

**E0 230: Computational Methods of Optimization**  
**Assignment 01**

**Q2. Critical point analysis of  $p(x, y) = x^4y^2 + x^2y^4 - 9x^2y^2$**

**solution**

Given,  $p(x, y) = x^4y^2 + x^2y^4 - 9x^2y^2$

To get critical point, we use the relation,  $\nabla p(x, y) = 0$

$$\nabla p(x, y) = \begin{bmatrix} 4x^3y^2 + 2xy^4 - 18xy^2 \\ 2x^2y^4 + 4x^2y^3 - 18x^2y \end{bmatrix}$$

We will find simultaneous solution of  $4x^3y^2 + 2xy^4 - 18xy^2 = 0$  and  $2x^2y^4 + 4x^2y^3 - 18x^2y = 0$ ,

They simplify as,

$$4x^3y^2 + 2xy^4 - 18xy^2 = 2xy^2(-9 + 2x^2 + y^2) = 0, \text{ and}$$

$$2x^2y^4 + 4x^2y^3 - 18x^2y = 2x^2y(-9 + x^2 + 2y^2) = 0$$

The simultaneous solution of the above equations:  $(x, y) = (0, c), (c, 0), (\sqrt{3}, \sqrt{3}), (-\sqrt{3}, \sqrt{3}), (\sqrt{3}, -\sqrt{3}), (-\sqrt{3}, -\sqrt{3})$

To find minima among the above critical points, we calculate Hessian of  $p(x, y)$ :

$$H[p(x, y)] = \begin{bmatrix} 12x^2y^2 + 2y^4 - 18y^2 & 8yx^3 + 8y^3x - 36yx \\ 8yx^3 + 8y^3x - 36yx & 2x^4 + 12y^2x^2 - 18x^2 \end{bmatrix}$$

$$\text{Value of Hessian at } x = [0, 0]^T \implies H[p(0, 0)] = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

• Hence,  $x = [0, 0]^T$  is a stationary point but not a (global) minima.

$$\text{Value of Hessian at } (\sqrt{3}, \sqrt{3}) \implies H[p(\sqrt{3}, \sqrt{3})] = \begin{bmatrix} 72 & -18 \\ -18 & 72 \end{bmatrix}$$

Its eigenvalue is 54 and 90 (see the Python script for eigenvalue estimation). Hence  $H[p(\sqrt{3}, \sqrt{3})]$  is psd.  
 $\implies$  it is local maxima.

$$\text{Value of Hessian at } (-\sqrt{3}, \sqrt{3}) \implies H[p(-\sqrt{3}, \sqrt{3})] = \begin{bmatrix} 72 & 18 \\ 18 & 72 \end{bmatrix}$$

Its eigenvalue is 54 and 90 (see the Python script for eigenvalue estimation). Hence  $H[p(\sqrt{3}, \sqrt{3})]$  is psd.  
 $\implies$  it is local maxima.

$$\text{Value of Hessian at } (\sqrt{3}, -\sqrt{3}) \implies H[p(\sqrt{3}, -\sqrt{3})] = \begin{bmatrix} 72 & 18 \\ 18 & 72 \end{bmatrix}$$

Its eigenvalue is 54 and 90 (see the Python script for eigenvalue estimation). Hence  $H[p(\sqrt{3}, \sqrt{3})]$  is psd.  
 $\implies$  it is local maxima.

$$\text{Value of Hessian at } (-\sqrt{3}, -\sqrt{3}) \implies H[p(-\sqrt{3}, -\sqrt{3})] = \begin{bmatrix} 72 & -18 \\ -18 & 72 \end{bmatrix}$$

Its eigenvalue is 54 and 90 (see the Python script for eigenvalue estimation). Hence  $H[p(\sqrt{3}, \sqrt{3})]$  is psd.  
 $\implies$  it is local maxima.

**Conclusion:** • Hence,  $x = [0, 0]^T$  is a stationary point but not a (global) minima.

• Global minima is not unique. There are four global minima. Because,  $p(\sqrt{3}, \sqrt{3}) = p(-\sqrt{3}, \sqrt{3}) = p(\sqrt{3}, -\sqrt{3}) = p(-\sqrt{3}, -\sqrt{3})$

### Q3. Estimate bound on eigenvalues

**solution:**

Given,  $f(x) = e^{x^T A x} \frac{e^{-x^T (B+C)x}}{1+e^{-x^T (C-B)x}}$

Equivalently,  $f(x) = \frac{e^{(x^T A x) - (x^T (B+C)x)}}{1+e^{-x^T (C-B)x}} = \frac{e^{x^T (A-B-C)x}}{1+e^{-x^T (C-B)x}}$

Coercivity requires:  $\lim_{(x^T x) \rightarrow \infty} f(x) \rightarrow \infty$ .

Using the below inequalities to get upper bound on the function-

$$\frac{e^{x^T (A-B-C)x}}{1+e^{-x^T (C-B)x}} \leq \frac{e^{x^T (A-B-C)x}}{e^{-x^T (C-B)x}} = e^{x^T (A-2B)x}$$

Now we need to find the condition on matrix A and B such that:

$$\lim_{(x^T x) \rightarrow \infty} e^{x^T (A-2B)x} \rightarrow \infty.$$

Since,  $\lim_{(t) \rightarrow \infty} e^{f(t)} \rightarrow \infty$ , if  $\lim_{(t) \rightarrow \infty} f(t) \rightarrow \infty$ . Hence, we need  $\lim_{(x^T x) \rightarrow \infty} x^T (A-2B)x \rightarrow \infty$ .

This is possible if  $A-2B$  is positive-definite.

The sum of two positive definite matrices is positive definite.

#### Q4. Least Square fit for Linera function

##### solution:

- Part-I: estimated  $w \in \mathbb{R}^5 = [-0.20, -0.42, -0.42, -0.09, -0.55]$

- Part-II: Closed-form solution for m data points and  $x \in \mathbb{R}^n$ :  
Error/cost function to be minimized over  $w \in \mathbb{R}^n$ ,  $b \in \mathbb{R}$  is:-

$$f(w, b) = \frac{1}{m} \sum_{i=0}^m (w^T x_i + b - y_i)^2 = \frac{1}{m} \sum_{i=0}^m (\sum_{j=0}^n w_j x_{ij} + b - y_i)^2$$

To minimize the cost function, we take partial derivatives as:

$$\frac{\partial f}{\partial w_l} = \frac{1}{2m} \sum_{i=0}^m x_{li} (\sum_{j=0}^n w_j x_{ij} + b - y_i)$$

$$\frac{\partial f}{\partial b} = \frac{1}{2m} \sum_{i=0}^m (\sum_{j=0}^n w_j x_{ij} + b - y_i)$$

Using,  $\frac{\partial f}{\partial w_l} = \frac{\partial f}{\partial b} = 0$  and simplifying calculation yields,

$$\frac{\partial f}{\partial w_l} = \frac{1}{2m} \sum_{i=0}^m x_{li} (\sum_{j=0}^n w_j x_{ij} + b - y_i) = 0$$

$$\frac{\partial f}{\partial b} = \frac{1}{2m} (\sum_{j=0}^n (\sum_{i=0}^m x_{li} x_{ij}) w_j) - \frac{1}{2m} (\sum_{i=0}^m x_{li} y_i) = 0$$

Solving it is equivalent to solving the m-linear equation in n-variables.

$\text{or, taking } \sum_{i=1}^m x_{li} x_{ij} = A_{lj}, \text{ and } \sum_{i=1}^m x_{li} y_i = c_l \implies \sum_{j=1}^n A_{lj} w_j - c_l; \forall l \in \{1, \dots, n\}$

We can solve the above system of equations using a linear equation solver in Python.

$w = (A^T A)^{-1} A^T c.$

**Conclusion-1:** Generally, a system with the same number of equations and unknowns has a single unique solution.

- If the number of data points 'm' is less than the number of variable 'n'

**Conclusion-2:** In this case  $m > n$ , also called undetermined system of equation. In general, a system with fewer equations than unknowns has infinitely many solutions, but it may have no solution, too.

Way to solve under-determines system: We can use the Moore-Penrose inverse ( $A^+$ ) technique. It generalizes the idea of matrix inverse for non-full-rank matrixes, which is the current case.