

Lesson 6 = Queue

□ ADT queue operations

- Create an empty queue 建構
- Destroy a queue 解構
- Determine whether a queue is empty $isEmpty()$ 是否為空
- Add a new item to the queue 新增: enqueue()
- Remove the item that was added earliest. 移除 dequeue()
- Retrieve the item that was added earliest. 擷取 getFront()

□ Recognizing Palindromes 迴文

- Use a queue in conjunction with a stack
 - A stack reverse the order of occurrences.
 - A queue preserves the order of occurrences.

□ A summary of Position-Oriented ADTs

- position-oriented ADTs 位置導向 = List, Stack, Queue
 - stack & queue = only the end position can be accessed
 - list = all positions can be accessed.

□ Application = Simulation 模擬

- modeling the behavior 行為模擬
- Goal = statistics 統計, predict 預測
- time-driven simulation 時間驅動
 - total waiting time
 - average waiting time

Lesson 1 = Algorithm Efficiency

□ Analysis of algorithms = Time efficiency, space efficient

□ A requires time $\rightarrow n^2$; B requires time $\rightarrow n$

- n^2 and n are growth-rate function 成長函數

- A is $O(n^2)$ - order n^2 大小位階

B is $O(n)$ - order n

- Big O notation

□ Order-of-Magnitude Analysis and Big O Notation.

1. $O(1)$ A 常數

2. $O(\log_2 n)$ B 對數

3. $O(n)$ C 線性

4. $O(n \log_2 n)$ D

5. $O(n^2)$ E 平方

6. $O(n^3)$ F 立方

7. $O(2^n)$ G 指數

□ Categories of sorting algorithms

- internal sort 內部排序 = 電腦內記憶體可容納的 data

- external sort 外部排序 = 內部記憶體無法容納的 data

secondary storage

□ Bubble Sort

□ Selection Sort

□ Insertion Sort

□ stable sort vs. Unstable sort

bubble

selection

insertion

quick

merge

heap

radix

相同值

維持不變
↓
順序

相同值

可能改變

→ 順序

□ Bubble Sort (Bubble down)

```
void BubbleSort (int A[], int n) {  
    for (pass = 1; pass < n; ++pass) {  
        for (int index = 0; index < n - pass; index++) {  
            if (A[index] > A[index+1]) // 相鄰兩筆排序  
                swap (A[index], A[index+1]);  
        }  
    }  
}
```

比較次數: $n + n[n(n-1) - \frac{n(n-1)}{2}] + (n-1) = n^2 + n - 1 \rightarrow O(n^2)$ (worst case)
best case $\Rightarrow O(n)$

□ Mergesort 合併排序

- A recursive sorting algorithm

- strategy:
1. Divide an array into halves
 2. sort each half
 3. Merge the sorted halves into one sorted array
 4. Divide-and-conquer
3. 邊合併邊排序

- stable!

- What is the big-O notation of merge()? $O(n)$

What is the number of recursive calls? $n-1$ 總數

- Analysis: Worst case = $O(n \log n)$

Average case = $O(n \log n)$

- 優: 快 缺: 需要額外2個陣列

□ Quicksort 快速排序

- strategy 1. choose a pivot 樞紐、車軸

2. 分組 (依車軸的位置)

▪ Items < pivot

▪ Items >= pivot

▪ Pivot is now in correct sorted position.

3. sort the left section

4. sort the right section

(遞迴呼叫)

- What is the big-O notation of partition()? $O(n)$
- What is the number of recursive calls? $O(\log n)$
- Worst case = $O(n^2)$
- Average case = $O(n \cdot \log n)$

□ Radix Sort

- 10 is the radix of the decimal system 基數(十進制)
- strategy = Decompose the sort key by the radix 分解取部份值
- LSD (Least Significant Digit) 從右到左
- MSD (Most Significant Digit) 排序時最重要的數
 - 從 LSD 開始做: 最後一次依 MSD 分配、串接
 - 從 MSD 開始做: 最後一次依 LSD 分配、串接
- Unstable!

Lesson 8 = Trees

□ General = Operations that Insert, delete, ask questions.

Position-oriented 位置導向

e.g. list, stack, queue, binary tree

Value-oriented 內容導向

e.g. sorted list, binary search tree

□ Terminology

親子關係 祖孫關係

- Trees are hierarchical = Parent-child, Ancestor-descendant

- subtree of tree 子樹

- General tree = one or more nodes 至少一個節點

• A single node r , the root

- Leaf = A node with no children (葉結點)

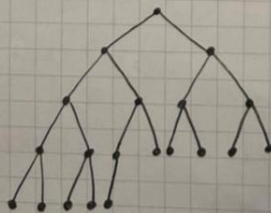
- siblings = Nodes with a common parent (兄弟結點)

□ Binary Tree

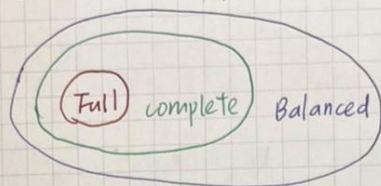
- Height of Tree = the longest path

□ Full Binary Tree 完全樹 = 沒有缺項, 資料量固定, 限制多

□ Complete Binary Tree 完整樹 = full to level $n-1$
filled from left to right



□ Balanced Binary Tree 平衡樹 = 任兩點的樹高差值
不超過 1.



□ Minimum height (complete binary tree) =

$$n \leq 2^h - 1 \Rightarrow \log_2(n+1) \leq \log_2(2^h) \Rightarrow h = \lceil \log_2(n+1) \rceil$$

□ Maximum height (complete binary tree) =

$$h = \lfloor \log_2(n) \rfloor + 1$$

□ Traversals of a Binary Tree =

```
traverse (Node* walk) {
```

```
  if (walk != NULL) {
```

```
    // printf
```

```
    traverse (walk -> left);
```

```
    // printf
```

```
    traverse (walk -> right);
```

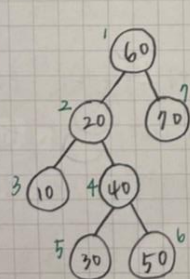
```
    // printf
```

```
  } // if
```

← 前序 preorder

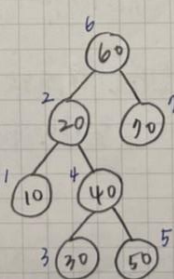
← 中序 inorder

← 後序 postorder



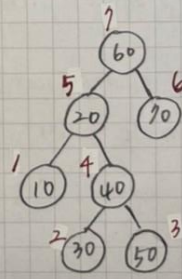
a) preorder:

60, 20, 10, 40, 30, 50, 70



b) inorder:

10, 20, 30, 50, 40, 60, 70



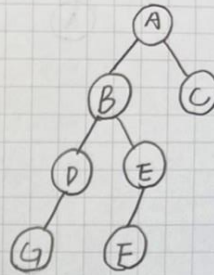
c) postorder:

10, 30, 50, 40, 20, 70, 60

□ Practice 8-1:

ex: Postorder = G D F E B (A) ^{樹根}

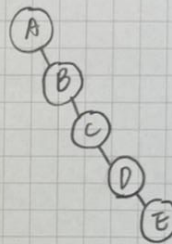
Inorder = G D B F E A C
_左 ^右



ex: Preorder = (A) B C D E ^{樹根}

Inorder = A B C D E

(Inorder = sort 排序)



□ Binary Search Tree

- Average case = $O(\log n)$

- Worst case = $O(n)$

□ Efficiency = 最高比較次數 = 樹高、
 加入移除的次序會影響樹高、
 隨機次序加入可逼近最小樹高

□ Tree sort: 建立二元樹 → 中序走訪 (排序)

- Build a binary search tree by n case =

• Average case = $O(n * \log n)$

• Worst case = $O(n * n)$

- Inorder traversal = $O(n)$