*p = *current; /* NOTE! this doesn't copy the supervisor stack */

进程运行轨迹的跟踪与统计

long

//添加新建标记 //进入就绪标记

- 1 内核代码修改 1.1对fork.c的修改: int copy_process long long long int long long long long long long

'操作系统原理与实践"实验报告 long long long long long long

- % 实验代码 task_struct struct *p; int i; struct file *f; p = (struct task_struct *) get_free_page(); if (!p) return - EAGAIN;

task[nr] = p;

p->pid = last_pid;

/**************/

/***************/

1.2 对sched.c的修改 1.2.1 void schedule(void)

struct task_struct ** p;

return last_pid;

void schedule(void)

int i,next,c;

while (1) {

进程准备运行*****/

switch_to(next);

1.2.2 int sys_pause(void)

int sys_pause(void)

schedule(); return 0;

if (!p)

tmp = *p;*p = current;

schedule(); if (tmp)

完成添加

return ;

}

{

c = -1;

if (*p)

/******修改完成******/

/*****进入阻塞标记****/

1.2.3 void sleep_on(struct task_struct **p)

struct task_struct *tmp;

/******阻塞标记******/

/*******添加完成*****/

// 若唤醒但未能执行,则处于就绪状态

tmp - >state= 0;

struct task_struct *tmp;

if (current == &(init_task.task))

if (!p)

tmp=*p; *p=current;

/*******/

/*******/

schedule();

*p=NULL; if (tmp)

repeat:

return ;

void sleep_on(struct task_struct **p)

if (current == &(init_task.task))

panic("task[0] trying to sleep");

if (current ->state != TASK_UNINTERRUPTIBLE)

current ->state = TASK_UNINTERRUPTIBLE;

if (tmp ->state != TASK_RUNNING)

/*******/

/*****/

1.2.4 void interruptible_sleep_on(struct task_struct **p)

void interruptible_sleep_on(struct task_struct **p)

panic("task[0] trying to sleep");

if (current ->state = TASK_INTERRUPTIBLE)

current ->state = TASK_INTERRUPTIBLE;

if (*p && *p != current) {

/*****添加就绪标记***/

if ((*p) ->state != 0)

/****添加就绪标记****/

if (tmp - >state != 0)

/****完成***/

tmp - > state = 0;

1.2.5 void wake_up(struct task_struct **p)

/*****添加标记***/ if ((**p).state!= 0)

/***完成**/

*p= NULL;

int do_exit(long

int i;

(**p).state= 0;

1.3 修改exit.c 1.3.1 int do_exit(long code)

if (current ->leader) kill_session();

/****添加退出标记****/

current ->exit_code = code; tell_father(current ->father);

int sys_waitpid pid_t unsigned

if (options & WNOHANG)

0;

/ **** 添加阻塞标记****/

goto repeat;

1.4 修改printk.c 直接使用老师提供的写文件程序

const char

"linux/sched.h"

"sys/stat.h"

static char logbuf[1024];

int

args;

file * file;

m_inode * inode;

fmt);

(logbuf,

_asm__("push %%fs\n\t"

if (!(file=task[0]->filp[fd]))

return 0; inode=file ->f_inode;

:: "r"

count;

2 对初始化程序main.c的修改

floppy_init();

move_to_user_mode();

(void) dup(0); (void) dup(0);

/****完成****/

init();

void init void

/*完成注释*/

void cpuio_bound(

int main(int argc,

if (! fork ())

HZ 100

把100改为200(或者是50,随意)

48

48

48

49

49

49

49

64

64

64

64

68

68

73

73 74

74

74

74

106

107

107

107

109

109

109

115

115

115

291

291

291

291

302

302

302

302

319

319

320

320

330

330

330

330

95

95

95

96

96

96

96

126

126

127

127

139

139

146

146

147

147

147

147

212

212

213

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547 547

547

547

567 567

567 568

596 596

596 596

614

614

614

614

使用老师提供的统计程序stat_log.py进行分析 日志1的结果(时间片100HZ):

CPU Burst

8

2

20

4

52

2

8

5

195

192

195

195

1

195

195

3

90

100

45

1

0

45 1

15

CPU Burst

55

3

38

12

5

0

16

180

156

195

195

195

171

0

0

6 总结 第一,系统中进程0、1以及shell进程是占用系统最多的进程,也是系统中必须存在的进程,也可以得出实

际上系统大部分时间都在等待中。第二,在修改了时间片后,进程占用时间也在修改,几乎也是一倍。要以看出一个

后记: 在本次实验中可以看到,记录文件并未记录到进程0的诞生,这是因为进程0不是通过fork产生的,而是由系统

15

0

3

100

3

I/O Burst

176

0

0

2357

2081

0

0

1056

0

110

0

0

539

0

102

0

0 0

0

543

631

0

524

0

I/O Burst

318

0

0

2265

2084

1035

206

1046

1042

205 0

0

0

0

0

0 0

0

0

1053

Waiting

67

0

4

0

52

0

0

96

1653

1531

1622

1591

1559

1378

0

883

989

625

32

49

395

33

1

448.31

Waiting

134

0

12

1

81

1

181

101

872

673

933

915

33

879

681

277.60

0

51

48

32

return 0;

#define

N

J

R

N

J

W

R

N

J

J

R

W

R

E

R

N J

W

R

N

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tick)

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3

4

5

6

7

8

9

10

11

12

13

14

15

16

17

18

19

20

26

27

28

35

Average: Throughout:

(Unit:

Process

Turnaround

551

24

4

3

8

2185

1157

1848

1833

1817

1104

1786

572

1754

1675

3

973

1089

670

576

.....

680

440

558

16

765.14

.....

1.44/s

Turnaround

1024

2268

50

13

6

197

1136

1052

1035

1128

1097

1110

1078

1074

1057

0

17

780.75

手动生成的,具体情况此次实验并未深入研究。

0.84/s

好的调度算法对系统是很重要的。

2265

日志2的结果(时间片200HZ):

tick)

0

1

2

3

4

5

6

7

8

9

10

12

13

14

15

16 17

18

19

Average:

Throughout:

2359

J

0 1

2 2

1

2

3

3

2

3

3

2

2

1

4

4

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5

5

4

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4

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4

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0

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4 0

4

4 4

0

日志2

1

0

1

2

2

1

2

3

3 2

3

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2

2

1

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(Unit:

Process

cpuio_bound(

cpuio_bound(

cpuio_bound(

cpuio_bound(

cpuio_bound(

cpuio_bound(

cpuio_bound(

cpuio_bound(

cpuio_bound(

修改时间片 打开sched.h头文件,修改

int pid,i; /*注释掉这段代码*/

> //(void) dup(0); //(void) dup(0);

/****将这段代码提前至此****/

setup((void *) &drive_info);

//setup((void *) &drive_info);

//(void) open("/dev/tty0",O_RDWR,0);

NR_BUFFERS*BLOCK_SIZE);

_exit(0); /* NOTE! _exit, not exit() */

int last , int cpu_time,

3 给定任务 修改/home/teacher 下的proccess.c给出测试的任务

char * argv[])

10, 0, 1);

10, 1, 0);

10, 1, 1);

10, 5, 0);

10, 0, 5);

10, 4, 4);

5, 0, 1);

5, 1, 0);

5, 1, 1);

(void) open("/dev/tty0" ,O_RDWR,0);

sti();

return

__asm__("push %%fs\n\t"

fmt, args);

:: "r" (count), "r" (fd): "ax", "cx", "dx");

(count), "r" (file), "r" (inode): "ax", "cx", "dx");

void main void /* This really IS void, no error here. */

(void) open("/var/process.log" , O_CREAT|O_TRUNC|O_WRONLY, 0666);

if (!fork()) { /* we count on this going ok */

printf ("%d buffers = %d bytes buffer space\n\r" ,NR_BUFFERS,

printf ("Free mem: %d bytes\n\r" ,memory_end - main_memory_start);

int io_time);

进行实验 挂载虚拟机硬盘把process.c拷贝到~/oslab/hdc/usr/root/,运行虚拟机编译process,然后执行,得到日

志process.log,将其拷贝到ubuntu下。修改时间片,编译内核,同样得到日志2。 日志1

return - EINTR;

current ->state=TASK_INTERRUPTIBLE;

code;

return

/****完成****/

schedule();

else

#include

#include

int

fprintk

va_list

struct

struct

else

int count;

va_start(args,

va_end(args);

if (fd < 3)

count= vsprintf

return - ECHILD;

struct task_struct

verify_area(stat_addr,

/****完成****/

schedule();

int flag,

flag= 0;

repeat:

code)

current ->state = TASK_ZOMBIE;

free_page_tables(get_base(current ->ldt[1]),get_limit(free_page_tables(get_base(current ->ldt[2]),get_limit(

fprintk(3, "%ld\t%c\t%ld\n" , current ->pid, "E" , jiffies);

long

 $fprintk(\ \ 3, \ \ "\%ld\t%c\t%ld\n" \ \ , \ current \ \ ->pid, \ \ "W" \ , \ jiffies);$

if (!(current ->signal &= ~(1<<(SIGCHLD-1))))

return (-1); /* just to suppress warnings */

4);

1.3.2 int sys_waitpid(pid_t pid,unsigned long *stat_addr, int options)

void wake_up struct

if (p &&*p) {

/****完成***/

(**p).state= 0;

goto repeat;

fprintk(3, "%ld\t%c\t%ld\n" , current ->pid, "W" , jiffies);

fprintk(3, "%ld\t%c\t%ld\n" , (**p).pid, " , jiffies);

fprintk(3, "%ld\t%c\t%ld\n" , tmp - >pid, 'J' , jiffies);

0x0f)); 0x17));

int

fprintk(3, "%ld\t%c\t%ld\n" , current ->pid, "W", jiffies);

fprintk(3, "%ld\t26c\t26ld\n" , current ->pid, ", jiffies);

if (current ->state !=TASK_INTERRUPTIBLE)

current ->state = TASK_INTERRUPTIBLE;

if (task[next] ->pid != current ->pid)

if (current ->state == TASK_RUNNING)

}

p->state = TASK_UNINTERRUPTIBLE;

set_tss_desc(gdt+(nr<< 1)+FIRST_TSS_ENTRY,&(p ->tss));

set_ldt_desc(gdt+(nr<< 1)+FIRST_LDT_ENTRY,&(p ->ldt));

for (p = &LAST_TASK; p > &FIRST_TASK; -- p)

(*p) - >priority;

(*p) ->counter = ((*p) ->counter >> 1) +

fprintk(3, "%ld\t%c\t%ld\n" , current ->pid, ", jiffies);

fprintk(3, "%ld\t%c\t%ld\n" , task[next] ->pid, 'R' , jiffies);

fprintk(3, "%ld\t%c\t%ld\n" , current ->pid, "W", jiffies);

/*******添加就绪或者是运行标记,若当前进程和下一个进程不相同则说明时间片用完,处于就绪状态,下一

fprintk(3, "%ld\t%c\t%ld\n" , last_pid, 'N' , jiffies);
fprintk(3, "%ld\t%c\t%ld\n" , last_pid, 'J' , jiffies);

p->state = TASK_RUNNING; /* do this last, just in case */