

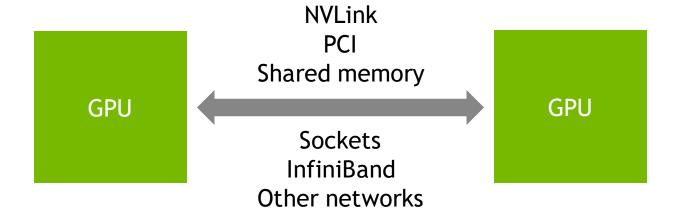
S31880 - NCCL: HIGH-SPEED INTER-GPU COMMUNICATION FOR LARGE-SCALE TRAINING

Sylvain Jeaugey

OPTIMIZED INTER-GPU COMMUNICATION

NCCL: NVIDIA Collective Communication Library

Communication library running on GPUs, for GPU buffers.

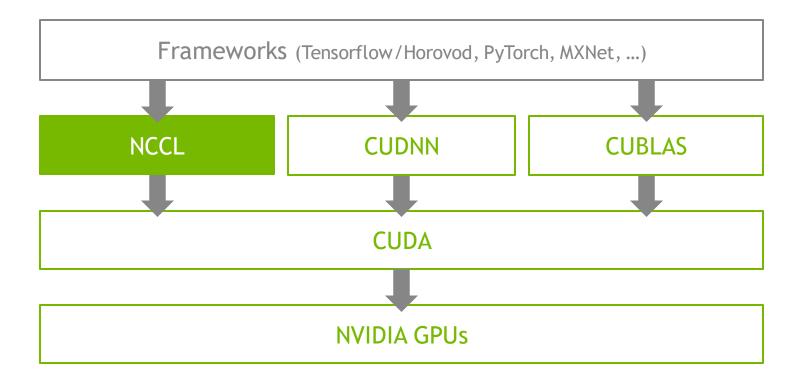


Binaries: https://developer.nvidia.com/nccl and in NGC containers

Source code: https://github.com/nvidia/nccl Perf tests: https://github.com/nvidia/nccl-tests

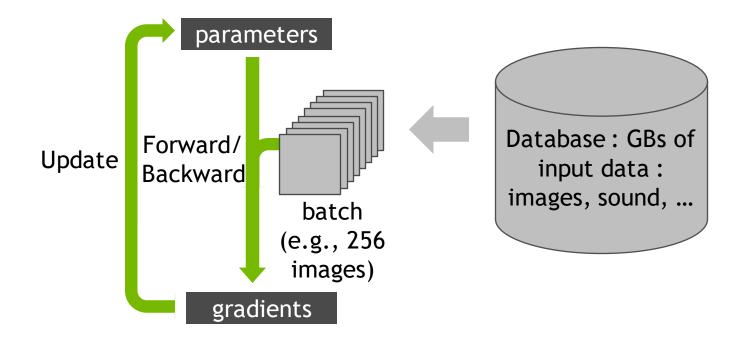


NCCL DL stack



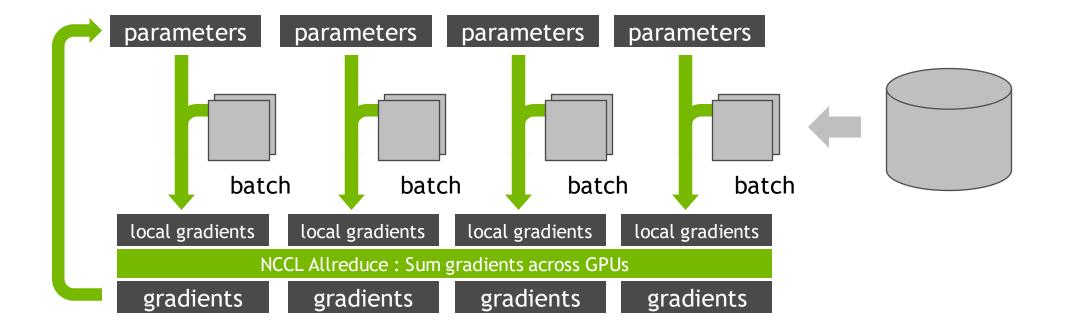
MULTI-GPU TRAINING

Single-GPU



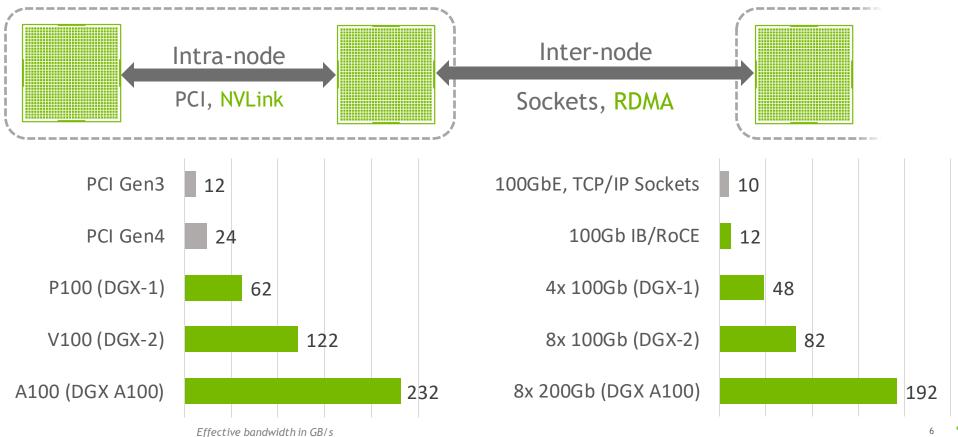
MULTI-GPU TRAINING

Data parallel



INTER-GPU COMMUNICATION

Intra-node and Inter-node



NCCL API

Overview

```
// Communicator creation
   ncclGetUniqueId(ncclUniqueId* commId);
   ncclCommInitRank(ncclComm t* comm, int nranks, ncclUniqueId commId, int rank);
   // Communicator destruction / fault tolerance
   ncclCommDestroy(ncclComm t comm);
   ncclCommAbort(ncclComm t comm);
    ncclCommGetAsyncError(ncclComm t comm, ncclResult t* asyncError);
   // Collective communication
   ncclAllReduce(void* sbuff, void* rbuff, size t count, ncclDataType t type, ncclRedOp t op,
                                                                                                        ncclComm t comm, cudaStream t stream);
    ncclBroadcast(void* sbuff, void* rbuff, size t count, ncclDataType t type,
                                                                                             int root, ncclComm t comm, cudaStream t stream);
       ncclReduce(void* sbuff, void* rbuff, size t count, ncclDataType t type, ncclRedOp t op, int root, ncclComm t comm, cudaStream t stream);
ncclReduceScatter(void* sbuff, void* rbuff, size t count, ncclDataType t type, ncclRedOp t op,
                                                                                                        ncclComm t comm, cudaStream t stream);
    ncclAllGather(void* sbuff, void* rbuff, size t count, ncclDataType t type,
                                                                                                        ncclComm t comm, cudaStream t stream);
   // Point-to-point communication
   ncclSend(void* sbuff, size t count, ncclDataType t type, int peer, ncclComm t comm, cudaStream t stream);
   ncclRecv(void* rbuff, size t count, ncclDataType t type, int peer, ncclComm t comm, cudaStream t stream);
   // Aggregation/Composition
   ncclGroupStart();
   ncclGroupEnd();
```



Principle

Once (typically on worker0): spawn ncclUniqueId id ncclGetUniqueId(&id); broadcast to all ranks(&id); Bootstrap Root thread

On all parallel workers:

```
get_unique_id(&id);
ncclCommInitRank(&comm, nranks, &id, rank);
ncclAllReduce(..., comm);
```

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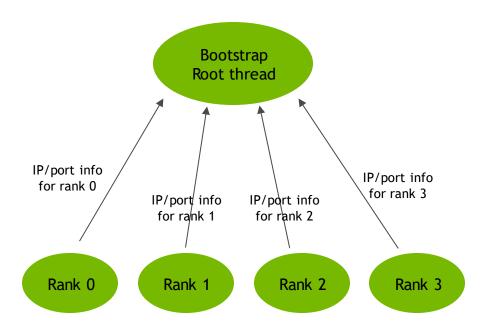
Principle

Once (typically on worker0):

```
ncclUniqueId id
ncclGetUniqueId(&id);
broadcast_to_all_ranks(&id);
```

On all parallel workers:

```
get_unique_id(&id);
ncclCommInitRank(&comm, nranks, &id, rank);
ncclAllReduce(..., comm);
```



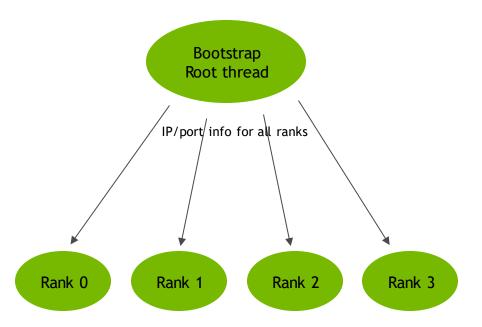
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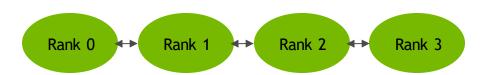
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On all parallel workers:

```
get_unique_id(&id);
ncclCommInitRank(&comm, nranks, &id, rank);
ncclAllReduce(..., comm);
```



Allgather rank information Allgather ring/tree information Exchange connection information as needed (ports, IB queue pair, ...)

Principle

NCCL Bootstrap uses plain TCP/IP sockets to connect ranks of the same job. It then provides an out-of-band channel to exchange information between ranks as needed.

Bootstrap operations are available during the entire life of the NCCL communicator. They are mostly used during init, but can also be used for dynamically connected send/recv operations.

There is currently no encryption, no security. Use NCCL_SOCKET_IFNAME to make sure NCCL uses a network interface which is private to your parallel job.



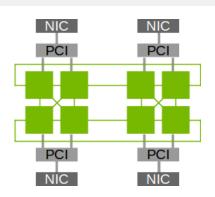
NCCL ARCHITECTURE

Optimized kernels for all platforms

Topology detection

Build graph with all GPUs, NICs, CPUs, PCI switches, NVLink, NVSwitch.

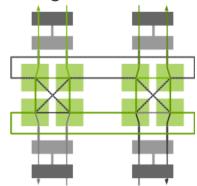
Topology injection for VMs.



Graph search

Extensive search to find optimal set of rings or trees.

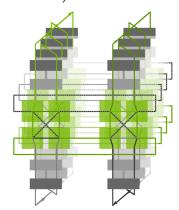
Performance prediction of each algorithm and autotuning.



Graph connect

Connect graphs between nodes.

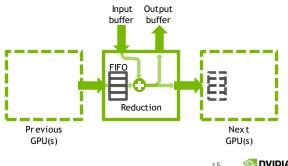
Connect GPUs with intermediate FIFOs, using PCI, NVLink, GPU Direct RDMA, ...



CUDA Kernels

Optimized reductions and copies for a minimal SM usage.

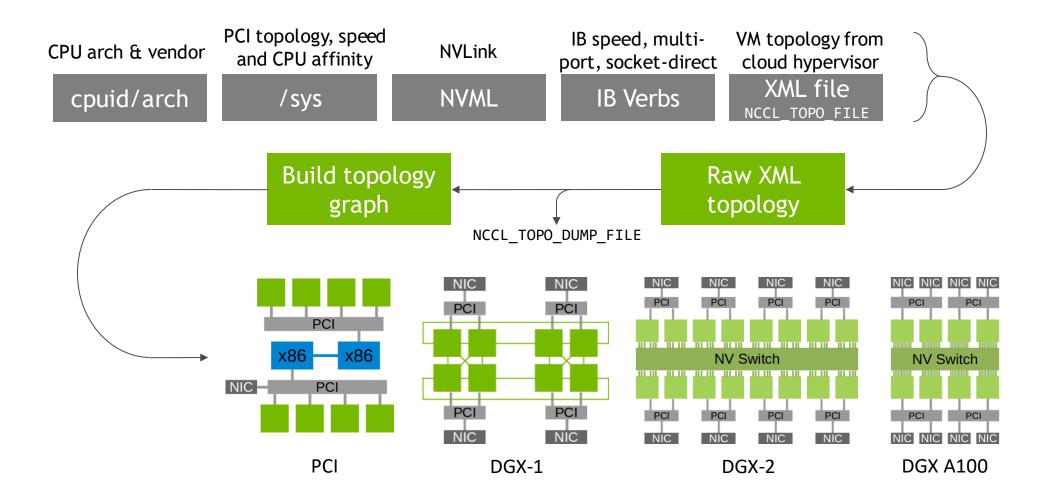
CPU threads for network communication.





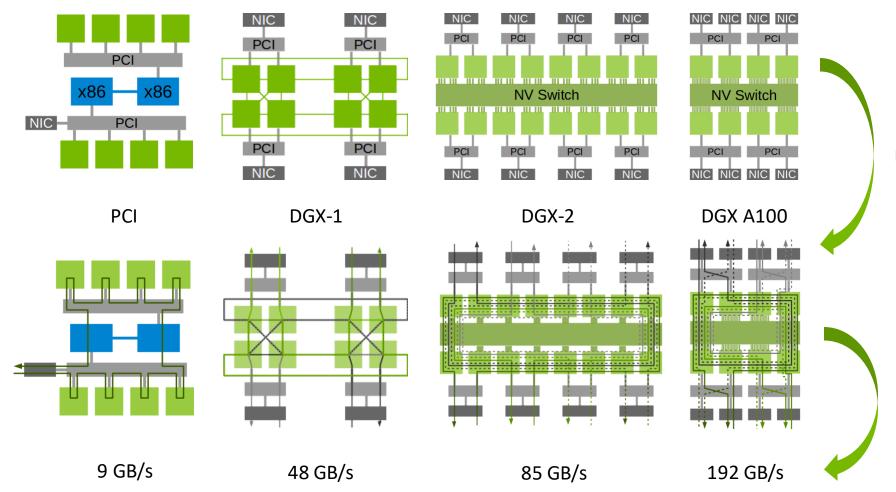
TOPOLOGY DETECTION

Extensive support for all platforms



FROM TOPOLOGY TO GRAPHS

Intra-node graph search

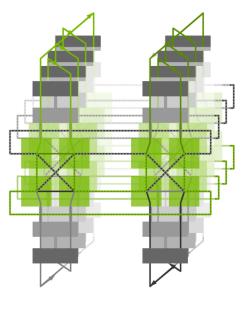


Multi-path search within the node to maximize intra- and inter- node bandwidth.

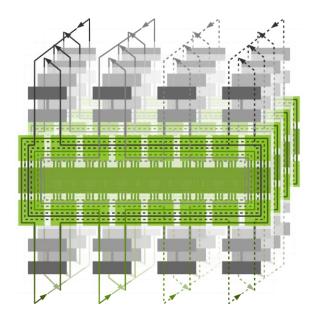
Model latency and bandwidth for each algorithm and protocol based on the number of channels and speed



Connect rails together



DGX-1

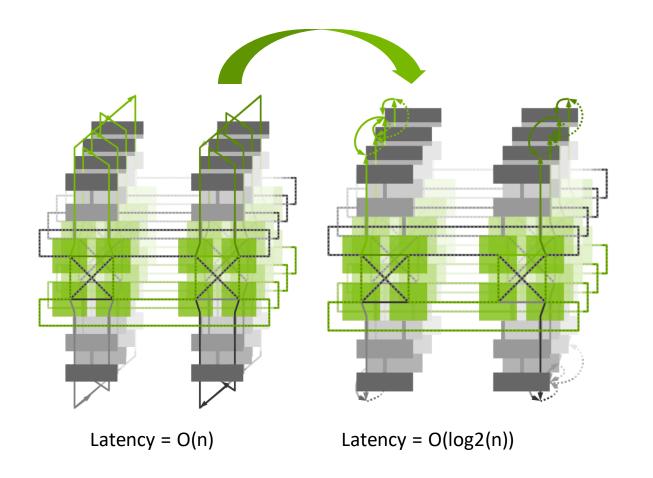


DGX-2

Rings (and trees) from each node are connected to each other.

It is assumed that same NICs can communicate efficiently across nodes

Rings vs Trees

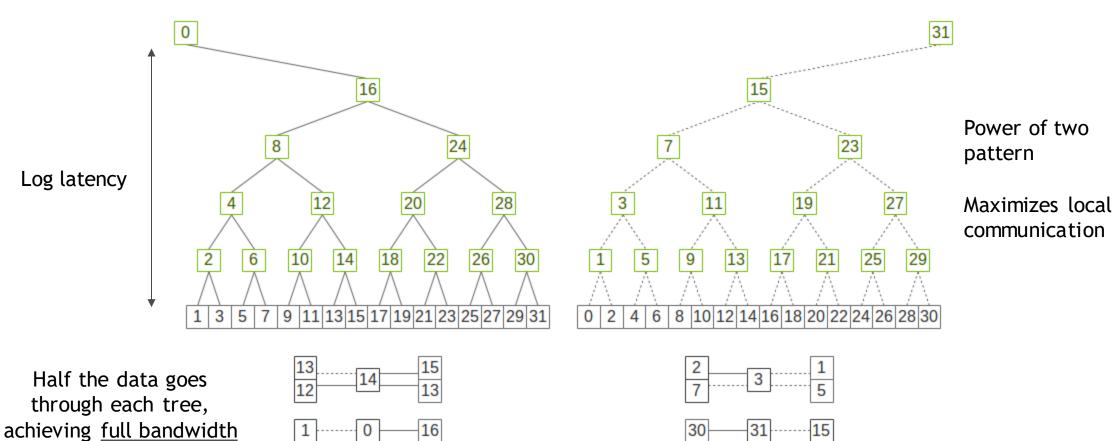


Similarly, trees are connected between nodes.

Intra-node still aggregates the bandwidth of multiple NICs.

NICs still communicate along planes.

Dual binary tree



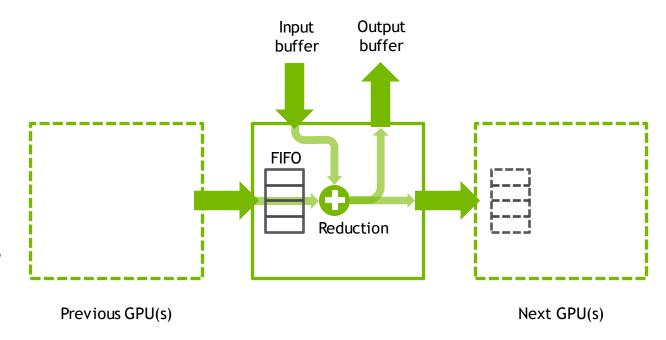


GPU COMMUNICATION KERNEL

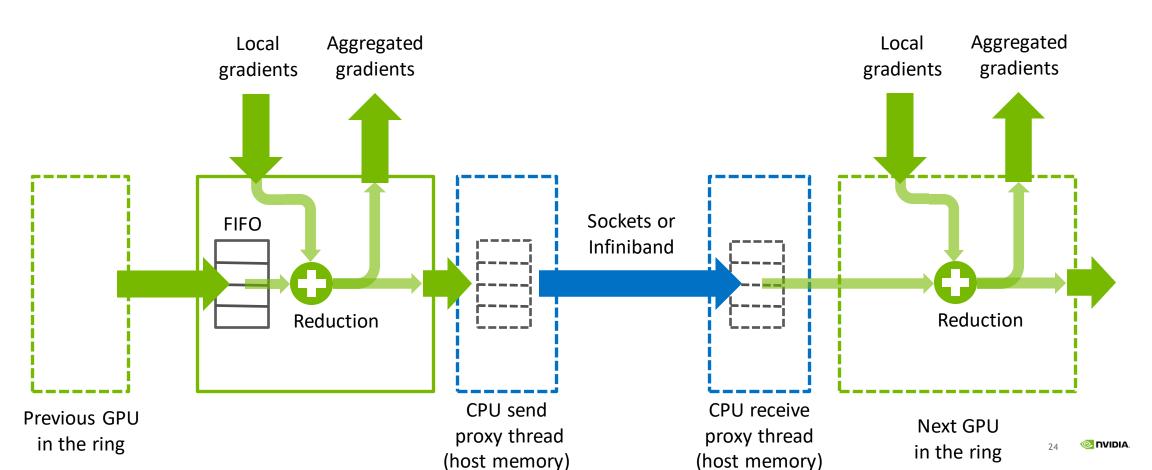
Principle

NCCL CUDA Kernel

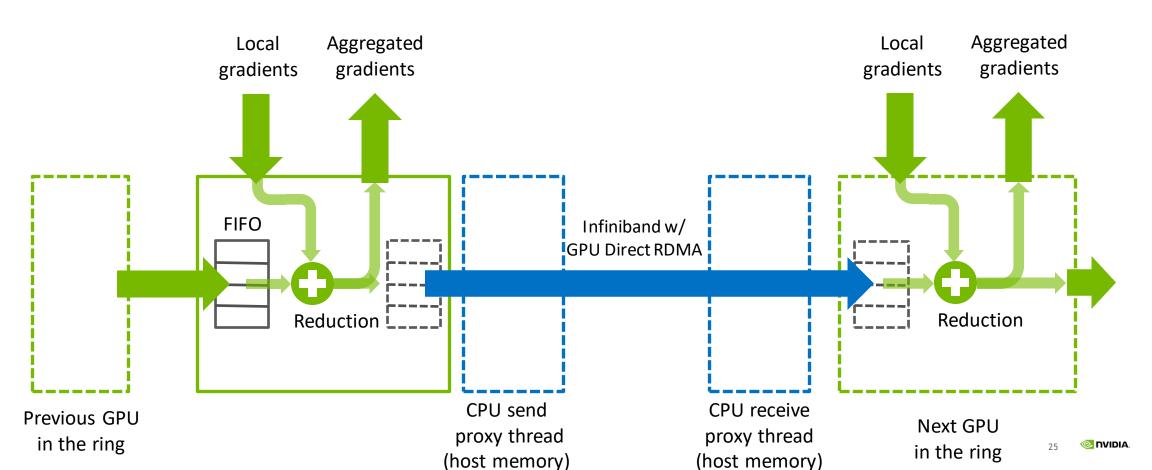
- runs on the GPU
- receives and sends from other peers through internal FIFOs
- perform reductions and copies with local and remote buffers



Network proxy



GPU Direct RDMA



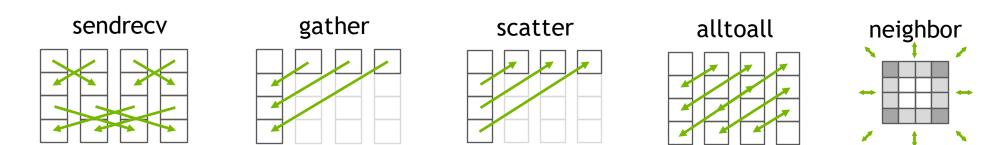


SEND/RECEIVE

Communication semantics

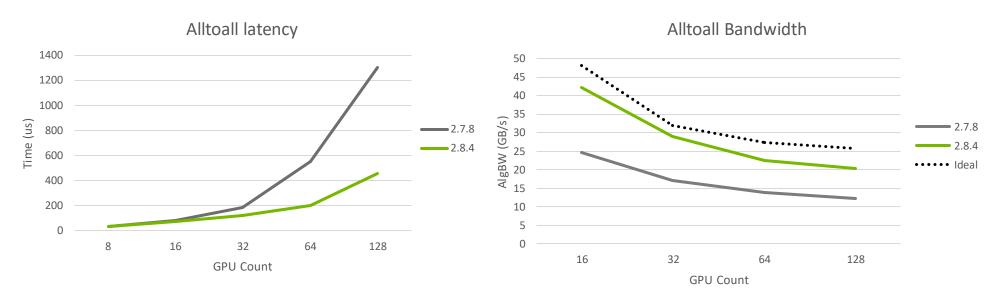
```
ncclGroupStart();
ncclSend(sbuf, ssize, sdtype, peer);
ncclRecv(rbuf, rsize, rdtype, peer);
ncclGroupEnd();
```

Create any operation involving sending and receiving to/from different peers. Grouping operation together is needed to guarantee forward progress and no deadlock.



SEND/RECEIVE

Optimizations (Cont'd)



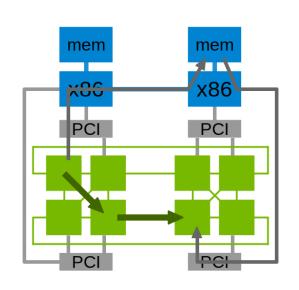
DGX A100, 8x A100, 8x IB HDR 200G, IB adaptive routing enabled

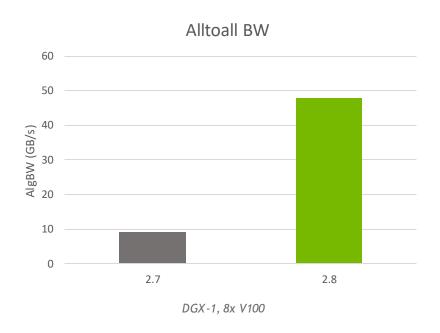
NCCL 2.8: increased send/receive parallelism and better NVLink/IB balancing.



SEND/RECEIVE

Optimizations





One hop NVLink for DGX-1 cube-mesh: alltoall >5x faster than communicating through shared memory.



CUDA GRAPHS

NCCL integration

```
cudaStreamBeginCapture(stream,
    cudaStreamCaptureModeGlobal);
cudaKernel1<<<..., stream>>>(...);
ncclAllreduce(..., stream);
cudaKernel2<<<..., stream>>>(...);
cudaStreamEndCapture(stream,
&graph);

cudaGraphLaunch(instance, stream);

cudaStreamSynchronize(stream);
```

Requires CUDA 11.3

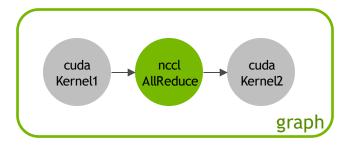


graph

CUDA GRAPHS

NCCL integration

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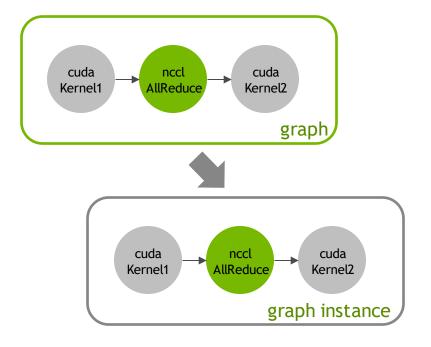
CUDA GRAPHS

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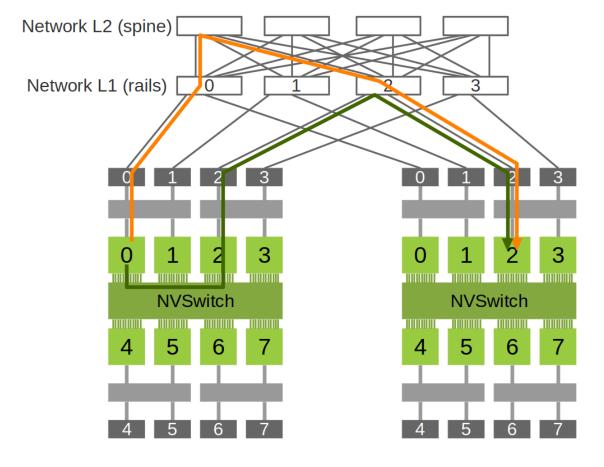
Requires CUDA 11.3



FUTURE

Rail-local alltoall

Use NVLink to avoid NIC crossing for send/receive operations.



FUTURE

ncclAvg

New "Average" operation, computes the sum divided by the number of ranks.

Allows to skip the buffer fusion and scaling step when combined with aggregation.

```
Fusion+Scaling
Single NCCL
AllReduce (Sum)
```



Grouped NCCL AllReduce(Avg)

FUTURE

Misc

Support for bfloat16.

Add ncclGetLastError() to get the WARN() error messages through the NCCL API.

Improved fault tolerance for ncclCommInit*/ncclCommDestroy.

Performance improvement for all platforms.





NCCL

Optimized inter-GPU communication for CUDA applications

Optimized for all NVIDIA platforms, most OEMs and Cloud Scales to 10,000s of GPUs.

Covers all communication needs for multi-GPU computing.

Requires only CUDA. Designed to easily integrate in any parallel environment (MPI or other).

Binaries: https://developer.nvidia.com/nccl and in NGC containers

Source code: https://github.com/nvidia/nccl

Perf tests: https://github.com/nvidia/nccl-tests

CWES1084: Multi-GPU Programming with CUDA, GPUDirect, NCCL, NVSHMEM, and MPI

CWES1186: Optimizing, Profiling, and Scaling Deep Learning Training



