
MODULE *Reachable*

This module specifies an algorithm for computing the set of nodes in a directed graph that are reachable from a given node called *Root*. The algorithm is due to *Jayadev Misra*. It is, to my knowledge, a new variant of a fairly obvious breadth-first search for reachable nodes. I find this algorithm interesting because it is easier to implement using multiple processors than the obvious algorithm. Module *ParReach* describes such an implementation. You may want to read it after reading this module.

The proof of *Misra's* variant is also subtler than that of the obvious algorithm. Module *ReachableProofs* contains a TLA+ proof of the algorithm's safety property—that is, partial correctness, which means that if the algorithm terminates then it produces the correct answer. That proof has been checked by *TLAPS*, the TLA+ proof system. The proof is based on ideas from an informal correctness proof by *Misra*.

In this module, reachability is expressed in terms of the operator *ReachableFrom*, where *ReachableFrom(S)* is the set of nodes reachable from the nodes in the set *S* of nodes. This operator is defined in module *Reachability*. That module describes a directed graph in terms of the constants *Nodes* and *Succ*, where *Nodes* is the set of nodes and *Succ* is a function with domain *Nodes* such that *Succ[m]* is the set of all nodes *n* such that there is an edge from *m* to *n*. If you are not familiar with directed graphs, you should read at least the opening comments in module *Reachability*.

EXTENDS *Reachability*, *Integers*, *FiniteSets*

CONSTANT *Root*

ASSUME *RootAssump* \triangleq *Root* \in *Nodes*

Reachable is defined to be the set of nodes reachable from *Root*. The purpose of the algorithm is to compute *Reachable*.

Reachable \triangleq *ReachableFrom*({*Root*})

The obvious algorithm for computing *Reachable*({*Root*}) is as follows. There are two variables which, following *Misra*, we call *marked* and *vroot*. Each variable holds a set of nodes that are reachable from *Root*. Initially, *marked* = {} and *vroot* = {*Root*}. While *vroot* is non-empty, the obvious algorithm removed an arbitrary node *v* from *vroot*, adds *v* to *marked*, and adds to *vroot* all nodes in *Succ[v]* that are not in *marked*. The algorithm terminates when *vroot* is empty, which will eventually be the case if and only if *Reachable*({*Root*}) is a finite set. When it terminates, *marked* equals *Reachable*({*Root*}).

In the obvious algorithm, *marked* and *vroot* are always disjoint sets of nodes. *Misra's* variant differs in that *marked* and *vroot* are not necessarily disjoint. While *vroot* is nonempty, it chooses an arbitrary node and does the following:

```
IF v is not in marked THEN it performs the same action as the obvious algorithm except:
    (1) it doesn't remove v from vroot, and
    (2) it adds all nodes in Succ[v] to vroot, not just the ones not in marked.
ELSE it removes v from vroot
```

Here is the algorithm's *PlusCal* code.

```
--fair algorithm Reachable{
  variables marked = {}, vroot = {Root};
  { a: while ( vroot  $\neq$  {} )
    { with ( v  $\in$  vroot )
      { if ( v  $\notin$  marked )
```

```

        { marked := marked ∪ {v};
          vroot := vroot ∪ Succ[v] }
      else { vroot := vroot \ {v} }
    }
  }
}

```

Here is the TLA+ translation of the *PlusCal* code.

```

BEGIN TRANSLATION
VARIABLES marked, vroot, pc

vars ≜ ⟨marked, vroot, pc⟩

Init ≜ Global variables
      ∧ marked = {}
      ∧ vroot = {Root}
      ∧ pc = "a"

a ≜ ∧ pc = "a"
    ∧ IF vroot ≠ {}
      THEN ∧ ∃ v ∈ vroot :
        IF v ∉ marked
          THEN ∧ marked' = (marked ∪ {v})
              ∧ vroot' = (vroot ∪ Succ[v])
          ELSE ∧ vroot' = vroot \ {v}
              ∧ UNCHANGED marked
        ∧ pc' = "a"
      ELSE ∧ pc' = "Done"
          ∧ UNCHANGED ⟨marked, vroot⟩

Next ≜ a
      ∨ Disjunct to prevent deadlock on termination
        (pc = "Done" ∧ UNCHANGED vars)

Spec ≜ ∧ Init ∧ □[Next]vars
      ∧ WFvars(Next)

Termination ≜ ◇(pc = "Done")

END TRANSLATION

```

Partial correctness is based on the invariance of the following four state predicates. I have sketched very informal proofs of their invariance, as well of proofs of the the two theorems that assert correctness of the algorithm. The module *ReachableProofs* contains rigorous, *TLAPS* checked TLA+ proofs of all except the last theorem. The last theorem asserts termination, which is a liveness property, and *TLAPS* is not yet capable of proving liveness properties.

$$\begin{aligned}
TypeOK &\triangleq \wedge marked \in \text{SUBSET } Nodes \\
&\wedge vroot \in \text{SUBSET } Nodes \\
&\wedge pc \in \{ "a", "Done" \} \\
&\wedge (pc = "Done") \Rightarrow (vroot = \{\})
\end{aligned}$$

The invariance of *TypeOK* is obvious. (I decided to make the obvious fact that *pc* equals "Done" only if *vroot* is empty part of the type-correctness invariant.)

$$\begin{aligned}
Inv1 &\triangleq \wedge TypeOK \\
&\wedge \forall n \in marked : Succ[n] \subseteq (marked \cup vroot)
\end{aligned}$$

The second conjunct of *Inv1* is invariant because each element of *Succ*[*n*] is added to *vroot* when *n* is added to *marked*, and it remains in *vroot* at least until it's added to *marked*. I made *TypeOK* a conjunct of *Inv1* to make *Inv1* an inductive invariant, which made the TLA+ proof of its invariance a tiny bit easier to read.

$$Inv2 \triangleq (marked \cup ReachableFrom(vroot)) = ReachableFrom(marked \cup vroot)$$

Since *ReachableFrom*(*marked* \cup *vroot*) is the union of *ReachableFrom*(*marked*) and *ReachableFrom*(*vroot*), to prove that *Inv2* is invariant we must show *ReachableFrom*(*marked*) is a subset of *marked* \cup *ReachableFrom*(*vroot*). For this, we assume that *m* is in *ReachableFrom*(*marked*) and show that it either is in *marked* or is reachable from a node in *vroot*.

Since *m* is in *ReachableFrom*(*marked*), there is a path with nodes *p*₁, *p*₂, ..., *p*_{*j*} such that *p*₁ is in *marked* and *p*_{*j*} = *m*. If all the *p*_{*i*} are in *marked*, then *m* is in *marked* and we're done. Otherwise, choose *i* such that *p*₁, ..., *p*_{*i*} are in *marked*, but *p*_(*i*+1) isn't in *marked*. Then *p*_(*i*+1) is in *succ*[*p*_{*i*}], which by *Inv1* implies that it's in *marked* \cup *vroot*. Since it isn't in *marked*, it must be in *vroot*. The path with nodes *p*_(*i*+1), ..., *p*_{*j*} shows that *p*_{*j*}, which equals *m*, is in *ReachableFrom*(*vroot*). This completes the proof that *m* is in *marked* or *ReachableFrom*(*vroot*).

$$Inv3 \triangleq Reachable = marked \cup ReachableFrom(vroot)$$

For convenience, let *R* equal *marked* \cup *ReachableFrom*(*vroot*). In the initial state, *marked* = {} and *vroot* = {*Root*}, so *R* equals *Reachable* and *Inv3* is true. We have to show that each action *a* step leaves *R* unchanged. There are two cases:

Case1: The *a* step adds an element *v* of *vroot* to *marked* and adds to *vroot* the nodes in *Succ*[*v*], which are all in *ReachableFrom*(*vroot*). Since *v* itself is also in *ReachableFrom*(*vroot*), the step leaves *R* unchanged.

Case 2: The *a* step removes from *vroot* an element *v* of *marked*. Since *Inv1* implies that every node in *Succ*[*v*] is in *vroot*, the only element that this step removes from *ReachableFrom*(*vroot*) is *v*, which the step adds to *marked*. Hence *R* is unchanged.

It is straightforward to use *TLC* to check that *Inv1-Inv3* are invariants of the algorithm for small graphs.

Partial correctness of the algorithm means that if it has terminated, then *marked* equals *Reachable*. The algorithm has terminated when *pc* equals "Done", so this theorem asserts partial correctness.

THEOREM *Spec* $\Rightarrow \Box((pc = "Done") \Rightarrow (marked = Reachable))$

TypeOK implies $(pc = "Done") \Rightarrow (vroot = \{\})$. Since, *ReachableFrom*({}) equals {}, *Inv3* implies $(vroot = \{\}) \Rightarrow (marked = Reachable)$. Hence the theorem follows from the invariance of *TypeOK* and *Inv3*.

The following theorem asserts that if the set of nodes reachable from *Root* is finite, then the algorithm eventually terminates. Of course, this liveness property can be true only because *Spec* implies weak fairness of *Next*, which equals action *a* .

THEOREM ASSUME $IsFiniteSet(Reachable)$
 PROVE $Spec \Rightarrow \Diamond(pc = \text{"Done"})$

To prove the theorem, we assume a behavior satisfies *Spec* and prove that it satisfies $\Diamond(pc = \text{"Done"})$. If $pc = \text{"a"}$ and $vroot = \{\}$, then an *a* step sets *pc* to "Done". Since invariance of *TypeOK* implies $\Box(pc \in \{\text{"a"}, \text{"Done"}\})$, weak fairness of *a* implies that to prove $\Diamond(pc = \text{"Done"})$, it suffices to prove $\Diamond(vroot = \{\})$.

We prove $\Diamond(vroot = \{\})$ by contradiction. We assume it's false, which means that $\Box(vroot \neq \{\})$ is true, and obtain a contradiction. From

$\Box TypeOK$, we infer that $\Box(vroot \neq \{\})$ implies $\Box(pc = \text{"a"})$. By weak fairness of action *a* , $\Box(vroot \neq \{\})$ implies that there are an infinite number of *a* steps. The assumption that *Reachable* is finite and $\Box Inv3$ imply that *marked* and *vroot* are always finite. Since *vroot* is always finite and nonempty, from any state there can be only a finite number of *a* steps that remove an element from *vroot* until there is an *a* step that adds a new element to *marked* . Since there are an infinite number of *a* steps, there must be an infinite number of steps that add new elements to *marked* . This is impossible because *marked* is a finite set. Hence, we have the required contradiction.

TLC can quickly check these two theorems on models containing a half dozen nodes.

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