

03

Error Analysis

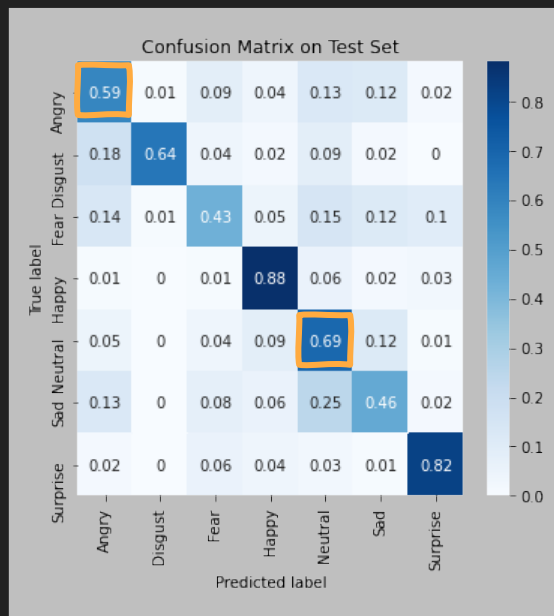
Confusion Matrix / Occlusion-based Saliency Map

Confusion Matrix

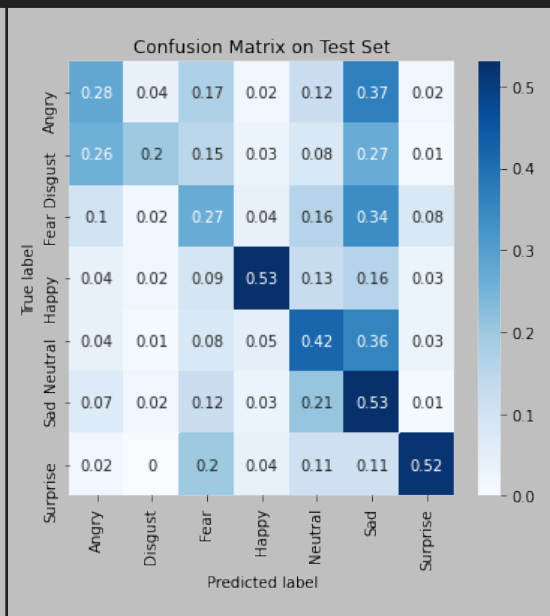
- A specific table layout that allows visualization of the performance of an (often supervised) learning algorithm

The diagram illustrates a 2x2 Confusion Matrix. A horizontal brace above the matrix is labeled "instances in an actual class". A vertical brace to the left of the matrix is labeled "instances in a predicted class". The matrix cells are labeled as follows:

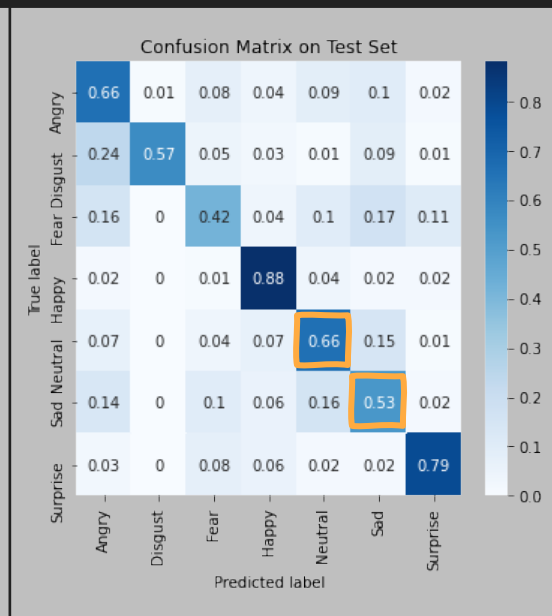
	TP	FP
	FN	TN



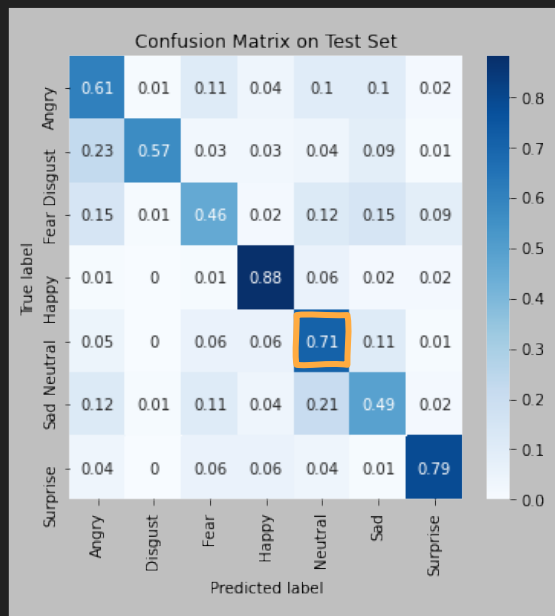
Baseline



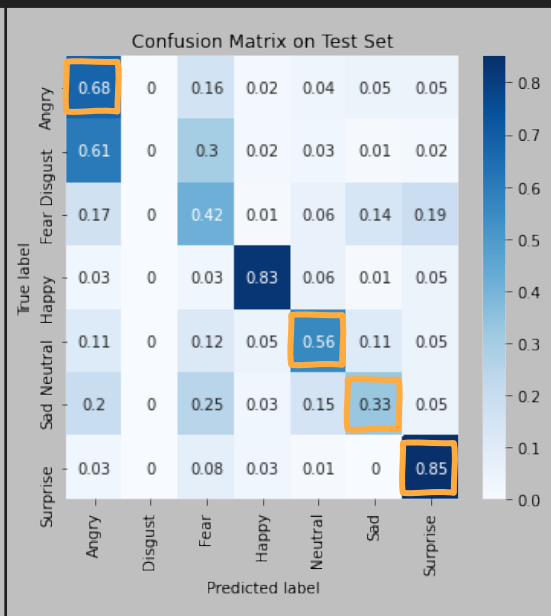
Resnet18



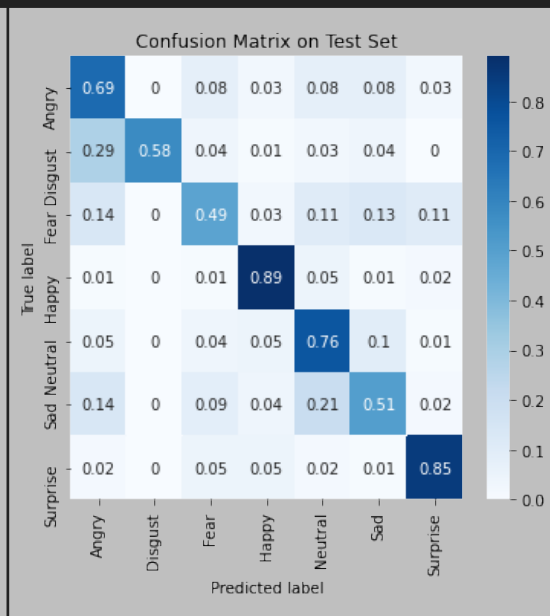
VGG16



Resnet50



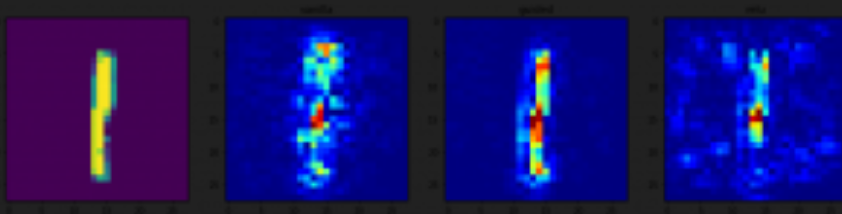
Senet50



Ensemble

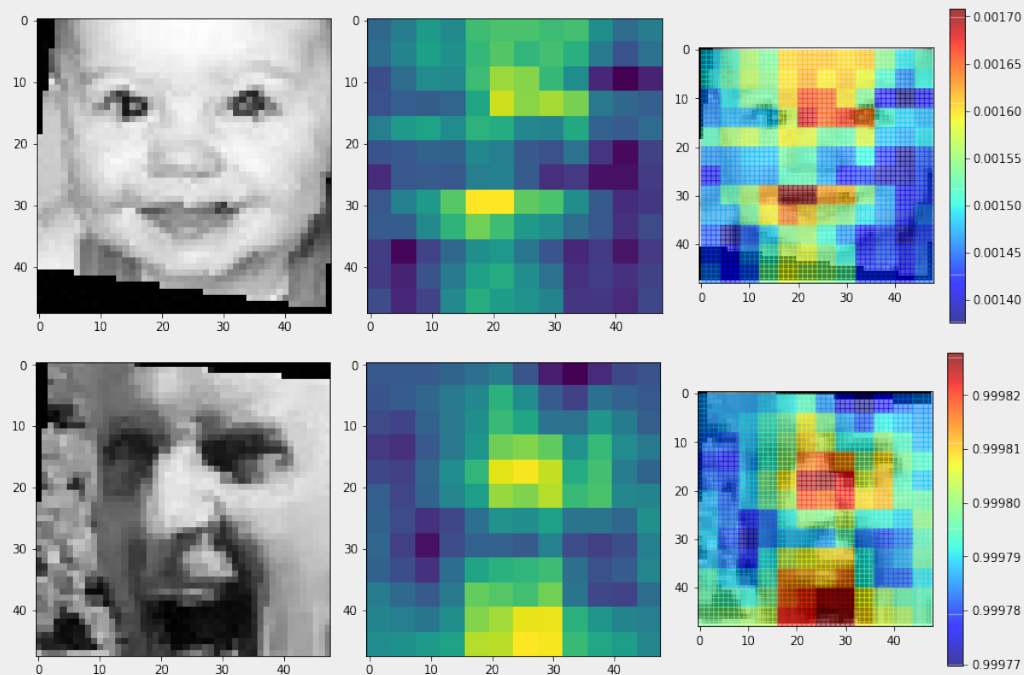
Occlusion-based Saliency Map

- Image occlusion: systematically occlude different portions of the input image and observe the output of the classifier
- Saliency map: compute the gradient of the output category with respect to the input image



Source: <https://www.kaggle.com/blargl/simple-occlusion-and-saliency-maps>

Interpretability





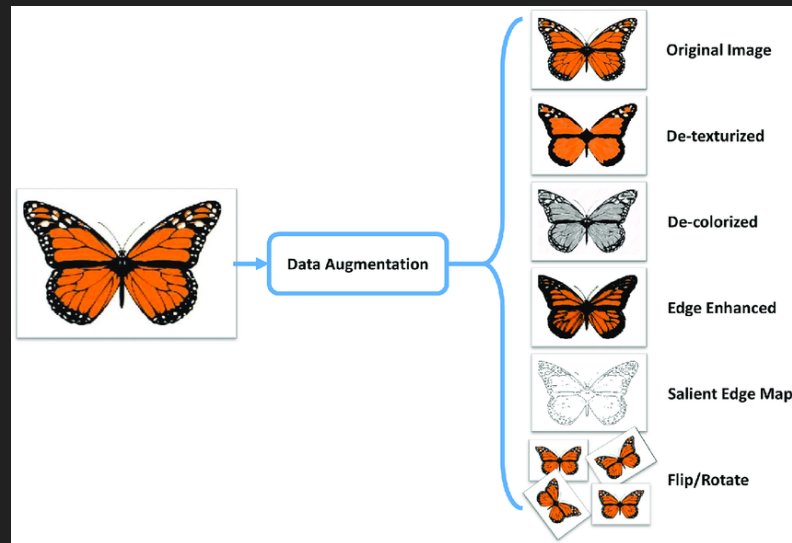
04

Future Works

Data Augmentation / Siamese Net / Triplet Loss

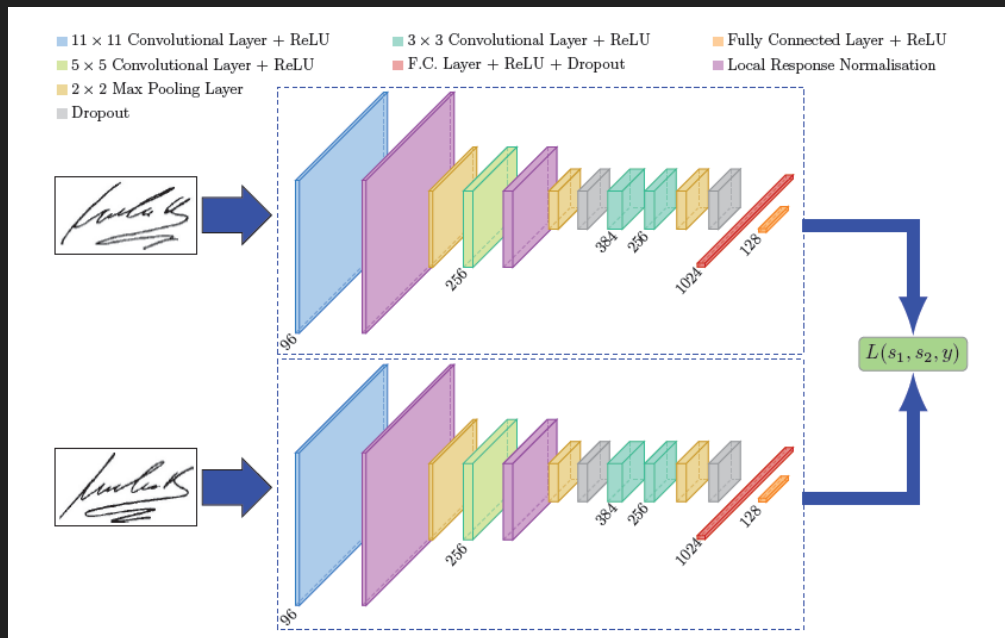
Data Augmentation

- increases the amount of data by adding slightly modified copies or newly created synthetic data from existing data
- acts as a regularizer and helps reduce overfitting



Source: Data augmentation-assisted deep learning of hand-drawn partially colored sketches for visual search

Siamese Network (SNN)



- a class of neural network architectures that contain two or more ‘identical’ subnetworks
- find the similarity of the inputs by comparing their feature vectors
- learn a similarity function

Source: Siamese Network used in Signet

Pros

More robust to class imbalance

Nicely ensembled with other supervised classifiers

Learning from Semantic similarity

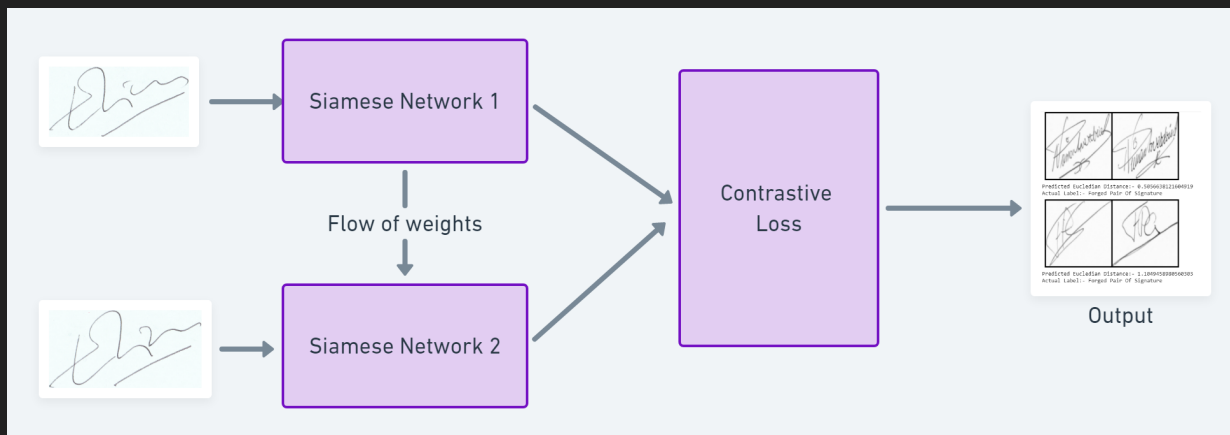
Cons

More training time

Doesn't output probabilities

Triplet Loss (Contrastive Loss)

- **Triplet loss** is a loss function where a baseline (anchor) input is compared to a positive (truthy) input and a negative (falsy) input
- **Contrastive loss** is a distance-based loss used to learn closest embeddings of two similar instances and farthest embeddings otherwise (as opposed to conventional error-prediction loss)



Acknowledgement

This work is inspired by the
awesome project by Khanzada *et al.*

References

- [1] C. DARWIN AND P. PRODGER, *The expression of the emotions in man and animals.*, (1998).
- [2] T. HASSNER, S. HAREL, E. PAZ, AND R. ENBAR, *Effective face frontalization in unconstrained images*, CoRR, abs/1411.7964 (2014).
- [3] A. KHANZADA, C. BAI, AND F. T. CELEPCIKAY, *Facial expression recognition with deep learning*, 2020.
- [4] S. LI AND W. DENG, *Deep facial expression recognition: A survey*, IEEE Transactions on Affective Computing, (2020), p. 1–1.
- [5] C. PRAMERDORFER AND M. KAMPEL, *Facial expression recognition using convolutional neural networks: State of the art*, 2016.
- [6] Y. TANG, *Deep learning using linear support vector machines*, 2015.