromic_tree{
    struct node{
        int next[26],f,len;
        int cnt,num,st,ed;
        node(int l=0):f(0),len(l),cnt(0),num(0) {
            memset(next, 0, sizeof(next)); }
    };
    vector<node> st;
    vector<char> s;
    int last,n;
    void init(){
        st.clear();s.clear();last=1; n=0;
        st.push_back(0);st.push_back(-1);
        st[0].f=1;s.push_back(-1); }
    int getFail(int x){
        while(s[n-st[x].len-1]!=s[n])x=st[x].f;
        return x; }
    void add(int c){
        s.push_back(c-'a'); ++n;
        int cur=getFail(last);
        if(!st[cur].next[c]){
            int now=st.size();
            st.push_back(st[cur].len+2);
            st[now].f=st[getFail(st[cur].f)].next[c];
            st[cur].next[c]=now;
            st[now].num=st[st[now].f].num+1;
        }
        last=st[cur].next[c];
        ++st[last].cnt; }
    int size(){ return st.size()-2; }
} pt;
int main() {
    string s; cin >> s; pt.init();
    for (int i=0; i<SZ(s); i++) {
        int prvsz = pt.size(); pt.add(s[i]);
        if (prvsz != pt.size()) {
            int r = i, l = r - pt.st[pt.last].len + 1;
            // pal @ [l,r]: s.substr(l, r-l+1)
        }
    }
    return 0;
}

```

## 8 Misc

### 8.1 Theorems

#### 8.1.1 Kirchhoff's Theorem

Denote  $L$  be a  $n \times n$  matrix as the Laplacian matrix of graph  $G$ , where  $L_{ii} = d(i)$ ,  $L_{ij} = -c$  where  $c$  is the number of edge  $(i, j)$  in  $G$ .

- The number of undirected spanning in  $G$  is  $|\det(\tilde{L}_{11})|$ .
- The number of directed spanning tree rooted at  $r$  in  $G$  is  $|\det(\tilde{L}_{rr})|$ .

#### 8.1.2 Tutte's Matrix

Let  $D$  be a  $n \times n$  matrix, where  $d_{ij} = x_{ij}$  ( $x_{ij}$  is chosen uniform randomly) if  $i < j$  and  $(i, j) \in E$ , otherwise  $d_{ij} = -d_{ji}$ .  $\frac{\text{rank}(D)}{2}$  is the maximum matching on  $G$ .

#### 8.1.3 Cayley's Formula

- Given a degree sequence  $d_1, d_2, \dots, d_n$  for each labeled vertices, there're  $\frac{(n-2)!}{(d_1-1)!(d_2-1)!\dots(d_n-1)!}$  spanning trees.
- Let  $T_{n,k}$  be the number of labeled forests on  $n$  vertices with  $k$  components, such that vertex  $1, 2, \dots, k$  belong to different components. Then  $T_{n,k} = kn^{n-k-1}$ .

#### 8.1.4 Erdős-Gallai theorem

A sequence of non-negative integers  $d_1 \geq d_2 \geq \dots \geq d_n$  can be represented as the degree sequence of a finite simple graph on  $n$  vertices if and only if  $d_1 + d_2 + \dots + d_n$  is even and

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k)$$

holds for all  $1 \leq k \leq n$ .

#### 8.1.5 Havel-Hakimi algorithm

find the vertex who has greatest degree unused, connect it with other greatest vertex.

#### 8.1.6 Hall's marriage theorem

Let  $G$  be a finite bipartite graph with bipartite sets  $X$  and  $Y$ . For a subset  $W$  of  $X$ , let  $N_G(W)$  denote the set of all vertices in  $Y$  adjacent to some element of  $W$ . Then there is an  $X$ -saturating matching iff  $\forall W \subseteq X, |W| \leq |N_G(W)|$

#### 8.1.7 Euler's planar graph formula

$$V - E + F = C + 1, \quad E \leq 3V - 6(?)$$

#### 8.1.8 Pick's theorem

For simple polygon, when points are all integer, we have  $A = \#\{\text{lattice points in the interior}\} + \frac{\#\{\text{lattice points on the boundary}\}}{2} - 1$

## 8.2 MaximumEmptyRect

```

int max_empty_rect(int n, int m, bool blocked[N][N]) {
    static int mxu[2][N], me=0, he=1, ans=0;
    for (int i=0; i<m; i++) mxu[he][i]=0;
    for (int i=0; i<n; i++) {
        stack<PII, vector<PII>> stk;
        for (int j=0; j<m; j++) {
            if (blocked[i][j]) mxu[me][j]=0;
            else mxu[me][j]=mxu[he][j]+1;
            int la = j;
            while (!stk.empty() && stk.top().FF > mxu[me][j]) {
                int x1 = i - stk.top().FF, x2 = i;
                int y1 = stk.top().SS, y2 = j;
                la = stk.top().SS; stk.pop();
                ans = max(ans, (x2-x1)*(y2-y1));
            }
            if (stk.empty() || stk.top().FF < mxu[me][j])
                stk.push({mxu[me][j], la});
        }
        while (!stk.empty()) {
            int x1 = i - stk.top().FF, x2 = i;
            int y1 = stk.top().SS-1, y2 = m-1;
            stk.pop(); ans = max(ans, (x2-x1)*(y2-y1));
        }
        swap(me, he);
    }
    return ans;
}

```

### 8.3 DP-opt Condition

#### 8.3.1 totally monotone (concave/convex)

$$\begin{aligned} \forall i < i', j < j', \quad B[i][j] \leq B[i'][j] &\implies B[i][j'] \leq B[i'][j'] \\ \forall i < i', j < j', \quad B[i][j] \geq B[i'][j] &\implies B[i][j'] \geq B[i'][j'] \end{aligned}$$

#### 8.3.2 monge condition (concave/convex)

$$\begin{aligned} \forall i < i', j < j', \quad B[i][j] + B[i'][j'] &\geq B[i][j'] + B[i'][j] \\ \forall i < i', j < j', \quad B[i][j] + B[i'][j] &\leq B[i][j'] + B[i'][j] \end{aligned}$$

## 8.4 Convex 1D/1D DP

```

struct segment {
    int i, l, r;
    segment() {}
    segment(int a, int b, int c): i(a), l(b), r(c) {}
};
inline lld f(int l, int r){return dp[l] + w(l+1, r);}
void solve() {
    dp[0] = 0;
    deque<segment> dq; dq.push_back(segment(0, 1, n));
    for (int i = 1; i <= n; ++i) {
        dp[i] = f(dq.front().i, i);
    }
}

```

```

while(dq.size() && dq.front().r < i+1) dq.pop_front();
dq.front().l = i + 1;
segment seg = segment(i, i + 1, n);
while (dq.size() &&
    f(i, dq.back().l) < f(dq.back().i, dq.back().l))
    dq.pop_back();
if (dq.size()) {
    int d = 1 << 20, c = dq.back().l;
    while (d >= 1) if (c + d <= dq.back().r)
        if (f(i, c+d) > f(dq.back().i, c+d)) c += d;
    dq.back().r = c; seg.l = c + 1;
}
if (seg.l <= n) dq.push_back(seg);
}
}

```

## 8.5 ConvexHull Optimization

```

inline lld DivCeil(lld n, lld d) { // ceil(n/d)
    return n / d + ((n < 0) != (d > 0)) && (n % d);
}
struct Line {
    static bool flag;
    lld a, b, l, r; // y=ax+b in [l, r)
    lld operator()(lld x) const { return a * x + b; }
    bool operator<(const Line& i) const {
        return flag ? tie(a, b) < tie(i.a, i.b) : l < i.l;
    }
    lld operator&(const Line& i) const {
        return DivCeil(b - i.b, i.a - a);
    }
};
bool Line::flag = true;
class ConvexHullMax {
    set<Line> L;
public:
    ConvexHullMax() { Line::flag = true; }
    void InsertLine(lld a, lld b) { // add y = ax + b
        Line now = {a, b, -INF, INF};
        if (L.empty()) {
            L.insert(now);
            return;
        }
        Line::flag = true;
        auto it = L.lower_bound(now);
        auto prv = it == L.begin() ? it : prev(it);
        if (it != L.end() && ((it != L.begin() &&
            (*it)(it->l) >= now(it->l) &&
            (*prv)(prv->r - 1) >= now(prv->r - 1)) ||
            (it == L.begin() && it->a == now.a))) return;
        if (it != L.begin()) {
            while (prv != L.begin() &&
                (*prv)(prv->l) <= now(prv->l))
                prv = --L.erase(prv);
            if (prv == L.begin() && now.a == prv->a)
                L.erase(prv);
        }
        if (it != L.end())
            while (it != --L.end() &&
                (*it)(it->r) <= now(it->r))
                it = L.erase(it);
        if (it != L.begin()) {
            prv = prev(it);
            const_cast<Line*>(&*prv)->r = now.l ((*prv) & now);
        }
        if (it != L.end())
            const_cast<Line*>(&*it)->l = now.r ((*it) & now);
        L.insert(it, now);
    }
    lld Query(lld a) const { // query max at x=a
        if (L.empty()) return -INF;
        Line::flag = false;
        auto it = --L.upper_bound({0, 0, a, 0});
        return (*it)(a);
    }
};

```

## 8.6 Josephus Problem

```

// n people kill m for each turn
int f(int n, int m) {

```

```

    int s = 0;
    for (int i = 2; i <= n; i++)
        s = (s + m) % i;
    return s;
}
// died at kth
int kth(int n, int m, int k) {
    if (m == 1) return n-1;
    for (k = k*m+m-1; k >= n; k = k-n+(k-n)/(m-1));
    return k;
}

```

## 8.7 Cactus Matching

```

vector<int> init_g[maxn], g[maxn*2];
int n, dfn[maxn], low[maxn], par[maxn], dfs_idx, bcc_id;
void tarjan(int u) {
    dfn[u] = low[u] = ++dfs_idx;
    for (int i = 0; i < (int) init_g[u].size(); i++) {
        int v = init_g[u][i];
        if (v == par[u]) continue;
        if (!dfn[v]) {
            par[v] = u;
            tarjan(v);
            low[u] = min(low[u], low[v]);
            if (dfn[u] < low[v]) {
                g[u].push_back(v);
                g[v].push_back(u);
            }
        } else {
            low[u] = min(low[u], dfn[v]);
            if (dfn[v] < dfn[u]) {
                int temp_v = u;
                bcc_id++;
                while (temp_v != v) {
                    g[bcc_id+n].push_back(temp_v);
                    g[temp_v].push_back(bcc_id+n);
                    temp_v = par[temp_v];
                }
                g[bcc_id+n].push_back(v);
                g[v].push_back(bcc_id+n);
                reverse(g[bcc_id+n].begin(), g[bcc_id+n].end());
            }
        }
    }
}
int dp[maxn][2], min_dp[2][2], tmp[2][2], tp[2];
void dfs(int u, int fa) {
    if (u <= n) {
        for (int i = 0; i < (int) g[u].size(); i++) {
            int v = g[u][i];
            if (v == fa) continue;
            dfs(v, u);
            memset(tp, 0x8f, sizeof tp);
            if (v <= n) {
                tp[0] = dp[u][0] + max(dp[v][0], dp[v][1]);
                tp[1] = max(
                    dp[u][0] + dp[v][0] + 1,
                    dp[u][1] + max(dp[v][0], dp[v][1])
                );
            } else {
                tp[0] = dp[u][0] + dp[v][0];
                tp[1] = max(dp[u][0] + dp[v][1], dp[u][1] + dp[v][0]);
            }
            dp[u][0] = tp[0], dp[u][1] = tp[1];
        }
    } else {
        for (int i = 0; i < (int) g[u].size(); i++) {
            int v = g[u][i];
            if (v == fa) continue;
            dfs(v, u);
        }
        min_dp[0][0] = 0;
        min_dp[1][1] = 1;
        min_dp[0][1] = min_dp[1][0] = -0x3f3f3f3f;
        for (int i = 0; i < (int) g[u].size(); i++) {
            int v = g[u][i];
            if (v == fa) continue;
            memset(tmp, 0x8f, sizeof tmp);
            tmp[0][0] = max(
                min_dp[0][0] + max(dp[v][0], dp[v][1]),

```

```

        min_dp[0][1]+dp[v][0]
    );
    tmp[0][1]=min_dp[0][0]+dp[v][0]+1;
    tmp[1][0]=max(
        min_dp[1][0]+max(dp[v][0],dp[v][1]),
        min_dp[1][1]+dp[v][0]
    );
    tmp[1][1]=min_dp[1][0]+dp[v][0]+1;
    memcpy(min_dp,tmp,sizeof tmp);
}
dp[u][1]=max(min_dp[0][1],min_dp[1][0]);
dp[u][0]=min_dp[0][0];
}
}
int main(){
    int m,a,b;
    scanf("%d%d",&n,&m);
    for(int i=0;i<m;i++){
        scanf("%d%d",&a,&b);
        init_g[a].push_back(b);
        init_g[b].push_back(a);
    }
    par[1]=-1;
    tarjan(1);
    dfs(1,-1);
    printf("%d\n",max(dp[1][0],dp[1][1]));
    return 0;
}

```

## 8.8 DLX

```

struct DLX {
    const static int maxn=210;
    const static int maxm=210;
    const static int maxnode=210*210;
    int n, m, size, row[maxnode], col[maxnode];
    int U[maxnode], D[maxnode], L[maxnode], R[maxnode];
    int H[maxn], S[maxm], ansd, ans[maxn];
    void init(int _n, int _m) {
        n = _n, m = _m;
        for(int i = 0; i <= m; ++i) {
            S[i] = 0;
            U[i] = D[i] = i;
            L[i] = i-1, R[i] = i+1;
        }
        R[L[0] = size = m] = 0;
        for(int i = 1; i <= n; ++i) H[i] = -1;
    }
    void Link(int r, int c) {
        ++S[col[++size] = c];
        row[size] = r; D[size] = D[c];
        U[D[c]] = size; U[size] = c; D[c] = size;
        if(H[r] < 0) H[r] = L[size] = R[size] = size;
        else {
            R[size] = R[H[r]];
            L[R[H[r]]] = size;
            L[size] = H[r];
            R[H[r]] = size;
        }
    }
    void remove(int c) {
        L[R[c]] = L[c]; R[L[c]] = R[c];
        for(int i = D[c]; i != c; i = D[i])
            for(int j = R[i]; j != i; j = R[j]) {
                U[D[j]] = U[j];
                D[U[j]] = D[j];
                --S[col[j]];
            }
    }
    void resume(int c) {
        L[R[c]] = c; R[L[c]] = c;
        for(int i = U[c]; i != c; i = U[i])
            for(int j = L[i]; j != i; j = L[j]) {
                U[D[j]] = j;
                D[U[j]] = j;
                ++S[col[j]];
            }
    }
    void dance(int d) {
        if(d>=ansd)return;
        if(R[0] == 0) {

```

```

            ansd = d;
            return;
        }
        int c = R[0];
        for(int i = R[0]; i; i = R[i])
            if(S[i] < S[c]) c = i;
        remove(c);
        for(int i = D[c]; i != c; i = D[i]) {
            ans[d] = row[i];
            for(int j = R[i]; j != i; j = R[j])
                remove(col[j]);
            dance(d+1);
            for(int j = L[i]; j != i; j = L[j])
                resume(col[j]);
        }
        resume(c);
    }
} sol;

```

## 8.9 Tree Knapsack

```

int dp[N][K];PII obj[N];
vector<int> G[N];
void dfs(int u, int mx){
    for(int s: G[u]) {
        if(mx < obj[s].first) continue;
        for(int i=0;i<=mx-obj[s].FF;i++){
            dp[s][i] = dp[u][i];
            dfs(s, mx - obj[s].first);
            for(int i=obj[s].FF;i<=mx;i++){
                dp[u][i] = max(dp[u][i],
                    dp[s][i - obj[s].FF] + obj[s].SS);
            }
        }
    }
}
int main(){
    int n, k; cin >> n >> k;
    for(int i=1;i<=n;i++){
        int p; cin >> p;
        G[p].push_back(i);
        cin >> obj[i].FF >> obj[i].SS;
    }
    dfs(0, k); int ans = 0;
    for(int i=0;i<=k;i++) ans = max(ans, dp[0][i]);
    cout << ans << '\n';
    return 0;
}

```

## 8.10 N Queens Problem

```

vector< int > solve( int n ) {
    // no solution when n=2, 3
    vector< int > ret;
    if ( n % 6 == 2 ) {
        for ( int i = 2 ; i <= n ; i += 2 )
            ret.push_back( i );
        ret.push_back( 3 ); ret.push_back( 1 );
        for ( int i = 7 ; i <= n ; i += 2 )
            ret.push_back( i );
        ret.push_back( 5 );
    } else if ( n % 6 == 3 ) {
        for ( int i = 4 ; i <= n ; i += 2 )
            ret.push_back( i );
        ret.push_back( 2 );
        for ( int i = 5 ; i <= n ; i += 2 )
            ret.push_back( i );
        ret.push_back( 1 ); ret.push_back( 3 );
    } else {
        for ( int i = 2 ; i <= n ; i += 2 )
            ret.push_back( i );
        for ( int i = 1 ; i <= n ; i += 2 )
            ret.push_back( i );
    }
    return ret;
}

```