

```
pop %fs
pop %es
pop %ds
iret
```

不要忘了在system_calls中把它们设为全局可见,而且在sched.c和fork.c这些引用它们的文件中加上声明.

```
70 .globl system_call,sys_fork,timer_interrupt,sys_execve,switch_to
71 .globl hd_interrupt,floppy_interrupt,parallel_interrupt
72 .globl device_not_available, coprocessor_error,first_return_from_kernel
73 -- -- -- -- --
```

```
50 extern int timer_interrupt(void);
51 extern int system_call(void);
52
53 extern void switch_to(struct task_struct * pnext,unsigned long idm);
54
```

```
--
20 extern void write_verify(unsigned long address);
21 extern void first_return_from_kernel(void);
22 long last_pid=0;
23
```

因为在PCB,即结构体task_struct中增加了kernelstack这个field,所以要修改一下system_calls中的一些硬编码,不过我没按实验指导书上说的把kernelstack 放在第四个field中,而是在blocked之后:

```
81 struct task_struct {
82     /* these are hardcoded - don't touch */
83     long state; /* -1 unrunnable, 0 runnable, >0 stopped */
84     long counter;
85     long priority;
86     long signal;
87     struct sigaction sigaction[32];
88     long blocked; /* bitmap of masked signals */
89     long kernelstack;
90     /* various fields */
91     int exit_code;
92     unsigned long start_code,end_code,end_data,brk,start_stack;
93     long pid,father,pggrp,session,leader;
94     unsigned short uid,euid,suid;
95     unsigned short gid,egid,sgid;
```

```
ESP0 = 4

state = 0 # these are offsets into the task_struct.
counter = 4
priority = 8
signal = 12
sigaction = 16 # MUST be 16 (= len of sigaction)
blocked = ( 33 * 16 )
KERNEL_STACK = ( 33 * 16 + 4 )
```

记得在sched.c中初始化全局变量tss:

```
--
55 union task_union {
56     struct task_struct task;
57     char stack[PAGE_SIZE];
58 };
59
60 static union task_union init_task = {INIT_TASK};
61
62 long volatile jiffies=0;
63 long startup_time=0;
64 struct task_struct *current = &(init_task.task);
65 struct tss_struct *tss = &(init_task.task.tss);
66 struct task_struct *last_task_used_math = NULL;
67
68 struct task_struct * task[NR_TASKS] = {&(init_task.task)};
69
70 long user_stack [ PAGE_SIZE>>2 ];
```

修改sched.h中的宏INIT_TASK

```
119 #/*
120  * INIT_TASK is used to set up the first task table, touch at
121  * your own risk. Base=0, limit=0x9ffff (=640kB)
122  */
123 #define INIT_TASK \
124     /* state,counter,priority */ { 0,15,15,\
125     /* signals */ 0,{0},0,PAGE_SIZE+(long)&init_task,\
126     /* ec,brk... */ 0,0,0,0,0,0,\
127     /* pid etc.. */ 0,-1,0,0,0,\
128     /* uid etc */ 0,0,0,0,0,0,\
129     /* alarm */ 0,0,0,0,0,0,\
130     /* math */ 0,\
131     /* tss info */ -1,0022,NULL,NULL,NULL,0,\
132     /* fild */ {NULL,},\
133     {\
134         {0,0},\
135         /* ldt */ {0x9f,0xc0fa00},\
136         {0x9f,0xc0f200},\
137     },\
138     /*tss*/ {0,PAGE_SIZE+(long)&init_task,0x10,0,0,0,0,(long)&pg_dir,\
139     0,0,0,0,0,0,0,0,\
140     0,0,0x17,0x17,0x17,0x17,0x17,0x17,\
141     _LDT(0),0x80000000,\
142     {\
143     },\
144 }
```

二.修改schedule()

直接上代码吧,详见注释:

```
void schedule(void)
{
    int i,next,c;
    struct task_struct ** p;
    struct task_struct * pnext=&(init_task.task); // pnext 是指向目标进程的PCB的指针

    /*
    pnext 必须初始化为指向0号进程的PCB的指针,一开始我并没有初始化pnext,
    就是一个声明,结果cs不停的宕机重启. 谷歌后发现,当cs中只有一个0号进程时,
    其会不停的调用schedule(),而schedule()最终会调用switch_to(pnext,_LDT(n)),
    已知switch_to()有个功能是当发现pnext==current时,就什么都不做,所以若pnext
    初始化指向0号进程的PCB,0号进程可以一直空转. 若pnext没初始化,那pnext就是个野指针,
    鬼知道switch_to()会切到什么地方去,自然就宕机了
    */

    /* check alarm, wake up any interruptible tasks that have got a signal */

    for (p = &LAST_TASK; p > &FIRST_TASK; -- p)
        if ((*p) & (
            if ((*p) ->alarm && (*p) ->alarm < jiffies) {
                (*p) ->signal |= (1<<(SIGALRM-1));
                (*p) ->alarm = 0;
            }
            if (((*p) ->signal & ~(BLOCKABLE & (*p) ->blocked)) &&
                (*p) ->state==TASK_INTERRUPTIBLE)
                (*p) ->state=TASK_RUNNING;
        )

    /* this is the scheduler proper: */

    while (1) {
        c = -1;
        next = 0;
        i = NR_TASKS;
        p = &task[NR_TASKS];
        while (--i) {
            if (!*p) continue;
            if ((*p) ->state == TASK_RUNNING && (*p) ->counter > c)
                c = (*p) ->counter, next = i, pnext=*p;
        }
        if (c) break;
        if (p = &LAST_TASK; p > &FIRST_TASK; -- p)
            if ((*p) ->counter == ((*p) ->counter >> 1) +
                (*p) ->priority;
        switch_to(pnext,_LDT(next)); //define _LDT(n) _LDT(n)
    }
}
```

三.修改copy_process()

直接上代码,详见注释

```
int copy_process(int nr,long ebp,long edi,long esi,long gs,long none,
                 long ebx,long ecx,long edx,
                 long fs,long es,long ds,
                 long ei,long cs,long eflags,long esp,long ss)
{
    struct task_struct *p;
    int i;
    struct file *f;

    p = (struct task_struct *) get_free_page();
    if (!p)
        return -EAGAIN;
    long * krmstack;
    krmstack=(PAGE_SIZE + (long) p); // krmstack指向内核栈的开端(即栈中无元素时的栈顶),记住栈从
    地址往低地址增长

    task[nr] = p;
    *p = *current; /* NOTE! this doesn't copy the supervisor stack */
    p->state = TASK_UNINTERRUPTIBLE;
    p->pid = last_pid;
    p->father = current ->pid;
    p->counter = p->priority;
    p->signal = 0;
    p->alarm = 0;
    p->leader = 0; /* process leadership doesn't inherit */
    p->utime = p->stime = 0;
    p->cutime = p->cstime = 0;
    p->start_time = jiffies;
    //对tss的操作可以去掉了

    /**
    要知道新fork出的进程从未调用过schedule(),switch_to()这些函数来切到别的进程中去,
    所以,新进程的内核栈中并没有用户栈的栈顶esp,cs:ip等等这些寄存器的值.
    也没有schedule()的右大括号'}'的地址,所以我们要"初始化"它的内核栈,往里面加一点东西,
    使别的进程调用了schedule(),并switch_to()到该新进程时,可以顺利的从内核态返回
    */

    //通过first_return_from_kernel的iret弹出
    *(-- krmstack) = ss & 0xffff; //因为ss只有16位,而入栈是以32入的
    *(-- krmstack) = esp;
    *(-- krmstack) = eflags;
```