

Advanced Digital Image Process

HW#7

作業#7

姓名：張耀中

學號：109368008

指導教授：高立人教授

Development environment :

OS : ubuntu18.04

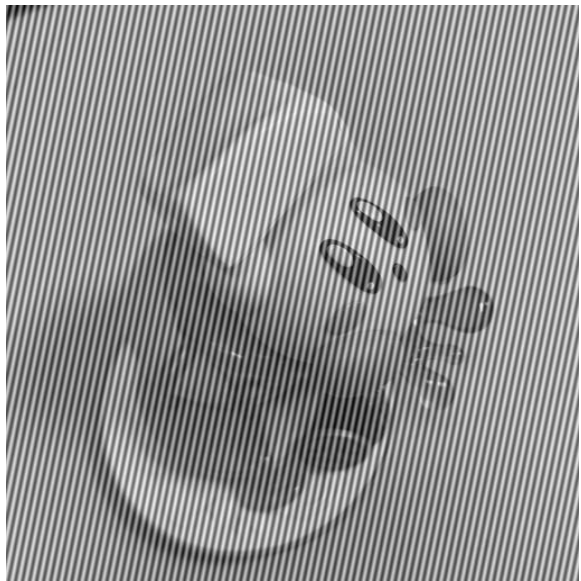
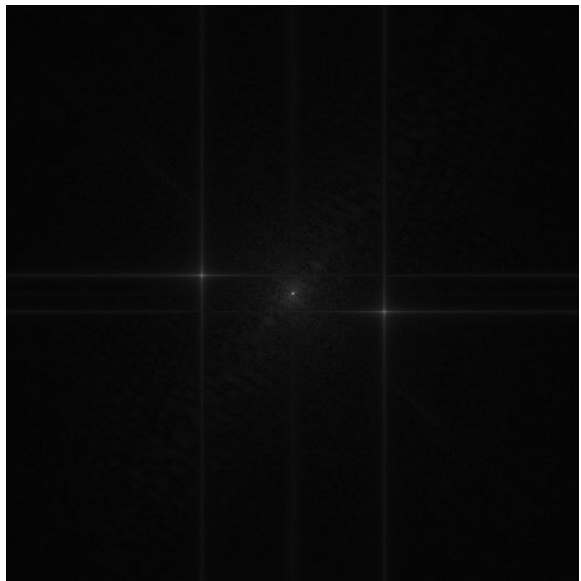
Editing tools : VScode

compilation tools : CMake

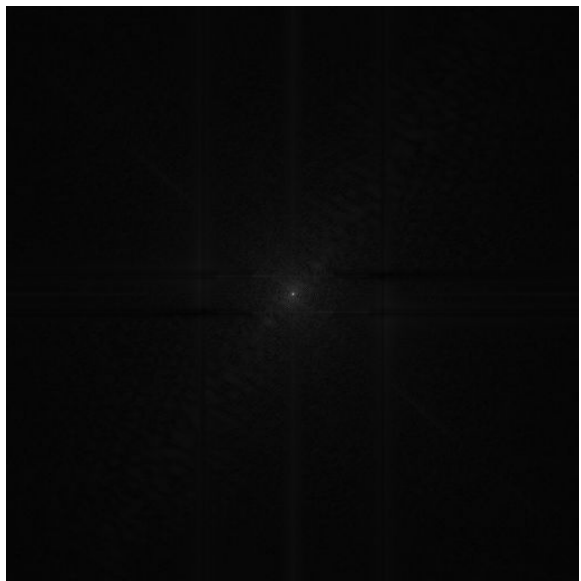

opencv version : 3.2.0

1.Periodic Noise

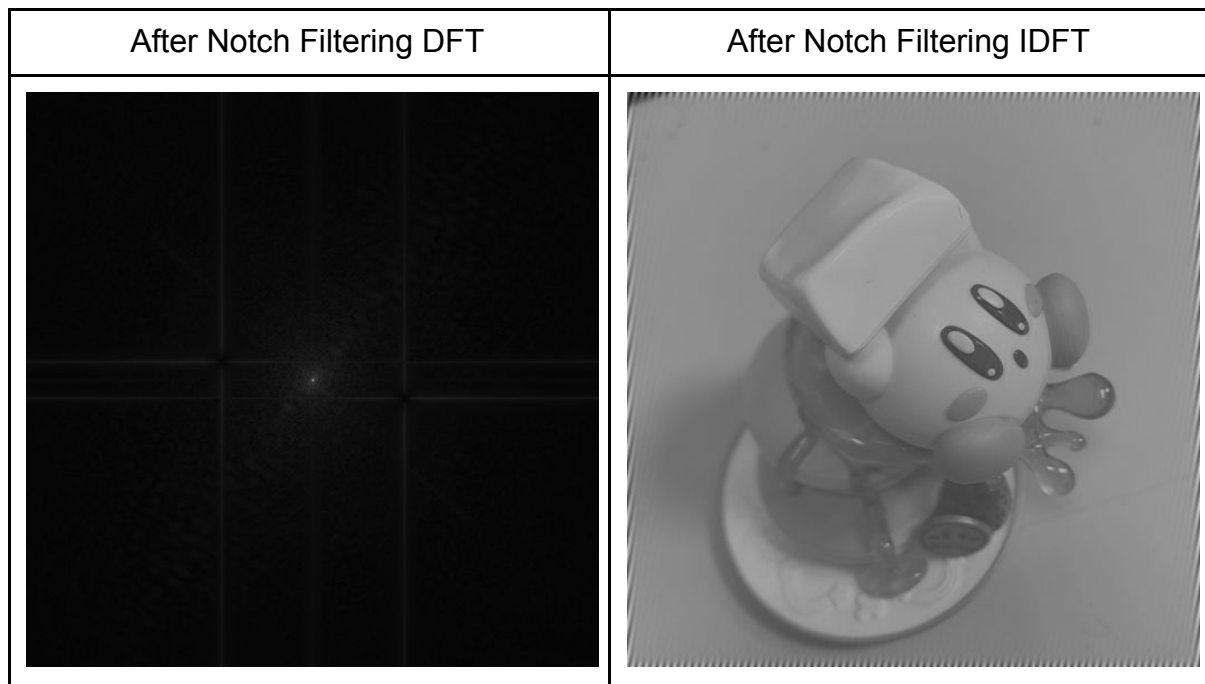
- (a) Use Notch filtering to remove the periodic noise in the frequency domain.
Show the clean image.

origin image	origin image DFT
	

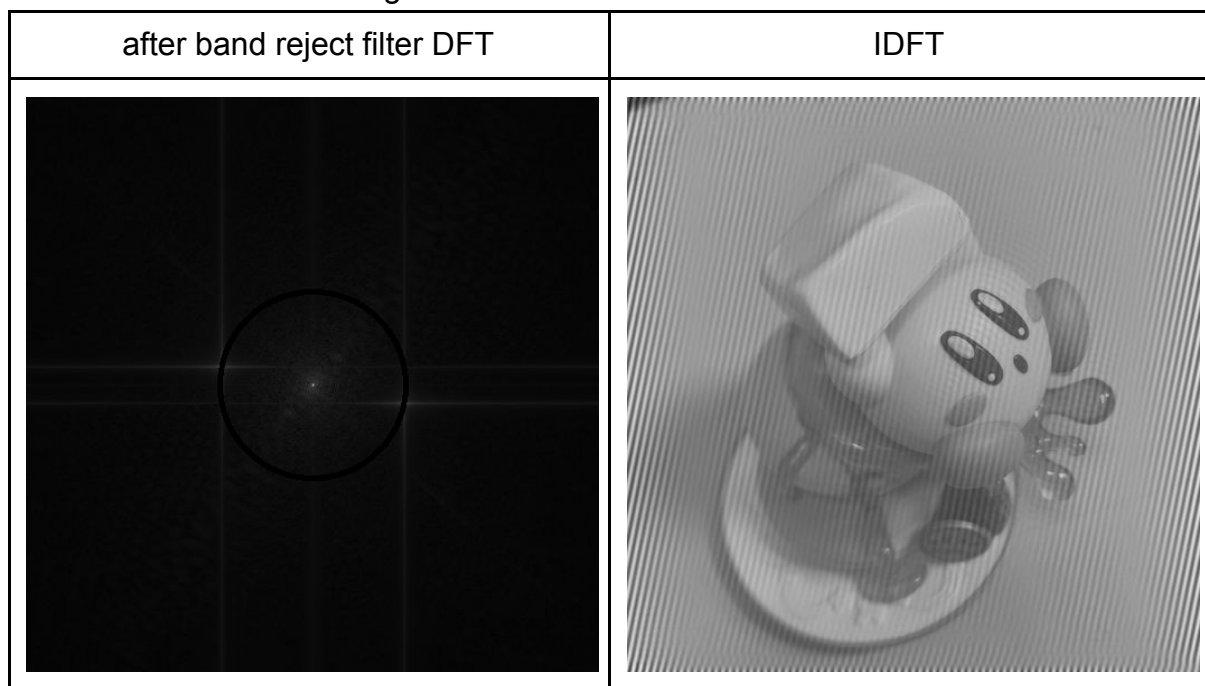
We use a notch filter to remove the periodic noise. After DFT the image, we can see two crosses on the image. This probably is the noise source so we try to remove the cross, but it isn't very good. As shown on the below.

after line removal DFT	IDFT
	

We can see Kirby's face is a little dirty, and there was some line still didn't removed. So we just remove the 2*2 points at the upper left and lower right point, the result is very good.



(b) Use band reject filtering to remove the periodic noise in the frequency domain. Show the clean image.



As we can see we still got noise on the Kirby. If we give a bigger d_0 we will get the noise off but a lot of details. So the Kirby image will become dirty.


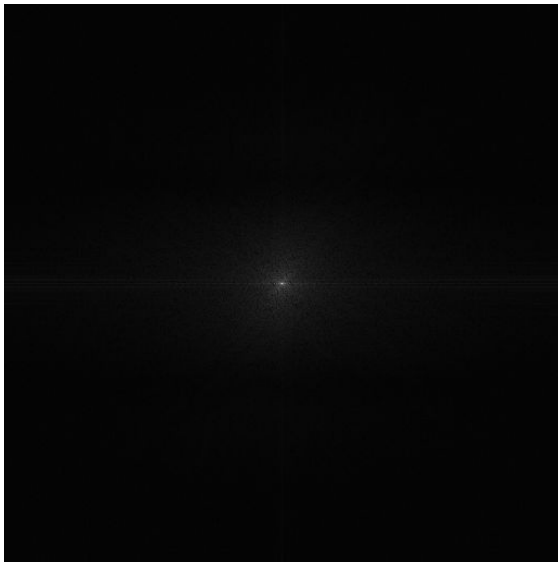
(c) Discuss and compare the effects of different methods.

The difference between band reject filter and Notch filter is the former will take a lot of detail of, so it will have a lot of dirty lines on the image, and the latter one can just take off what you don't want, so it can make the image more clean.

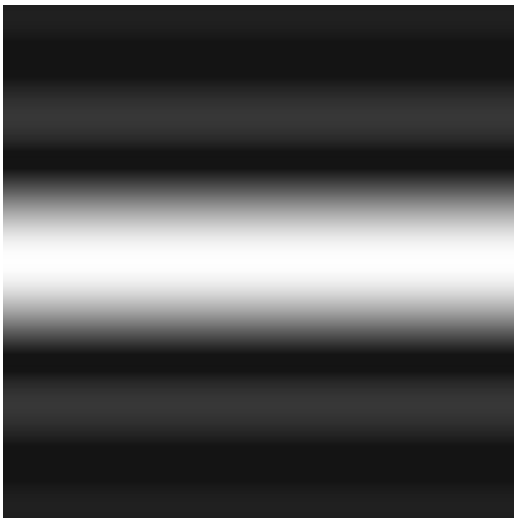
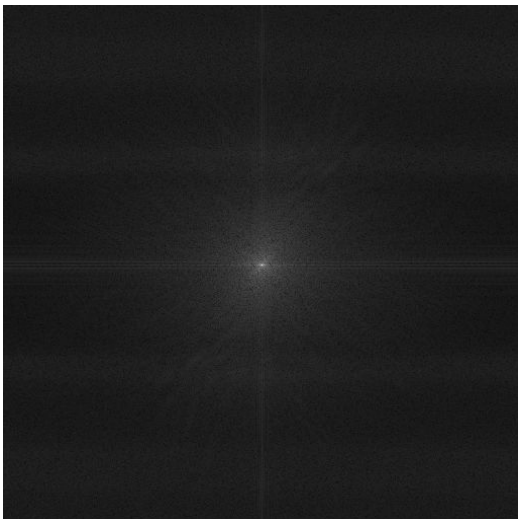
2. Deblurring

Perform inverse filter and Wiener filter separately on motion_flower.raw to unblur the image which is blurred by motion as $g(x,y)$ function. Show the output images and discuss the visual difference between the result images.

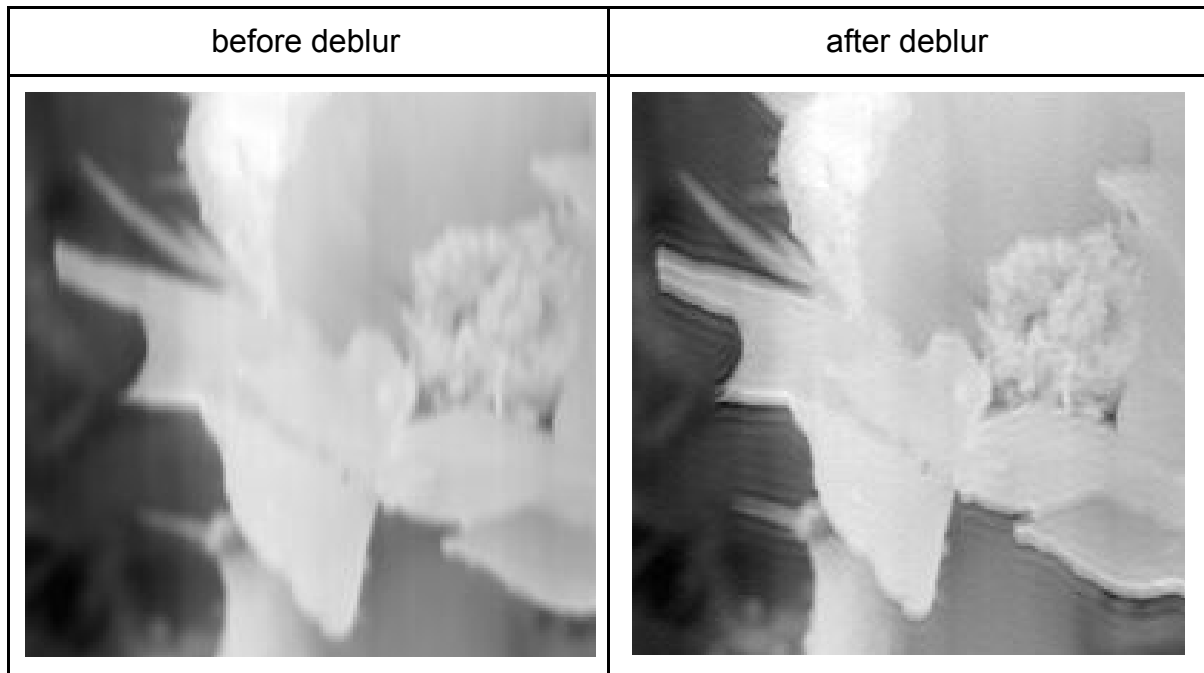
$$g(x,y) = \int_0^1 f(x,y + 0.01t) dt$$

motion flower	DFT
	

(a) Inverse filter

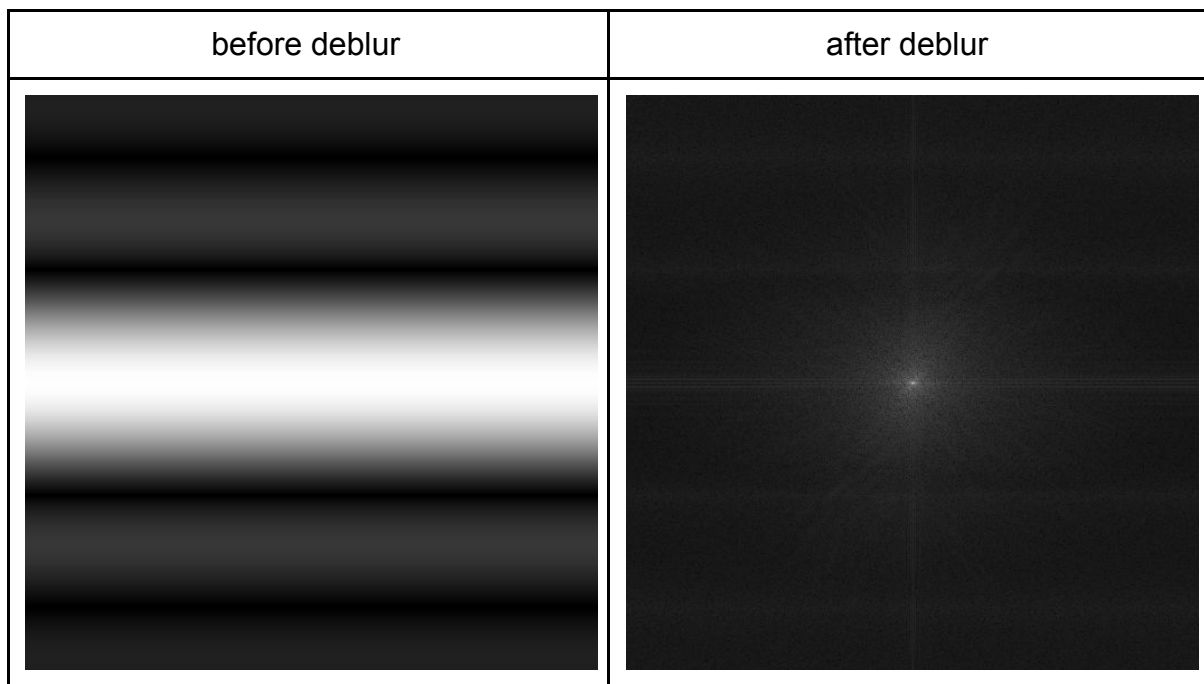
inverse filter $H(u,v)$	DFT
	

We saw the motion flower's DFT has some unnatural dark region, so we thought if we increase the dark part then we can have a deblur image.
result

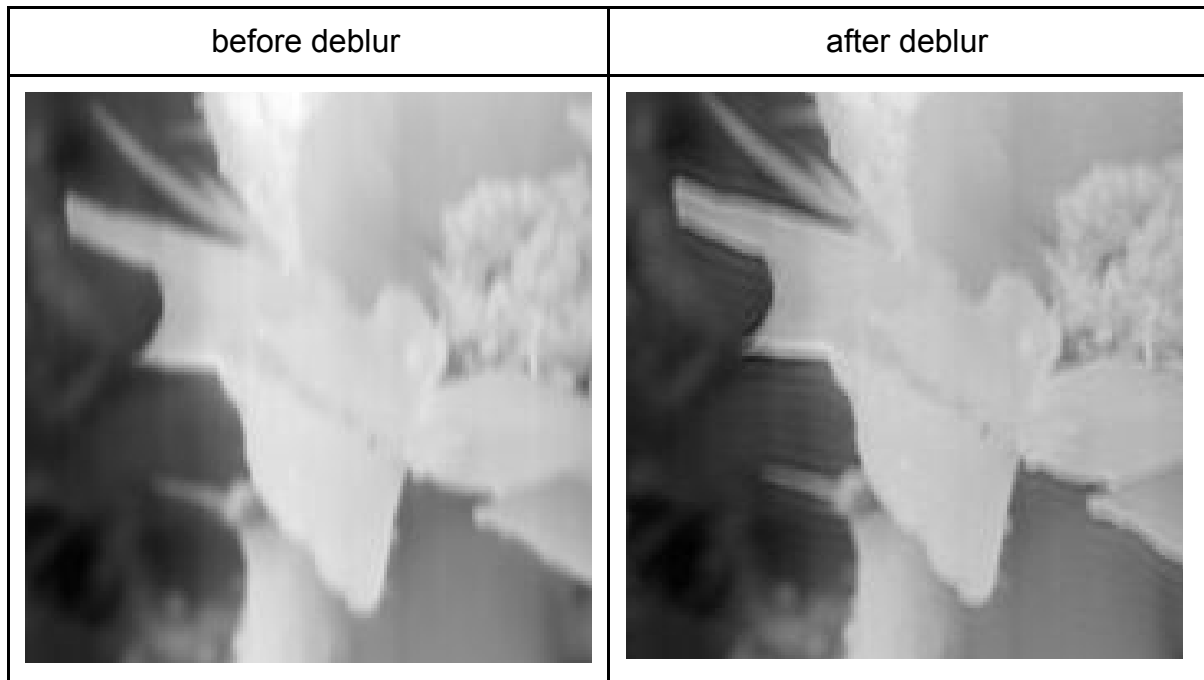


As we can see after we deblur there is some weird effect, but the edge of the image is more intense, especially at the stamen.

(b) Wiener filter



Same as inverse filter we enhance the dark region at DFT. Let see the effect.



The wiener filter can enhance the edge too but inhibition the noise.but it is not obvious at this image because the image didn't have a right noise.

The difference between inverse and wiener is the former cannot predict the SNR of the image but the latter can. So when the inverse filter $H(u,v)$ is very small the noise will dominate the image, so we need to set a lower limit, but the wiener filter can predict the SNR so we can set the parameter k to remove the noise.

We can't see the difference between these two images because the teaching assistant didn't put a gaussian noise on the blur image.

Image link: [google drive](#)