

一.改写bootsect.s在屏幕上打出的Logo信息

1.注意msg1段中还含有回车,换行,计算总字节数时不要漏了

```
31         .word 0
32
33 msg1:
34     .byte 13,10
35     .ascii "BrickOS is booting"
36     .byte 13,10,13,10
37
38     ---  ---
```

所以CX=22+6=28 bytes

```
88         mov  ax, 0x10000
89         mov  es, ax
90
91
92 ! Print some inane message
93
94     mov  ah, #0x03          ! read cursor pos
95     xor  bh, bh
96     int  0x10
97
98     mov  cx, #28
99     mov  bx, #0x0007        ! page 0, attribute 7 (normal)
100    mov  bp, #msg1
101    mov  ax, #0x1301        ! write string, move cursor
102    int  0x10
103
104    ---  ---
```

2.删掉bootsect.s中多余的代码.因为实验要求中说:

setup.s不再加载Linux内核.

即无需加载system模块,所以bootsect.s中加载system的部分都可删掉.比如,这个把system读到0x10000的read_it函数删掉

```
104 ! ok, we've written the message, now
105 ! we want to load the system (at 0x10000)
106
107     mov  ax, #SYSSEG
108     mov  es, ax             ! segment of 0x010000
109     call read_it
110
111     ---  ---
112
142 ! no 64kB boundaries are crossed. We try to load it as fast as
143 ! possible, loading whole tracks whenever we can.
144 !
145 ! in:  es - starting address segment (normally 0x1000)
146 !
147 sread: .word 1+SETUPLEN    ! sectors read of current track
148 head:  .word 0            ! current head
149 track:  .word 0            ! current track
150
151 read_it:
152     mov  ax, es
153     test ax, #0x0fff
154 die:    jne die             ! es must be at 64kB boundary
155     xor  bx, bx             ! bx is starting address within segment
156 rp_read:
157     mov  ax, es
158     cmp  ax, #ENDSEG        ! have we loaded all yet?
159     jb  ok1_read
160     ret
161 ok1_read:
162     seg  cs
163     mov  ax, sectors
164     sub  ax, sread
165     mov  cx, ax
166     shl  cx, #9
167     add  cx, bx
168     jnc  ok2_read
169     je  ok2_read
170     xor  ax, ax
171     sub  ax, bx
172     shr  ax, #9
173 ok2_read:
174     call read_track
175     mov  cx, ax
176     add  ax, sread
177     seg  cs
178     cmp  ax, sectors
179     jne ok3_read
```

二.改写setup.s

1.在准备好标号msg2后,在setup.s的起始处打出"Now we are in SETUP"

```
30 entry_start
31 start:
32
33 ! ok, the read went well so we get current cursor position and save it for
34 ! posterity.
35     mov  ax, cs             ! 因为跳到cs==0x9020处执行setup, 所以es的值也要随之改变
36     mov  es, ax
37
38     mov  ah, #0x03          ! read cursor pos
39     xor  bh, bh
40     int  0x10
41
42     mov  cx, #23
43     mov  bx, #0x0007        ! 打出警告信息
44     mov  bp, #msg2
45     mov  ax, #0x1301        ! write string, move cursor
46     int  0x10
47
48     mov  ax, #INITSEG ! this is done in bootsect already, but...
49     mov  ds, ax
50     mov  ah, #0x03          ! read cursor pos
51     xor  bh, bh
52     int  0x10              ! save it in known place, con_init fetches
53     mov  [0], dx            ! it from 0x90000.
```

2.打出硬件信息

-把各硬件的参数以16进制输出,所以准备好函数print_hex,函数参数存放在DX中

```
160 print_hex:
161     mov  cx, #4             ! 4个十六进制数字
162     print_digit:
163         rol  dx, #4          ! 循环以便低4比特用上 !! 取dx的高4比特移到低4比特处。
164         mov  ax, #0xe0f      ! ah = 请求的功能值, al = 半字节(4个比特)掩码。
165         and  al, dl           ! 取dl的低4比特值。
166         add  al, #0x30       ! 给al数字加上十六进制0x30
167         cmp  al, #0x3a
168         jl  outp             ! 是一个不大于十的数字
169         add  al, #0x07        ! 是a~f, 要多加7
170     outp:
171         int  0x10
172         loop print_digit
173     ret
```

-还要专门用一个函数打印换行回车

```
174
175     print_nl:               ! 打印回车换行
176         mov  ax, #0xe0d      ! CR
177         int  0x10
178         mov  al, #0xa        ! LF
179         int  0x10
180         ret
```

-准备好硬件参数前的提示信息

```
181 cursor:
182     .ascii "Cursor POS: "   ! 各硬件参数前面的废话
183 memory:
184     .ascii "Memory SIZE: "
185 cyls:
186     .ascii "Cyls: "
```

-然后就可以正式的输出硬件信息了.以内存信息为例,先用0x10中断定位光标位置,再用该中断的 0x13号功能打印提示信息.最后调用print_hex打印16进制的硬件参数

```
127     mov  ah, #0x03          ! read cursor pos
128     xor  bh, bh
129     int  0x10
130
131     mov  cx, #12
132     mov  bx, #0x0007        ! 开始打印内存信息
133     mov  bp, #memory
134     mov  ax, #0x1301
135     int  0x10
136
137     mov  dx, [2]
138     call print_hex
139     call print_nl
140
```

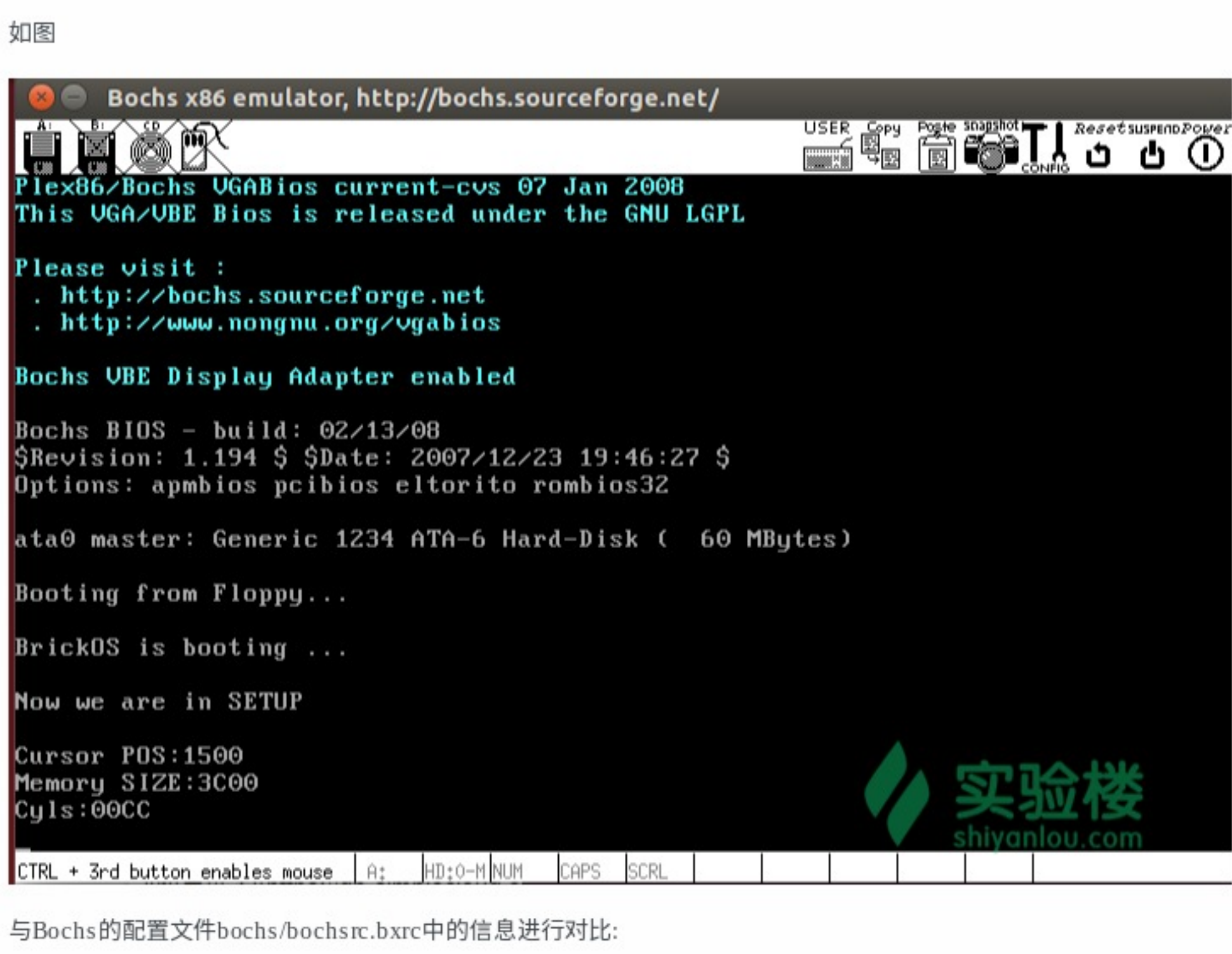
3.删除多余的代码 同理,由于无需继续载入system模块,所以把setup.s中诸如-"把system模块移动到0x0000处"-"重设中断向量表"-"从实模式进入保护模式"-"跳到system模块执行"等等都可删除

4.也因为现在这个操作系统只剩bootsect.s和setup.s了,不可能继续往下执行,所以在打印玩硬件参数后, 用一个无限循环保持上述信息在屏幕上显示

```
154
155     pop  dx
156
157     unlimited:
158     jmp  unlimited
159
```

三.运行结果

如图



与Bochs的配置文件bochs/bochsrc.bxrc中的信息进行对比:

```
2 megs: 16
3 vga: vm: file=$OSLAB_PATH/bochs/vgabios.bin
4 floppyas: 1,44-"$OSLAB_PATH/linux-0.11/image", status=inserted
5 ata0-master: type=disk, path="$OSLAB_PATH/hdc-0.11.img", mode=flat, cylinders=204, heads=16, sectors=25
6 boot: a
7 log: $OSLAB_PATH/bochsout.txt
```

发现参数都是吻合的,说明实验成功

四.找出x86为了向下兼容而多此一举的步骤

通过这个实验,个人认为有:

1.必须以老掉牙的实模式启动操作系统,则可寻址的范围只有那1M多,尽管当下计算机的内存大小以及寻址能力已经大大超过这个范围了

2.由于1中的原因,编写的bootsect.s和setup.s所占空间都不能太大,以免超过实模式的寻址范围.