

Lecture 3

Fisher Discriminant

Outline

- ▶ Recap:
 - ▶ Bayes Optimal Classifier
 - ▶ Parameter Estimation
- ▶ Classification without Learning Distributions
 - ▶ Mean Separation
 - ▶ Fisher Discriminant
 - ▶ Perceptron
 - ▶ Large Margin Classifiers

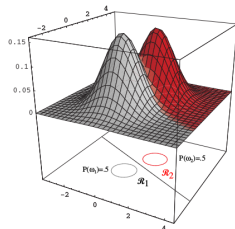
Recap: Bayes Optimal Classifier

Recap:

- Assume our data is generated for each class ω_j according to the multivariate Gaussian distribution $p(\mathbf{x}|\omega_j) = \mathcal{N}(\boldsymbol{\mu}_j, \Sigma)$ and with class priors $P(\omega_j)$. The Bayes optimal classifier is derived as

$$\begin{aligned} & \arg \max_j \{P(\omega_j|\mathbf{x})\} \\ &= \arg \max_j \{\log p(\mathbf{x}|\omega_j) + \log P(\omega_j)\} \\ &= \arg \max_j \left\{ \mathbf{x}^\top \Sigma^{-1} \boldsymbol{\mu}_j - \frac{1}{2} \boldsymbol{\mu}_j^\top \Sigma^{-1} \boldsymbol{\mu}_j + \log P(\omega_j) \right\} \end{aligned}$$

- Given our generative assumptions, there is no better classifier than the one above.
- However, in practice, we don't know these distributions and only have the data.



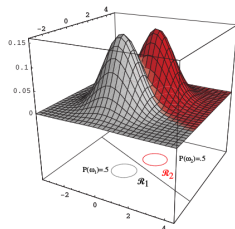
Recap: Parameter Estimation

Example of estimator:

- ▶ Maximum likelihood estimator:

$$\boldsymbol{\mu} = \frac{1}{N} \sum_{k=1}^N \mathbf{x}_k$$

$$\hat{\boldsymbol{\Sigma}} = \frac{1}{N} \sum_{k=1}^N (\mathbf{x}_k - \boldsymbol{\mu})(\mathbf{x}_k - \boldsymbol{\mu})^\top$$



Problem:

- ▶ The covariance matrix (and its inverse) may be difficult to estimate.
- ▶ We make an assumption about the data (e.g. Gaussian-distributed) which may not correspond to reality.

Distribution-Free Approaches

“When solving a problem of interest, do not solve a more general problem as an intermediate step.” (V. Vapnik)

Interpretation in our setting:

- ▶ Don't take the intermediate step of learning distributions to build the classifier. Build the classifier directly.
- ▶ That is, rather than assuming a set of distributions (e.g. Gaussian), assume a set of models (e.g. linear), and find the parameters of the model that optimize some classification objective (e.g. based on the statistics of the data in projected space).

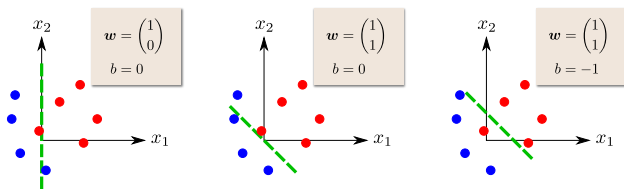
Linear Classifiers

- Functions of the type

$$f(\mathbf{x}; \mathbf{w}, b) = \mathbf{w}^\top \mathbf{x} + b$$

where $\mathbf{w} \in \mathbb{R}^d$ and $b \in \mathbb{R}$ are parameters to learn. We decide for class ω_1 if $f(\mathbf{x}) > 0$ and for class ω_2 if $f(\mathbf{x}) < 0$.

- Examples of linear classifiers on a simple 2d example:



- **Question:** Based on what criterion do we choose the parameters \mathbf{w}, b ?

Mean Separation Criterion

Idea:

- ▶ Build a projection the data $z = \mathbf{w}^T \mathbf{x}$ with $\|\mathbf{w}\| = 1$ such that the means of classes in projected space are as distant as possible.

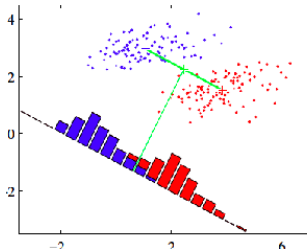
Approach:

- ▶ First, we compute the means in projected space for the two classes

$$\mu_1 = \frac{1}{N_1} \sum_{k \in \mathcal{C}_1} z_k \quad \mu_2 = \frac{1}{N_2} \sum_{k \in \mathcal{C}_2} z_k$$

- ▶ Then we would like to find \mathbf{w} that maximizes the difference of means, i.e. we express the means as a function of \mathbf{w} and pose the optimization problem:

$$\arg \max_{\mathbf{w}} |\mu_2(\mathbf{w}) - \mu_1(\mathbf{w})| \quad \text{with} \quad \|\mathbf{w}\| = 1$$



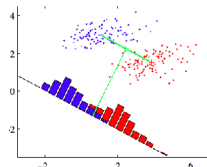
Derivation of Mean Separation

- ▶ The constrained optimization problem (subject to the constraint $\|\mathbf{w}\| = 1$) can be developed as:

$$\begin{aligned} & \arg \max_{\mathbf{w}} |\mu_2(\mathbf{w}) - \mu_1(\mathbf{w})| \\ &= \arg \max_{\mathbf{w}} \left| \frac{1}{N_2} \sum_{k \in \mathcal{C}_2} z_k(\mathbf{w}) - \frac{1}{N_1} \sum_{k \in \mathcal{C}_1} z_k(\mathbf{w}) \right| \\ &= \arg \max_{\mathbf{w}} \left| \frac{1}{N_2} \sum_{k \in \mathcal{C}_2} \mathbf{w}^\top \mathbf{x}_k - \frac{1}{N_1} \sum_{k \in \mathcal{C}_1} \mathbf{w}^\top \mathbf{x}_k \right| \\ &= \arg \max_{\mathbf{w}} \left| \mathbf{w}^\top \left(\frac{1}{N_2} \sum_{k \in \mathcal{C}_2} \mathbf{x}_k \right) - \mathbf{w}^\top \left(\frac{1}{N_1} \sum_{k \in \mathcal{C}_1} \mathbf{x}_k \right) \right| \\ &= \arg \max_{\mathbf{w}} |\mathbf{w}^\top (\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)| \end{aligned}$$

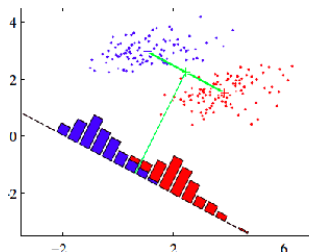
where $\boldsymbol{\mu}_2$ and $\boldsymbol{\mu}_1$ are the means in *input space*.

- ▶ The best vector \mathbf{w} is the one that aligns with $(\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)$, i.e. $\mathbf{w} = (\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1) / \|\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1\|$.



Limitations of Mean Separation

- ▶ There is a significant class overlap in projected space.
- ▶ A better classifier seems achievable if we rotate the projection a few degrees clockwise.
- ▶ Making means distant may not be sufficient to induce class separability in projected space.



Fisher Discriminant



R.A. Fisher (1890 - 1962)

Idea:

- ▶ In addition to maximizing the separation between class means in projected space, also consider to reduce the within-class variance.

$$\begin{aligned}\mu_1 &= \frac{1}{|\mathcal{C}_1|} \sum_{k \in \mathcal{C}_1} z_k & \mu_2 &= \frac{1}{|\mathcal{C}_2|} \sum_{k \in \mathcal{C}_2} z_k \\ s_1 &= \sum_{k \in \mathcal{C}_1} (z_k - \mu_1)^2 & s_2 &= \sum_{k \in \mathcal{C}_2} (z_k - \mu_2)^2\end{aligned}$$

- ▶ Maximizing distance between means while minimizing within-class variance can be formulated as:

$$\arg \max_w \frac{(\mu_2(\mathbf{w}) - \mu_1(\mathbf{w}))^2}{s_1(\mathbf{w}) + s_2(\mathbf{w})}$$

Deriving the Fisher Discriminant (1)

The within-class variance can be expanded as:

$$\begin{aligned} s_j(\mathbf{w}) &= \sum_{k \in \mathcal{C}_j} (z_k - \mu_j)^2 \\ &= \sum_{k \in \mathcal{C}_j} (\mathbf{w}^\top \mathbf{x}_k - \mathbf{w}^\top \boldsymbol{\mu}_j)^2 \\ &= \mathbf{w}^\top \underbrace{\sum_{k \in \mathcal{C}_j} (\mathbf{x}_k - \boldsymbol{\mu}_j)(\mathbf{x}_k - \boldsymbol{\mu}_j)^\top}_{S_j} \mathbf{w} \end{aligned}$$

where S_j is a scatter matrix (unnormalized covariance matrix) for the data of class j .

Observations:

- ▶ Similar structure as the PCA objective (but for each class separately)
- ▶ Unlike PCA, we want to *minimize* the variance rather than maximize it.

Deriving the Fisher Discriminant (2)

Making use of the results of Slide 7 and 10, we can rewrite the Fisher objective

$$J(\mathbf{w}) = \frac{(\mu_2(\mathbf{w}) - \mu_1(\mathbf{w}))^2}{s_1(\mathbf{w}) + s_2(\mathbf{w})}$$

as

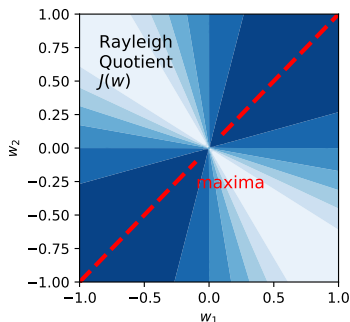
$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{S}_B \mathbf{w}}{\mathbf{w}^T \mathbf{S}_W \mathbf{w}} \quad (1)$$

where

$$\mathbf{S}_B = (\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)(\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)^T$$

$$\mathbf{S}_W = \mathbf{S}_1 + \mathbf{S}_2$$

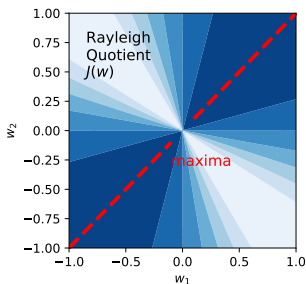
are the '**B**etween-Class' and '**W**ithin-Class' scatter matrices respectively. The form of Eq. (1) is known as *Rayleigh Co-efficient*.



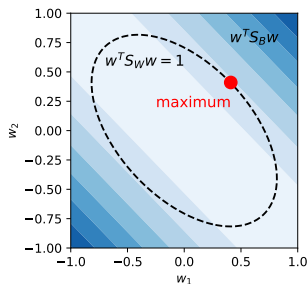
Deriving the Fisher Discriminant (3)

- ▶ A solution that maximizes the Rayleigh quotient $J(\mathbf{w})$ can be obtained by first observing that $\forall \alpha \neq 0 : J(\alpha \mathbf{w}) = J(\mathbf{w})$ and searching for the particular solution for which the denominator is exactly one. This can be stated as the constrained optimization problem

$$\arg \max_{\mathbf{w}} \mathbf{w}^T \mathbf{S}_B \mathbf{w} \quad \text{s.t.} \quad \mathbf{w}^T \mathbf{S}_W \mathbf{w} = 1$$



Constrained
formulation
→



Deriving the Fisher Discriminant (4)

We start with the constrained optimization problem:

$$\arg \max_{\mathbf{w}} \mathbf{w}^\top \mathbf{S}_B \mathbf{w} \quad \text{s.t.} \quad \mathbf{w}^\top \mathbf{S}_W \mathbf{w} = 1$$

Method of Lagrange Multipliers

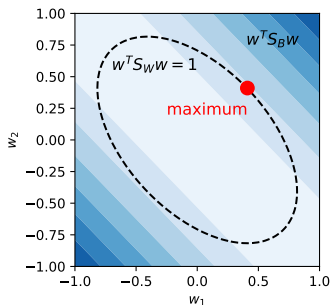
Step 1: We build the Lagrangian

$$\begin{aligned} \mathcal{L}(\mathbf{w}, \lambda) &= \mathbf{w}^\top \mathbf{S}_B \mathbf{w} \\ &\quad + \lambda \cdot (1 - \mathbf{w}^\top \mathbf{S}_W \mathbf{w}) \end{aligned}$$

Step 2: We look for potential solutions by posing $\nabla \mathcal{L}(\mathbf{w}, \lambda) = \mathbf{0}$, which leads to the equation:

$$\mathbf{S}_B \mathbf{w} = \lambda \mathbf{S}_W \mathbf{w}$$

This is a generalized eigenvalue problem.



Deriving the Fisher Discriminant (5)

Further steps:

- ▶ If \mathbf{S}_W is invertible, it can be restated as the standard eigenvalue problem

$$(\mathbf{S}_W^{-1} \mathbf{S}_B) \mathbf{w} = \lambda \mathbf{w}$$

- ▶ Expanding the term \mathbf{S}_B , we get:

$$\mathbf{S}_W^{-1} (\mu_2 - \mu_1) \underbrace{(\mu_2 - \mu_1)^T \mathbf{w}}_{\text{scalar!}} = \lambda \mathbf{w}$$

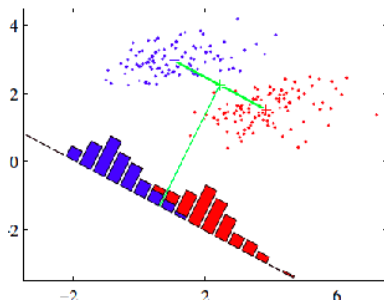
- ▶ Therefore, one possible solution for \mathbf{w} is given by

$$\mathbf{w} = \mathbf{S}_W^{-1} (\mu_2 - \mu_1)$$

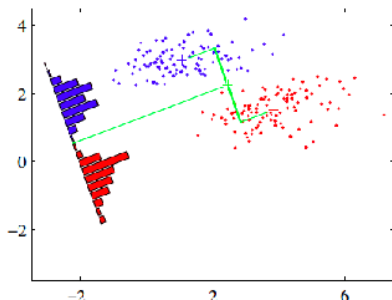
(Reminder, in our original Rayleigh quotient formulation, $J(\alpha \mathbf{w}) = J(\mathbf{w})$, i.e. the optimum is defined up to a scaling factor.)

Mean Separation vs. Fisher Discriminant

Maximum Mean Separation



Fisher Discriminant



- ▶ Fisher Discriminant leads (in general) to better class separability, and therefore, better classification accuracy.
- ▶ Fisher Discriminant requires inversion of a covariance matrix (only tractable for low-dimensional data).

Decision Theory vs. Fisher Discriminant

Bayes decision theory (Lecture 1)

Discriminant has the form

$$\mathbf{w} = \Sigma^{-1}(\mu_2 - \mu_1)$$

- ▶ ...under the assumption that the data-generating distributions are *Gaussian* (with means μ_1, μ_2 for each class, and *same* covariance Σ).
- ▶ Bias is also given by the analysis (cf. Slide 2).

Fisher discriminant (today)

Discriminant has the form

$$\mathbf{w} = \mathbf{S}_W^{-1}(\mu_2 - \mu_1)$$

- ▶ No generative assumption. Classifier only derived from a criterion on mean and dispersion of data in projected space.
- ▶ Bias is not provided by the analysis but it can be fitted in a second step.

Application: P300 BCI Speller



BCI with ML: Calibration and Feedback

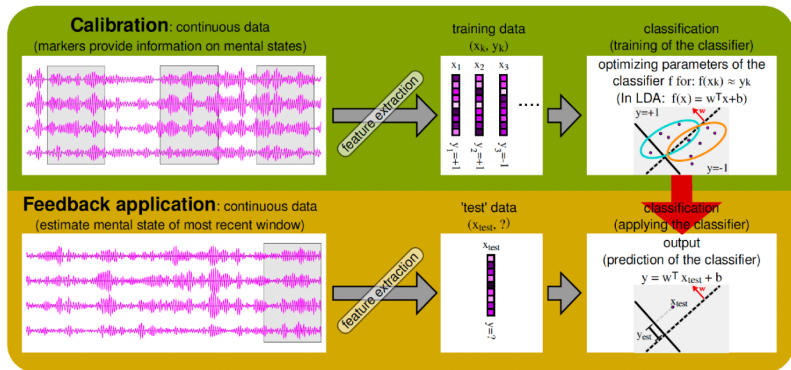
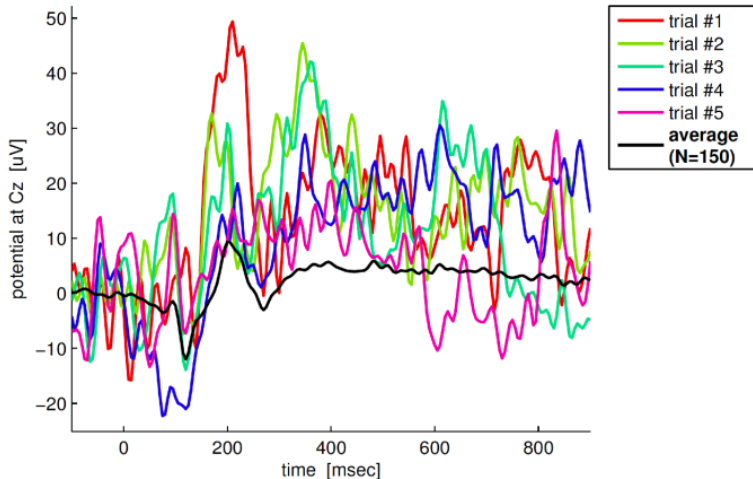
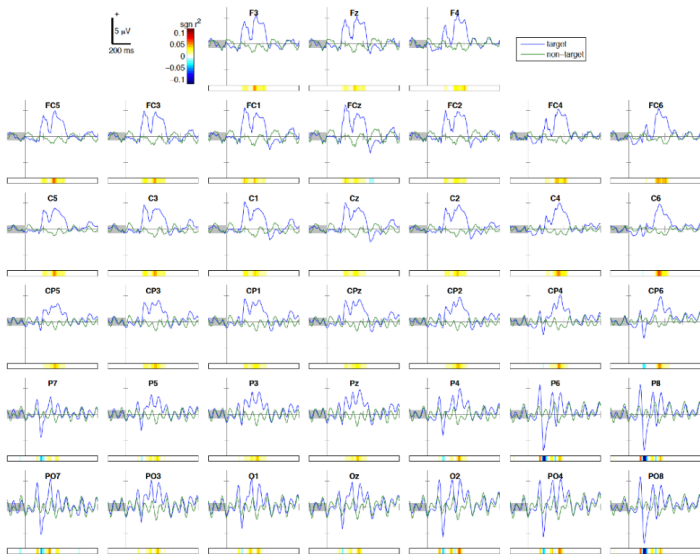


Illustration: Single-Trials and ERPs

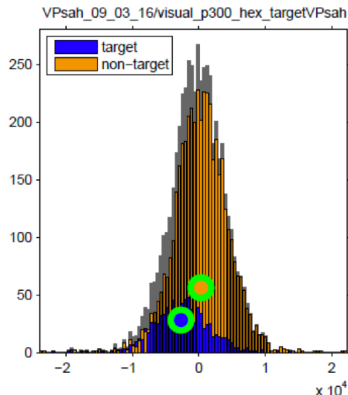


Scalp Potentials In Response to (Non-)Targets

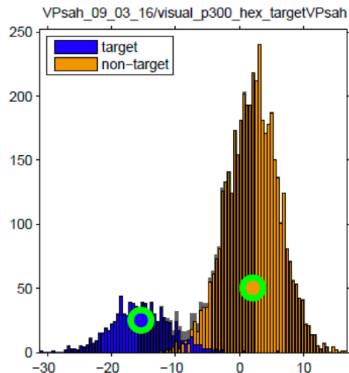


A BCI example: P300 speller

Mean Separation



Fisher Discriminant



Fisher Discriminant (Strengths/Limitations)

Strengths:

- ▶ Accurate when the means/covariances describe well the data, and close to optimal when the data is Gaussian of fixed covariance.
- ▶ The Fisher discriminant is given in closed form and is fast to compute.

Limitations:

- ▶ Although applicable to non-Gaussian distributions, the resulting decision boundary can become in that case strongly suboptimal.
- ▶ In particular, like principal component analysis, Fisher Discriminant is not robust to outliers.

Idea:

- ▶ To overcome these limitations, we will discuss other learning algorithms that more specifically focus on modeling the decision boundary between the two classes.

The Perceptron



F. Rosenblatt (1928–1971)

- ▶ Proposed by F. Rosenblatt in 1958.
- ▶ Classifier that perfectly separates training data (if the data is linearly separable).
- ▶ Trained using a simple and cheap iterative procedure.
- ▶ The perceptron gave rise to artificial neural networks.

The Perceptron Algorithm

- ▶ Consider our linear model

$$z_k = \mathbf{w}^\top \mathbf{x}_k + b \quad y_k = \text{sign}(z_k)$$

and let t_k be 1 and -1 when the true class of \mathbf{x}_k is ω_1 and ω_2 respectively.

Algorithm

- ▶ Iterate over all examples $k = 1 \dots, N$ (multiple times).
 - ▶ If example \mathbf{x}_k is correctly classified ($y_k = t_k$), continue.
 - ▶ If example \mathbf{x}_k is wrongly classified ($y_k \neq t_k$), apply:

$$\mathbf{w} \leftarrow \mathbf{w} + \eta \cdot \mathbf{x}_k t_k \quad (2)$$

$$b \leftarrow b + \eta \cdot t_k \quad (3)$$

where η is a learning rate.

- ▶ The algorithm stops once all examples are correctly classified.

The Perceptron: Optimization View

- ▶ The perceptron can be seen as the minimization of the error function

$$\mathcal{E}(\mathbf{w}, b) = \frac{1}{N} \sum_{k=1}^N \underbrace{\max(0, -z_k t_k)}_{\mathcal{E}_k(\mathbf{w}, b)}$$

- ▶ *Proof:* Computing the gradient of \mathcal{E}_k gives

$$\begin{aligned}\nabla_{\mathbf{w}} \mathcal{E}_k(\mathbf{w}, b) &= 1_{-z_k t_k > 0} \cdot (-\mathbf{x}_k t_k) \\ &= 1_{y_k \neq t_k} \cdot (-\mathbf{x}_k t_k) \\ &= \begin{cases} 0 & y_k = t_k \\ -\mathbf{x}_k t_k & y_k \neq t_k \end{cases}\end{aligned}$$

And we observe that the update rule $\mathbf{w} \leftarrow \mathbf{w} - \eta \cdot \nabla_{\mathbf{w}} \mathcal{E}_k(\mathbf{w}, b)$ is equivalent to that of Eq. (2)

- ▶ Similar result can be obtained for the bias.

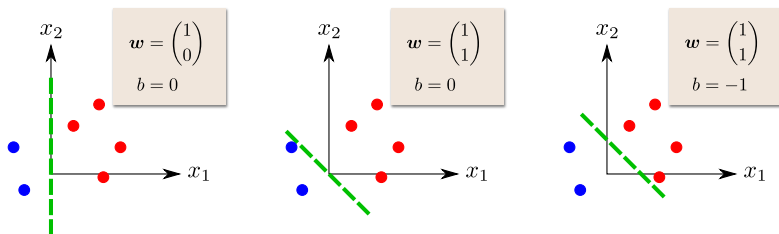
The Perceptron: Optimization View

- ▶ Recall: The objective function corresponding to the perceptron algorithm is given by:

$$\mathcal{E}(\mathbf{w}, b) = \frac{1}{N} \sum_{k=1}^N \underbrace{\max(0, -z_k t_k)}_{\mathcal{E}_k(\mathbf{w}, b)}$$

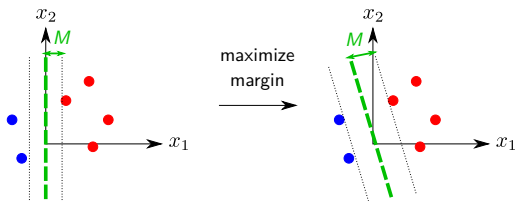
- ▶ This objective can be interpreted as measuring for each wrongly classified data point how far the data point is from the decision boundary, and penalizing accordingly.
- ▶ In practice various strategies can be implemented to optimize this objective (e.g. gradient descent on $\mathcal{E}(\mathbf{w}, b)$ directly, or adding momentum to the gradient descent).
- ▶ Optimization of the objective also works for data that is not linearly separable.

A Problem of the Perceptron



- ▶ All these solutions have an error $\mathcal{E}(\mathbf{w}, b) = 0$.
- ▶ Some solutions are obviously better than other, e.g. those where the decision boundary is separated from the data with a large margin.

Large Margin Classifiers

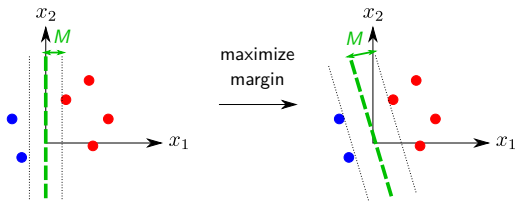


Idea: Induce large margin M by redefining the optimization problem as:

$$\underbrace{\arg \min_{w,b,M}}_{(1)} \left[\underbrace{\frac{1}{M}}_{(2)} + \frac{1}{N} \sum_{k=1}^N \underbrace{\max(0, M - (\mathbf{w}^T \mathbf{x}_k + b)t_k)}_{(3)} \right] \quad \text{s.t.} \quad \underbrace{\|\mathbf{w}\| = 1}_{(4)} \quad (4)$$

- ▶ (1) actively optimize the margin
- ▶ (2) apply a penalty if the margin is too small
- ▶ (3) apply a penalty if some points violate the margin and
- ▶ (4) constrain the projection so that M is interpretable as a margin.

Large Margin Classifiers



- ▶ An equivalent (and more standard) formulation of the optimization problem is given by:

$$\arg \min_{\mathbf{w}, b} \frac{1}{N} \sum_{k=1}^N \max(0, 1 - (\mathbf{w}^\top \mathbf{x}_k + b)t_k) + \|\mathbf{w}\|^2 \quad (5)$$

(proof in next slide).

- ▶ Large Margin Classifiers are typically solved using (stochastic) gradient descent or quadratic programming.
- ▶ More will be said about these model during the lecture on support vector machines.

Derivation of Eq. (5) from Eq. (4)

$$\arg \min_{w,b,M} \frac{1}{N} \sum_{k=1}^N \max(0, M - (w^\top x_k + b)t_k) + \frac{1}{M} \quad \text{s.t.} \quad \|w\| = 1$$

The same objective can be rewritten as:

$$= \arg \min_{w,b,M} \frac{1}{N} \sum_{k=1}^N \max(0, M - (w^\top x_k + b)t_k) + \frac{\|w\|^2}{M} \quad \text{s.t.} \quad \|w\| = 1$$

Dividing by M does not change the argmin nor the constraint

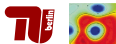
$$= \arg \min_{w,b,M} \frac{1}{N} \sum_{k=1}^N \max(0, 1 - (\frac{w^\top}{M} x_k + \frac{b}{M}) t_k) + \frac{\|w\|^2}{M^2} \quad \text{s.t.} \quad \frac{\|w\|}{M} = \frac{1}{M}$$

and redefining $w \leftarrow w/M$ and $b \leftarrow b/M$, we get:

$$= \arg \min_{w,b,M} \frac{1}{N} \sum_{k=1}^N \max(0, 1 - (w^\top x_k + b)t_k) + \|w\|^2 \quad \text{s.t.} \quad \|w\| = \frac{1}{M}$$

Because optimizing w.r.t. M is now trivial, we can further simplify to

$$= \arg \min_{w,b} \frac{1}{N} \sum_{k=1}^N \max(0, 1 - (w^\top x_k + b)t_k) + \|w\|^2$$



Advanced Classification Topics

- ▶ **Nonlinear Classification** (Kernel SVM, Artificial Neural Networks, Decision Trees, Random Forests, Boosting). (Covered in ML1)
- ▶ Incorporating **prior knowledge** such as invariances into a classifier. Example: the convolutional neural network. (Covered in ML2)
- ▶ Classification in **high dimensions**: Unintuitively, methods that actually promote within-class variance instead of reducing it tend to perform better in this setting.

Summary

- ▶ In practice, it is preferable to **train a classifier directly** rather than learning the class distributions in the first place.
- ▶ The **maximum mean separation** and **Fisher discriminant** are two such instances, where one only needs to estimate the mean and the covariance of the data, without having to estimate full distributions.
- ▶ The **perceptron** (and its **large-margin** extension) more specifically focus on the decision boundary, which typically leads to higher classification accuracy on general tasks.