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## 1 Basic

### 1.1 vimrc

```
se is nu ru et tgc sc hls cin cino+=j1 sw=2 sts=2 bs=2
mouse=a "encoding=utf-8 ls=2
syn on | colo desert | filetype indent on
inoremap {<CR> {<CR>}<ESC>O
map <F8> <ESC>:w<CR>:!g++ "%> -o "%> -g -std=gnu++20 -
    DCKISEKI -Wall -Wextra -Wshadow -Wfatal-errors -
    Wconversion -fsanitize=address,undefined,float-
    divide-by-zero,float-cast-overflow && echo success<
    CR>
map <F9> <ESC>:w<CR>:!g++ "%> -o "%> -O2 -g -std=gnu
    ++20 && echo success<CR>
map <F10> <ESC>:!. / "%> <CR>
ca Hash w !cpp -dD -P -fpreprocessed \ | tr -d '[:space
    :]' \ | md5sum \ | cut -c-6
let c_no_curly_error=1
" setxkbmap -option caps:ctrl_modifier
```

### 1.2 Debug Macro [a45c59]

```
#define all(x) begin(x), end(x)
#ifdef CKISEKI
#include <experimental/iterator>
#define safe cerr<<__PRETTY_FUNCTION__<<" line "<<
    __LINE__<<" safe\n"
#define debug(a...) debug(#a, a)
#define orange(a...) orange(#a, a)
void debug_(auto s, auto ...a) {
    cerr << "\e[1;32m(" << s << ") = (" ;
    int f = 0;
    (... , (cerr << (f++ ? ", " : "") << a));
    cerr << ") \e[0m\n";
}
void orange_(auto s, auto L, auto R) {
    cerr << "\e[1;33m[ " << s << " ] = [ " ;
    using namespace experimental;
    copy(L, R, make_ostream_joiner(cerr, ", "));
    cerr << " ] \e[0m\n";
}
#else
#define safe ((void)0)
#define debug(...) safe
#define orange(...) safe
#endif
```

### 1.3 Increase Stack [b6856c]

```
const int size = 256 << 20;
register long rsp asm("rsp");
char *p = (char*)malloc(size)+size, *bak = (char*)rsp;
__asm__ ("movq %0, %%rsp\n"::"r"(p));
// main
__asm__ ("movq %0, %%rsp\n"::"r"(bak));
```

### 1.4 Pragma Optimization [6006f6]

```
#pragma GCC optimize("Ofast,no-stack-protector")
#pragma GCC optimize("no-math-errno,unroll-loops")
#pragma GCC target("sse,sse2,sse3,ssse3,sse4")
#pragma GCC target("popcnt,abm,mmx,avx,arch=skylake")
__builtin_ia32_ldmxcsr(__builtin_ia32_stmxcsr()|0x8040)
```

### 1.5 IO Optimization [c9494b]

```
static inline int gc() {
    constexpr int B = 1<<20; static char buf[B], *p, *q;
    if (p == q) q = (p = buf) + fread(buf, 1, B, stdin);
    return q == buf ? EOF : *p++;
}
```

### 1.6 SVG Writer [ac13c8]

```
#ifdef CKISEKI
class SVG {
    void p(string_view s) { o << s; }
    void p(string_view s, auto v, auto... vs) {
        auto i = s.find('$');
        o << s.substr(0, i) << v, p(s.substr(i + 1), vs...);
    }
    ostream o; string c = "red";
public:
    SVG(auto f, auto x1, auto y1, auto x2, auto y2) : o(f) {
        p("<svg xmlns='http://www.w3.org/2000/svg' "
            "viewBox='$ $ $ $'>\n"
            "<style>{*stroke-width:0.5%;}</style>\n",
            x1, -y2, x2 - x1, y2 - y1);
    }
    ~SVG() { p("</svg>\n"); }
    void color(string nc) { c = nc; }
    void line(auto x1, auto y1, auto x2, auto y2) {
        p("<line x1='$' y1='$' x2='$' y2='$' stroke='$'/>\n",
```

```

    x1, -y1, x2, -y2, c); }
void circle(auto x, auto y, auto r) {
    p("<circle cx='$' cy='$' r='$' stroke='$' "
      "fill='none'/>\n", x, -y, r, c); }
void text(auto x, auto y, string s, int w = 12) {
    p("<text x='$' y='$' font-size='$px'>$</text>\n",
      x, -y, w, s); }
}; // write wrapper for complex if use complex
#else
class SVG { SVG(auto ...) {} }; // you know how to
#endif

```

## 2 Data Structure

### 2.1 Dark Magic [095f25]

```

#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/priority_queue.hpp>
using namespace __gnu_pbds;
// heap tags: paring/binary/binomial/rc_binomial/thin
template<typename T>
using pbds_heap=__gnu_pbds::prioity_queue<T,less<T>, \
    pairing_heap_tag>;
// pbds_heap::point_iterator
// x = pq.push(10); pq.modify(x, 87); a.join(b);
// tree tags: rb_tree_tag/ov_tree_tag/splay_tree_tag
template<typename T>
using ordered_set = tree<T, null_type, less<T>,
    rb_tree_tag, tree_order_statistics_node_update>;
// find_by_order, order_of_key
// hash tables: cc_hash_table/gp_hash_table

```

### 2.2 Link-Cut Tree [60627f]

```

template <typename Val, typename SVal> class LCT {
    struct node {
        int pa, ch[2];
        bool rev;
        Val v, prod, rprod;
        SVal sv, sub, vir;
        node() : pa{0}, ch{0, 0}, rev{false}, v{}, prod{},
            rprod{}, sv{}, sub{}, vir{} {};
    };
    #define cur o[u]
    #define lc cur.ch[0]
    #define rc cur.ch[1]
    vector<node> o;
    bool is_root(int u) const {
        return o[cur.pa].ch[0] != u && o[cur.pa].ch[1] != u;
    }
    bool is_rch(int u) const {
        return o[cur.pa].ch[1] == u && !is_root(u);
    }
    void down(int u) {
        if (not cur.rev) return;
        if (lc) set_rev(lc);
        if (rc) set_rev(rc);
        cur.rev = false;
    }
    void up(int u) {
        cur.prod = o[lc].prod * cur.v * o[rc].prod;
        cur.rprod = o[rc].rprod * cur.v * o[lc].rprod;
        cur.sub = cur.vir + o[lc].sub + o[rc].sub + cur.sv;
    }
    void set_rev(int u) {
        swap(lc, rc); swap(cur.prod, cur.rprod);
        cur.rev ^= 1;
    }
    void rotate(int u) {
        int f = cur.pa, g = o[f].pa, l = is_rch(u);
        if (cur.ch[l ^ 1]) o[cur.ch[l ^ 1]].pa = f;
        if (not is_root(f)) o[g].ch[is_rch(f)] = u;
        o[f].ch[l] = cur.ch[l ^ 1];
        cur.ch[l ^ 1] = f;
        cur.pa = g, o[f].pa = u;
        up(f);
    }
    void splay(int u) {
        vector<int> stk = {u};
        while (not is_root(stk.back()))
            stk.push_back(o[stk.back()].pa);
        while (not stk.empty()) {
            down(stk.back());
            stk.pop_back();
        }
        for (int f = cur.pa; not is_root(u); f = cur.pa) {
            if (!is_root(f))

```

```

            rotate(is_rch(u) == is_rch(f) ? f : u);
            rotate(u);
        }
        up(u);
    }
    void access(int x) {
        for (int u = x, last = 0; u; u = cur.pa) {
            splay(u);
            cur.vir = cur.vir + o[rc].sub - o[last].sub;
            rc = last; up(last = u);
        }
        splay(x);
    }
    int find_root(int u) {
        int la = 0;
        for (access(u); u; u = lc) down(la = u);
        return la;
    }
    void split(int x, int y) { chroot(x); access(y); }
    void chroot(int u) { access(u); set_rev(u); }
public:
    LCT(int n = 0) : o(n + 1) {}
    int add(const Val &v = {}) {
        o.push_back(v);
        return int(o.size()) - 2;
    }
    void set_val(int u, const Val &v) {
        splay(++u); cur.v = v; up(u);
    }
    void set_sval(int u, const SVal &v) {
        access(++u); cur.sv = v; up(u);
    }
    Val query(int x, int y) {
        split(++x, ++y); return o[y].prod;
    }
    SVal subtree(int p, int u) {
        chroot(++p); access(++u);
        return cur.vir + cur.sv;
    }
    bool connected(int u, int v) {
        return find_root(++u) == find_root(++v);
    }
    void link(int x, int y) {
        chroot(++x); access(++y);
        o[y].vir = o[y].vir + o[x].sub;
        up(o[x].pa = y);
    }
    void cut(int x, int y) {
        split(++x, ++y);
        o[y].ch[0] = o[x].pa = 0; up(y);
    }
    #undef cur
    #undef lc
    #undef rc
};

```

### 2.3 LiChao Segment Tree [b9c827]

```

struct L {
    int m, k, id;
    L() : id(-1) {}
    L(int a, int b, int c) : m(a), k(b), id(c) {}
    int at(int x) { return m * x + k; }
};
class LiChao {
private:
    int n; vector<L> nodes;
    static int lc(int x) { return 2 * x + 1; }
    static int rc(int x) { return 2 * x + 2; }
    void insert(int l, int r, int id, L ln) {
        int m = (l + r) >> 1;
        if (nodes[id].id == -1)
            return nodes[id] = ln, void();
        bool atLeft = nodes[id].at(l) < ln.at(l);
        if (nodes[id].at(m) < ln.at(m))
            atLeft ^= 1, swap(nodes[id], ln);
        if (r - l == 1) return;
        if (atLeft) insert(l, m, lc(id), ln);
        else insert(m, r, rc(id), ln);
    }
    int query(int l, int r, int id, int x) {
        int m = (l + r) >> 1, ret = 0;
        if (nodes[id].id != -1) ret = nodes[id].at(x);
        if (r - l == 1) return ret;
    }
};

```

```

    if (x < m) return max(ret, query(l, m, lc(id), x));
    return max(ret, query(m, r, rc(id), x));
}
public:
    LiChao(int n_) : n(n_), nodes(n * 4) {}
    void insert(L ln) { insert(0, n, 0, ln); }
    int query(int x) { return query(0, n, 0, x); }
};

```

## 2.4 Treap [ae576c]

```

__gnu_cxx::sfmt19937 rnd(7122); // <ext/random>
namespace Treap {
    struct node {
        int size, pri; node *lc, *rc, *pa;
        node() : size(1), pri(rnd()), lc(0), rc(0), pa(0) {}
        void pull() {
            size = 1; pa = 0;
            if (lc) { size += lc->size; lc->pa = this; }
            if (rc) { size += rc->size; rc->pa = this; }
        }
    };
    int SZ(node *x) { return x ? x->size : 0; }
    node *merge(node *L, node *R) {
        if (not L or not R) return L ? L : R;
        if (L->pri > R->pri)
            return L->rc = merge(L->rc, R), L->pull(), L;
        else
            return R->lc = merge(L, R->lc), R->pull(), R;
    }
    void splitBySize(node *o, int k, node *&L, node *&R) {
        if (not o) L = R = 0;
        else if (int s = SZ(o->lc) + 1; s <= k)
            L = o, splitBySize(o->rc, k-s, L->rc, R), L->pull();
        else
            R = o, splitBySize(o->lc, k, L, R->lc), R->pull();
    } // SZ(L) == k
    int getRank(node *o) { // 1-base
        int r = SZ(o->lc) + 1;
        for (; o->pa; o = o->pa)
            if (o->pa->rc == o) r += SZ(o->pa->lc) + 1;
        return r;
    }
} // namespace Treap

```

## 2.5 Linear Basis [138d5d]

```

template <int BITS, typename S = int> struct Basis {
    static constexpr S MIN = numeric_limits<S>::min();
    array<pair<llu, S>, BITS> b;
    Basis() { b.fill({0, MIN}); }
    void add(llu x, S p) {
        for (int i = BITS-1; i >= 0; i--) if (x >> i & 1) {
            if (b[i].first == 0) return b[i] = {x, p}, void();
            if (b[i].second < p)
                swap(b[i].first, x), swap(b[i].second, p);
            x ^= b[i].first;
        }
    }
    optional<llu> query_kth(llu v, llu k) {
        vector<pair<llu, int>> o;
        for (int i = 0; i < BITS; i++)
            if (b[i].first) o.emplace_back(b[i].first, i);
        if (k >= (1ULL << o.size())) return {};
        for (int i = int(o.size()) - 1; i >= 0; i--)
            if ((k >> i & 1) ^ (v >> o[i].second & 1))
                v ^= o[i].first;
        return v;
    }
    Basis filter(S l) {
        Basis res = *this;
        for (int i = 0; i < BITS; i++)
            if (res.b[i].second < l) res.b[i] = {0, MIN};
        return res;
    }
};

```

## 2.6 Binary Search on Segtree [6c61c0]

```

// find_first = l -> minimal x s.t. check([l, x])
// find_last = r -> maximal x s.t. check([x, r])
int find_first(int l, auto &&check) {
    if (l >= n) return n + 1;
    l += sz; push(l); Monoid sum; // identity
    do {
        while ((l & 1) == 0) l >>= 1;
        if (auto s = sum + nd[l]; check(s)) {

```

```

            while (l < sz) {
                prop(l); l = (l << 1);
                if (auto nxt = sum + nd[l]; not check(nxt))
                    sum = nxt, l++;
            }
            return l + 1 - sz;
        } else sum = s, l++;
    } while (lowbit(l) != l);
    return n + 1;
}
int find_last(int r, auto &&check) {
    if (r <= 0) return -1;
    r += sz; push(r - 1); Monoid sum; // identity
    do {
        r--;
        while (r > 1 and (r & 1)) r >>= 1;
        if (auto s = nd[r] + sum; check(s)) {
            while (r < sz) {
                prop(r); r = (r << 1) | 1;
                if (auto nxt = nd[r] + sum; not check(nxt))
                    sum = nxt, r--;
            }
            return r - sz;
        } else sum = s;
    } while (lowbit(r) != r);
    return -1;
}

```

## 3 Graph

### 3.1 SCC [16c7d6]

```

class SCC { // test @ library checker
protected:
    int n, dfc, nsc; vector<vector<int>> G;
    vector<int> vis, low, idx, stk;
    void dfs(int i) {
        vis[i] = low[i] = ++dfc; stk.push_back(i);
        for (int j : G[i])
            if (!vis[j])
                dfs(j), low[i] = min(low[i], low[j]);
            else if (vis[j] != -1)
                low[i] = min(low[i], vis[j]);
        if (low[i] == vis[i])
            for (idx[i] = nsc++; vis[i] != -1;) {
                int x = stk.back(); stk.pop_back();
                idx[x] = idx[i]; vis[x] = -1;
            }
    }
public:
    SCC(int n_) : n(n_), dfc(0), nsc(0), G(n),
        vis(n), low(n), idx(n) {}
    void add_edge(int u, int v) { G[u].push_back(v); }
    void solve() {
        for (int i = 0; i < n; i++) if (!vis[i]) dfs(i);
    }
    int get_id(int x) { return idx[x]; }
    int count() { return nsc; }
}; // dag edges point from idx large to idx small

```

### 3.2 2-SAT [ca961f]

```

struct TwoSat : SCC {
    void orr(int x, int y) {
        if ((x ^ y) == 1) return;
        add_edge(x ^ 1, y); add_edge(y ^ 1, x);
    }
    vector<int> solve2sat() {
        solve(); vector<int> res(n);
        for (int i = 0; i < n; i += 2)
            if (idx[i] == idx[i + 1]) return {};
        for (int i = 0; i < n; i++)
            res[i] = idx[i] < idx[i ^ 1];
        return res;
    }
};

```

### 3.3 BCC [6ac6db]

```

class BCC {
    int n, ecnt, bcnt;
    vector<vector<pair<int, int>>> g;
    vector<int> dfn, low, bcc, stk;
    vector<bool> ap, bridge;
    void dfs(int u, int f) {
        dfn[u] = low[u] = dfn[f] + 1;
        int ch = 0;
        for (auto [v, t] : g[u]) if (bcc[t] == -1) {
            bcc[t] = 0; stk.push_back(t);

```

```

if (dfn[v]) {
    low[u] = min(low[u], dfn[v]);
    continue;
}
++ch, dfs(v, u);
low[u] = min(low[u], low[v]);
if (low[v] > dfn[u]) bridge[t] = true;
if (low[v] < dfn[u]) continue;
ap[u] = true;
while (not stk.empty()) {
    int o = stk.back(); stk.pop_back();
    bcc[o] = bcnt;
    if (o == t) break;
}
bcnt += 1;
}
ap[u] = ap[u] and (ch != 1 or u != f);
}
public:
BCC(int n_) : n(n_), ecnt(0), bcnt(0), g(n), dfn(n),
    low(n), stk(), ap(n) {}
void add_edge(int u, int v) {
    g[u].emplace_back(v, ecnt);
    g[v].emplace_back(u, ecnt++);
}
void solve() {
    bridge.assign(ecnt, false); bcc.assign(ecnt, -1);
    for (int i = 0; i < n; ++i) if (!dfn[i]) dfs(i, i);
}
int bcc_id(int x) const { return bcc[x]; }
bool is_ap(int x) const { return ap[x]; }
bool is_bridge(int x) const { return bridge[x]; }
};

```

### 3.4 Round Square Tree [cf6d74]

```

struct RST { // be careful about isolate point
    int n; vector<vector<int>> T;
    RST(auto &G) : n(G.size()), T(n) {
        vector<int> stk, vis(n), low(n);
        auto dfs = [&](auto self, int u, int d) -> void {
            low[u] = vis[u] = d; stk.push_back(u);
            for (int v : G[u]) if (!vis[v]) {
                self(self, v, d + 1);
                if (low[v] == vis[u]) {
                    int cnt = T.size(); T.emplace_back();
                    for (int x = -1; x != v; stk.pop_back())
                        T[cnt].push_back(x = stk.back());
                    T[u].push_back(cnt); // T is rooted
                } else low[u] = min(low[u], low[v]);
            } else low[u] = min(low[u], vis[v]);
        };
        for (int u = 0; u < n; u++)
            if (!vis[u]) dfs(dfs, u, 1);
    } // T may be forest; after dfs, stk are the roots
}; // test @ 2020 Shanghai K

```

### 3.5 Edge TCC [5a2668]

```

vector<vector<int>> ETCC(auto &adj) {
    const int n = static_cast<int>(adj.size());
    vector<int> up(n), low(n), in, out, nx, id;
    in = out = nx = id = vector<int>(n, -1);
    int dfc = 0, cnt = 0; Dsu dsu(n);
    auto merge = [&](int u, int v) {
        dsu.join(u, v); up[u] += up[v]; };
    auto dfs = [&](auto self, int u, int p) -> void {
        in[u] = low[u] = dfc++;
        for (int v : adj[u]) if (v != u) {
            if (v == p) { p = -1; continue; }
            if (in[v] == -1) {
                self(self, v, u);
                if (nx[v] == -1 && up[v] <= 1) {
                    up[u] += up[v]; low[u] = min(low[u], low[v]);
                    continue;
                }
            }
            if (up[v] == 0) v = nx[v];
            if (low[u] > low[v])
                low[u] = low[v], swap(nx[u], v);
            for (; v != -1; v = nx[v]) merge(u, v);
        } else if (in[v] < in[u]) {
            low[u] = min(low[u], in[v]); up[u]++;
        } else {
            for (int &x = nx[u]; x != -1 &&
                in[x] <= in[v] && in[v] < out[x]; x = nx[x])

```

```

                merge(u, x);
                up[u]--;
            }
        }
        out[u] = dfc;
    };
    for (int i = 0; i < n; i++)
        if (in[i] == -1) dfs(dfs, i, -1);
    for (int i = 0; i < n; i++)
        if (dsu.anc(i) == i) id[i] = cnt++;
    vector<vector<int>> comps(cnt);
    for (int i = 0; i < n; i++)
        comps[id[dsu.anc(i)]].push_back(i);
    return comps;
} // test @ yosupo judge

```

### 3.6 Bipolar Orientation [9d5557]

```

struct BipolarOrientation {
    int n; vector<vector<int>> g;
    vector<int> vis, low, pa, sgn, ord;
    BipolarOrientation(int n_) : n(n_),
        g(n), vis(n), low(n), pa(n, -1), sgn(n) {}
    void dfs(int i) {
        ord.push_back(i); low[i] = vis[i] = int(ord.size());
        for (int j : g[i])
            if (!vis[j])
                pa[j] = i, dfs(j), low[i] = min(low[i], low[j]);
            else
                low[i] = min(low[i], vis[j]);
    }
    vector<int> solve(int S, int T) {
        g[S].insert(g[S].begin(), T); dfs(S);
        vector<int> nxt(n, -1), prv(n, -1);
        nxt[S] = T; prv[T] = S; sgn[S] = -1;
        for (int i : ord) if (i != S && i != T) {
            int p = pa[i], l = ord[low[i] - 1];
            if (sgn[l] > 0) { // insert after
                nxt[i] = nxt[p]; prv[i] = p;
                if (nxt[p] != -1) prv[nxt[p]] = i;
                nxt[p] = i;
            } else {
                prv[i] = prv[p]; nxt[i] = p;
                if (prv[p] != -1) nxt[prv[p]] = i;
                prv[p] = i;
            }
            sgn[p] = -sgn[l];
        }
        vector<int> v;
        for (int x = S; x != -1; x = nxt[x]) v.push_back(x);
        return v;
    }
    void add_edge(int a, int b) {
        g[a].emplace_back(b); g[b].emplace_back(a);
    }
}; // codeforces.com/contest/1916/submission/244774734

```

### 3.7 DMST [f4317e]

```

using lld = int64_t;
struct E { int s, t; lld w; }; // 0-base
struct PQ {
    struct P {
        lld v; int i;
        bool operator<(const P &b) const { return v > b.v; }
    };
    min_heap<P> pq; lld tag;
    void push(P p) { p.v -= tag; pq.emplace(p); }
    P top() { P p = pq.top(); p.v += tag; return p; }
    void join(PQ &b) {
        if (pq.size() < b.pq.size())
            swap(pq, b.pq), swap(tag, b.tag);
        while (!b.pq.empty()) push(b.top()), b.pq.pop();
    }
};
vector<int> dmst(const vector<E> &e, int n, int root) {
    vector<PQ> h(n * 2);
    for (int i = 0; i < int(e.size()); ++i)
        h[e[i].t].push({e[i].w, i});
    vector<int> a(n * 2); iota(all(a), 0);
    vector<int> v(n * 2, -1), pa(n * 2, -1), r(n * 2);
    auto o = [&](auto Y, int x) -> int {
        return x == a[x] ? x : a[x] = Y(Y, a[x]); };
    auto S = [&](int i) { return o(o, e[i].s); };
    int pc = v[root] = n;

```



```

for (int i = 0; i < n; ++i) if (v[i] == -1)
    for (int p = i; v[p]<0 || v[p]==i; p = S(r[p])) {
        if (v[p] == i)
            for (int q = pc++; p != q; p = S(r[p])) {
                h[p].tag -= h[p].top().v; h[q].join(h[p]);
                pa[p] = a[p] = q;
            }
        while (S(h[p].top().i) == p) h[p].pq.pop();
        v[p] = i; r[p] = h[p].top().i;
    }
vector<int> ans;
for (int i = pc - 1; i >= 0; i--) if (v[i] != n) {
    for (int f = e[r[i]].t; f!=-1 && v[f]!=n; f = pa[f])
        v[f] = n;
    ans.push_back(r[i]);
}
return ans; // default minimize, returns edgeid array
}

```

### 3.8 Dominator Tree [ea5b7c]

```

struct Dominator {
    vector<vector<int>>> g, r, rdom; int tk;
    vector<int> dfn, rev, fa, sdom, dom, val, rp;
    Dominator(int n) : g(n), r(n), rdom(n), tk(0) {
        dfn = rev = fa = sdom = dom =
            val = rp = vector<int>(n, -1); }
    void add_edge(int x, int y) { g[x].push_back(y); }
    void dfs(int x) {
        rev[dfn[x] = tk] = x;
        fa[tk] = sdom[tk] = val[tk] = tk; tk++;
        for (int u : g[x]) {
            if (dfn[u] == -1) dfs(u), rp[dfn[u]] = dfn[x];
            r[dfn[u]].push_back(dfn[x]);
        }
    }
    void merge(int x, int y) { fa[x] = y; }
    int find(int x, int c = 0) {
        if (fa[x] == x) return c ? -1 : x;
        if (int p = find(fa[x], 1); p != -1) {
            if (sdom[val[x]] > sdom[val[fa[x]]])
                val[x] = val[fa[x]];
            fa[x] = p;
            return c ? p : val[x];
        } else return c ? fa[x] : val[x];
    }
    vector<int> build(int s, int n) {
        // return the father of each node in dominator tree
        dfs(s); // p[i] = -2 if i is unreachable from s
        for (int i = tk - 1; i >= 0; --i) {
            for (int u : r[i])
                sdom[i] = min(sdom[i], sdom[find(u)]);
            if (i) rdom[sdom[i]].push_back(i);
            for (int u : rdom[i]) {
                int p = find(u);
                dom[u] = (sdom[p] == i ? i : p);
            }
            if (i) merge(i, rp[i]);
        }
        vector<int> p(n, -2); p[s] = -1;
        for (int i = 1; i < tk; ++i)
            if (sdom[i] != dom[i]) dom[i] = dom[dom[i]];
        for (int i = 1; i < tk; ++i)
            p[rev[i]] = rev[dom[i]];
        return p;
    } // test @ yosupo judge
};

```

### 3.9 Edge Coloring [029763]

```

// max(d_u) + 1 edge coloring, time: O(NM)
int C[kN][kN], G[kN][kN]; // 1-based, G: ans
void clear(int N) {
    for (int i = 0; i <= N; i++)
        for (int j = 0; j <= N; j++)
            C[i][j] = G[i][j] = 0;
}
void solve(vector<pair<int, int>> &E, int N) {
    int X[kN] = {}, a;
    auto update = [&](int u) {
        for (X[u] = 1; C[u][X[u]]; X[u]++);
    };
    auto color = [&](int u, int v, int c) {
        int p = G[u][v];
        G[u][v] = G[v][u] = c;
    };
}

```

```

C[u][c] = v, C[v][c] = u;
C[u][p] = C[v][p] = 0;
if (p) X[u] = X[v] = p;
else update(u), update(v);
return p;
};
auto flip = [&](int u, int c1, int c2) {
    int p = C[u][c1];
    swap(C[u][c1], C[u][c2]);
    if (p) G[u][p] = G[p][u] = c2;
    if (!C[u][c1]) X[u] = c1;
    if (!C[u][c2]) X[u] = c2;
    return p;
};
for (int i = 1; i <= N; i++) X[i] = 1;
for (int t = 0; t < E.size(); t++) {
    auto [u, v] = E[t];
    int v0 = v, c = X[u], c0 = c, d;
    vector<pair<int, int>> L; int vst[kN] = {};
    while (!G[u][v0]) {
        L.emplace_back(v, d = X[v]);
        if (!C[v][c]) for (a=L.size()-1; a>=0; a--)
            c = color(u, L[a].first, c);
        else if (!C[u][d]) for (a=L.size()-1; a>=0; a--)
            color(u, L[a].first, L[a].second);
        else if (vst[d]) break;
        else vst[d] = 1, v = C[u][d];
    }
    if (!G[u][v0]) {
        for (; v; v = flip(v, c, d), swap(c, d));
        if (C[u][c0]) { a = int(L.size()) - 1;
            while (--a >= 0 && L[a].second != c);
            for (; a>=0; a--) color(u, L[a].first, L[a].second);
        } else t--;
    }
}
}

```

### 3.10 Centroid Decomp. [670cdd]

```

class Centroid {
    vector<vector<pair<int, int>>> g; // g[u] = {(v, w)}
    vector<int> pa, dep, vis, sz, mx;
    vector<vector<int64_t>> Dist;
    vector<int64_t> Sub, Sub2;
    vector<int> Cnt, Cnt2;
    void DfsSz(vector<int> &tmp, int x) {
        vis[x] = true, sz[x] = 1, mx[x] = 0;
        for (auto [u, w] : g[x]) if (not vis[u]) {
            DfsSz(tmp, u); sz[x] += sz[u];
            mx[x] = max(mx[x], sz[u]);
        }
        tmp.push_back(x);
    }
    void DfsDist(int x, int64_t D = 0) {
        Dist[x].push_back(D); vis[x] = true;
        for (auto [u, w] : g[x])
            if (not vis[u]) DfsDist(u, D + w);
    }
    void DfsCen(int x, int D, int p) {
        vector<int> tmp; DfsSz(tmp, x);
        int M = int(tmp.size()), C = -1;
        for (int u : tmp)
            if (max(M - sz[u], mx[u]) * 2 <= M) C = u;
        for (int u : tmp) vis[u] = false;
        DfsDist(C);
        for (int u : tmp) vis[u] = false;
        pa[C] = p, vis[C] = true, dep[C] = D;
        for (auto [u, w] : g[C])
            if (not vis[u]) DfsCen(u, D + 1, C);
    }
public:
    Centroid(int N) : g(N), pa(N), dep(N),
        vis(N), sz(N), mx(N), Dist(N),
        Sub(N), Sub2(N), Cnt(N), Cnt2(N) {}
    void AddEdge(int u, int v, int w) {
        g[u].emplace_back(v, w);
        g[v].emplace_back(u, w);
    }
    void Build() { DfsCen(0, 0, -1); }
    void Mark(int v) {
        int x = v, z = -1;
        for (int i = dep[v]; i >= 0; --i) {

```

```

    Sub[x] += Dist[v][i], Cnt[x]++;
    if (z != -1)
        Sub2[z] += Dist[v][i], Cnt2[z]++;
    x = pa[z = x];
}
}
int64_t Query(int v) {
    int64_t res = 0;
    int x = v, z = -1;
    for (int i = dep[v]; i >= 0; --i) {
        res += Sub[x] + 1LL * Cnt[x] * Dist[v][i];
        if (z != -1)
            res -= Sub2[z] + 1LL * Cnt2[z] * Dist[v][i];
        x = pa[z = x];
    }
    return res;
}
}; // pa, dep are centroid tree attributes

```

### 3.11 Lowbit Decomp. [d1d724]

```

class LBD {
    int timer, chains;
    vector<vector<int>>> G;
    vector<int> tl, tr, chain, head, dep, pa;
    // chains : number of chain
    // tl, tr[u] : subtree interval in the seq. of u
    // head[i] : head of the chain i
    // chain[u] : chain id of the chain u is on
    void predfs(int u, int f) {
        dep[u] = dep[pa[u] = f] + 1;
        for (int v : G[u]) if (v != f) {
            predfs(v, u);
            if (lowbit(chain[u]) < lowbit(chain[v]))
                chain[u] = chain[v];
        }
        if (chain[u] == 0) chain[u] = ++chains;
    }
    void dfschain(int u, int f) {
        tl[u] = timer++;
        if (head[chain[u]] == -1)
            head[chain[u]] = u;
        for (int v : G[u])
            if (v != f and chain[v] == chain[u])
                dfschain(v, u);
        for (int v : G[u])
            if (v != f and chain[v] != chain[u])
                dfschain(v, u);
        tr[u] = timer;
    }
public:
    LBD(auto &&G_) : n((int)size(G_)),
        timer(0), chains(0), G(G_), tl(n), tr(n),
        chain(n), head(n + 1, -1), dep(n), pa(n)
    { predfs(0, 0); dfschain(0, 0); }
    PII get_subtree(int u) { return {tl[u], tr[u]}; }
    vector<PII> get_path(int u, int v) {
        vector<PII> res;
        while (chain[u] != chain[v]) {
            if (dep[head[chain[u]]] < dep[head[chain[v]]])
                swap(u, v);
            int s = head[chain[u]];
            res.emplace_back(tl[s], tl[u] + 1);
            u = pa[s];
        }
        if (dep[u] < dep[v]) swap(u, v);
        res.emplace_back(tl[v], tl[u] + 1);
        return res;
    }
}; // 記得在資結上對點的修改要改成對其 dfs 序的修改

```

### 3.12 Virtual Tree [ad5cf5]

```

vector<pair<int, int>> build(vector<int> vs, int r) {
    vector<pair<int, int>> res;
    sort(vs.begin(), vs.end(), [](int i, int j) {
        return dfn[i] < dfn[j]; });
    vector<int> s = {r};
    for (int v : vs) if (v != r) {
        if (int o = lca(v, s.back()); o != s.back()) {
            while (s.size() >= 2) {
                if (dfn[s[s.size() - 2]] < dfn[o]) break;
                res.emplace_back(s[s.size() - 2], s.back());
                s.pop_back();
            }
        }
    }
}

```

```

    if (s.back() != o) {
        res.emplace_back(o, s.back());
        s.back() = o;
    }
}
s.push_back(v);
}
for (size_t i = 1; i < s.size(); ++i)
    res.emplace_back(s[i - 1], s[i]);
return res; // (x, y): x->y
}

```

### 3.13 Tree Hashing [d6a9f9]

```

vector<int> g[maxn]; ll u h[maxn];
ll F(ll u) { // xorshift64star from iwiwi
    z ^= z >> 12; z ^= z << 25; z ^= z >> 27;
    return z * 2685821657736338717LL;
}
ll hsah(int u, int f) {
    ll r = 127; // bigger?
    for (int v : g[u]) if (v != f) r += hsah(v, u);
    return h[u] = F(r);
} // test @ UOJ 763 & yosupo library checker

```

### 3.14 Mo's Algo on Tree

```

dfs u:
    push u
    iterate subtree
    push u
Let P = LCA(u, v) with St(u) <= St(v)
if (P == u) query[St(u), St(v)]
else query[Ed(u), St(v)], query[St(P), St(P)]

```

### 3.15 Count Cycles [c7e8f2]

```

// ord = sort by deg decreasing, rk[ord[i]] = i
// D[i] = edge point from rk small to rk big
for (int x : ord) { // c3
    for (int y : D[x]) vis[y] = 1;
    for (int y : D[x]) for (int z : D[y]) c3 += vis[z];
    for (int y : D[x]) vis[y] = 0;
}
for (int x : ord) { // c4
    for (int y : D[x]) for (int z : adj[y])
        if (rk[z] > rk[x]) c4 += vis[z]++;
    for (int y : D[x]) for (int z : adj[y])
        if (rk[z] > rk[x]) --vis[z];
} // both are O(M*sqrt(M)), test @ 2022 CCPC guangzhou

```

### 3.16 MaximalClique [293730]

```

// contain a self loop u to u, than u won't in clique
template <size_t maxn> class MaxClique {
private:
    using bits = bitset<maxn>;
    bits popped, G[maxn], ans;
    size_t deg[maxn], deo[maxn], n;
    void sort_by_degree() {
        popped.reset();
        for (size_t i = 0; i < n; ++i)
            deg[i] = G[i].count();
        for (size_t i = 0; i < n; ++i) {
            size_t mi = maxn, id = 0;
            for (size_t j = 0; j < n; ++j)
                if (not popped[j] and deg[j] < mi)
                    mi = deg[id = j];
            popped[deo[i] = id] = 1;
            for (size_t u = G[id]._Find_first(); u < n;
                u = G[id]._Find_next(u))
                --deg[u];
        }
    }
    void BK(bits R, bits P, bits X) {
        if (R.count() + P.count() <= ans.count()) return;
        if (not P.count() and not X.count()) {
            if (R.count() > ans.count()) ans = R;
            return;
        }
        /* greedily choose max degree as pivot
        bits cur = P | X; size_t pivot = 0, sz = 0;
        for (size_t u = cur._Find_first();
            u < n; u = cur._Find_next(u))
            if (deg[u] > sz) sz = deg[pivot = u];
        cur = P & (~G[pivot]);
        */ // or simply choose first
        bits cur = P & (~G[P | X]._Find_first());
        for (size_t u = cur._Find_first(); u < n;

```

```

    u = cur._Find_next(u)) {
    if (R[u]) continue;
    R[u] = 1;
    BK(R, P & G[u], X & G[u]);
    R[u] = P[u] = 0, X[u] = 1;
}
}
public:
void init(size_t n_) {
    n = n_;
    for (size_t i = 0; i < n; ++i) G[i].reset();
    ans.reset();
}
void add_edges(int u, bits S) { G[u] = S; }
void add_edge(int u, int v) { G[u][v] = G[v][u] = 1; }
int solve() {
    sort_by_degree(); // or simply iota( deo... )
    for (size_t i = 0; i < n; ++i)
        deg[i] = G[i].count();
    bits pob, nob = 0; pob.set();
    for (size_t i = n; i < maxn; ++i) pob[i] = 0;
    for (size_t i = 0; i < n; ++i) {
        size_t v = deo[i];
        bits tmp;
        tmp[v] = 1;
        BK(tmp, pob & G[v], nob & G[v]);
        pob[v] = 0, nob[v] = 1;
    }
    return static_cast<int>(ans.count());
}
};

```

### 3.17 MaximumClique [aee5d8]

```

constexpr size_t KN = 150; using bits = bitset<KN>;
struct MaxClique {
    bits G[KN], cs[KN];
    int ans, sol[KN], q, cur[KN], d[KN], n;
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i) G[i].reset();
    }
    void add_edge(int u, int v) { G[u][v] = G[v][u] = 1; }
    void pre_dfs(vector<int> &v, int i, bits mask) {
        if (i < 4) {
            for (int x : v) d[x] = (int)(G[x] & mask).count();
            sort(all(v), [&](int x, int y) {
                return d[x] > d[y]; });
        }
        vector<int> c(v.size());
        cs[1].reset(), cs[2].reset();
        int l = max(ans - q + 1, 1), r = 2, tp = 0, k;
        for (int p : v) {
            for (k = 1; (cs[k] & G[p]).any(); ++k);
            if (k >= r) cs[++r].reset();
            cs[k][p] = 1;
            if (k < l) v[tp++] = p;
        }
        for (k = l; k < r; ++k)
            for (auto p = cs[k]._Find_first();
                 p < KN; p = cs[k]._Find_next(p))
                v[tp] = (int)p, c[tp] = k, ++tp;
        dfs(v, c, i + 1, mask);
    }
    void dfs(vector<int> &v, vector<int> &c,
            int i, bits mask) {
        while (!v.empty()) {
            int p = v.back(); v.pop_back(); mask[p] = 0;
            if (q + c.back() <= ans) return;
            cur[q++] = p;
            vector<int> nr;
            for (int x : v) if (G[p][x]) nr.push_back(x);
            if (!nr.empty()) pre_dfs(nr, i, mask & G[p]);
            else if (q > ans) ans = q, copy_n(cur, q, sol);
            c.pop_back(); --q;
        }
    }
    int solve() {
        vector<int> v(n); iota(all(v), 0);
        ans = q = 0; pre_dfs(v, 0, bits(string(n, '1')));
        return ans; // sol[0 ~ ans-1]
    }
} cliq; // test@ yosupo judge

```

### 3.18 Min Mean Cycle [e23bc0]

```

// WARNING: TYPE matters
struct Edge { int s, t; llf c; };
llf solve(vector<Edge> &e, int n) {
    // O(VE), returns inf if no cycle, mmc otherwise
    vector<VI> prv(n + 1, VI(n)), prve = prv;
    vector<vector<llf>> d(n + 1, vector<llf>(n, inf));
    d[0] = vector<llf>(n, 0);
    for (int i = 0; i < n; i++) {
        for (int j = 0; j < (int)e.size(); j++) {
            auto [s, t, c] = e[j];
            if (d[i][s] < inf && d[i + 1][t] > d[i][s] + c) {
                d[i + 1][t] = d[i][s] + c;
                prv[i + 1][t] = s; prve[i + 1][t] = j;
            }
        }
    }
    llf mmc = inf; int st = -1;
    for (int i = 0; i < n; i++) {
        llf avg = -inf;
        for (int k = 0; k < n; k++) {
            if (d[n][i] < inf - eps)
                avg = max(avg, (d[n][i] - d[k][i]) / (n - k));
            else avg = inf;
        }
        if (avg < mmc) tie(mmc, st) = tie(avg, i);
    }
    if (st == -1) return inf;
    vector<int> vst(n), eid, cycle, rho;
    for (int i = n; !vst[st]; st = prv[i--][st]) {
        vst[st]++; eid.emplace_back(prve[i][st]);
        rho.emplace_back(st);
    }
    while (vst[st] != 2) {
        int v = rho.back(); rho.pop_back();
        cycle.emplace_back(v); vst[v]++;
    }
    reverse(all(eid)); eid.resize(cycle.size());
    return mmc;
}

```

## 4 Flow & Matching

### 4.1 HopcroftKarp [930040]

```

struct HK {
    vector<int> l, r, a, p; int ans;
    HK(int n, int m, auto &g) : l(n, -1), r(m, -1), ans(0) {
        for (bool match = true; match;) {
            match = false; a.assign(n, -1); p.assign(m, -1);
            queue<int> q;
            for (int i = 0; i < n; i++)
                if (l[i] == -1) q.push(a[i] = p[i] = i);
            // bitset<maxn> nvis, t; nvis.set();
            while (!q.empty()) {
                int z, x = q.front(); q.pop();
                if (l[a[x]] != -1) continue;
                for (int y : g[x]) { // or iterate t = g[x]&nvis
                    // nvis.reset(y);
                    if (r[y] == -1) {
                        for (z = y; z != -1; )
                            r[z] = x, swap(l[x], z), x = p[x];
                        match = true; ++ans; break;
                    } else if (p[r[y]] == -1)
                        q.push(z = r[y]), p[z] = x, a[z] = a[x];
                }
            }
        }
    }
};

```

### 4.2 Kuhn Munkres [2c09ed]

```

struct KM { // maximize, test @ UOJ 80
    int n, l, r; lld ans; // fl and fr are the match
    vector<lld> hl, hr; vector<int> fl, fr, pre, q;
    void bfs(const auto &w, int s) {
        vector<int> vl(n), vr(n); vector<lld> slk(n, INF);
        l = r = 0; vr[q[r++] = s] = true;
        const auto check = [&](int x) -> bool {
            if (vl[x] || slk[x] > 0) return true;
            vl[x] = true; slk[x] = INF;
            if (fl[x] != -1) return vr[q[r++] = fl[x]] = true;
            while (x != -1) swap(x, fr[fl[x] = pre[x]]);
            return false;
        };
    }
};

```

```

while (true) {
    while (l < r)
        for (int x = 0, y = q[l++]; x < n; ++x) if (!vl[x])
            if (chmin(slk[x], hl[x] + hr[y] - w[x][y]))
                if (pre[x] = y, !check(x)) return;
        lld d = ranges::min(slk);
        for (int x = 0; x < n; ++x)
            vl[x] ? hl[x] += d : slk[x] -= d;
        for (int x = 0; x < n; ++x) if (vr[x]) hr[x] -= d;
        for (int x = 0; x < n; ++x) if (!check(x)) return;
    }
}
KM(int n_, const auto &w) : n(n_), ans(0),
    hl(n), hr(n), fl(n, -1), fr(fl), pre(n), q(n) {
    for (int i = 0; i < n; ++i) hl[i] = ranges::max(w[i]);
    for (int i = 0; i < n; ++i) bfs(w, i);
    for (int i = 0; i < n; ++i) ans += w[i][fl[i]];
}
};

```

### 4.3 Flow Models

- Maximum/Minimum flow with lower bound / Circulation problem
  - Construct super source  $S$  and sink  $T$ .
  - For each edge  $(x, y, l, u)$ , connect  $x \rightarrow y$  with capacity  $u - l$ .
  - For each vertex  $v$ , denote by  $in(v)$  the difference between the sum of incoming lower bounds and the sum of outgoing lower bounds.
  - If  $in(v) > 0$ , connect  $S \rightarrow v$  with capacity  $in(v)$ , otherwise, connect  $v \rightarrow T$  with capacity  $-in(v)$ .
    - To maximize, connect  $t \rightarrow s$  with capacity  $\infty$  (skip this in circulation problem), and let  $f$  be the maximum flow from  $S$  to  $T$ . If  $f \neq \sum_{v \in V, in(v) > 0} in(v)$ , there's no solution. Otherwise, the maximum flow from  $s$  to  $t$  is the answer. Also,  $f$  is a mincost valid flow.
    - To minimize, let  $f$  be the maximum flow from  $S$  to  $T$ . Connect  $t \rightarrow s$  with capacity  $\infty$  and let the flow from  $S$  to  $T$  be  $f'$ . If  $f + f' \neq \sum_{v \in V, in(v) > 0} in(v)$ , there's no solution. Otherwise,  $f'$  is the answer.
  - The solution of each edge  $e$  is  $l_e + f_e$ , where  $f_e$  corresponds to the flow of edge  $e$  on the graph.
- Construct minimum vertex cover from maximum matching  $M$  on bipartite graph  $(X, Y)$ 
  - Redirect every edge:  $y \rightarrow x$  if  $(x, y) \in M$ ,  $x \rightarrow y$  otherwise.
  - DFS from unmatched vertices in  $X$ .
  - $x \in X$  is chosen iff  $x$  is unvisited;  $y \in Y$  is chosen iff  $y$  is visited.
- Minimum cost cyclic flow
  - Construct super source  $S$  and sink  $T$
  - For each edge  $(x, y, c)$ , connect  $x \rightarrow y$  with  $(cost, cap) = (c, 1)$  if  $c > 0$ , otherwise connect  $y \rightarrow x$  with  $(cost, cap) = (-c, 1)$
  - For each edge with  $c < 0$ , sum these cost as  $K$ , then increase  $d(y)$  by 1, decrease  $d(x)$  by 1
  - For each vertex  $v$  with  $d(v) > 0$ , connect  $S \rightarrow v$  with  $(cost, cap) = (0, d(v))$
  - For each vertex  $v$  with  $d(v) < 0$ , connect  $v \rightarrow T$  with  $(cost, cap) = (0, -d(v))$
  - Flow from  $S$  to  $T$ , the answer is the cost of the flow  $C + K$
- Maximum density induced subgraph
  - Binary search on answer, suppose we're checking answer  $T$
  - Construct a max flow model, let  $K$  be the sum of all weights
  - Connect source  $s \rightarrow v, v \in G$  with capacity  $K$
  - For each edge  $(u, v, w)$  in  $G$ , connect  $u \rightarrow v$  and  $v \rightarrow u$  with capacity  $w$
  - For  $v \in G$ , connect it with sink  $v \rightarrow t$  with capacity  $K + 2T - (\sum_{e \in E(v)} w(e)) - 2w(v)$
  - $T$  is a valid answer if the maximum flow  $f < K|V|$
- Minimum weight edge cover
  - For each  $v \in V$  create a copy  $v'$ , and connect  $u' \rightarrow v'$  with weight  $w(u, v)$ .
  - Connect  $v \rightarrow v'$  with weight  $2\mu(v)$ , where  $\mu(v)$  is the cost of the cheapest edge incident to  $v$ .
  - Find the minimum weight perfect matching on  $G'$ .
- Project selection cheat sheet:  $S, T$  分別代表 0, 1 側，最小化總花費。
 

$i$ 為 0 時花費 $c$	$(i, T, c)$
$i$ 為 1 時花費 $c$	$(S, i, c)$
$i \in I$ 有任何一個為 0 時花費 $c$	$(i, w, \infty), (w, T, c)$
$i \in I$ 有任何一個為 1 時花費 $c$	$(S, w, c), (w, i, \infty)$
$i$ 為 0 時得到 $c$	直接得到 $c; (S, i, c)$
$i$ 為 1 時得到 $c$	直接得到 $c; (i, T, c)$
$i$ 為 0, $j$ 為 1 時花費 $c$	$(i, j, c)$
$i, j$ 不同時花費 $c$	$(i, j, c), (j, i, c)$
$i, j$ 同時是 0 時得到 $c$	直接得到 $c; (S, w, c), (w, i, \infty), (w, j, \infty)$
$i, j$ 同時是 1 時得到 $c$	直接得到 $c; (i, w, \infty), (j, w, \infty), (w, T, c)$
- Submodular functions minimization
  - For a function  $f: 2^V \rightarrow \mathbb{R}$ ,  $f$  is a submodular function iff
    - $\forall S, T \subseteq V, f(S) + f(T) \geq f(S \cup T) + f(S \cap T)$ , or
    - $\forall X \subseteq Y \subseteq V, x \notin Y, f(X \cup \{x\}) - f(X) \geq f(Y \cup \{x\}) - f(Y)$ .
  - To minimize  $\sum_i \theta_i(x_i) + \sum_{i < j} \phi_{ij}(x_i, x_j) + \sum_{i < j < k} \psi_{ijk}(x_i, x_j, x_k)$
  - If  $\theta_i(1) \geq \theta_i(0)$ , add edge  $(S, i, \theta_i(1) - \theta_i(0))$  and  $\theta_i(0)$  to answer; otherwise,  $(i, T, \theta_i(0) - \theta_i(1))$  and  $\theta_i(1)$ .
  - Add edges  $(i, j, \phi_{ij}(0, 1) + \phi_{ij}(1, 0) - \phi_{ij}(0, 0) - \phi_{ij}(1, 1))$ .
  - Denote  $x_{ijk}$  as helper nodes. Let  $P = \psi_{ijk}(0, 0, 0) + \psi_{ijk}(0, 1, 1) + \psi_{ijk}(1, 1, 0) - \psi_{ijk}(0, 0, 1) - \psi_{ijk}(0, 1, 0) - \psi_{ijk}(1, 0, 0) - \psi_{ijk}(1, 1, 1)$ . Add  $-P$  to answer. If  $P \geq 0$ , add edges  $(i, x_{ijk}, P), (j, x_{ijk}, P), (k, x_{ijk}, P), (x_{ijk}, T, P)$ ; otherwise  $(x_{ijk}, i, -P), (x_{ijk}, j, -P), (x_{ijk}, k, -P), (S, x_{ijk}, -P)$ .
  - The minimum cut of this graph will be the the minimum value of the

function above.

### 4.4 Dinic [32c53e]

```

template <typename Cap = int64_t> class Dinic {
private:
    struct E { int to, rev; Cap cap; }; int n, st, ed;
    vector<vector<E>> G; vector<size_t> lv, idx;
    bool BFS(int k) {
        lv.assign(n, 0); idx.assign(n, 0);
        queue<int> bfs; bfs.push(st); lv[st] = 1;
        while (not bfs.empty() and not lv[ed]) {
            int u = bfs.front(); bfs.pop();
            for (auto e: G[u]) if (e.cap >> k and !lv[e.to])
                bfs.push(e.to), lv[e.to] = lv[u] + 1;
        }
        return lv[ed];
    }
    Cap DFS(int u, Cap f = numeric_limits<Cap>::max()) {
        if (u == ed) return f;
        Cap ret = 0;
        for (auto &i = idx[u]; i < G[u].size(); ++i) {
            auto &[to, rev, cap] = G[u][i];
            if (cap <= 0 or lv[to] != lv[u] + 1) continue;
            Cap nf = DFS(to, min(f, cap));
            ret += nf; cap -= nf; f -= nf;
            G[to][rev].cap += nf;
            if (f == 0) return ret;
        }
        if (ret == 0) lv[u] = 0;
        return ret;
    }
public:
    void init(int n_) { G.assign(n = n_, vector<E>()); }
    void add_edge(int u, int v, Cap c) {
        G[u].push_back({v, int(G[v].size()), c});
        G[v].push_back({u, int(G[u].size())-1, 0});
    }
    Cap max_flow(int st_, int ed_) {
        st = st_, ed = ed_; Cap ret = 0;
        for (int i = 63; i >= 0; --i)
            while (BFS(i)) ret += DFS(st);
        return ret;
    }
}; // test @ luogu P3376

```

### 4.5 HLPP [198e4e]

```

template <typename T> struct HLPP {
    struct Edge { int to, rev; T flow, cap; };
    int n, mx; vector<vector<Edge>> adj; vector<T> excess;
    vector<int> d, cnt, active; vector<vector<int>> B;
    void add_edge(int u, int v, int f) {
        Edge a{v, (int)size(adj[v]), 0, f};
        Edge b{u, (int)size(adj[u]), 0, 0};
        adj[u].push_back(a), adj[v].push_back(b);
    }
    void enqueue(int v) {
        if (!active[v] && excess[v] > 0 && d[v] < n) {
            mx = max(mx, d[v]);
            B[d[v]].push_back(v); active[v] = 1;
        }
    }
    void push(int v, Edge &e) {
        T df = min(excess[v], e.cap - e.flow);
        if (df <= 0 || d[v] != d[e.to] + 1) return;
        e.flow += df, adj[e.to][e.rev].flow -= df;
        excess[e.to] += df, excess[v] -= df;
        enqueue(e.to);
    }
    void gap(int k) {
        for (int v = 0; v < n; v++) if (d[v] >= k)
            cnt[d[v]]--, d[v] = n, cnt[d[v]]++;
    }
    void relabel(int v) {
        cnt[d[v]]--; d[v] = n;
        for (auto e: adj[v])
            if (e.cap > e.flow) d[v] = min(d[v], d[e.to] + 1);
        cnt[d[v]]++; enqueue(v);
    }
    void discharge(int v) {
        for (auto &e: adj[v])
            if (excess[v] > 0) push(v, e);
        else break;
        if (excess[v] <= 0) return;
    }
};

```



```

    if (cnt[d[v]] == 1) gap(d[v]);
    else relabel(v);
}
T max_flow(int s, int t) {
    for (auto &e : adj[s]) excess[s] += e.cap;
    cnt[0] = n; enqueue(s); active[t] = 1;
    for (mx = 0; mx >= 0; )
        if (!B[mx].empty()) {
            int v = B[mx].back(); B[mx].pop_back();
            active[v] = 0; discharge(v);
        } else --mx;
    return excess[t];
}
HLPP(int _n) : n(_n), adj(n), excess(n),
    d(n), cnt(n + 1), active(n), B(n) {}
};

```

#### 4.6 Global Min-Cut [ae7013]

```

void add_edge(auto &w, int u, int v, int c) {
    w[u][v] += c; w[v][u] += c; }
auto phase(const auto &w, int n, vector<int> id) {
    vector<int> g(n); int s = -1, t = -1;
    while (!id.empty()) {
        int c = -1;
        for (int i : id) if (c == -1 || g[i] > g[c]) c = i;
        s = t; t = c;
        id.erase(ranges::find(id, c));
        for (int i : id) g[i] += w[c][i];
    }
    return tuple{s, t, g[t]};
}
lld mincut(auto w, int n) {
    lld cut = numeric_limits<lld>::max();
    vector<int> id(n); iota(all(id), 0);
    for (int i = 0; i < n - 1; ++i) {
        auto [s, t, gt] = phase(w, n, id);
        id.erase(ranges::find(id, t));
        cut = min(cut, gt);
        for (int j = 0; j < n; ++j)
            w[s][j] += w[t][j], w[j][s] += w[j][t];
    }
    return cut;
} // O(V^3), can be O(VE + V^2 log V)?

```

#### 4.7 GomoryHu Tree [5edb29]

```

vector<tuple<int, int, int>> GomoryHu(int n) {
    vector<tuple<int, int, int>> rt;
    vector<int> g(n);
    for (int i = 1; i < n; ++i) {
        int t = g[i];
        auto f = flow;
        rt.emplace_back(f.max_flow(i, t), i, t);
        f.walk(i); // bfs points that connected to i (use
            edges with .cap > 0)
        for (int j = i + 1; j < n; ++j)
            if (g[j] == t && f.connect(j)) // check if i can reach j
                g[j] = i;
    }
    return rt;
}
/* for our dinic:
 * void walk(int) { BFS(0); }
 * bool connect(int i) { return lv[i]; } */

```

#### 4.8 MCMF [04f9cb]

```

template <typename F, typename C> class MCMF {
    static constexpr F INF_F = numeric_limits<F>::max();
    static constexpr C INF_C = numeric_limits<C>::max();
    struct E { int to, r; F f; C c; };
    vector<vector<E>> g; vector<pair<int, int>> f;
    vector<bool> inq; vector<F> up; vector<C> d;
    optional<pair<F, C>> step(int S, int T) {
        queue<int> q;
        for (q.push(S), d[S] = 0, up[S] = INF_F;
            not q.empty(); q.pop()) {
            int u = q.front(); inq[u] = false;
            if (up[u] == 0) continue;
            for (int i = 0; i < int(g[u].size()); ++i) {
                auto e = g[u][i]; int v = e.to;
                if (e.f <= 0 or d[v] <= d[u] + e.c) continue;
                d[v] = d[u] + e.c; f[v] = {u, i};
                up[v] = min(up[u], e.f);
                if (not inq[v]) q.push(v);
                inq[v] = true;
            }
        }
    }
};

```

```

    }
}
if (d[T] == INF_C) return nullopt;
for (int i = T; i != S; i = f[i].first) {
    auto &eg = g[f[i].first][f[i].second];
    eg.f -= up[T]; g[eg.to][eg.r].f += up[T];
}
return pair{up[T], d[T]};
}
public:
MCMF(int n) : g(n), f(n), inq(n), up(n), d(n, INF_C) {}
void add_edge(int s, int t, F c, C w) {
    g[s].emplace_back(t, int(g[t].size()), c, w);
    g[t].emplace_back(s, int(g[s].size()) - 1, 0, -w);
}
pair<F, C> solve(int a, int b) {
    F c = 0; C w = 0;
    while (auto r = step(a, b)) {
        c += r->first, w += r->first * r->second;
        ranges::fill(inq, false); ranges::fill(d, INF_C);
    }
    return {c, w};
}
};

```

#### 4.9 Dijkstra Cost Flow [d0cfd9]

```

template <typename F, typename C> class MCMF {
    static constexpr F INF_F = numeric_limits<F>::max();
    static constexpr C INF_C = numeric_limits<C>::max();
    struct E { int to, r; F f; C c; };
    vector<vector<E>> g; vector<pair<int, int>> f;
    vector<F> up; vector<C> d, h;
    optional<pair<F, C>> step(int S, int T) {
        priority_queue<pair<C, int>> q;
        q.emplace(d[S] = 0, S), up[S] = INF_F;
        while (not q.empty()) {
            auto [l, u] = q.top(); q.pop();
            if (up[u] == 0 or l != -d[u]) continue;
            for (int i = 0; i < int(g[u].size()); ++i) {
                auto e = g[u][i]; int v = e.to;
                auto nd = d[u] + e.c + h[u] - h[v];
                if (e.f <= 0 or d[v] <= nd) continue;
                f[v] = {u, i}; up[v] = min(up[u], e.f);
                q.emplace(-(d[v] = nd), v);
            }
        }
        if (d[T] == INF_C) return nullopt;
        for (size_t i = 0; i < d.size(); ++i) h[i] += d[i];
        for (int i = T; i != S; i = f[i].first) {
            auto &eg = g[f[i].first][f[i].second];
            eg.f -= up[T]; g[eg.to][eg.r].f += up[T];
        }
        return pair{up[T], h[T]};
    }
public:
MCMF(int n) : g(n), f(n), up(n), d(n, INF_C) {}
void add_edge(int s, int t, F c, C w) {
    g[s].emplace_back(t, int(g[t].size()), c, w);
    g[t].emplace_back(s, int(g[s].size()) - 1, 0, -w);
}
pair<F, C> solve(int a, int b) {
    h.assign(g.size(), 0);
    F c = 0; C w = 0;
    while (auto r = step(a, b)) {
        c += r->first, w += r->first * r->second;
        fill(d.begin(), d.end(), INF_C);
    }
    return {c, w};
}
};

```

#### 4.10 Min Cost Circulation [3f7d84]

```

template <typename F, typename C>
struct MinCostCirculation {
    struct ep { int to; F flow; C cost; };
    int n; vector<int> vis; int visc;
    vector<int> fa, fae; vector<vector<int>> g;
    vector<ep> e; vector<C> pi;
    MinCostCirculation(int n_) : n(n_), vis(n), visc(0), g(
        n), pi(n) {}
    void add_edge(int u, int v, F fl, C cs) {
        g[u].emplace_back((int)e.size());
        e.emplace_back(v, fl, cs);
    }
};

```

```

    g[v].emplace_back((int)e.size());
    e.emplace_back(u, 0, -cs);
}
C phi(int x) {
    if (fa[x] == -1) return 0;
    if (vis[x] == visc) return pi[x];
    vis[x] = visc;
    return pi[x] = phi(fa[x]) - e[fae[x]].cost;
}
int lca(int u, int v) {
    for (; u != -1 || v != -1; swap(u, v)) if (u != -1) {
        if (vis[u] == visc) return u;
        vis[u] = visc;
        u = fa[u];
    }
    return -1;
}
void pushflow(int x, C &cost) {
    int v = e[x ^ 1].to, u = e[x].to;
    ++visc;
    if (int w = lca(u, v); w == -1) {
        while (v != -1)
            swap(x ^ 1, fae[v]), swap(u, fa[v]), swap(u, v);
    } else {
        int z = u, dir = 0; F f = e[x].flow;
        vector<int> cyc = {x};
        for (int d : {0, 1})
            for (int i = (d ? u : v); i != w; i = fa[i]) {
                cyc.push_back(fae[i] ^ d);
                if (chmin(f, e[fae[i] ^ d].flow)) z = i, dir = d;
            }
        for (int i : cyc) {
            e[i].flow -= f; e[i ^ 1].flow += f;
            cost += f * e[i].cost;
        }
        if (dir) x ^ 1, swap(u, v);
        while (u != z)
            swap(x ^ 1, fae[v]), swap(u, fa[v]), swap(u, v);
    }
}
void dfs(int u) {
    vis[u] = visc;
    for (int i : g[u])
        if (int v = e[i].to; vis[v] != visc and e[i].flow)
            fa[v] = u, fae[v] = i, dfs(v);
}
C simplex() {
    C cost = 0;
    fa.assign(g.size(), -1); fae.assign(e.size(), -1);
    ++visc; dfs(0);
    for (int fail = 0; fail < ssize(e); )
        for (int i = 0; i < ssize(e); i++)
            if (e[i].flow and e[i].cost < phi(e[i ^ 1].to) -
                phi(e[i].to))
                fail = 0, pushflow(i, cost), ++visc;
            else ++fail;
    return cost;
}
};

```

## 4.11 General Matching [5f2293]

```

struct Matching {
    queue<int> q; int ans, n;
    vector<int> fa, s, v, pre, match;
    int Find(int u) {
        return u == fa[u] ? u : fa[u] = Find(fa[u]);
    }
    int LCA(int x, int y) {
        static int tk = 0; tk++; x = Find(x); y = Find(y);
        for (; swap(x, y)) if (x != n) {
            if (v[x] == tk) return x;
            v[x] = tk;
            x = Find(pre[match[x]]);
        }
    }
    void Blossom(int x, int y, int l) {
        for (; Find(x) != l; x = pre[y]) {
            pre[x] = y, y = match[x];
            if (s[y] == 1) q.push(y), s[y] = 0;
            for (int z : {x, y}) if (fa[z] == z) fa[z] = l;
        }
    }
    bool Bfs(auto &&g, int r) {

```

```

        iota(all(fa), 0); ranges::fill(s, -1);
        q = queue<int>(); q.push(r); s[r] = 0;
        for (; !q.empty(); q.pop()) {
            for (int x = q.front(); int u : g[x])
                if (s[u] == -1) {
                    if (pre[u] = x, s[u] = 1, match[u] == n) {
                        for (int a = u, b = x, last;
                            b != n; a = last, b = pre[a])
                            last = match[b], match[b] = a, match[a] = b;
                        return true;
                    }
                    q.push(match[u]); s[match[u]] = 0;
                } else if (!s[u] && Find(u) != Find(x)) {
                    int l = LCA(u, x);
                    Blossom(x, u, l); Blossom(u, x, l);
                }
            }
        }
        return false;
    }
    Matching(auto &&g) : ans(0), n((int)g.size()),
        fa(n+1), s(n+1), v(n+1), pre(n+1, n), match(n+1, n) {
        for (int x = 0; x < n; ++x)
            if (match[x] == n) ans += Bfs(g, x);
    } // match[x] == n means not matched
}; // test @ yosupo judge

```

## 4.12 Weighted Matching [94ca35]

```

#define pb emplace_back
#define rep(i, l, r) for (int i=(l); i<=(r); ++i)
struct WeightGraph { // 1-based
    static const int inf = INT_MAX;
    struct edge { int u, v, w; }; int n, nx;
    vector<int> lab; vector<vector<edge>> g;
    vector<int> slack, match, st, pa, S, vis;
    vector<vector<int>> flo, flo_from; queue<int> q;
    WeightGraph(int n_) : n(n_), nx(n * 2), lab(nx + 1),
        g(nx + 1, vector<edge>(nx + 1)), slack(nx + 1),
        flo(nx + 1), flo_from(nx + 1, vector(n + 1, 0)) {
        match = st = pa = S = vis = slack;
        rep(u, 1, n) rep(v, 1, n) g[u][v] = {u, v, 0};
    }
    int ED(edge e) {
        return lab[e.u] + lab[e.v] - g[e.u][e.v].w * 2;
    }
    void update_slack(int u, int x, int &s) {
        if (!s || ED(g[u][x]) < ED(g[s][x])) s = u;
    }
    void set_slack(int x) {
        slack[x] = 0;
        for (int u = 1; u <= n; ++u)
            if (g[u][x].w > 0 && st[u] != x && S[st[u]] == 0)
                update_slack(u, x, slack[x]);
    }
    void q_push(int x) {
        if (x <= n) q.push(x);
        else for (int y : flo[x]) q_push(y);
    }
    void set_st(int x, int b) {
        st[x] = b;
        if (x > n) for (int y : flo[x]) set_st(y, b);
    }
    vector<int> split_flo(auto &f, int xr) {
        auto it = find(all(f), xr);
        if (auto pr = it - f.begin(); pr % 2 == 1)
            reverse(1 + all(f), it = f.end() - pr);
        auto res = vector(f.begin(), it);
        return f.erase(f.begin(), it), res;
    }
    void set_match(int u, int v) {
        match[u] = g[u][v].v;
        if (u <= n) return;
        int xr = flo_from[u][g[u][v].u];
        auto &f = flo[u], z = split_flo(f, xr);
        rep(i, 0, (int)z.size()-1) set_match(z[i], z[i ^ 1]);
        set_match(xr, v); f.insert(f.end(), all(z));
    }
    void augment(int u, int v) {
        for (;) {
            int xnv = st[match[u]]; set_match(u, v);
            if (!xnv) return;
            set_match(xnv, st[pa[xnv]]);
            u = st[pa[xnv]], v = xnv;
        }
    }
};

```



$$h(a, b, c, n) = \sum_{i=0}^n \left\lfloor \frac{ai+b}{c} \right\rfloor^2$$

$$= \begin{cases} \left\lfloor \frac{a}{c} \right\rfloor^2 \cdot \frac{n(n+1)(2n+1)}{6} + \left\lfloor \frac{b}{c} \right\rfloor^2 \cdot (n+1) \\ + \left\lfloor \frac{a}{c} \right\rfloor \cdot \left\lfloor \frac{b}{c} \right\rfloor \cdot n(n+1) \\ + h(a \bmod c, b \bmod c, c, n) \\ + 2 \left\lfloor \frac{a}{c} \right\rfloor \cdot g(a \bmod c, b \bmod c, c, n) \\ + 2 \left\lfloor \frac{b}{c} \right\rfloor \cdot f(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ nm(m+1) - 2g(c, c-b-1, a, m-1) \\ - 2f(c, c-b-1, a, m-1) - f(a, b, c, n), & \text{otherwise} \end{cases}$$

## 5.4 Integer Division [cd017d]

```
lld fdiv(lld a, lld b)
{ return a / b - (a % b && (a < 0) ^ (b < 0)); }
lld cdiv(lld a, lld b)
{ return a / b + (a % b && (a < 0) ^ (b > 0)); }
```

## 5.5 FloorSum [fb5917]

```
// @param n 'n < 2^32'
// @param m '1 <= m < 2^32'
// @return sum_{i=0}^{n-1} floor((ai + b)/m) mod 2^64
llu floor_sum_unsigned(llu n, llu m, llu a, llu b) {
    llu ans = 0;
    while (true) {
        if (a >= m) ans += n*(n-1)/2 * (a/m), a %= m;
        if (b >= m) ans += n * (b/m), b %= m;
        if ((llu) y_max = a * n + b; y_max >= m) {
            n = (llu)(y_max / m), b = (llu)(y_max % m);
            swap(m, a);
        } else break;
    }
    return ans;
}
lld floor_sum(lld n, lld m, lld a, lld b) {
    llu ans = 0;
    if (a < 0) {
        llu a2 = (a % m + m), d = (a2 - a) / m;
        ans -= 1ULL * n * (n - 1) / 2 * d; a = a2;
    }
    if (b < 0) {
        llu b2 = (b % m + m), d = (b2 - b) / m;
        ans -= 1ULL * n * d; b = b2;
    }
    return ans + floor_sum_unsigned(n, m, a, b);
}
```

## 5.6 ModMin [253e4d]

```
// min{k | l <= ((ak) mod m) <= r}
optional<llu> mod_min(u32 a, u32 m, u32 l, u32 r) {
    if (a == 0) return l ? nullopt : 0;
    if (auto k = llu(l + a - 1) / a; k * a <= r)
        return k;
    auto b = m / a, c = m % a;
    if (auto y = mod_min(c, a, a - r % a, a - l % a))
        return (l + *y * c + a - 1) / a + *y * b;
    return nullopt;
}
```

## 5.7 Floor Monoid Product [416e89]

```
/* template <typename T>
T brute(llu a, llu b, llu c, llu n, T U, T R) {
    T res;
    for (llu i = 1, l = 0; i <= n; i++, res = res * R)
        for (llu r = (a*i+b)/c; l < r; ++l) res = res * U;
    return res;
} */
template <typename T>
T euclid(llu a, llu b, llu c, llu n, T U, T R) {
    if (!n) return T{};
    if (b >= c)
        return mpow(U, b / c) * euclid(a, b % c, c, n, U, R);
    if (a >= c)
        return euclid(a % c, b, c, n, U, mpow(U, a / c) * R);
    llu m = (u128(a) * n + b) / c;
    if (!m) return mpow(R, n);
    return mpow(R, (c - b - 1) / a) * U
        * euclid(c, (c - b - 1) % a, a, m - 1, R, U)
        * mpow(R, n - (u128(c) * m - b - 1) / a);
}
// time complexity is O(log max(a, b, c))
// UUUU R UUUUU R ... UUU R 共 N 個 R, 最後一個必是 R
// 一直到第 k 個 R 前總共有 (ak+b)/c 個 U
5.8 ax+by=gcd [d0cbdd]
```

```
// ax+ny = 1, ax+ny == ax == 1 (mod n)
void exgcd(lld x, lld y, lld &g, lld &a, lld &b) {
    if (y == 0) g = x, a = 1, b = 0;
    else exgcd(y, x % y, g, b, a), b -= (x / y) * a;
}
```

## 5.9 Chinese Remainder [d69e74]

```
// please ensure r_i \in [0, m_i)
bool crt(lld &m1, lld &r1, lld m2, lld r2) {
    if (m2 > m1) swap(m1, m2), swap(r1, r2);
    lld g, a, b; exgcd(m1, m2, g, a, b);
    if ((r2 - r1) % g != 0) return false;
    m2 /= g; lld D = (r2 - r1) / g % m2 * a % m2;
    r1 += (D < 0 ? D + m2 : D) * m1; m1 *= m2;
    assert(r1 >= 0 && r1 < m1);
    return true;
}
```

## 5.10 DiscreteLog [86e463]

```
template<typename Int>
Int BSGS(Int x, Int y, Int M) {
    // x^? \equiv y (mod M)
    Int t = 1, c = 0, g = 1;
    for (Int M_ = M; M_ > 0; M_ >>= 1) g = g * x % M;
    for (g = gcd(g, M); t % g != 0; ++c) {
        if (t == y) return c;
        t = t * x % M;
    }
    if (y % g != 0) return -1;
    t /= g, y /= g, M /= g;
    Int h = 0, gs = 1;
    for (; h * h < M; ++h) gs = gs * x % M;
    unordered_map<Int, Int> bs;
    for (Int s = 0; s < h; bs[y] = ++s) y = y * x % M;
    for (Int s = 0; s < M; s += h) {
        t = t * gs % M;
        if (bs.count(t)) return c + s + h - bs[t];
    }
    return -1;
}
```

## 5.11 Quadratic Residue [f0baec]

```
int get_root(int n, int P) { // ensure 0 <= n < p
    if (P == 2 or n == 0) return n;
    auto check = [&](lld x) {
        return modpow(int(x), (P - 1) / 2, P);
    };
    if (check(n) != 1) return -1;
    mt19937 rnd(7122); lld z = 1, w;
    while (check(w = (z * z - n + P) % P) != P - 1)
        z = rnd() % P;
    const auto M = [P, w](auto &u, auto &v) {
        auto [a, b] = u; auto [c, d] = v;
        return make_pair((a * c + b * d % P * w) % P,
            (a * d + b * c) % P);
    };
    pair<lld, lld> r(1, 0), e(z, 1);
    for (int q = (P + 1) / 2; q; q >>= 1, e = M(e, e))
        if (q & 1) r = M(r, e);
    return int(r.first); // sqrt(n) mod P where P is prime
}
```

## 5.12 FWT [f82550]

```
/* or convolution:
* x = (x0, x0+x1), inv = (x0, x1-x0) w/o final div
* and convolution:
* x = (x0+x1, x1), inv = (x0-x1, x1) w/o final div */
void fwt(int x[], int N, bool inv = false) {
    for (int d = 1; d < N; d <<= 1)
        for (int s = 0; s < N; s += d * 2)
            for (int i = s; i < s + d; i++) {
                int j = i + d, ta = x[i], tb = x[j];
                x[i] = add(ta, tb);
                x[j] = sub(ta, tb);
            }
    if (inv) {
        const int invn = modinv(N);
        for (int i = 0; i < N; i++)
            x[i] = mul(x[i], invn);
    }
}
```

## 5.13 Packed FFT [0a6af5]

```
VL convolution(const VI &a, const VI &b) {
    if (a.empty() || b.empty()) return {};
    const int sz = bit_ceil(a.size() + b.size() - 1);
    // Should be able to handle N <= 10^5, C <= 10^4
}
```



```

vector<P> v(sz);
for (size_t i = 0; i < a.size(); ++i) v[i].RE(a[i]);
for (size_t i = 0; i < b.size(); ++i) v[i].IM(b[i]);
fft(v.data(), sz, /*inv=*/false);
auto rev = v; reverse(1 + all(rev));
for (int i = 0; i < sz; ++i) {
    P A = (v[i] + conj(rev[i])) / P(2, 0);
    P B = (v[i] - conj(rev[i])) / P(0, 2);
    v[i] = A * B;
}
VL c(sz); fft(v.data(), sz, /*inv=*/true);
for (int i = 0; i < sz; ++i) c[i] = roundl(RE(v[i]));
return c;
}

VI convolution_mod(const VI &a, const VI &b) {
    if (a.empty() || b.empty()) return {};
    const int sz = bit_ceil(a.size() + b.size() - 1);
    vector<P> fa(sz), fb(sz);
    for (size_t i = 0; i < a.size(); ++i)
        fa[i] = P(a[i] & ((1 << 15) - 1), a[i] >> 15);
    for (size_t i = 0; i < b.size(); ++i)
        fb[i] = P(b[i] & ((1 << 15) - 1), b[i] >> 15);
    fft(fa.data(), sz); fft(fb.data(), sz);
    auto rfa = fa; reverse(1 + all(rfa));
    for (int i = 0; i < sz; ++i) fa[i] *= fb[i];
    for (int i = 0; i < sz; ++i) fb[i] *= conj(rfa[i]);
    fft(fa.data(), sz, true); fft(fb.data(), sz, true);
    vector<int> res(sz);
    for (int i = 0; i < sz; ++i) {
        lld A = (lld)roundl(RE((fa[i] + fb[i]) / P(2, 0)));
        lld C = (lld)roundl(IM((fa[i] - fb[i]) / P(0, 2)));
        lld B = (lld)roundl(IM(fa[i])); B %= p; C %= p;
        res[i] = (A + (B << 15) + (C << 30)) % p;
    }
    return res;
} // test @ yosupo judge with long double

```

## 5.14 CRT for arbitrary mod [e4dde7]

```

const int mod = 1000000007;
const int M1 = 985661441; // G = 3 for M1, M2, M3
const int M2 = 998244353;
const int M3 = 1004535809;
int superBigCRT(lld A, lld B, lld C) {
    static_assert(M1 < M2 && M2 < M3);
    constexpr lld r12 = modpow(M1, M2-2, M2);
    constexpr lld r13 = modpow(M1, M3-2, M3);
    constexpr lld r23 = modpow(M2, M3-2, M3);
    constexpr lld M1M2 = 1LL * M1 * M2 % mod;
    B = (B - A + M2) * r12 % M2;
    C = (C - A + M3) * r13 % M3;
    C = (C - B + M3) * r23 % M3;
    return (A + B * M1 + C * M1M2) % mod;
}

```

## 5.15 NTT / FFT [41cf12]

```

template <int mod, int G, int maxn> struct NTT {
    static_assert(maxn == (maxn & -maxn));
    int roots[maxn];
    NTT () {
        int r = modpow(G, (mod - 1) / maxn);
        for (int i = maxn >> 1; i; i >>= 1) {
            roots[i] = 1;
            for (int j = 1; j < i; j++)
                roots[i + j] = mul(roots[i + j - 1], r);
            r = mul(r, r);
            // for (int j = 0; j < i; j++) // FFT (tested)
            // roots[i+j] = polar<llf>(1, PI * j / i);
        }
    }
    // n must be 2^k, and 0 <= F[i] < mod
    template <typename T>
    void operator()(int F[], T n, bool inv = false) {
        for (T i = 0, j = 0; i < n; i++) {
            if (i < j) swap(F[i], F[j]);
            for (T k = n >> 1; (j ^= k) < k; k >>= 1);
        }
        for (T s = 1; s < n; s *= 2) {
            for (T i = 0; i < n; i += s * 2) {
                for (T j = 0; j < s; j++) {
                    int a = F[i+j], b = mul(F[i+j+s], roots[s+j]);
                    F[i+j] = add(a, b); // a + b
                    F[i+j+s] = sub(a, b); // a - b
                }
            }
        }
    }
}

```

```

}
}
if (inv) {
    int iv = modinv(int(n));
    for (T i = 0; i < n; i++) F[i] = mul(F[i], iv);
    reverse(F + 1, F + n);
}
}
};

```

## 5.16 Formal Power Series [c6b99a]

```

#define fi(l, r) for (size_t i = (l); i < (r); i++)
using S = vector<int>;
auto Mul(auto a, auto b, size_t sz) {
    a.resize(sz), b.resize(sz);
    ntt(a.data(), sz); ntt(b.data(), sz);
    fi(0, sz) a[i] = mul(a[i], b[i]);
    return ntt(a.data(), sz, true), a;
}

S Newton(const S &v, int init, auto &&iter) {
    S Q = { init };
    for (int sz = 2; Q.size() < v.size(); sz *= 2) {
        S A{begin(v), begin(v) + min(sz, int(v.size()))};
        A.resize(sz * 2), Q.resize(sz * 2);
        iter(Q, A, sz * 2); Q.resize(sz);
    }
    return Q.resize(v.size()), Q;
}

S Inv(const S &v) { // v[0] != 0
    return Newton(v, modinv(v[0]),
        [](S &X, S &A, int sz) {
            ntt(X.data(), sz), ntt(A.data(), sz);
            for (int i = 0; i < sz; i++)
                X[i] = mul(X[i], sub(2, mul(X[i], A[i])));
            ntt(X.data(), sz, true);
        });
}

S Dx(S A) {
    fi(1, A.size()) A[i - 1] = mul(i, A[i]);
    return A.empty() ? A : (A.pop_back(), A);
}

S Sx(S A) {
    A.insert(A.begin(), 0);
    fi(1, A.size()) A[i] = mul(modinv(int(i)), A[i]);
    return A;
}

S Ln(const S &A) { // coef[0] == 1; res[0] == 0
    auto B = Sx(Mul(Dx(A), Inv(A), bit_ceil(A.size()*2)));
    return B.resize(A.size()), B;
}

S Exp(const S &v) { // coef[0] == 0; res[0] == 1
    return Newton(v, 1,
        [](S &X, S &A, int sz) {
            auto Y = X; Y.resize(sz / 2); Y = Ln(Y);
            fi(0, Y.size()) Y[i] = sub(A[i], Y[i]);
            Y[0] = add(Y[0], 1); X = Mul(X, Y, sz);
        });
}

S Pow(S a, lld M) { // period mod*(mod-1)
    assert(!a.empty() && a[0] != 0);
    const auto imul = [&a](int s) {
        for (int &x: a) x = mul(x, s);
    };
    auto c = a[0];
    imul(modinv(c)); a = Ln(a); imul(int(M % mod));
    a = Exp(a); imul(modpow(c, int(M % (mod - 1))));
    return a; // mod x^N where N=a.size()
}

S Sqrt(const S &v) { // need: QuadraticResidue
    assert(!v.empty() && v[0] != 0);
    const int r = get_root(v[0]); assert(r != -1);
    return Newton(v, r,
        [](S &X, S &A, int sz) {
            auto Y = X; Y.resize(sz / 2);
            auto B = Mul(A, Inv(Y), sz);
            for (int i = 0, inv2 = mod / 2 + 1; i < sz; i++)
                X[i] = mul(inv2, add(X[i], B[i]));
        });
}

S Mul(auto &&a, auto &&b) {
    const auto n = a.size() + b.size() - 1;
    auto R = Mul(a, b, bit_ceil(n));
    return R.resize(n), R;
}

S MulT(S a, S b, size_t k) {
    assert(b.size()); reverse(all(b)); auto R = Mul(a, b);
    R = vector(R.begin() + b.size() - 1, R.end());
}

```

```

return R.resize(k), R;
}
S Eval(const S &f, const S &x) {
    if (f.empty()) return vector(x.size(), 0);
    const int n = int(max(x.size(), f.size()));
    auto q = vector(n * 2, S(2, 1)); S ans(n);
    fi(0, x.size()) q[i + n][1] = sub(0, x[i]);
    for (int i = n - 1; i > 0; i--)
        q[i] = Mul(q[i << 1], q[i << 1 | 1]);
    q[1] = Mult(f, Inv(q[1]), n);
    for (int i = 1; i < n; i++) {
        auto L = q[i << 1], R = q[i << 1 | 1];
        q[i << 1 | 0] = Mult(q[i], R, L.size());
        q[i << 1 | 1] = Mult(q[i], L, R.size());
    }
    for (int i = 0; i < n; i++) ans[i] = q[i + n][0];
    return ans.resize(x.size()), ans;
}
pair<S, S> DivMod(const S &A, const S &B) {
    assert(!B.empty() && B.back() != 0);
    if (A.size() < B.size()) return {{}, A};
    const auto sz = A.size() - B.size() + 1;
    S X = B; reverse(all(X)); X.resize(sz);
    S Y = A; reverse(all(Y)); Y.resize(sz);
    S Q = Mul(Inv(X), Y);
    Q.resize(sz); reverse(all(Q)); X = Mul(Q, B); Y = A;
    fi(0, Y.size()) Y[i] = sub(Y[i], X[i]);
    while (Y.size() && Y.back() == 0) Y.pop_back();
    while (Q.size() && Q.back() == 0) Q.pop_back();
    return {Q, Y};
} // empty means zero polynomial
int LinearRecursionKth(S a, S c, int64_t k) {
    const auto d = a.size(); assert(c.size() == d + 1);
    const auto sz = bit_ceil(2 * d + 1), o = sz / 2;
    S q = c; for (int &x: q) x = sub(0, x); q[0] = 1;
    S p = Mul(a, q); p.resize(sz); q.resize(sz);
    for (int r; r = (k & 1), k; k >= 1) {
        fill(d + all(p), 0); fill(d + 1 + all(q), 0);
        ntt(p.data(), sz); ntt(q.data(), sz);
        for (size_t i = 0; i < sz; i++)
            p[i] = mul(p[i], q[(i + o) & (sz - 1)]);
        for (size_t i = 0, j = o; j < sz; i++, j++)
            q[i] = q[j] = mul(q[i], q[j]);
        ntt(p.data(), sz, true); ntt(q.data(), sz, true);
        for (size_t i = 0; i < d; i++) p[i] = p[i << 1 | r];
        for (size_t i = 0; i <= d; i++) q[i] = q[i << 1];
    } // Bostan-Mori
    return mul(p[0], modinv(q[0]));
} // a_n = \sum c_j a_{n-j}, c_0 is not used

```

### 5.17 Partition Number [9bb845]

```

ans[0] = tmp[0] = 1;
for (int i = 1; i * i <= n; i++) {
    for (int rep = 0; rep < 2; rep++)
        for (int j = i; j <= n - i * i; j++)
            modadd(tmp[j], tmp[j - i]);
    for (int j = i * i; j <= n; j++)
        modadd(ans[j], tmp[j - i * i]);
}

```

### 5.18 Pi Count [715863]

```

struct S { int rough; lld large; int id; };
lld PrimeCount(lld n) { // n ~ 10^13 => < 1s
    if (n <= 1) return 0;
    const int v = static_cast<int>(sqrtl(n)); int pc = 0;
    vector<int> smalls(v + 1), skip(v + 1); vector<S> z;
    for (int i = 2; i <= v; ++i) smalls[i] = (i + 1) / 2;
    for (int i : views::iota(0, (v + 1) / 2))
        z.emplace_back(2*i+1, (n / (2*i+1) + 1) / 2, i);
    for (int p = 3; p <= v; ++p)
        if (smalls[p] > smalls[p - 1]) {
            const int q = p * p; ++pc;
            if (1LL * q * q > n) break;
            skip[p] = 1;
            for (int i = q; i <= v; i += 2 * p) skip[i] = 1;
            int ns = 0;
            for (auto e : z) if (!skip[e.rough]) {
                lld d = 1LL * e.rough * p;
                e.large += pc - (d <= v ? z[smalls[d] - pc].large :
                    smalls[n / d]);
                e.id = ns; z[ns++] = e;
            }
            z.resize(ns);
}

```

```

for (int j = v / p; j >= p; --j) {
    int c = smalls[j] - pc, e = min(j * p + p, v + 1);
    for (int i = j * p; i < e; ++i) smalls[i] -= c;
}
}
lld ans = z[0].large; z.erase(z.begin());
for (auto &[rough, large, k] : z) {
    const lld m = n / rough; --k;
    ans -= large - (pc + k);
    for (auto [p, _, l] : z)
        if (l >= k || p * p > m) break;
    else ans += smalls[m / p] - (pc + l);
}
return ans;
} // test @ yosupo library checker w/ n=1e11, 68ms

```

### 5.19 Miller Rabin [fbd812]

```

bool isprime(llu x) {
    auto withn = [&](llu a, int t) {
        for (llu a2; t--; a = a2) {
            a2 = mmul(a, a, x);
            if (a2 == 1 && a != 1 && a != x - 1) return true;
        }
        return a != 1;
    };
    if (x <= 2 || ~x & 1) return x == 2;
    int t = countr_zero(x - 1); llu odd = (x - 1) >> t;
    for (llu m : {2, 325, 9375, 28178, 450775, 9780504, 1795265022})
        if (m % x != 0 && withn(mpow(m % x, odd, x), t))
            return false;
    return true;
} // test @ luogu 143 & yosupo judge, ~1700ms for Q=1e5
// if use montgomery, ~250ms for Q=1e5

```

### 5.20 Pollard Rho [57ad88]

```

// does not work when n is prime or n == 1
// return any non-trivial factor
llu pollard_rho(llu n) {
    static mt19937_64 rnd(120821011);
    if (!(n & 1)) return 2;
    llu y = 2, z = y, c = rnd() % n, p = 1, i = 0, t;
    auto f = [&](llu x) {
        return madd(mmul(x, x, n), c, n);
    };
    do {
        p = mmul(msub(z = f(f(z)), y = f(y), n), p, n);
        if (++i &= 63) if (i == (i & -i)) t = gcd(p, n);
    } while (t == 1);
    return t == n ? pollard_rho(n) : t;
} // test @ yosupo judge, ~270ms for Q=100
// if use montgomery, ~70ms for Q=100

```

### 5.21 Berlekamp Massey [a94d00]

```

template <typename T>
vector<T> BerlekampMassey(const vector<T> &output) {
    vector<T> d(output.size() + 1), me, he;
    for (size_t f = 0, i = 1; i <= output.size(); ++i) {
        for (size_t j = 0; j < me.size(); ++j)
            d[i] += output[i - j - 2] * me[j];
        if ((d[i] == output[i - 1]) == 0) continue;
        if (me.empty()) {
            me.resize(f = i);
            continue;
        }
        vector<T> o(i - f - 1);
        T k = -d[i] / d[f]; o.push_back(-k);
        for (T x : he) o.push_back(x * k);
        if (o.size() < me.size()) o.resize(me.size());
        for (size_t j = 0; j < me.size(); ++j) o[j] += me[j];
        if (i - f + he.size() >= me.size()) he = me, f = i;
        me = o;
    }
    return me;
}

```

### 5.22 Gauss Elimination [1f5f8c]

```

using VI = vector<int>;
using VVI = vector<VI>;
pair<VI, VVI> gauss(VVI A, VI b) { // solve Ax=b
    const int N = (int)A.size(), M = (int)A[0].size();
    vector<int> depv, free(M, true); int rk = 0;
    for (int i = 0; i < M; ++i) {
        int p = -1;
        for (int j = rk; j < N; ++j)
            if (p == -1 || abs(A[j][i]) > abs(A[p][i]))

```

```

    p = j;
    if (p == -1 || A[p][i] == 0) continue;
    swap(A[p], A[rk]); swap(b[p], b[rk]);
    const int inv = modinv(A[rk][i]);
    for (int &x : A[rk]) x = mul(x, inv);
    b[rk] = mul(b[rk], inv);
    for (int j = 0; j < N; ++j) if (j != rk) {
        int z = A[j][i];
        for (int k = 0; k < M; ++k)
            A[j][k] = sub(A[j][k], mul(z, A[rk][k]));
        b[j] = sub(b[j], mul(z, b[rk]));
    }
    depv.push_back(i); free[i] = false; ++rk;
}
for (int i = rk; i < N; i++)
    if (b[i] != 0) return {{}, {}}; // not consistent
VI x(M); VVI h;
for (int i = 0; i < rk; i++) x[depv[i]] = b[i];
for (int i = 0; i < N - 2; ++i) if (free[i]) {
    h.emplace_back(M); h.back()[i] = 1;
    for (int j = 0; j < rk; j++)
        h.back()[depv[j]] = sub(0, A[j][i]);
}
return {x, h}; // solution = x + span(h[i])
}

```

## 5.23 CharPoly [cd559d]

```

#define rep(x, y, z) for (int x=y; x<z; x++)
using VI = vector<int>; using VVI = vector<VI>;
void Hessenberg(VVI &H, int N) {
    for (int i = 0; i < N - 2; ++i) {
        for (int j = i + 1; j < N; ++j) if (H[j][i]) {
            rep(k, i, N) swap(H[i+1][k], H[j][k]);
            rep(k, 0, N) swap(H[k][i+1], H[k][j]);
            break;
        }
        if (!H[i + 1][i]) continue;
        for (int j = i + 2; j < N; ++j) {
            int co = mul(modinv(H[i + 1][i]), H[j][i]);
            rep(k, i, N) subeq(H[j][k], mul(H[i+1][k], co));
            rep(k, 0, N) addeq(H[k][i+1], mul(H[k][j], co));
        }
    }
}
VI CharacteristicPoly(VVI A) {
    int N = (int)A.size(); Hessenberg(A, N);
    VVI P(N + 1, VI(N + 1)); P[0][0] = 1;
    for (int i = 1; i <= N; ++i) {
        rep(j, 0, i+1) P[i][j] = j ? P[i-1][j-1] : 0;
        for (int j = i - 1, val = 1; j >= 0; --j) {
            int co = mul(val, A[j][i - 1]);
            rep(k, 0, j+1) subeq(P[i][k], mul(P[j][k], co));
            if (j) val = mul(val, A[j][j - 1]);
        }
    }
    if (N & 1) for (int &x: P[N]) x = sub(0, x);
    return P[N]; // test: 2021 PTZ Korea K
}

```

## 5.24 Simplex [c9c93b]

```

namespace simplex {
    // maximize c^T x under Ax <= B and x >= 0
    // return VD(n, -inf) if the solution doesn't exist
    // return VD(n, +inf) if the solution is unbounded
    using VD = vector<llf>;
    using VVD = vector<vector<llf>>;
    const llf eps = 1e-9, inf = 1e+9;
    int n, m; VVD d; vector<int> p, q;
    void pivot(int r, int s) {
        llf inv = 1.0 / d[r][s];
        for (int i = 0; i < m + 2; ++i)
            for (int j = 0; j < n + 2; ++j)
                if (i != r && j != s)
                    d[i][j] -= d[r][j] * d[i][s] * inv;
        for (int i = 0; i < m + 2; ++i) if (i != r) d[i][s] *= -inv;
        for (int j = 0; j < n + 2; ++j) if (j != s) d[r][j] *= +inv;
        d[r][s] = inv; swap(p[r], q[s]);
    }
    bool phase(int z) {
        int x = m + z;
        while (true) {
            int s = -1;
            for (int i = 0; i <= n; ++i) {

```

```

                if (!z && q[i] == -1) continue;
                if (s == -1 || d[x][i] < d[x][s]) s = i;
            }
            if (s == -1 || d[x][s] > -eps) return true;
            int r = -1;
            for (int i = 0; i < m; ++i) {
                if (d[i][s] < eps) continue;
                if (r == -1 ||
                    d[i][n+1]/d[i][s] < d[r][n+1]/d[r][s]) r = i;
            }
            if (r == -1) return false;
            pivot(r, s);
        }
    }
    VD solve(const VVD &a, const VD &b, const VD &c) {
        m = (int)b.size(), n = (int)c.size();
        d = VVD(m + 2, VD(n + 2));
        for (int i = 0; i < m; ++i)
            for (int j = 0; j < n; ++j) d[i][j] = a[i][j];
        p.resize(m), q.resize(n + 1);
        for (int i = 0; i < m; ++i)
            p[i] = n + i, d[i][n] = -1, d[i][n + 1] = b[i];
        for (int i = 0; i < n; ++i) q[i] = i, d[m][i] = -c[i];
        q[n] = -1, d[m + 1][n] = 1;
        int r = 0;
        for (int i = 1; i < m; ++i)
            if (d[i][n + 1] < d[r][n + 1]) r = i;
        if (d[r][n + 1] < -eps) {
            pivot(r, n);
            if (!phase(1) || d[m + 1][n + 1] < -eps)
                return VD(n, -inf);
            for (int i = 0; i < m; ++i) if (p[i] == -1) {
                int s = min_element(d[i].begin(), d[i].end() - 1)
                    - d[i].begin();
                pivot(i, s);
            }
        }
        if (!phase(0)) return VD(n, inf);
        VD x(n);
        for (int i = 0; i < m; ++i)
            if (p[i] < n) x[p[i]] = d[i][n + 1];
        return x;
    }
} // use double instead of long double if possible

```

## 5.25 Simplex Construction

Standard form: maximize  $\sum_{1 \leq i \leq n} c_i x_i$  such that  $\sum_{1 \leq i \leq n} A_{ji} x_i \leq b_j$  for all  $1 \leq j \leq m$  and  $x_i \geq 0$  for all  $1 \leq i \leq n$ .

1. In case of minimization, let  $c'_i = -c_i$
2.  $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j \rightarrow \sum_{1 \leq i \leq n} -A_{ji} x_i \leq -b_j$
3.  $\sum_{1 \leq i \leq n} A_{ji} x_i = b_j \rightarrow \text{add } \leq \text{ and } \geq$ .
4. If  $x_i$  has no lower bound, replace  $x_i$  with  $x_i - x'_i$

## 5.26 Adaptive Simpson [b8cef9]

```

llf integrate(auto &&f, llf L, llf R) {
    auto simp = [&](llf l, llf r) {
        llf m = (l + r) / 2;
        return (f(l) + f(r) + 4.0 * f(m)) * (r - l) / 6.0;
    };
    auto F = [&](auto Y, llf l, llf r, llf v, llf eps) {
        llf m = (l+r)/2, vl = simp(l, m), vr = simp(m, r);
        if (abs(vl + vr - v) <= 15 * eps)
            return vl + vr + (vl + vr - v) / 15.0;
        return Y(Y, l, m, vl, eps / 2.0) +
            Y(Y, m, r, vr, eps / 2.0);
    };
    return F(F, L, R, simp(L, R), 1e-6);
}

```

## 5.27 Golden Ratio Search [376bcb]

```

llf gss(llf a, llf b, auto &&f) {
    llf r = (sqrt(5)-1)/2, eps = 1e-7;
    llf x1 = b - r*(b-a), x2 = a + r*(b-a);
    llf f1 = f(x1), f2 = f(x2);
    while (b-a > eps)
        if (f1 < f2) { //change to > to find maximum
            b = x2; x2 = x1; f2 = f1;
            x1 = b - r*(b-a); f1 = f(x1);
        } else {
            a = x1; x1 = x2; f1 = f2;
            x2 = a + r*(b-a); f2 = f(x2);
        }
    return a;
}

```

## 6 Geometry

### 6.1 Basic Geometry [1d2d70]

```
#define IM imag
#define RE real
using lld = int64_t;
using llf = long double;
using PT = complex<lld>;
using PF = complex<llf>;
using P = PT;
llf abs(P p) { return sqrtl(norm(p)); }
PF toPF(PT p) { return PF(RE(p), IM(p)); }
int sgn(lld x) { return (x > 0) - (x < 0); }
lld dot(P a, P b) { return RE(conj(a) * b); }
lld cross(P a, P b) { return IM(conj(a) * b); }
int ori(P a, P b, P c) {
    return sgn(cross(b - a, c - a));
}
int quad(P p) {
    return (IM(p) == 0) // use sgn for PF
        ? (RE(p) < 0 ? 3 : 1) : (IM(p) < 0 ? 0 : 2);
}
int argCmp(P a, P b) {
    // returns 0/+1, starts from theta = -PI
    int qa = quad(a), qb = quad(b);
    if (qa != qb) return sgn(qa - qb);
    return sgn(cross(b, a));
}
P rot90(P p) { return P(-IM(p), RE(p)); }
template <typename V> llf area(const V & pt) {
    lld ret = 0;
    for (int i = 1; i + 1 < (int)pt.size(); i++)
        ret += cross(pt[i] - pt[0], pt[i+1] - pt[0]);
    return ret / 2.0;
}
template <typename V> PF center(const V & pt) {
    P ret = 0; lld A = 0;
    for (int i = 1; i + 1 < (int)pt.size(); i++) {
        lld cur = cross(pt[i] - pt[0], pt[i+1] - pt[0]);
        ret += (pt[i] + pt[i + 1] + pt[0]) * cur; A += cur;
    }
    return toPF(ret) / llf(A * 3);
}
PF project(PF p, PF q) { // p onto q
    return dot(p, q) * q / dot(q, q); // dot<llf>
}
```

### 6.2 2D Convex Hull [ecba37]

```
// from NaCl, counterclockwise, be careful of n<=2
vector<P> convex_hull(vector<P> v) {
    sort(all(v)); // by X then Y
    if (v[0] == v.back()) return {v[0]};
    int t = 0, s = 1; vector<P> h(v.size() + 1);
    for (int _ = 2; _--; s = t--, reverse(all(v)))
        for (P p : v) {
            while (t > s && ori(p, h[t-1], h[t-2]) >= 0) t--;
            h[t++] = p;
        }
    return h.resize(t), h;
}
```

### 6.3 2D Farthest Pair [8b5844]

```
// p is CCW convex hull w/o colinear points
int n = (int)p.size(), pos = 1; lld ans = 0;
for (int i = 0; i < n; i++) {
    P e = p[(i + 1) % n] - p[i];
    while (cross(e, p[(pos + 1) % n] - p[i]) >
            cross(e, p[pos] - p[i]))
        pos = (pos + 1) % n;
    for (int j: {i, (i + 1) % n})
        ans = max(ans, norm(p[pos] - p[j]));
} // tested @ A0J CGL_4.B
```

### 6.4 MinMax Enclosing Rect [e4470c]

```
// from 8BQube, plz ensure p is strict convex hull
const llf INF = 1e18, qi = acos(-1) / 2 * 3;
pair<llf, llf> solve(const vector<P> &p) {
    llf mx = 0, mn = INF; int n = (int)p.size();
    for (int i = 0, u = 1, r = 1, l = 1; i < n; ++i) {
#define Z(v) (p[(v) % n] - p[i])
        P e = Z(i + 1);
        while (cross(e, Z(u + 1)) > cross(e, Z(u))) ++u;
        while (dot(e, Z(r + 1)) > dot(e, Z(r))) ++r;
        if (!i) l = r + 1;
        while (dot(e, Z(l + 1)) < dot(e, Z(l))) ++l;

```

```
        P D = p[r % n] - p[l % n];
        llf H = cross(e, Z(u)) / llf(norm(e));
        mn = min(mn, dot(e, D) * H);
        llf B = sqrt(norm(D)) * sqrt(norm(Z(u)));
        llf deg = (qi - acos(dot(D, Z(u)) / B)) / 2;
        mx = max(mx, B * sin(deg) * sin(deg));
    }
    return {mn, mx};
} // test @ UVA 819
```

### 6.5 Minkowski Sum [602806]

```
// A, B are strict convex hull rotate to min by (X, Y)
vector<P> Minkowski(vector<P> A, vector<P> B) {
    const int N = (int)A.size(), M = (int)B.size();
    vector<P> sa(N), sb(M), C(N + M + 1);
    for (int i = 0; i < N; i++) sa[i] = A[(i+1)%N] - A[i];
    for (int i = 0; i < M; i++) sb[i] = B[(i+1)%M] - B[i];
    C[0] = A[0] + B[0];
    for (int i = 0, j = 0; i < N || j < M; ) {
        P e = (j >= M || (i < N && cross(sa[i], sb[j]) >= 0))
            ? sa[i++] : sb[j++];
        C[i + j] = e;
    }
    partial_sum(all(C), C.begin()); C.pop_back();
    return convex_hull(C); // just to remove colinear
}
```

### 6.6 Segment Intersection [60d016]

```
struct Seg { // closed segment
    P st, dir; // represent st + t*dir for 0<=t<=1
    Seg(P s, P e) : st(s), dir(e - s) {}
    static bool valid(lld p, lld q) {
        // is there t s.t. 0 <= t <= 1 && qt == p ?
        if (q < 0) q = -q, p = -p;
        return 0 <= p && p <= q;
    }
    vector<P> ends() const { return { st, st + dir }; }
};
template <typename T> bool isInter(T A, P p) {
    if (A.dir == P(0)) return p == A.st; // BE CAREFUL
    return cross(p - A.st, A.dir) == 0 &&
        T::valid(dot(p - A.st, A.dir), norm(A.dir));
}
template <typename U, typename V>
bool isInter(U A, V B) {
    if (cross(A.dir, B.dir) == 0) { // BE CAREFUL
        bool res = false;
        for (P p: A.ends()) res |= isInter(B, p);
        for (P p: B.ends()) res |= isInter(A, p);
        return res;
    }
    P D = B.st - A.st; lld C = cross(A.dir, B.dir);
    return U::valid(cross(D, B.dir), C) &&
        V::valid(cross(D, A.dir), C);
}
```

### 6.7 Halfplane Intersection [31e216]

```
struct Line {
    P st, ed, dir;
    Line(P s, P e) : st(s), ed(e), dir(e - s) {}
}; using LN = const Line &;
PF intersect(LN A, LN B) {
    llf t = cross(B.st - A.st, B.dir) /
        llf(cross(A.dir, B.dir));
    return toPF(A.st) + toPF(A.dir) * t; // C^3 / C^2
}
bool cov(LN l, LN A, LN B) {
    i128 u = cross(B.st - A.st, B.dir);
    i128 v = cross(A.dir, B.dir);
    // ori(l.st, l.ed, A.st + A.dir*(u/v)) <= 0?
    i128 x = RE(A.dir) * u + RE(A.st - l.st) * v;
    i128 y = IM(A.dir) * u + IM(A.st - l.st) * v;
    return sgn(x*IM(l.dir) - y*RE(l.dir)) * sgn(v) >= 0;
} // x, y are C^3, also sgn<i128> is needed
bool operator<(LN a, LN b) {
    if (int c = argCmp(a.dir, b.dir)) return c == -1;
    return ori(a.st, a.ed, b.st) < 0;
}
// cross(pt-line.st, line.dir)<=0 <-> pt in half plane
// the half plane is the LHS when going from st to ed
llf HPI(vector<Line> &q) {
    sort(q.begin(), q.end());
    int n = (int)q.size(), l = 0, r = -1;
    for (int i = 0; i < n; i++) {

```



```

    if (i && !argCmp(q[i].dir, q[i-1].dir)) continue;
    while (l < r && cov(q[i], q[r-1], q[r])) --r;
    while (l < r && cov(q[i], q[l], q[l+1])) ++l;
    q[++r] = q[i];
}
while (l < r && cov(q[l], q[r-1], q[r])) --r;
while (l < r && cov(q[r], q[l], q[l+1])) ++l;
n = r - l + 1; // q[l .. r] are the lines
if (n <= 1 || !argCmp(q[l].dir, q[r].dir)) return 0;
vector<PF> pt(n);
for (int i = 0; i < n; i++)
    pt[i] = intersect(q[i+l], q[(i+1)%n+l]);
return area(pt);
} // test @ 2020 Nordic NCPD : BigBrother

```

## 6.8 SegmentDist (Sausage) [9d8603]

```

// be careful of abs<complex<int>> (replace _abs below)
llf PointSegDist(P A, Seg B) {
    if (B.dir == P(0)) return _abs(A - B.st);
    if (sgn(dot(A - B.st, B.dir)) *
        sgn(dot(A - B.ed, B.dir)) <= 0)
        return abs(cross(A - B.st, B.dir)) / _abs(B.dir);
    return min(_abs(A - B.st), _abs(A - B.ed));
}
llf SegSegDist(const Seg &s1, const Seg &s2) {
    if (isInter(s1, s2)) return 0;
    return min({
        PointSegDist(s1.st, s2),
        PointSegDist(s1.ed, s2),
        PointSegDist(s2.st, s1),
        PointSegDist(s2.ed, s1) });
} // test @ QOJ2444 / PTZ19 Summer.D3

```

## 6.9 Rotating Sweep Line [8aff27]

```

struct Event {
    P d; int u, v;
    bool operator<(const Event &b) const {
        return sgn(cross(d, b.d)) > 0;
    }
};
P makePositive(P z) { return cmpxy(z, 0) ? -z : z; }
void rotatingSweepLine(const vector<P> &p) {
    const int n = int(p.size());
    vector<Event> e; e.reserve(n * (n - 1) / 2);
    for (int i = 0; i < n; i++)
        for (int j = i + 1; j < n; j++)
            e.emplace_back(makePositive(p[i] - p[j]), i, j);
    sort(all(e));
    vector<int> ord(n), pos(n);
    iota(all(ord), 0);
    sort(all(ord), [&p](int i, int j) {
        return cmpxy(p[i], p[j]);
    });
    for (int i = 0; i < n; i++) pos[ord[i]] = i;
    const auto makeReverse = [](auto &v) {
        sort(all(v)); v.erase(unique(all(v)), v.end());
        vector<pair<int, int>> segs;
        for (size_t i = 0, j = 0; i < v.size(); i = j) {
            for (; j < v.size() && v[j] - v[i] <= j - i; j++);
            segs.emplace_back(v[i], v[j - 1] + 1 + 1);
        }
        return segs;
    };
    for (size_t i = 0, j = 0; i < e.size(); i = j) {
        /* do here */
        vector<size_t> tmp;
        for (; j < e.size() && !(e[i] < e[j]); j++)
            tmp.push_back(min(pos[e[j].u], pos[e[j].v]));
        for (auto [l, r] : makeReverse(tmp)) {
            reverse(ord.begin() + l, ord.begin() + r);
            for (int t = l; t < r; t++) pos[ord[t]] = t;
        }
    }
}

```

## 6.10 Hull Cut [277def]

```

vector<P> cut(const vector<P> &p, P s, P e) {
    vector<P> res;
    for (size_t i = 0; i < p.size(); i++) {
        P cur = p[i], prv = i ? p[i-1] : p.back();
        bool side = ori(s, e, cur) < 0;
        if (side != (ori(s, e, prv) < 0))
            res.push_back(intersect({s, e}, {cur, prv}));
        if (side) res.push_back(cur);
    } // P is complex<llf>
    return res; // hull intersection with halfplane
}

```

```

} // left of the line s -> e

```

## 6.11 Point In Hull [13edeb]

```

bool isAnti(P a, P b) {
    return cross(a, b) == 0 && dot(a, b) <= 0;
}
bool PIH(const vector<P> &h, P z, bool strict = true) {
    int n = (int)h.size(), a = 1, b = n - 1, r = !strict;
    if (n < 3) return r && isAnti(h[0] - z, h[n-1] - z);
    if (ori(h[0], h[a], h[b]) > 0) swap(a, b);
    if (ori(h[0], h[a], z) >= r || ori(h[0], h[b], z) <= -r)
        return false;
    while (abs(a - b) > 1) {
        int c = (a + b) / 2;
        (ori(h[0], h[c], z) > 0 ? b : a) = c;
    }
    return ori(h[a], h[b], z) < r;
}

```

## 6.12 Point In Polygon [037c52]

```

bool PIP(const vector<P> &p, P z, bool strict = true) {
    int cnt = 0, n = (int)p.size();
    for (int i = 0; i < n; i++) {
        P A = p[i], B = p[(i + 1) % n];
        if (isInter(Seg(A, B), z)) return !strict;
        auto zy = IM(z), Ay = IM(A), By = IM(B);
        cnt ^= ((zy < Ay) - (zy < By)) * ori(z, A, B) > 0;
    }
    return cnt;
}

```

## 6.13 Point In Polygon (Fast) [00590a]

```

vector<int> PIPfast(vector<P> p, vector<P> q) {
    const int N = int(p.size()), Q = int(q.size());
    vector<pair<P, int>> evt;
    vector<Seg> edge;
    for (int i = 0; i < N; i++) {
        int a = i, b = (i + 1) % N;
        P A = p[a], B = p[b];
        assert(A < B || B < A); // std::operator<
        if (B < A) swap(A, B);
        evt.emplace_back(A, i);
        evt.emplace_back(B, ~i);
        edge.emplace_back(A, B);
    }
    for (int i = 0; i < Q; i++)
        evt.emplace_back(q[i], i + N);
    sort(all(evt));
    auto vtx = p; sort(all(vtx));
    auto eval = [](const Seg &a, lld x) -> llf {
        if (RE(a.dir) == 0) {
            assert(x == RE(a.st));
            return IM(a.st) + llf(IM(a.dir)) / 2;
        }
        llf t = (x - RE(a.st)) / llf(RE(a.dir));
        return IM(a.st) + IM(a.dir) * t;
    };
    lld cur_x = 0;
    auto cmp = [&](const Seg &a, const Seg &b) -> bool {
        if (int s = sgn(eval(a, cur_x) - eval(b, cur_x)))
            return s == -1;
        int s = sgn(cross(b.dir, a.dir));
        if (cur_x != RE(a.st) && cur_x != RE(b.st)) s *= -1;
        return s == -1;
    };
    namespace pbds = __gnu_pbds;
    using Tree = pbds::tree<Seg, int, decltype(cmp),
        pbds::rb_tree_tag,
        pbds::tree_order_statistics_node_update>;
    Tree st(cmp);
    auto answer = [&](P ep) {
        if (binary_search(all(vtx), ep))
            return 1; // on vertex
        Seg H(ep, ep); // ??
        auto it = st.lower_bound(H);
        if (it != st.end() && isInter(it->first, ep))
            return 1; // on edge
        if (it != st.begin() && isInter(prev(it)->first, ep))
            return 1; // on edge
        auto rk = st.order_of_key(H);
        return rk % 2 == 0 ? 0 : 2; // 0: outside, 2: inside
    };
    vector<int> ans(Q);
    for (auto [ep, i] : evt) {
        cur_x = RE(ep);
    }
}

```

```

if (i < 0) { // remove
    st.erase(edge[~i]);
} else if (i < N) { // insert
    auto [it, succ] = st.insert({edge[i], i});
    assert (succ);
} else
    ans[i - N] = answer(ep);
}
return ans;
} // test @ AOJ CGL_3_C

```

#### 6.14 Cyclic Ternary Search [i62adf]

```

int cyclic_ternary_search(int N, auto &&lt;int> {
    auto lt = [&](int x, int y) {
        return lt_(x % N, y % N); };
    int l = 0, r = N; bool up = lt(0, 1);
    while (r - l > 1) {
        int m = (l + r) / 2;
        if (lt(m, 0) ? up : !lt(m, m+1)) r = m;
        else l = m;
    }
    return (lt(l, r) ? r : l) % N;
}

```

#### 6.15 Tangent of Points To Hull [8e1343]

```

pair<int, int> get_tangent(const vector<P> &v, P p) {
    auto gao = [&](int s) {
        return cyclic_ternary_search(v.size(),
            [&](int x, int y) {
                return ori(p, v[x], v[y]) == s; });
    }; // test @ codeforces.com/gym/101201/problem/E
    return {gao(1), gao(-1)}; // (a,b):ori(p,v[a],v[b])<0
} // plz ensure that point strictly out of hull
// if colinear, returns arbitrary point on line

```

#### 6.16 Circle Class & Intersection [d5df51]

```

llf FMOD(llf x) {
    if (x < -PI) x += PI * 2;
    if (x > PI) x -= PI * 2;
    return x;
}
struct Cir { PF o; llf r; };
// be carefule when tangent
vector<llf> intersectAngle(Cir a, Cir b) {
    PF dir = b.o - a.o; llf d2 = norm(dir);
    if (norm(a.r - b.r) >= d2) { // norm(x) := |x|^2
        if (a.r < b.r) return {-PI, PI}; // a in b
        else return {}; // b in a
    } else if (norm(a.r + b.r) <= d2) return {};
    llf dis = abs(dir), theta = arg(dir);
    llf phi = acos((a.r * a.r + d2 - b.r * b.r) /
        (2 * a.r * dis)); // is acos_safe needed?
    llf L = FMOD(theta - phi), R = FMOD(theta + phi);
    return {L, R};
}
vector<PF> intersectPoint(Cir a, Cir b) {
    llf d = abs(a.o - b.o);
    if (d > b.r + a.r || d < abs(b.r - a.r)) return {};
    llf dt = (b.r * b.r - a.r * a.r) / d, d1 = (d + dt) / 2;
    PF dir = (a.o - b.o) / d;
    PF u = dir * d1 + b.o;
    PF v = rot90(dir) * sqrt(max(0.0L, b.r * b.r - d1 * d1));
    return {u + v, u - v};
} // test @ AOJ CGL probs

```

#### 6.17 Circle Common Tangent [d97f1c]

```

// be careful of tangent / exact same circle
// sign1 = 1 for outer tang, -1 for inter tang
vector<Line> common_tan(const Cir &a, const Cir &b, int
    sign1) {
    if (norm(a.o - b.o) < eps) return {};
    llf d = abs(a.o - b.o), c = (a.r - sign1 * b.r) / d;
    PF v = (b.o - a.o) / d;
    if (c * c > 1) return {};
    if (abs(c * c - 1) < eps) {
        PF p = a.o + c * v * a.r;
        return {Line(p, p + rot90(b.o - a.o))};
    }
    vector<Line> ret; llf h = sqrt(max(0.0L, 1 - c * c));
    for (int sign2 : {1, -1}) {
        PF n = c * v + sign2 * h * rot90(v);
        PF p1 = a.o + n * a.r;
        PF p2 = b.o + n * (b.r * sign1);
        ret.emplace_back(p1, p2);
    }
}

```

```

return ret;
}

```

#### 6.18 Line-Circle Intersection [i0786a]

```

vector<PF> LineCircleInter(PF p1, PF p2, PF o, llf r) {
    PF ft = p1 + project(o - p1, p2 - p1), vec = p2 - p1;
    llf dis = abs(o - ft);
    if (abs(dis - r) < eps) return {ft};
    if (dis > r) return {};
    vec = vec * sqrt(r * r - dis * dis) / abs(vec);
    return {ft + vec, ft - vec}; // sqrt_safe?
}

```

#### 6.19 Poly-Circle Intersection [8e5133]

```

// Divides into multiple triangle, and sum up
// from 8BQube, test by HDU2892 & AOJ CGL_7_H
llf _area(PF pa, PF pb, llf r) {
    if (abs(pa) < abs(pb)) swap(pa, pb);
    if (abs(pb) < eps) return 0;
    llf S, h, theta;
    llf a = abs(pb), b = abs(pa), c = abs(pb - pa);
    llf cB = dot(pb, pb - pa) / a / c, B = acos_safe(cB);
    llf cC = dot(pa, pb) / a / b, C = acos_safe(cC);
    if (a > r) {
        S = (C / 2) * r * r; h = a * b * sin(C) / c;
        if (h < r && B < PI / 2)
            S -= (acos_safe(h/r) * r * r - h * sqrt_safe(r * r - h * h));
    } else if (b > r) {
        theta = PI - B - asin_safe(sin(B) / r * a);
        S = 0.5 * a * r * sin(theta) + (C - theta) / 2 * r * r;
    } else
        S = 0.5 * sin(C) * a * b;
    return S;
}
llf area_poly_circle(const vector<PF> &v, PF o, llf r)
{
    llf S = 0;
    for (size_t i = 0, N = v.size(); i < N; ++i)
        S += _area(v[i] - o, v[(i + 1) % N] - o, r) *
            ori(o, v[i], v[(i + 1) % N]);
    return abs(S);
}

```

#### 6.20 Min Covering Circle [92bb15]

```

Cir getCircum(P a, P b, P c) { // P = complex<llf>
    P z1 = a - b, z2 = a - c; llf D = cross(z1, z2) * 2;
    auto c1 = dot(a + b, z1), c2 = dot(a + c, z2);
    P o = rot90(c2 * z1 - c1 * z2) / D;
    return {o, abs(o - a)};
}
Cir minCircleCover(vector<P> p) {
    assert (!p.empty());
    ranges::shuffle(p, mt19937(114514));
    Cir c = {0, 0};
    for (size_t i = 0; i < p.size(); i++) {
        if (abs(p[i] - c.o) <= c.r) continue;
        c = {p[i], 0};
        for (size_t j = 0; j < i; j++) {
            if (abs(p[j] - c.o) <= c.r) continue;
            c.o = (p[i] + p[j]) / llf(2);
            c.r = abs(p[i] - c.o);
            for (size_t k = 0; k < j; k++) {
                if (abs(p[k] - c.o) <= c.r) continue;
                c = getCircum(p[i], p[j], p[k]);
            }
        }
    }
    return c;
} // test @ TIOJ 1093 & luogu P1742

```

#### 6.21 Circle Union [073c1c]

```

#define eb emplace_back
struct Teve { // test@SPOJ N=1000, 0.3~0.5s
    PF p; llf a; int add; // point, ang, add
    Teve(PF x, llf y, int z) : p(x), a(y), add(z) {}
    bool operator<(Teve &b) const { return a < b.a; }
};
// strict: x = 0, otherwise x = -1
bool disjunct(Cir &a, Cir &b, int x)
{ return sgn(abs(a.o - b.o) - a.r - b.r) > x; }
bool contain(Cir &a, Cir &b, int x)
{ return sgn(a.r - b.r - abs(a.o - b.o)) > x; }
vector<llf> CircleUnion(vector<Cir> &c) {
    // area[i] : area covered by at least i circles
    int N = (int)c.size(); vector<llf> area(N + 1);
}

```

```

vector<vector<int>> overlap(N, vector<int>(N));
auto g = overlap; // use simple 2darray to speedup
for (int i = 0; i < N; ++i)
    for (int j = 0; j < N; ++j) {
        /* c[j] is non-strictly in c[i]. */
        overlap[i][j] = i != j &&
            (sgn(c[i].r - c[j].r) > 0 ||
             (sgn(c[i].r - c[j].r) == 0 && i < j)) &&
            contain(c[i], c[j], -1);
    }
for (int i = 0; i < N; ++i)
    for (int j = 0; j < N; ++j)
        g[i][j] = i != j && !(overlap[i][j] ||
            overlap[j][i] || disjunct(c[i], c[j], -1));
for (int i = 0; i < N; ++i) {
    vector<Tev> eve; int cnt = 1;
    for (int j = 0; j < N; ++j) cnt += overlap[j][i];
    // if (cnt > 1) continue; (if only need area[1])
    for (int j = 0; j < N; ++j) if (g[i][j]) {
        auto IP = intersectPoint(c[i], c[j]);
        PF aa = IP[1], bb = IP[0];
        llf A = arg(aa - c[i].o), B = arg(bb - c[i].o);
        eve.eb(bb, B, 1); eve.eb(aa, A, -1);
        if (B > A) ++cnt;
    }
    if (eve.empty()) area[cnt] += PI*c[i].r*c[i].r;
    else {
        sort(eve.begin(), eve.end());
        eve.eb(eve[0]); eve.back().a += PI * 2;
        for (size_t j = 0; j + 1 < eve.size(); j++) {
            cnt += eve[j].add;
            area[cnt] += cross(eve[j].p, eve[j+1].p) *.5;
            llf t = eve[j + 1].a - eve[j].a;
            area[cnt] += (t-sin(t)) * c[i].r * c[i].r *.5;
        }
    }
}
return area;
}

```

## 6.22 Polygon Union [42e75b]

```

llf polyUnion(const vector<vector<P>> &p) {
    vector<tuple<P, P, int>> seg;
    for (int i = 0; i < ssize(p); i++)
        for (int j = 0, m = int(p[i].size()); j < m; j++)
            seg.emplace_back(p[i][j], p[i][(j + 1) % m], i);
    llf ret = 0; // area of p[i] must be non-negative
    for (auto [A, B, i] : seg) {
        vector<pair<llf, int>> evt{{0, 0}, {1, 0}};
        for (auto [C, D, j] : seg) {
            int sc = ori(A, B, C), sd = ori(A, B, D);
            if (sc != sd && i != j && min(sc, sd) < 0) {
                llf sa = cross(D-C, A-C), sb = cross(D-C, B-C);
                evt.emplace_back(sa / (sa - sb), sgn(sc - sd));
            } else if (!sc && !sd && j < i
                && sgn(dot(B - A, D - C)) > 0) {
                evt.emplace_back(real((C - A) / (B - A)), 1);
                evt.emplace_back(real((D - A) / (B - A)), -1);
            }
        }
        for (auto &[q, _] : evt) q = clamp<llf>(q, 0, 1);
        sort(evt.begin(), evt.end());
        llf sum = 0, last = 0; int cnt = 0;
        for (auto [q, c] : evt) {
            if (!cnt) sum += q - last;
            cnt += c; last = q;
        }
        ret += cross(A, B) * sum;
    }
    return ret / 2;
}

```

## 6.23 3D Point [46b73b]

```

struct P3 {
    llf x, y, z;
    P3 operator^(const P3 &b) const {
        return {y*b.z-b.y*z, z*b.x-b.z*x, x*b.y-b.x*y};
    }
    //Azimuthal angle (longitude) to x-axis. \in [-pi, pi]
    llf phi() const { return atan2(y, x); }
    //Zenith angle (latitude) to the z-axis. \in [0, pi]
    llf theta() const { return atan2(sqrt(x*x+y*y), z); }
};

```

```

P3 ver(P3 a, P3 b, P3 c) { return (b - a) ^ (c - a); }
llf volume(P3 a, P3 b, P3 c, P3 d) {
    return dot(ver(a, b, c), d - a);
}
P3 rotate_around(P3 p, llf angle, P3 axis) {
    llf s = sin(angle), c = cos(angle);
    P3 u = normalize(axis);
    return u*dot(u, p)*(1-c) + p * c + cross(u, p)*s;
}

```

## 6.24 3D Convex Hull [01652a]

```

struct Face {
    int a, b, c;
    Face(int ta, int tb, int tc) : a(ta), b(tb), c(tc) {}
};
auto preprocess(const vector<P3> &pt) {
    auto G = pt.begin();
    auto a = find_if(all(pt), [&](P3 z) {
        return z != *G; }) - G;
    auto b = find_if(all(pt), [&](P3 z) {
        return ver(*G, pt[a], z) != P3(0, 0, 0); }) - G;
    auto c = find_if(all(pt), [&](P3 z) {
        return volume(*G, pt[a], pt[b], z) != 0; }) - G;
    vector<size_t> id;
    for (size_t i = 0; i < pt.size(); i++)
        if (i != a && i != b && i != c) id.push_back(i);
    return tuple{a, b, c, id};
}
// return the faces with pt indexes
// all points coplanar case will WA
vector<Face> convex_hull_3D(const vector<P3> &pt) {
    const int n = int(pt.size());
    if (n <= 3) return {}; // be careful about edge case
    vector<Face> now;
    vector<vector<int>> z(n, vector<int>(n));
    auto [a, b, c, ord] = preprocess(pt);
    now.emplace_back(a, b, c); now.emplace_back(c, b, a);
    for (auto i : ord) {
        vector<Face> next;
        for (const auto &f : now) {
            llf v = volume(pt[f.a], pt[f.b], pt[f.c], pt[i]);
            if (v <= 0) next.push_back(f);
            z[f.a][f.b] = z[f.b][f.c] = z[f.c][f.a] = sgn(v);
        }
        const auto F = [&](int x, int y) {
            if (z[x][y] > 0 && z[y][x] <= 0)
                next.emplace_back(x, y, i);
        };
        for (const auto &f : now)
            F(f.a, f.b), F(f.b, f.c), F(f.c, f.a);
        now = next;
    }
    return now;
}
// n^2 delaunay: facets with negative z normal of
// convexhull of (x, y, x^2 + y^2), use a pseudo-point
// (0, 0, inf) to avoid degenerate case
// test @ SPOJ CH3D
// llf area = 0, vol = 0; // surface area / volume
// for (auto [a, b, c] : faces)
//     area += abs(ver(p[a], p[b], p[c]))/2.0,
//     vol += volume(P3(0, 0, 0), p[a], p[b], p[c])/6.0;

```

## 6.25 3D Projection [68f350]

```

using P3F = valarray<llf>;
P3F toP3F(P3 p) { return {p.x, p.y, p.z}; }
llf dot(P3F a, P3F b) {
    return a[0]*b[0]+a[1]*b[1]+a[2]*b[2];
}
P3F housev(P3 A, P3 B, int s) {
    const llf a = abs(A), b = abs(B);
    return toP3F(A) / a + s * toP3F(B) / b;
}

```

```

P project(P3 p, P3 q) {
    P3 o(0, 0, 1);
    P3F u = housev(q, o, q.z > 0 ? 1 : -1);
    auto pf = toP3F(p);
    auto np = pf - 2 * u * dot(u, pf) / dot(u, u);
    return P(np[0], np[1]);
} // project p onto the plane q^Tx = 0

```

## 6.26 3D Skew Line Nearest Point

- $L_1 : v_1 = p_1 + t_1 d_1, L_2 : v_2 = p_2 + t_2 d_2$
- $n = d_1 \times d_2$
- $n_1 = d_1 \times n, n_2 = d_2 \times n$

$$\cdot c_1 = p_1 + \frac{(p_2 - p_1) \cdot n_2}{d_1 \cdot n_2} d_1, c_2 = p_2 + \frac{(p_1 - p_2) \cdot n_1}{d_2 \cdot n_1} d_2$$

## 6.27 Delaunay [3a4ff1]

```

/* please ensure input points are unique */
/* A triangulation such that no points will strictly
inside circumcircle of any triangle. C should be big
enough s.t. the initial triangle contains all points */
#define L(i) ((i)==0 ? 2 : (i)-1)
#define R(i) ((i)==2 ? 0 : (i)+1)
#define F3 for (int i = 0; i < 3; i++)
bool is_inf(P z) { return RE(z) <= -C || RE(z) >= C; }
bool in_cc(const array<P,3> &p, P q) {
    i128 inf_det = 0, det = 0, inf_N, N;
    F3 {
        if (is_inf(p[i]) && is_inf(q)) continue;
        else if (is_inf(p[i])) inf_N = 1, N = -norm(q);
        else if (is_inf(q)) inf_N = -1, N = norm(p[i]);
        else inf_N = 0, N = norm(p[i]) - norm(q);
        lld D = cross(p[R(i)] - q, p[L(i)] - q);
        inf_det += inf_N * D; det += N * D;
    }
    return inf_det != 0 ? inf_det > 0 : det > 0;
}
P v[maxn];
struct Tri;
struct E {
    Tri *t; int side;
    E(Tri *t_=0, int side_=0) : t(t_), side(side_) {}
};
struct Tri {
    array<int,3> p; array<Tri*,3> ch; array<E,3> e;
    Tri(int a=0, int b=0, int c=0) : p{a, b, c}, ch{} {}
    bool has_chd() const { return ch[0] != nullptr; }
    bool contains(int q) const {
        F3 if (ori(v[p[i]], v[p[R(i)]], v[q]) < 0)
            return false;
        return true;
    }
    bool check(int q) const {
        return in_cc({v[p[0]], v[p[1]], v[p[2]]}, v[q]);
    }
    pool<maxn * 10>, *it, *root;
    void link(const E &a, const E &b) {
        if (a.t) a.t->e[a.side] = b;
        if (b.t) b.t->e[b.side] = a;
    }
    void flip(Tri *A, int a) {
        auto [B, b] = A->e[a]; /* flip edge between A,B */
        if (!B || !A->check(B->p[b])) return;
        Tri *X = new (it++) Tri(A->p[R(a)], B->p[b], A->p[a]);
        Tri *Y = new (it++) Tri(B->p[R(b)], A->p[a], B->p[b]);
        link(E(X, 0), E(Y, 0));
        link(E(X, 1), A->e[L(a)]); link(E(X, 2), B->e[R(b)]);
        link(E(Y, 1), B->e[L(b)]); link(E(Y, 2), A->e[R(a)]);
        A->ch = B->ch = {X, Y, nullptr};
        flip(X, 1); flip(X, 2); flip(Y, 1); flip(Y, 2);
    }
    void add_point(int p) {
        Tri *r = root;
        while (r->has_chd()) for (Tri *c: r->ch)
            if (c && c->contains(p)) { r = c; break; }
        array<Tri*, 3> t; /* split into 3 triangles */
        F3 t[i] = new (it++) Tri(r->p[i], r->p[R(i)], p);
        F3 link(E(t[i], 0), E(t[R(i)], 1));
        F3 link(E(t[i], 2), r->e[L(i)]);
        r->ch = t;
        F3 flip(t[i], 2);
    }
    auto build(const vector<P> &p) {
        it = pool; int n = (int)p.size();
        vector<int> ord(n); iota(all(ord), 0);
        shuffle(all(ord), mt19937(114514));
        root = new (it++) Tri(n, n + 1, n + 2);
        copy_n(p.data(), n, v); v[n++] = P(-C, -C);
        v[n++] = P(C * 2, -C); v[n++] = P(-C, C * 2);
        for (int i : ord) add_point(i);
        vector<array<int, 3>> res;
        for (Tri *now = pool; now != it; now++)
            if (!now->has_chd()) res.push_back(now->p);
        return res;
    }
}

```

## 6.28 Build Voronoi [94f000]

```
void build_voronoi_cells(auto &&p, auto &&res) {
```

```

vector<vector<int>> adj(p.size());
for (auto f: res) F3 {
    int a = f[i], b = f[R(i)];
    if (a >= p.size() || b >= p.size()) continue;
    adj[a].emplace_back(b);
}
// use `adj` and `p` and HPI to build cells
for (size_t i = 0; i < p.size(); i++) {
    vector<Line> ls = frame; // the frame
    for (int j : adj[i]) {
        P m = p[i] + p[j], d = rot90(p[j] - p[i]);
        assert (norm(d) != 0);
        ls.emplace_back(m, m + d); // doubled coordinate
    } // HPI(ls)
}
}

```

## 6.29 kd Tree (Nearest Point) [f733e5]

```

struct KDTree {
    struct Node {
        int x, y, x1, y1, x2, y2, id, f; Node *L, *R;
    } tree[maxn], *root;
    lld dis2(int x1, int y1, int x2, int y2) {
        lld dx = x1 - x2, dy = y1 - y2;
        return dx * dx + dy * dy;
    }
    static bool cmpx(Node& a, Node& b) { return a.x < b.x; }
    static bool cmpy(Node& a, Node& b) { return a.y < b.y; }
    void init(vector<pair<int,int>> &ip) {
        for (int i = 0; i < ssize(ip); i++)
            tie(tree[i].x, tree[i].y) = ip[i], tree[i].id = i;
        root = build(0, (int)ip.size()-1, 0);
    }
    Node* build(int L, int R, int d) {
        if (L > R) return nullptr;
        int M = (L+R)/2;
        nth_element(tree+L, tree+M, tree+R+1, d%2?cmpy:cmpx);
        Node &o = tree[M]; o.f = d % 2;
        o.x1 = o.x2 = o.x; o.y1 = o.y2 = o.y;
        o.L = build(L, M-1, d+1); o.R = build(M+1, R, d+1);
        for (Node *s: {o.L, o.R}) if (s) {
            o.x1 = min(o.x1, s->x1); o.x2 = max(o.x2, s->x2);
            o.y1 = min(o.y1, s->y1); o.y2 = max(o.y2, s->y2);
        }
        return tree+M;
    }
    bool touch(int x, int y, lld d2, Node *r) {
        lld d = (lld)sqrt(d2)+1;
        return x >= r->x1 - d && x <= r->x2 + d &&
            y >= r->y1 - d && y <= r->y2 + d;
    }
    using P = pair<lld, int>;
    void dfs(int x, int y, P &mn, Node *r) {
        if (!r || !touch(x, y, mn.first, r)) return;
        mn = min(mn, P(dis2(r->x, r->y, x, y), r->id));
        if (r->f == 1 ? y < r->y : x < r->x)
            dfs(x, y, mn, r->L), dfs(x, y, mn, r->R);
        else
            dfs(x, y, mn, r->R), dfs(x, y, mn, r->L);
    }
    int query(int x, int y) {
        P mn(INF, -1); dfs(x, y, mn, root);
        return mn.second;
    }
} tree;

```

## 6.30 kd Closest Pair (3D ver.) [84d9eb]

```

llf solve(vector<P> v) {
    shuffle(v.begin(), v.end(), mt19937());
    unordered_map<lld, unordered_map<lld,
        unordered_map<lld, int>>> m;
    llf d = dis(v[0], v[1]);
    auto Idx = [&d] (llf x) -> lld {
        return round(x * 2 / d) + 0.1;
    };
    auto rebuild_m = [&m, &v, &Idx] (int k) {
        m.clear();
        for (int i = 0; i < k; ++i)
            m[Idx(v[i].x)][Idx(v[i].y)]
                [Idx(v[i].z)] = i;
        return rebuild_m(2);
    };
    for (size_t i = 2; i < v.size(); ++i) {
        const lld kx = Idx(v[i].x), ky = Idx(v[i].y),
            kz = Idx(v[i].z); bool found = false;

```



```

for (int dx = -2; dx <= 2; ++dx) {
    const lld nx = dx + kx;
    if (m.find(nx) == m.end()) continue;
    auto& mm = m[nx];
    for (int dy = -2; dy <= 2; ++dy) {
        const lld ny = dy + ky;
        if (mm.find(ny) == mm.end()) continue;
        auto& mmm = mm[ny];
        for (int dz = -2; dz <= 2; ++dz) {
            const lld nz = dz + kz;
            if (mmm.find(nz) == mmm.end()) continue;
            const int p = mmm[nz];
            if (dis(v[p], v[i]) < d) {
                d = dis(v[p], v[i]);
                found = true;
            }
        }
    }
}
if (found) rebuild_m(i + 1);
else m[kx][ky][kz] = i;
}
return d;
}

```

### 6.31 Simulated Annealing [4e0fe5]

```

llf anneal() {
    mt19937 rnd_engine(seed);
    uniform_real_distribution<llf> rnd(0, 1);
    const llf dT = 0.001;
    // Argument p
    llf S_cur = calc(p), S_best = S_cur;
    for (llf T = 2000; T > EPS; T -= dT) {
        // Modify p to p_prime
        const llf S_prime = calc(p_prime);
        const llf delta_c = S_prime - S_cur;
        llf prob = min((llf)1, exp(-delta_c / T));
        if (rnd(rnd_engine) <= prob)
            S_cur = S_prime, p = p_prime;
        if (S_prime < S_best) // find min
            S_best = S_prime, p_best = p_prime;
    }
    return S_best;
}

```

### 6.32 Triangle Centers [adb146]

```

O = ... // see min circle cover
G = (A + B + C) / 3;
H = G * 3 - O * 2; // orthogonal center
llf a = abs(B - C), b = abs(A - C), c = abs(A - B);
I = (a * A + b * B + c * C) / (a + b + c);
// FermatPoint: minimizes sum of distance
// if max. angle >= 120 deg then vertex
// otherwise, make eq. triangle AB'C, CA'B, BC'A
// line AA', BB', CC' intersects at P

```

## 7 Stringology

### 7.1 Hash [ce7fad]

```

template <int P = 127, int Q = 1051762951>
class Hash {
    vector<int> h, p;
public:
    Hash(const auto &s) : h(s.size()+1), p(s.size()+1) {
        for (size_t i = 0; i < s.size(); ++i)
            h[i + 1] = add(mul(h[i], P), s[i]);
        generate(all(p), [x = 1, y = 1, this]() mutable {
            return y = x, x = mul(x, P), y; });
    }
    int query(int l, int r) const { // 0-base [l, r)
        return sub(h[r], mul(h[l], p[r - l]));
    }
};

```

### 7.2 Suffix Array [da27c7]

```

auto sais(const auto &s) {
    const int n = (int)s.size(), z = ranges::max(s) + 1;
    vector<int> c(z); for (int x : s) ++c[x];
    partial_sum(all(c), begin(c));
    vector<int> sa(n); auto I = views::iota(0, n);
    if (ranges::max(c) <= 1) {
        for (int i : I) sa[--c[s[i]]] = i;
        return sa;
    }
    vector<bool> t(n); t[n - 1] = true;
    for (int i = n - 2; i >= 0; --i)

```

```

    t[i] = (s[i]==s[i + 1] ? t[i + 1] : s[i]<s[i + 1]);
    auto is_lms = views::filter([&t](int x) {
        return x && t[x] && !t[x - 1]; });
    auto induce = [&] {
        for (auto x = c; int y : sa)
            if (y-- if (!t[y]) sa[x[s[y] - 1]++] = y;
        for (auto x = c; int y : sa | views::reverse)
            if (y-- if (t[y]) sa[--x[s[y]]] = y;
    };
    vector<int> lms, q(n); lms.reserve(n);
    for (auto x = c; int i : I | is_lms) {
        q[i] = int(lms.size());
        lms.push_back(sa[--x[s[i]]] = i);
    }
    induce(); vector<int> ns(lms.size());
    for (int j = -1, nz = 0; int i : sa | is_lms) {
        if (j >= 0) {
            int len = min({n - i, n - j, lms[q[i] + 1] - i});
            ns[q[i]] = nz += lexicographical_compare(
                begin(s) + j, begin(s) + j + len,
                begin(s) + i, begin(s) + i + len);
        }
        j = i;
    }
    ranges::fill(sa, 0); auto nsa = sais(ns);
    for (auto x = c; int y : nsa | views::reverse)
        y = lms[y], sa[--x[s[y]]] = y;
    return induce(), sa;
}
// sa[i]: sa[i]-th suffix is the
// i-th lexicographically smallest suffix.
// hi[i]: LCP of suffix sa[i] and suffix sa[i - 1].
struct Suffix {
    int n; vector<int> sa, hi, rev;
    Suffix(const auto &s) : n((int)s.size()),
        hi(n), rev(n) {
        vector<int> _s(n + 1); // _s[n] = 0;
        copy(all(s), begin(_s)); // s shouldn't contain 0
        sa = sais(_s); sa.erase(sa.begin());
        for (int i = 0; i < n; ++i) rev[sa[i]] = i;
        for (int i = 0, h = 0; i < n; ++i) {
            if (!rev[i]) { h = 0; continue; }
            for (int j = sa[rev[i] - 1]; i + h < n && j + h < n
                && s[i + h] == s[j + h];) ++h;
            hi[rev[i]] = h ? h-- : 0;
        }
    }
};

```

### 7.3 Suffix Array Tools [be0061]

```

struct OfflineGetRange : Suffix {
    vector<vector<pair<int, int>>> qs; int qid;
    OfflineGetRange(const auto &s)
        : Suffix(s), qs(n), qid(0) {}
    int offline_get_range(int x, int len) {
        return qs[len].eb(rev[x], qid), qid++;
    }
    vector<pair<int, int>> solve_get_range() {
        vector<pair<int, int>> ans(qid); Dsu dsu(n);
        for (int i = 1; i < n; i++) qs[hi[i]].eb(i, -1);
        for (int i = n - 1; i >= 0; i--)
            for (auto [pos, id] : qs[i] | views::reverse)
                if (id == -1) dsu.join(pos - 1, pos);
                else ans[id] = {dsu.get_min(pos), dsu.get_max(pos) + 1};
        return qs.assign(n, qid = 0, ans);
    }
};
template <int LG = 20> struct SparseTableSA : Suffix {
    array<vector<int>, LG> mn;
    SparseTableSA(const auto &s) : Suffix(s), mn[hi] {
        for (int l = 0; l + 1 < LG; l++) { mn[l+1].resize(n);
            for (int i = 0, len = 1 << l; i + len < n; i++)
                mn[l + 1][i] = min(mn[l][i], mn[l][i + len]);
        }
    }
    int lcp(int a, int b) {
        if (a == b) return n - a;
        a = rev[a] + 1, b = rev[b] + 1;
        if (a > b) swap(a, b);
        const int lg = __lg(b - a);
        return min(mn[lg][a], mn[lg][b - (1 << lg)]);
    }
};

```

```

}
pair<int,int> get_range(int x, int len) { // WIP
    int a = rev[x] + 1, b = rev[x] + 1;
    for (int l = LG - 1; l >= 0; l--) {
        const int s = 1 << l;
        if (a + s <= n && mn[l][a] >= len) a += s;
        if (b - s >= 0 && mn[l][b - s] >= len) b -= s;
    }
    return {b - 1, a};
}
};

```

## 7.4 Ex SAM [58374b]

```

struct exSAM {
    int len[maxn * 2], link[maxn * 2]; // maxlen, suflink
    int next[maxn * 2][maxc], tot; // [0, tot), root = 0
    int ord[maxn * 2]; // topo. order (sort by length)
    int cnt[maxn * 2]; // occurrence
    int newnode() {
        fill_n(next[tot], maxc, 0);
        return len[tot] = cnt[tot] = link[tot] = 0, tot++;
    }
    void init() { tot = 0, newnode(), link[0] = -1; }
    int insertSAM(int last, int c) {
        int cur = next[last][c];
        len[cur] = len[last] + 1;
        int p = link[last];
        while (p != -1 && !next[p][c])
            next[p][c] = cur, p = link[p];
        if (p == -1) return link[cur] = 0, cur;
        int q = next[p][c];
        if (len[p] + 1 == len[q]) return link[cur] = q, cur;
        int clone = newnode();
        for (int i = 0; i < maxc; ++i)
            next[clone][i] = len[next[q][i]] ? next[q][i] : 0;
        len[clone] = len[p] + 1;
        while (p != -1 && next[p][c] == q)
            next[p][c] = clone, p = link[p];
        link[link[cur] = clone] = link[q];
        link[q] = clone;
        return cur;
    }
    void insert(const string &s) {
        int cur = 0;
        for (char ch : s) {
            int &nxt = next[cur][int(ch - 'a')];
            if (!nxt) nxt = newnode();
            cnt[cur = nxt] += 1;
        }
    }
    void build() {
        queue<int> q; q.push(0);
        while (!q.empty()) {
            int cur = q.front(); q.pop();
            for (int i = 0; i < maxc; ++i)
                if (next[cur][i]) q.push(insertSAM(cur, i));
        }
        vector<int> lc(tot);
        for (int i = 1; i < tot; ++i) ++lc[len[i]];
        partial_sum(all(lc), lc.begin());
        for (int i = 1; i < tot; ++i) ord[--lc[len[i]]] = i;
    }
    void solve() {
        for (int i = tot - 2; i >= 0; --i)
            cnt[link[ord[i]]] += cnt[ord[i]];
    }
};

```

## 7.5 KMP [281185]

```

vector<int> kmp(const auto &s) {
    vector<int> f(s.size());
    for (int i = 1, k = 0; i < (int)s.size(); ++i) {
        while (k > 0 && s[i] != s[k]) k = f[k - 1];
        f[i] = (k += (s[i] == s[k]));
    }
    return f;
}
vector<int> search(const auto &s, const auto &t) {
    // return 0-indexed occurrence of t in s
    vector<int> f = kmp(t), r;
    for (int i = 0, k = 0; i < (int)s.size(); ++i) {
        while (k > 0 && s[i] != t[k]) k = f[k - 1];
        k += (s[i] == t[k]);
    }
}

```

```

if (k == (int)t.size()) {
    r.push_back(i - t.size() + 1);
    k = f[k - 1];
}
}
return r;
}

```

## 7.6 Z value [6a7fd0]

```

vector<int> Zalgo(const string &s) {
    vector<int> z(s.size(), s.size());
    for (int i = 1, l = 0, r = 0; i < z[0]; ++i) {
        int j = clamp(r - i, 0, z[i - l]);
        for (; i + j < z[0] && s[i + j] == s[j]; ++j);
        if (i + (z[i] = j) > r) r = i + z[i];
    }
    return z;
}

```

## 7.7 Manacher [c938a9]

```

vector<int> manacher(const string &s) {
    const int n = (int)s.size(), m = n * 2 + 1;
    vector<int> z(m);
    string t = "."; for (char c: S) t += c, t += '.';
    for (int i = 1, l = 0, r = 0; i < m; ++i) {
        z[i] = (r > i ? min(z[2 * l - i], r - i) : 1);
        while (i - z[i] >= 0 && i + z[i] < m) {
            if (t[i - z[i]] == t[i + z[i]]) ++z[i];
            else break;
        }
        if (i + z[i] > r) r = i + z[i], l = i;
    }
    return z; // the palindrome lengths are z[i] - 1
}
/* for (int i = 1; i + 1 < m; ++i) {
    int l = (i - z[i] + 2) / 2, r = (i + z[i]) / 2;
    if (l != r) // [l, r) is maximal palindrome
} */

```

## 7.8 Lyndon Factorization [d22cc9]

```

// partition s = w[0] + w[1] + ... + w[k-1],
// w[0] >= w[1] >= ... >= w[k-1]
// each w[i] strictly smaller than all its suffix
void duval(const auto &s, auto &&report) {
    for (int n = (int)s.size(), i = 0, j, k; i < n; ) {
        for (j = i + 1, k = i; j < n && s[k] <= s[j]; j++)
            k = (s[k] < s[j] ? i : k + 1);
        // if (i < n / 2 && j >= n / 2) {
        // for min cyclic shift, call duval(s + s)
        // then here s.substr(i, n / 2) is min cyclic shift
        // }
        for (; i <= k; i += j - k)
            report(i, j - k); // s.substr(l, len)
    }
} // tested @ luogu 6114, 1368 & UVA 719

```

## 7.9 Main Lorentz [615b8f]

```

vector<pair<int, int>> rep[kN]; // 0-base [l, r]
void main_lorentz(const string &s, int sft = 0) {
    const int n = s.size();
    if (n == 1) return;
    const int nu = n / 2, nv = n - nu;
    const string u = s.substr(0, nu), v = s.substr(nu),
        ru(u.rbegin(), u.rend()), rv(v.rbegin(), v.rend());
    main_lorentz(u, sft), main_lorentz(v, sft + nu);
    const auto z1 = Zalgo(ru), z2 = Zalgo(v + '#' + u),
        z3 = Zalgo(ru + '#' + rv), z4 = Zalgo(v);
    auto get_z = [](const vector<int> &z, int i) {
        return (0 <= i && i < (int)z.size()) ? z[i] : 0;
    };
    auto add_rep = [&](bool left, int c, int l, int k1,
        int k2) {
        const int L = max(1, l - k2), R = min(l - left, k1);
        if (L > R) return;
        if (left) rep[l].emplace_back(sft + c - R, sft + c - L);
        else rep[l].emplace_back(sft + c - R - l + 1, sft + c - L - l + 1);
    };
    for (int cntr = 0; cntr < n; cntr++) {
        int l, k1, k2;
        if (cntr < nu) {
            l = nu - cntr;
            k1 = get_z(z1, nu - cntr);
            k2 = get_z(z2, nv + 1 + cntr);
        } else {

```

```

    l = cntr - nu + 1;
    k1 = get_z(z3, nu + 1 + nv - 1 - (cntr - nu));
    k2 = get_z(z4, (cntr - nu) + 1);
}
if (k1 + k2 >= l)
    add_rep(cntr < nu, cntr, l, k1, k2);
}
}

```

## 7.10 BWT [5a9b3a]

```

vector<int> v[SIGMA];
void BWT(char *ori, char *res) {
    // make ori -> ori + ori
    // then build suffix array
}
void iBWT(char *ori, char *res) {
    for (int i = 0; i < SIGMA; i++) v[i].clear();
    const int len = strlen(ori);
    for (int i = 0; i < len; i++)
        v[ori[i] - 'a'].push_back(i);
    vector<int> a;
    for (int i = 0, ptr = 0; i < SIGMA; i++)
        for (int j : v[i]) {
            a.push_back(j);
            ori[ptr++] = 'a' + i;
        }
    for (int i = 0, ptr = 0; i < len; i++) {
        res[i] = ori[a[ptr]];
        ptr = a[ptr];
    }
    res[len] = 0;
}

```

## 7.11 Palindromic Tree [0673ee]

```

struct PalindromicTree {
    struct node {
        int nxt[26], f, len; // num = depth of fail link
        int cnt, num; // = #pal_suffix of this node
        node(int l = 0) : nxt{}, f(0), len(l), cnt(0), num(0) {}
    };
    vector<node> st; vector<char> s; int last, n;
    void init() {
        st.clear(); s.clear();
        last = 1; n = 0;
        st.push_back(0); st.push_back(-1);
        st[0].f = 1; s.push_back(-1);
    }
    int getFail(int x) {
        while (s[n - st[x].len - 1] != s[n]) x = st[x].f;
        return x;
    }
    void add(int c) {
        s.push_back(c - 'a'); ++n;
        int cur = getFail(last);
        if (!st[cur].nxt[c]) {
            int now = st.size();
            st.push_back(st[cur].len + 2);
            st[now].f = st[getFail(st[cur].f)].nxt[c];
            st[cur].nxt[c] = now;
            st[now].num = st[st[now].f].num + 1;
        }
        last = st[cur].nxt[c]; ++st[last].cnt;
    }
    void dpCnt() { // cnt = #occurrence in whole str
        for (int i = st.size() - 1; i >= 0; i--)
            st[st[i].f].cnt += st[i].cnt;
    }
    int size() { return st.size() - 2; }
} pt;
/* usage
string s; cin >> s; pt.init();
for (int i = 0; i < SZ(s); i++) {
    int prvsz = pt.size(); pt.add(s[i]);
    if (prvsz != pt.size()) {
        int r = i, l = r - pt.st[pt.last].len + 1;
        // pal @ [l,r]: s.substr(l, r-l+1)
    }
} */

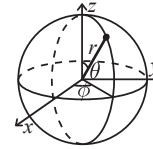
```

## 8 Misc

### 8.1 Theorems

#### Spherical Coordinate

$$\begin{aligned}
 x &= r \sin \theta \cos \phi \\
 y &= r \sin \theta \sin \phi \\
 z &= r \cos \theta
 \end{aligned}$$



$$\begin{aligned}
 r &= \sqrt{x^2 + y^2 + z^2} \\
 \theta &= \arccos(z / \sqrt{x^2 + y^2 + z^2}) \\
 \phi &= \operatorname{atan2}(y, x)
 \end{aligned}$$

#### Spherical Cap

- A portion of a sphere cut off by a plane.
- $r$ : sphere radius,  $a$ : radius of the base of the cap,  $h$ : height of the cap,  $\theta$ :  $\arcsin(a/r)$ .
- Volume =  $\pi h^2(3r - h)/3 = \pi h(3a^2 + h^2)/6 = \pi r^3(2 + \cos \theta)(1 - \cos \theta)^2/3$ .
- Area =  $2\pi r h = \pi(a^2 + h^2) = 2\pi r^2(1 - \cos \theta)$ .

#### Sherman-Morrison formula

$$(A + uv^T)^{-1} = A^{-1} - \frac{A^{-1}uv^T A^{-1}}{1 + v^T A^{-1}u}$$

#### Kirchhoff's Theorem

Denote  $L$  be a  $n \times n$  matrix as the Laplacian matrix of graph  $G$ , where  $L_{ii} = d(i)$ ,  $L_{ij} = -c$  where  $c$  is the number of edge  $(i, j)$  in  $G$ .

- The number of undirected spanning in  $G$  is  $\det(\tilde{L}_{11})$ .
- The number of directed spanning tree rooted at  $r$  in  $G$  is  $\det(\tilde{L}_{rr})$ .

#### BEST Theorem

$$\#\{\text{Eulerian circuits}\} = \#\{\text{arborescences rooted at } 1\} \cdot \prod_{v \in V} (\deg(v) - 1)!$$

#### Random Walk on Graph

Let  $P$  be the transition matrix of a strongly connected directed graph,  $\sum_j P_{i,j} = 1$ . Let  $F_{i,j}$  be the expected time to reach  $j$  from  $i$ . Let  $g_i$  be the expected time from  $i$  to  $i$ ,  $G = \text{diag}(g)$  and  $J$  be a matrix all of 1, i.e.  $J_{i,j} = 1$ . Then,  $F = J - G + PF$ .

First solve  $G$ : let  $\pi P = \pi$  be a stationary distribution. Then  $\pi_i g_i = 1$ . The rank of  $I - P$  is  $n - 1$ , so we first solve a special solution  $X$  such that  $(I - P)X = J - G$  and adjust  $X$  to  $F$  by  $F_{i,j} = X_{i,j} - X_{j,j}$ .

#### Tutte Matrix

For  $i < j$ ,  $d_{ij} = x_{ij}$  (in practice, a random number) if  $(i, j) \in E$ , otherwise  $d_{ij} = 0$ . For  $i \geq j$ ,  $d_{ij} = -d_{ji}$ .  $\frac{\text{rank}(D)}{2}$  is the maximum matching.

#### Cayley's Formula

- Given a degree sequence  $d_1, d_2, \dots, d_n$  for each labeled vertices, there're  $\frac{(n-2)!}{(d_1-1)!(d_2-1)!\dots(d_n-1)!}$  spanning trees.
- Let  $T_{n,k}$  be the number of labeled forests on  $n$  vertices with  $k$  components, such that vertex  $1, 2, \dots, k$  belong to different components. Then  $T_{n,k} = k n^{n-k-1}$ .

#### Erdős-Gallai theorem

A sequence of non-negative integers  $d_1 \geq d_2 \geq \dots \geq d_n$  can be represented as the degree sequence of a finite simple graph on  $n$  vertices if and only if  $d_1 + d_2 + \dots + d_n$  is even and  $\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k)$  holds for all  $1 \leq k \leq n$ .

#### Havel-Hakimi algorithm

Find the vertex who has greatest degree unused, connect it with other great-est vertex.

#### Gale-Ryser theorem

A pair of sequences of nonnegative integers  $a_1 \geq \dots \geq a_n$  and  $b_1, \dots, b_n$  is bigraphic if and only if  $\sum_{i=1}^n a_i = \sum_{i=1}^n b_i$  and  $\sum_{i=1}^k a_i \leq \sum_{i=1}^n \min(b_i, k)$  holds for every  $1 \leq k \leq n$ .

#### Fulkerson-Chen-Anstee theorem

A sequence  $(a_1, b_1), \dots, (a_n, b_n)$  of nonnegative integer pairs with  $a_1 \geq \dots \geq a_n$  is digraphic if and only if  $\sum_{i=1}^n a_i = \sum_{i=1}^n b_i$  and  $\sum_{i=1}^k a_i \leq \sum_{i=1}^k \min(b_i, k-1) + \sum_{i=k+1}^n \min(b_i, k)$  holds for every  $1 \leq k \leq n$ .

#### Euler's planar graph formula

$$V - E + F = C + 1, E \leq 3V - 6 \text{ (when } V \geq 3)$$

#### Pick's theorem

For simple polygon, when points are all integer, we have  $A = \#\{\text{lattice points in the interior}\} + \frac{1}{2}\#\{\text{lattice points on the boundary}\} - 1$

#### Matroid

- $B \subseteq A \wedge A \in \mathcal{I} \Rightarrow B \in \mathcal{I}$ .
  - If  $A, B \in \mathcal{I}$  and  $|A| > |B|$ , then  $\exists x \in A \setminus B, B \cup \{x\} \in \mathcal{I}$ .
- |                       |  |
|-----------------------|--|
| Linear matroid        | $A \in \mathcal{I}$ iff linear indep.                                    |
| Graphic matroid       | $\mathcal{I}$ = forests of undirected graph                              |
| Colorful matroid (EX) | Each color $c$ has an upper bound $R_c$ .                                |
| Transversal matroid   | $A \in \mathcal{I}$ iff $\exists$ matching $M$ whose right part is $A$ . |
| Bond matroid          | $A \in \mathcal{I}$ iff $G$ is connected after removing edges $A$ .      |
| Dual matroid          | $A \in \mathcal{I}^*$ iff there is a basis $\subseteq E \setminus A$     |
| Truncated matroid     | $A \in \mathcal{I}'$ iff $A \in \mathcal{I} \wedge  A  \leq k$           |

#### Matroid Intersection

Given matroids  $M_1 = (G, \mathcal{I}_1)$ ,  $M_2 = (G, \mathcal{I}_2)$ , find maximum  $S \in \mathcal{I}_1 \cap \mathcal{I}_2$ . For each iteration, build the directed graph and find a shortest path from  $s$  to  $t$ .

- $s \rightarrow x : S \sqcup \{x\} \in \mathcal{I}_1$
- $x \rightarrow t : S \sqcup \{x\} \in \mathcal{I}_2$
- $y \rightarrow x : S \setminus \{y\} \sqcup \{x\} \in \mathcal{I}_1$  ( $y$  is in the unique circuit of  $S \sqcup \{x\}$ )
- $x \rightarrow y : S \setminus \{y\} \sqcup \{x\} \in \mathcal{I}_2$  ( $y$  is in the unique circuit of  $S \sqcup \{x\}$ )

Alternate the path, and  $|S|$  will increase by 1. In each iteration,  $|E| = O(RN)$ , where  $R = \min(\text{rank}(I_1), \text{rank}(I_2))$ ,  $N = |G|$ . For weighted case, assign weight  $-w(x)$  and  $w(x)$  to  $x \in S$  and  $x \notin S$ , resp. Find the shortest path by Bellman-Ford. The maximum iteration of the Bellman-Ford is  $2R + 1$ .

#### Dual of LP

Primal	Dual
Maximize $c^T x$ s.t. $Ax \leq b, x \geq 0$	Minimize $b^T y$ s.t. $A^T y \geq c, y \geq 0$
Maximize $c^T x$ s.t. $Ax \leq b$	Minimize $b^T y$ s.t. $A^T y = c, y \geq 0$
Maximize $c^T x$ s.t. $Ax = b, x \geq 0$	Minimize $b^T y$ s.t. $A^T y \geq c$

## Minimax Theorem

Let  $f : X \times Y \rightarrow \mathbb{R}$  be continuous where  $X \subseteq \mathbb{R}^n, Y \subseteq \mathbb{R}^m$  are compact and convex. If  $f(\cdot, y) : X \rightarrow \mathbb{R}$  is concave for fixed  $y$ , and  $f(x, \cdot) : Y \rightarrow \mathbb{R}$  is convex for fixed  $x$ , then  $\max_{x \in X} \min_{y \in Y} f(x, y) = \min_{y \in Y} \max_{x \in X} f(x, y)$ , e.g.  $f(x, y) = x^T A y$  for zero-sum matrix game.

## Parallel Axis Theorem

The second moment of area is  $I_z = \iint x^2 + y^2 dA$ .  $I_{z'} = I_z + A d^2$  where  $d$  is the distance between two parallel axis  $z, z'$ .

## 8.2 Weight Matroid Intersection [d00ee8]

```
struct Matroid {
    Matroid(bitset<N>); // init from an independent set
    bool can_add(int); // check if break independence
    Matroid remove(int); // removing from the set
};

auto matroid_intersection(const vector<int> &w) {
    const int n = (int)w.size(); bitset<N> S;
    for (int sz = 1; sz <= n; sz++) {
        Matroid M1(S), M2(S); vector<vector<pii>> e(n + 2);
        for (int j = 0; j < n; j++) if (!S[j]) {
            if (M1.can_add(j)) e[n].eb(j, -w[j]);
            if (M2.can_add(j)) e[j].eb(n + 1, 0);
        }
        for (int i = 0; i < n; i++) if (S[i]) {
            Matroid T1 = M1.remove(i), T2 = M2.remove(i);
            for (int j = 0; j < n; j++) if (!S[j]) {
                if (T1.can_add(j)) e[i].eb(j, -w[j]);
                if (T2.can_add(j)) e[j].eb(i, w[i]);
            }
        } // maybe implicit build graph for more speed
        vector<pii> d(n + 2, {INF, 0}); d[n] = {0, 0};
        vector<int> prv(n + 2, -1);
        // change to SPFA for more speed, if necessary
        for (int upd = 1; upd--;)
            for (int u = 0; u < n + 2; u++)
                for (auto [v, c] : e[u]) {
                    pii x(d[u].first + c, d[u].second + 1);
                    if (x < d[v]) d[v] = x, prv[v] = u, upd = 1;
                }
        if (d[n + 1].first >= INF) break;
        for (int x = prv[n + 1]; x != n; x = prv[x]) S.flip(x);
        // S is the max-weighted independent set w/ size sz
    }
    return S;
} // from Nacl
```

## 8.3 Stable Marriage

- 1: Initialize  $m \in M$  and  $w \in W$  to free
- 2: while  $\exists$  free man  $m$  who has a woman  $w$  to propose to do
- 3:  $w \leftarrow$  first woman on  $m$ 's list to whom  $m$  has not yet proposed
- 4: if  $\exists$  some pair  $(m', w)$  then
- 5: if  $w$  prefers  $m$  to  $m'$  then
- 6:  $m' \leftarrow$  free
- 7:  $(m, w) \leftarrow$  engaged
- 8: end if
- 9: else
- 10:  $(m, w) \leftarrow$  engaged
- 11: end if
- 12: end while

## 8.4 Bitset LCS [4155ab]

```
cin >> n >> m;
for (int i = 1, x; i <= n; ++i)
    cin >> x, p[x].set(i);
for (int i = 1, x; i <= m; ++i) {
    cin >> x, (g = f) |= p[x];
    f.shiftLeftByOne(), f.set(0);
    ((f = g - f) ^= g) &= g;
}
cout << f.count() << '\n';
```

## 8.5 Prefix Substring LCS [7d8faf]

```
void all_lcs(string S, string T) { // 0-base
    vector<size_t> h(T.size()); iota(all(h), 1);
    for (size_t a = 0; a < S.size(); ++a) {
        for (size_t c = 0, v = 0; c < T.size(); ++c)
            if (S[a] == T[c] || h[c] < v) swap(h[c], v);
        // here, LCS(s[0, a], t[b, c]) =
        // c - b + 1 - sum([h[i] > b] | i <= c)
    }
} // test @ yosupo judge
```

## 8.6 Convex 1D/1D DP [e5ab4b]

```
struct S { int i, l, r; };
auto solve(int n, int k, auto &w) {
    vector<int64_t> dp(n + 1);
    auto f = [&](int l, int r) -> int64_t {
```

```
    if (r - l > k) return -INF;
    return dp[l] + w(l + 1, r);
};
dp[0] = 0;
deque<S> dq; dq.emplace_back(0, 1, n);
for (int i = 1; i <= n; ++i) {
    dp[i] = f(dq.front().i, i);
    while (!dq.empty() && dq.front().r <= i)
        dq.pop_front();
    dq.front().l = i + 1;
    while (!dq.empty() &&
        f(i, dq.back().l) >= f(dq.back().i, dq.back().l))
        dq.pop_back();
    int p = i + 1;
    if (!dq.empty()) {
        auto [j, l, r] = dq.back();
        for (int s = 1 << 20; s; s >= 1)
            if (l + s <= n && f(i, l + s) < f(j, l + s))
                l += s;
        dq.back().r = l; p = l + 1;
    }
    if (p <= n) dq.emplace_back(i, p, n);
}
return dp;
} // test @ tioj 烏龜疊疊樂
```

## 8.7 ConvexHull Optimization [b4318e]

```
struct L {
    mutable lld a, b, p;
    bool operator<(const L &r) const {
        return a < r.a; /* here */
    }
    bool operator<(lld x) const { return p < x; }
};

lld Div(lld a, lld b) {
    return a / b - ((a ^ b) < 0 && a % b);
}

struct DynamicHull : multiset<L, less<>> {
    static const lld kInf = 1e18;
    bool Isect(iterator x, iterator y) {
        if (y == end()) { x->p = kInf; return false; }
        if (x->a == y->a)
            x->p = x->b > y->b ? kInf : -kInf; /* here */
        else x->p = Div(y->b - x->b, x->a - y->a);
        return x->p >= y->p;
    }

    void Insert(lld a, lld b) {
        auto z = insert({a, b, 0}), y = z++, x = y;
        while (Isect(y, z)) z = erase(z);
        if (x != begin() && Isect(--x, y)) Isect(x, y = erase(y));
        while ((y = x) != begin() && (--x)->p >= y->p)
            Isect(x, erase(y));
    }

    lld Query(lld x) { // default chmax
        auto l = *lower_bound(x); // to chmin:
        return l.a * x + l.b; // modify the 2 "<>"
    }
};
```

## 8.8 Min Plus Convolution [464dcd]

```
// a is convex a[i+1]-a[i] <= a[i+2]-a[i+1]
vector<int> min_plus_convolution(auto &a, auto &b) {
    const int n = (int)a.size(), m = (int)b.size();
    vector<int> c(n + m - 1, numeric_limits<int>::max());
    auto dc = [&](auto Y, int l, int r, int jl, int jr) {
        if (l > r) return;
        int mid = (l + r) / 2, from = -1, &best = c[mid];
        for (int j = jl; j <= jr; ++j)
            if (int i = mid - j; i >= 0 && i < n)
                if (best > a[i] + b[j]) best = a[i] + b[j], from = j;
        Y(Y, l, mid - 1, jl, from); Y(Y, mid + 1, r, from, jr);
    };
    return dc(dc, 0, n - 1 + m - 1, 0, m - 1), c;
}
```

## 8.9 SMAWK [9fca41]

```
// For all 2x2 submatrix:
// If M[1][0] < M[1][1], M[0][0] < M[0][1]
// If M[1][0] == M[1][1], M[0][0] <= M[0][1]
// M[i][ans_i] is the best value in the i-th row
VI smawk(int N, int M, auto &&select) {
    auto solve = [&](const VI &r, const VI &c) {
        if (r.empty()) return {};
        const int n = (int)r.size(); vector<int> c2;
        for (int i : c) {
```



```

while (!c2.empty() && select(r[c2.size() - 1], c2.
    back(), i))
    c2.pop_back();
if (c2.size() < n) c2.push_back(i);
}
vector<int> r2;
for (int i = 1; i < n; i += 2) r2.push_back(r[i]);
const auto a2 = solve(r2, c2);
vector<int> ans(n);
for (size_t i = 0; i < a2.size(); i++)
    ans[i * 2 + 1] = a2[i];
for (int i = 0, j = 0; i < n; i += 2) {
    ans[i] = c2[j];
    const int end = i + 1 == n ? c2.back() : ans[i + 1];
    while (c2[j] != end) {
        j++;
        if (select(r[i], ans[i], c2[j])) ans[i] = c2[j];
    }
}
return ans;
};
vector<int> row(N), col(M);
iota(all(row), 0), iota(all(col), 0);
return dc(dc, row, col);
}
// if f(r, v) is better than f(r, v), return true
bool min_plus_conv_select(int r, int u, int v) {
    auto f = [](int i, int j) {
        if (0 <= i - j && i - j < n) return b[j] + a[i - j];
        return 2100000000 + (i - j);
    };
    return f(r, u) > f(r, v);
}

```

### 8.10 De-Bruijn [aa7700]

```

vector<int> de_bruijn(int k, int n) {
    // return cyclic string of len k^n s.t. every string
    // of len n using k char appears as a substring.
    vector<int> aux(n + 1), res;
    auto db = [&](auto self, int t, int p) -> void {
        if (t <= n)
            for (int i = aux[t - p]; i < k; ++i, p = t)
                aux[t] = i, self(self, t + 1, p);
        else if (n % p == 0) for (int i = 1; i <= p; ++i)
            res.push_back(aux[i]);
    };
    return db(db, 1, 1), res;
}

```

### 8.11 Josephus Problem [7f9ceb]

```

lld f(lld n, lld m, lld k) { // n people kill m for
    each turn
    lld s = (m - 1) % (n - k); // O(k)
    for (lld i = n - k + 1; i <= n; i++) s = (s + m) % i;
    return s;
}
lld kth(lld n, lld m, lld k) { // died at kth
    if (m == 1) return k; // O(m log(n))
    for (k = k*m+m-1; k >= n; k = k-n + (k-n)/(m-1));
    return k;
} // k and result are 0-based, test @ CF 101955

```

### 8.12 N Queens Problem [31f83e]

```

void solve(VI &ret, int n) { // no sol when n=2,3
    if (n % 6 == 2) {
        for (int i = 2; i <= n; i += 2) ret.push_back(i);
        ret.push_back(3); ret.push_back(1);
        for (int i = 7; i <= n; i += 2) ret.push_back(i);
        ret.push_back(5);
    } else if (n % 6 == 3) {
        for (int i = 4; i <= n; i += 2) ret.push_back(i);
        ret.push_back(2);
        for (int i = 5; i <= n; i += 2) ret.push_back(i);
        ret.push_back(1); ret.push_back(3);
    } else {
        for (int i = 2; i <= n; i += 2) ret.push_back(i);
        for (int i = 1; i <= n; i += 2) ret.push_back(i);
    }
}

```

### 8.13 Tree Knapsack [f42766]

```

vector<int> G[N]; int dp[N][K]; pair<int, int> obj[N];
void dfs(int u, int mx) {
    for (int s : G[u]) {
        auto [w, v] = obj[s];

```

```

        if (mx < w) continue;
        for (int i = 0; i <= mx - w; i++)
            dp[s][i] = dp[u][i];
        dfs(s, mx - w);
        for (int i = w; i <= mx; i++)
            dp[u][i] = max(dp[u][i], dp[s][i - w] + v);
    }
}

```

### 8.14 Manhattan MST [1008bc]

```

vector<array<int, 3>> manhattanMST(vector<P> ps) {
    vector<int> id(ps.size()); iota(all(id), 0);
    vector<array<int, 3>> edges;
    for (int k = 0; k < 4; k++) {
        sort(all(id), [&](int i, int j) {
            return (ps[i] - ps[j]).x < (ps[j] - ps[i]).y; });
        map<int, int> sweep;
        for (int i : id) {
            for (auto it = sweep.lower_bound(-ps[i].y);
                it != sweep.end(); sweep.erase(it++)) {
                if (P d = ps[i] - ps[it->second]; d.y > d.x) break;
                else edges.push_back({d.y + d.x, i, it->second});
            }
            sweep[-ps[i].y] = i;
        }
        for (P &p : ps)
            if (k & 1) p.x = -p.x;
            else swap(p.x, p.y);
    }
    return edges; // [{w, i, j}, ...]
} // test @ yosupo judge

```

### 8.15 Binary Search On Fraction [765c5a]

```

struct Q {
    ll p, q;
    Q go(Q b, ll d) { return {p + b.p*d, q + b.q*d}; }
};
bool pred(Q);
// returns smallest p/q in [lo, hi] such that
// pred(p/q) is true, and 0 <= p, q <= N
Q frac_bs(ll N) {
    Q lo{0, 1}, hi{1, 0};
    if (pred(lo)) return lo;
    assert(pred(hi));
    bool dir = 1, L = 1, H = 1;
    for (; L || H; dir = !dir) {
        ll len = 0, step = 1;
        for (int t = 0; t < 2 && (t ? step/=2 : step*=2);)
            if (Q mid = hi.go(lo, len + step);
                mid.p > N || mid.q > N || dir ^ pred(mid))
                t++;
            else len += step;
        swap(lo, hi = hi.go(lo, len));
        (dir ? L : H) = !len;
    }
    return dir ? hi : lo;
}

```

### 8.16 Barrett Reduction [d44617]

```

struct FastMod {
    using Big = __uint128_t; ll b, m;
    FastMod(llu b) : b(b), m(-1ULL / b) {}
    llu reduce(llu a) { // a % b
        llu r = a - (llu)((Big(m) * a) >> 64) * b;
        return r >= b ? r - b : r;
    }
};

```

### 8.17 Montgomery [648fb3]

```

struct Mont { // Montgomery multiplication
    constexpr static int W = 64, L = 6;
    ll mod, R1, R2, xinv;
    void set_mod(llu _mod) {
        mod = _mod; assert(mod & 1); xinv = 1;
        for (int j = 0; j < L; j++) xinv *= 2 - xinv * mod;
        assert(xinv * mod == 1);
        const u128 R = (u128(1) << W) % mod;
        R1 = ll(R); R2 = ll(R*R % mod);
    }
    llu redc(llu a, llu b) const {
        u128 T = u128(a) * b, m = -llu(T) * xinv;
        T += m * mod; T >>= W;
        return ll(T >= mod ? T - mod : T);
    }
    llu from(llu x) const {

```

```

    assert(x < mod); return redc(x, R2); }
    llu get(llu a) const { return redc(a, 1); }
    llu one() const { return R1; }
} mont;
// a * b % mod == get(redc(from(a), from(b)))

```

## 8.18 Nim Product [4ac1ce]

```

#define rep(i, r) for (int i = 0; i < r; i++)
struct NimProd {
    llu bit_prod[64][64] {}, prod[8][8][256][256] {};
    NimProd() {
        rep(i, 64) rep(j, 64) if (i & j) {
            int a = lowbit(i & j);
            bit_prod[i][j] = bit_prod[i ^ a][j] ^
                bit_prod[(i ^ a) | (a-1)][(j ^ a) | (i & (a-1))];
        } else bit_prod[i][j] = 1ULL << (i | j);
        rep(e, 8) rep(f, 8) rep(x, 256) rep(y, 256)
            rep(i, 8) if (x >> i & 1) rep(j, 8) if (y >> j & 1)
                prod[e][f][x][y] ^= bit_prod[e * 8 + i][f * 8 + j];
    }
    llu operator()(llu a, llu b) const {
        llu r = 0;
        rep(e, 8) rep(f, 8)
            r ^= prod[e][f][a >> (e*8) & 255][b >> (f*8) & 255];
        return r;
    }
};

```