

Priority Queues (search key + priority value)

• Heap (實現的其中一個方法)

• 用選擇排序 (先放入, 再排) 用二元樹 (邊放邊排)

Insert: $O(n)$, Delete: $O(n)$

效率最好: balance tree

Insert: $O(n)$, Delete: $O(n)$

插入排序 Insert: $O(n)$, Delete: $O(1)$

min-heap 找小

max-heap 找大

• 基本性質:

• complete binary tree

• the value stored at a node is greater (smaller) or equal to the values stored at the children (heap property)

• 應用: 霍夫曼編碼

• Void ReheapDown (int, int);

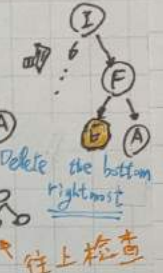
Void ReheapUp (int, int);

↳ the rightmost node at the last level (bottom) of the tree

[由下而上放入, 由機會在中間就停止]

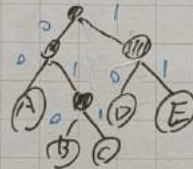
• (MAX) Insert: $O(\log n)$

把大值移上去



Delete the bottom rightmost

往上檢查



A: 00 D: 10

B: 010 E: 11

C: 011

Probabilities → weight

• Void heapInsert (heapItemType & newItem);

{ if (size >= MAX_HEAP)

throw HeapException("Heap full");

Items[size] = newItem;

int place = size;

int parent = (place - 1) / 2;

while ((parent >= 0) && (items[place] > items[parent]))

{ HeapItemType temp = items[parent];

items[parent] = items[place];

items[place] = temp;

place = parent;

parent = (place - 1) / 2; } +size; }

• void heapRebuild(int root); [use recursive]

// Converts the semi-heap rooted at index root into a heap

這有樹根不對

{ int child = 2 * root + 1;

if (child < size)

{ int rightChild = child + 1;

if ((rightChild < size) && (items[rightChild] > items[child]))

child = rightChild;

if (items[root] < items[child])

MAX heap

{ HeapItemType temp = items[root];

items[root] = items[child];

items[child] = temp;

heapRebuild(child);

}

}

• void heapDelete (heapItemType & rootItem);

節點刪去, 將 bottom rightmost 移上去空位

變成 semi-heap

{ if (heapIsEmpty())

throw HeapException("Heap Empty");

rootItem = items[0];

--size;

if (!heapIsEmpty())

{ item[0] = item[size];

// move the last item (bottom) in the heap to the root

heapRebuild(0);

// trickles it down to its proper position.

}

}

Heap Sort: Pseudocode

```

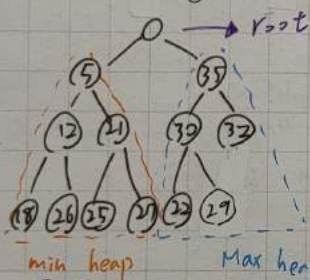
• void heapSort(int size) {
    int index;
    // convert array [0...size-1] into a heap.
    for (index = (size-1)/2; index >= 0; index--)
        ReheapDown(index, size); // => heapRebuild(index)
    // Sort the array.
    for (index = size-1; index >= 1; index--) {
        Swap(items[0], items[index]);
        ReheapDown(index, index); // => heapRebuild(0)
    }
}

```

Variations of Heap

- Double-ended Priority Queues (DEPQ)
 - Min-max Heap
 - Double-ended Heap (DEAP)
- Forest (union) of Heaps
 - Binomial Heap
 - Fibonacci Heap
- Double-ended Heap (IDEAP) (complete tree)
 - Double-ended Priority Queue (DEPQ)

ex.



Insert: ① Examine the corresponding nodes: $Left < Right$
 ② ReheapUp is necessary (recursion)

→ Two heap:

- ↳ Pseudo root + min-heap + max-heap
- ↳ each node in max-heap corresponds to one in min-heap

• 考驗排序方法: 當東西大到記憶體放不下

• 應用: External sort (外排序)
 eg. quicksort + heapsort

Merge of priority queues (合併排序)

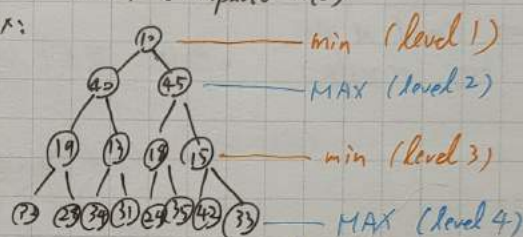
Binomial Heap → root has k children

- Merged by two binomial trees of order $k-1$
- Number of nodes = 2^k
- Tree height = $k+1 \rightarrow O(\log n)$
- $\binom{k}{i}$ nodes at level i , for $i=0 \dots k$

• Fibonacci Heap

Min-max Heap (complete Tree)

ex:



Insert: ① Decide which level → min or MAX

② check whether to swap with its parent

↳ No: ReheapUp from the current node

Yes: ReheapUp from its parent

→ max-heap + min-heap + max-heap

→ each node in max-heap has its parent in min-heap

Min-max heap = 1 min-heap + 2 max-heaps

▼ The ADT table, or dictionary

- Uses a search key to identify its items
- Its items are records that contain several pieces of data

• Nonlinear implementations

↳ Binary search tree

- Our table assumes distinct search keys

- Other tables could allow duplicate search keys

- The traverseTable operation visits table items in a specified order

- One common order is by sorted search key

▼ Linear

- easy to understand conceptually

- May be appropriate for small tables or unsorted tables with few deletions

▼ Nonlinear

- Is usually a better choice than a linear implementation

- A balanced binary search tree

↳ Increases the efficiency of the table operations

	Insertion	Deletion	Retrieval	Traversal
Unsorted array based	$O(n)$	$O(n)$	$O(n)$	$O(n)$
Unsorted pointer based	$O(1)$	$O(n)$	$O(n)$	$O(n)$
sorted array based	$O(n)$	$O(n)$	$O(\log n)$	$O(n)$
sorted pointer based	$O(n)$	$O(n)$	$O(n)$	$O(n)$
Binary search tree	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(n)$

效率與樹高有關

- Height of a binary search tree of n items

- Maximum: n

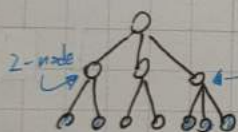
- Minimum: $\lceil \log_2(n+1) \rceil$

- Sensitive to the order of insertions and deletions

[2-3 tree
2-3-4 tree

[AVL tree
Red-black tree

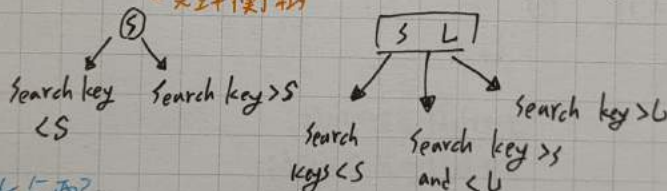
▼ 2-3 Tree



• Are general trees, not binary trees

• never taller than a minimum-height binary tree

完全平衡樹



► 刪除 重新分配

- Redistribute values
- Merge into a leaf 合併
- Redistribute values and children
- 它是樹根, Delete the root

• 若是分裂根節點

→ 分裂

→ 設立根點

→ 樹高增加

- traverse a 2-3 tree

↳ Perform the analogue of an inorder traversal

- Searching 2-3 tree

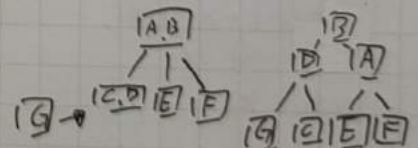
↳ $O(\log_3 n)$

(shortest binary search tree)

- 插入 2 node 的葉

- 插入 3 node 的葉

(要分裂 [divide])



▼ 2-3-4 Tree

- 遇到 3-nodes 就分裂

(一路上不會有 3-nodes)

splits occur only at the path from the root to a leaf (downward)!

▲ 不需要 recursion

Delete:

- Transformations occur only at the path from the root to a leaf (不需要 recursion)

遇到 1 個的, 就合併

▲ Summary

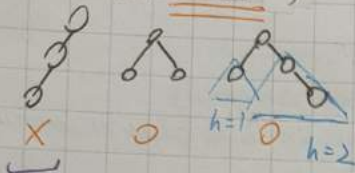
- 2-3-4 tree always 平衡

- 2-3-4, 2-3, 都是用空間換時間

每個節點有很多key, 可能造成空間的浪費

AVL Tree

- tree balanced (左、右差, 不超过 1)



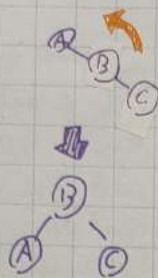
处理方法 (旋轉) rotate

- 平衡系数 (BF)

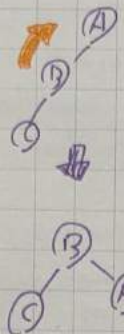
$$BF(a \text{ node}) = h(\text{left subtree}) - h(\text{right subtree})$$

差必需 $\leq 1 \Rightarrow -1 \leq BF \leq 1$

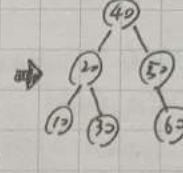
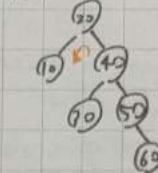
左轉



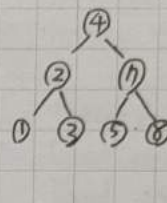
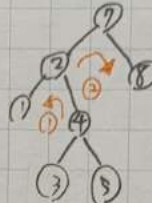
右轉



ex:



single rotation



Double rotation

- Height of $x \rightarrow \text{left} \rightarrow \text{left}$: $h+1$

$x \rightarrow \text{left} \rightarrow \text{right}$: h or $h+1$

single rotation with the left child (LL)

- two subtree: $h+2, h$

- Height of $x \rightarrow \text{left} \rightarrow \text{right}$: $h+1$

double rotation with the left child (LR)

$$\Delta BF(x) = +2, BF(x \rightarrow \text{Left}) = -1$$

- Height of $x \rightarrow \text{right} \rightarrow \text{right}$: $h+1$

$x \rightarrow \text{right} \rightarrow \text{left}$: h or $h+1$

single rotation with the right child (RR)

- Height of $x \rightarrow \text{right} \rightarrow \text{left}$: $h+1$

double rotation with the right child (RL)

$$\Delta BF(x) = -2, BF(x \rightarrow \text{Right}) = +1$$

ex: LR Rotation

① nodeType rotateLR (nodeType x) {

nodeType y = x → left;

nodeType z = y → right;

// RR rotation on y

y → right = z → left;

z → left = y;

x → left = z;

// LL rotation on x

x → left = z → right;

z → right = x;

return z;

}

②

{

y → right = z → right;

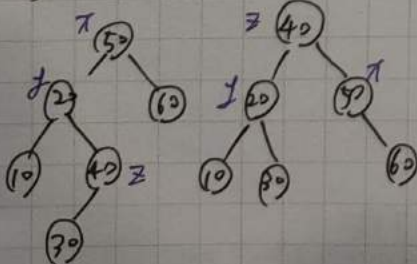
x → left = z → right;

z → right = x;

z → left = y;

return z;

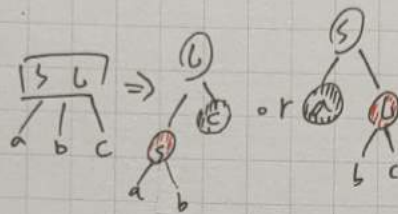
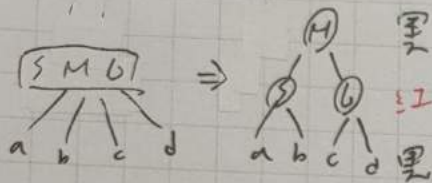
}



補充: B-tree

Red-black tree = Rotations + 2-3-4 tree + Binary Search Tree

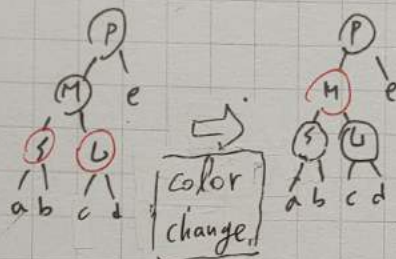
- 3node, 4node
- rotations
- 有 2-3-4 tree 的平衡優點, 沒有空間浪費的問題
- 2-3-4 tree 的高度
- Every external path has an equal number of Black pointers
- External path cannot have two consecutive Red pointers
- easy to keep balanced and simple insertion/deletion



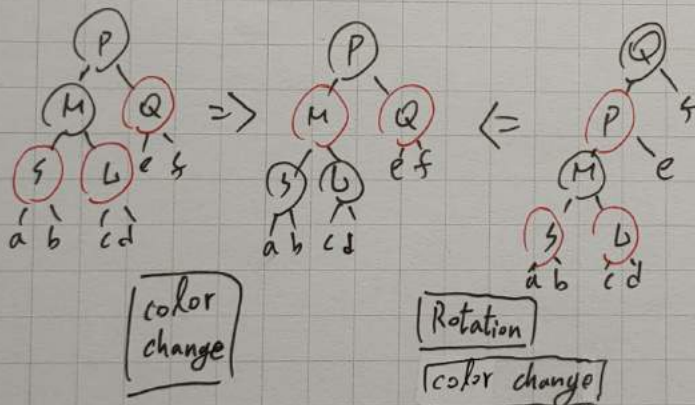
1. Parent is a 2-node

Only change the colors

- to child: red \rightarrow black
- from parent: black \rightarrow red



2. Parent is 3-node



Insertion

1. Splits of a node with two red pointers (like the 4-node in a 2-3-4 tree) occur only on the path from the root to a leaf (downward)!
2. Set the pointer to a new-added node as red
3. Rotate if there are two consecutive red pointers

Deletion

1. Find the node to delete, as in a binary search tree
 - \rightarrow two children \rightarrow swap with the in-order successor
 - \rightarrow Only one child \rightarrow pointed to by a black pointer
 - \rightarrow Leaf \rightarrow pointed to by a red or black pointer
2. Replace the node if only one child with its child
3. Delete the leaf if the pointer to it is red
4. Recolor or rotate
 - \rightarrow Leaf pointed to by a black pointer