

① 14-bit accelerometer:  $X = 10429$ ;  $Y = 6626$ .  
 $\pm 3g$ .

Sensitivity:  $1g \rightarrow (2^{14} - 1) / 6g$   
 $S = 2730 \text{ (count/g)}.$

$$A_0 (0g) = 2^{13} = 8192$$

$$A_x = (X - A_0) / S = 0.8194$$

$$A_y = (Y - A_0) / S = -0.5736$$

$$\alpha = \tan^{-1} (A_y / A_x)$$

$$= \tan^{-1} (-0.5736 / 0.8194)$$

$$= \boxed{-34.993}$$

② Completed in Matlab.

$$\textcircled{3} \quad \frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 10 y(t) = \frac{dx(t)}{dt}$$

$$s^2 Y(s) - 1 + 2s Y(s) + 10 Y(s) = 1$$

$$Y(s) (s^2 + 2s + 10) = 2$$

$$Y(s) = \frac{2}{s^2 + 2s + 10} = \frac{2}{(s+1)^2 + 9}$$

$$\therefore y(t) = \mathcal{L}^{-1} \left( \frac{2}{3} \cdot \frac{3}{(s+1)^2 + 9} \right)$$

$$= \frac{2}{3} e^{-t} \sin(3t) \text{ ut.}$$

Steady State response =  $\boxed{0}$

transient response:

$$y_{tr} = \frac{2}{3} e^{-t} \sin(3t) \text{ ut.}$$

at  $t = 1.4 \text{ s}$ :

$$y(1.4) = \frac{2}{3} e^{-1.4} \sin(3 \times 1.4)$$

$$= \boxed{-0.143}$$

④

$$\frac{3s + 4}{s^2 + 2s + 4}$$

$$X(s) = \frac{3s + 4}{s^2 + 2s + 4} = \frac{3s + 4}{(s+1)^2 + 3}$$

$$= \frac{3(s+1) + 1}{(s+1)^2 + 3}$$

$$= 3 \frac{(s+1)}{(s+1)^2 + 3} + \frac{1}{\sqrt{3}} \frac{\sqrt{3}}{(s+1)^2 + 3}$$

So:

$$x(t) = 3 \cdot e^{-t} \cos(\sqrt{3}t) + \frac{1}{\sqrt{3}} e^{-t} \sin(\sqrt{3}t)$$

$$x(1) = 3e^{-1} \cos(\sqrt{3} \cdot 1) + \frac{1}{\sqrt{3}} e^{-1} \sin(\sqrt{3} \cdot 1)$$

$$= \boxed{0.032}$$

## Console window Calculations. (MATLAB).

```
>> otieno_midterm
```

```
Value of  $h(\tau-t)$  at  $t = 1.4s$ : 0.522
```

```
>> (2/3)*exp(-1.4)*sin(3*1.4)
```

```
ans =
```

```
-0.1433
```

```
>> 3*exp(-1)*cos(sqrt(3))+(1/sqrt(3))*exp(-1)*sin(sqrt(3))
```

```
ans =
```

```
0.0324
```

```
>>
```