### **SEM VI**

# **Professional Core** (Theory)

		Wald	chand College	of Engineering	, Sang	gli							
	(Government Aided Autonomous Institute)  AY 2023-24												
	AY 2023-24  Course Information												
Progra	amme												
Class,	Seme	ster	Third Year B. Tee	ch., Sem VI									
Cours	e Cod	e	6EL321										
Cours	e Nan	ne	Power System Pro										
Desire	d Rec	quisites:	Power System En	gineering									
		ning Scheme		Examination S		·							
Lectur	re	3 Hrs/week	MSE	ISE		SE	Total						
Tutori	ial	-	30	20		50	100						
				Cred	its: 3								
				Objectives									
1		each need for power	-				•						
2		iscuss protection of				rators and tl	neir						
	_	ementation using ele											
3	To d	iscuss causes of ove		-	_		er voltages.						
A 4 4 la a				vith Bloom's Taxor	nomy L	evel							
At the	ena o	f the course, the stud	ients will be able to	,		Bloom's	Bloom's						
CO		Cours	se Outcome Staten	nent/s		Taxonomy Level							
CO1		eribe basic principle et proper CB/fuse for	_		s and	II	Understanding						
CO2		sify the requirement											
	pow	er system and select	proper relay schem	e.		III	Applying						
CO3		<b>lyse</b> the performance al relaying technique	_	ion devices and disc	cuss	IV	Analysing						
Modu	ıle		Module (	Contents			Hours						
	(	Over Current Relay	'S										
	Need of protection, Brief theory and construction of electromagnetic relays.												
I		Different time curren		•		-	7						
		Microprocessor based	· · · · · · · · · · · · · · · · · · ·	, Directional over co	urrent re	elay,							
	Ċ	rawbacks of over cu	rrent schemes.										
		Arc Interruption Pr			1 4 6								
		/oltage - current cha		6									
II			resistance and current zero interruption, arc voltage,										
		Transient Restriking	-	•		rent							
	C	hopping, resistance	switching, capacitiv	e current interruption	on								

	Circuit Breakers & Fuses Classification of circuit breakers, brief study of construction and working of						
III	Air break and Air Blast CB, SF6 and Vacuum CB, HVDC breakers, ratings of	6					
	CB and testing of CB, Fuse –Rewirable and HRC fuse, fuse characteristics,	, and the second					
	application and selection of fuse						
	Protection of Transformer, Generator and Bus Bar						
	Circulating current differential protection, percentage differential protection of						
17.7	power transformers, through fault stability, effect of magnetizing inrush, effect						
IV	of over voltage inrush ,Buchholz relay, Differential protection of generator,	7					
	stator and rotor protection schemes of generator, loss of excitation, prime						
	mover failure protection, bus bar protection.						
	Protection of Transmission Line						
	Principles of distance relays, Effect of arc resistance, and power swing on relay						
V	operation, Microprocessor based impedance, reactance and admittance relays,	7					
	Quadrilateral characteristics, carrier aided protection of transmission line.						
	Protection Against Over Voltages.						
	Recent Developments in Protection						
VI	Introduction to numerical/digital relay techniques. New numerical /digital	6					
V1	relaying algorithms, introduction of various transform techniques - Discrete	U					
	Fourier Transform, Haar Transform etc.						
1	Textbooks						
1	S.S. Rao, "Switchgear & Protection", Khanna Pub., XI edition, 2005.  B.Ram & Vishwakarma, "Power System Protection & Switchgear", TMH P	uh III adition					
2	2008.	ub., III edition,					
	References						
1	Oza, Nair, Mehta & Makwana," Power System Protection & Switchgear", MGH	l pub., 2011.					
2	2 C.R. Mason, "Art & Science of Protective Relaying", GE e-book.						
3	Y.G. Paithankar & S.R. Bhide, "Fundamentals of Power System Protection", PHI pub., I						
	edition, 2004.						
1	Useful Links						
1	https://nptel.ac.in/courses/108/101/108101039/						

	CO-PO Mapping													
		Programme Outcomes (PO)												<b>SO</b>
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	2													
CO2		3												
CO3			3											

#### Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

		Wald	rhand College	of Engineering, Sai	าฮโ่					
		wan		d Autonomous Institute)	ign					
			AY	2022-23						
			Course	Information						
Progr	amme		B.Tech. (Electrication	al Engineering)						
	Semester		Third Year B. Te	ch., Sem VI						
Cours	e Code		6EL322							
Cours	e Name		Industrial Drives	and Control						
Desire	ed Requisi	tes:	DC Machines and	d Transformer, AC Machin	nes and Power	Electronics				
	Teaching	Scheme		<b>Examination Scheme</b>	(Marks)					
Lectu	re	3 Hrs/week	MSE	ISE	ESE	Total				
Tutor	ial	-	30	20	50	100				
				Credits: 3	,					
			Course	Objectives						
1	To make Electric		tand concept of fur	ndamental knowledge in d	ynamics and c	ontrol of				
2										
3	To cover principles of selection of Electric Motors and highlights the applications of Electrical									
		Course	Outcomes (CO) v	vith Bloom's Taxonomy	Level					
At the	end of the	course, the stud	ents will be able to	,	I					
СО		Cours	se Outcome Staten	nent/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description				
CO1	Explain	the various cond	cepts used in Electr	ic drives.	II	Understanding				
CO2	Apply th	ne control techni	ques for Electric dr	ives for speed control.	III	Applying				
CO3		•		trol techniques used in						
			c drives and selec	et a drive for particular	IV	Analysing				
	applicati	OII.								
Modu	ıle		Module (	Contents		Hours				
1/1040		lamentals of El				110015				
I	Types & parts of the Electrical drives, Selection criteria of drives, motor rating, selection based on duty cycle, selection of converter rating, fundamental torque									
П	Meth three quad DC o	phases full contract operation of drives, circulating eries motor drives.	trolled and half cor f separately excite g and non – circul ve, chopper control	d braking operation, sing atrolled converter fed DC d DC shunt motor, dual ating mode of operation, of DC shunt and series oC shunt motor drive.	drives, Multi converter fed converter fed	7				

T. L. C. M. A. D.							
Torque equation, Speed control methods for three phase cage induction motor, braking methods, stator voltage control induction motor drive, VSI fed induction motor drive, constant torque (constant E/F and constant V/F), constant HP operation, closed loop speed control block diagram, Stator current control methods fed induction motor drive, speed torque characteristics of CSI fed drive, closed loop speed control block diagram, comparison of CSI fed and VSI fed induction motor drive.	7						
Slip Ring Induction Motor Drives Chopper controlled resistance in rotor circuit, slip power recovery using converter cascade in rotor circuit, sub synchronous and super synchronous speed control, Kramer speed control, cyclo - converter in rotor circuit.	6						
Synchronous Motor Drives and Brushless DC Motor Drives  VSI fed synchronous motor drives, true synchronous and self-control mode, open loop and closed loop speed control of Permanent magnet synchronous machine, brushless DC motor drives.	6						
Special Drives  Construction and operating principle of switched reluctance motors, Current / Voltage control, torque equation, converter circuits, operating modes and applications of switched reluctance motors. Solar panel VI characteristics, solar powered pump, maximum power point tracking and battery-operated vehicles.	6						
Textbooks							
"Fundamentals of Electrical Drives", G. K. Dubey, Narosa publication, 2nd edit	ion.						
References							
Department of Electrical Engineering, IIT Kanpur.							
"Power Electronics - Converter Application", By N. Mohan T.M. Undel and John Wiely and sons.	W. P. Robbins,						
"Electrical Drives - Concept and application", Vedam Subramanyam.							
Useful Links							
https://nptel.ac.in/courses/108/104/108104140/							
	braking methods, stator voltage control induction motor drive, VSI fed induction motor drive, constant torque (constant E/F and constant V/F), constant HP operation, closed loop speed control block diagram, Stator current control methods fed induction motor drive, speed torque characteristics of CSI fed drive, closed loop speed control block diagram, comparison of CSI fed and VSI fed induction motor drive.  Slip Ring Induction Motor Drives Chopper controlled resistance in rotor circuit, slip power recovery using converter cascade in rotor circuit, sub synchronous and super synchronous speed control, Kramer speed control, cyclo - converter in rotor circuit.  Synchronous Motor Drives and Brushless DC Motor Drives VSI fed synchronous motor drives, true synchronous and self-control mode, open loop and closed loop speed control of Permanent magnet synchronous machine, brushless DC motor drives.  Special Drives Construction and operating principle of switched reluctance motors, Current / Voltage control, torque equation, converter circuits, operating modes and applications of switched reluctance motors. Solar panel VI characteristics, solar powered pump, maximum power point tracking and battery-operated vehicles.  Textbooks  "Fundamentals of Electrical Drives", G. K. Dubey, Narosa publication, 2nd edit  References  "Fundamentals of Electrical Engineering, IIT Kanpur.  "Power Electronics - Converter Application", By N. Mohan T.M. Undel and John Wiely and sons.  "Electrical Drives - Concept and application", Vedam Subramanyam.						

	CO-PO Mapping													
		Programme Outcomes (PO) PSO												
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1		3												2
CO2			2											2
CO3			2											2
CO4														

#### Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

#### Walchand College of Engineering, Sangli (Government Aided Autonomous Institute) AY 2023-24 **Course Information** B.Tech. (Electrical Engineering) **Programme** Class, Semester Third Year B. Tech., Sem VI **Course Code** 6EL323 **Course Name** Microcontroller and Applications Analog and Digital Circuits **Desired Requisites: Teaching Scheme Examination Scheme (Marks)** Lecture 3 Hrs/week **MSE ISE ESE** Total **Tutorial** 30 20 50 100 **Credits: 3 Course Objectives** To develop basic knowledge of microcontrollers and their features. 1 To provide skills for programming microcontroller for applications in Electrical Engineering. 2 To enable students to interface and program different peripherals to microcontrollers. 3 Course Outcomes (CO) with Bloom's Taxonomy Level At the end of the course, the students will be able to, Bloom's Bloom's CO **Course Outcome Statement/s** Taxonomy **Taxonomy Description** Level Explain the architecture and features of microcontrollers. Understanding CO<sub>1</sub> П Apply programming techniques to implement counters, timers, Ш CO<sub>2</sub> Applying interrupts and other peripherals. Implement the applications related to interface microcontroller CO<sub>3</sub> III Applying with electrical and electronics systems. Construct a microcontroller based application. Ш CO<sub>4</sub> Applying Module **Module Contents** Hours **Microcontroller Basics** Overview of 8051, features, Architecture, Pin out and pin functions, program Ι 6 memory, data memory, SFR area, PSW, Code memory (Internal/External), Port structure, clock circuit, Addressing Modes **Programming ports and timers** Introduction to Embedded C programming ,Basic I/O programming Development tools for 8051 programs, Programming Timers and counters 7 II Timer block diagram and function, Timer modes 0, 1, 2 and their Applications, Timer and Counter Programming **Interrupts and Serial Communication** Interrupt structure, Writing ISR, interrupt, Interrupt priorities, Programming III for external interrupt. Programming timer interrupts. 6 Serial Communication: Serial communication modes, RS232 signals of PC, Programming through Serial communication Peripheral Interfacing- I Interfacing of microcontrollers to external peripherals and programming, 7 IV LCD interfacing, Interfacing of Analog to Digital Converters and Digital to

Analog Converters, Stepper motor interfacing

V	Peripheral Interfacing- II DC motor interfacing, PWM programming using microcontrollers, Use of Arduino in Power Electronics Applications, Interfacing Temperature Sensors, Relay Interfacing, concept of hardware-in-loop simulation, programming examples	7						
VI	Introduction to Advanced microcontrollers  Introduction to APM and PIC processors of MSP 430 microcontroller, 16 bit							
	Textbooks							
1	Muhammad Mazidi, Janice Mazidi and Rolin McKinlay, 'The 8051 Mici Embedded systems using Assembly and C', Pearson Education, 2nd Edition, 20							
2	Kenneth Ayala, '8051 Architecture, Programming and Applications', 3rd Editi							
3	Massimo Banzi and Michael Shilah Make: Gatting Started With Arduing The Open Source							
	References							
1	Subrata Ghoshal, 'Embedded Systems and Robots- Projects using the 8051 N Cengage Learning, 1st Edition, 2009	Microcontroller',						
2	Michael Margolis, 'Arduino Cookbook', Shroff/ O'Reilly,2nd Edition, 2012							
3	Mazidi, RolinMc Kinlay and Danny Causey, 'PIC Microcontroller and Emusing Assembly and C for PIC18', Pearson Education, 2007	bedded Systems						
4	Andrew N. Sloss, 'Arm System Developer's Guide: Designing and Opt Software', Elsevier Publication, 2005	imizing System						
5	Texas Instruments MSP 430 microcontroller: Guide and Datasheets							
	Useful Links							
1	https://nptel.ac.in/courses/106/108/106108100/							
2	https://nptel.ac.in/courses/117/104/117104072/							
3	https://nptel.ac.in/courses/108/102/108102045/							

	CO-PO Mapping													
		Programme Outcomes (PO) PSO												
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1			3											
CO2					3									
CO3					3									
CO4			3											2

#### Assessment

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		W		e of Engineering, Sa ed Autonomous Institute)	ngli							
			AY	2023-24								
	Course Information											
Progr	rogramme B.Tech. (Electrical Engineering)											
Class,	lass, Semester Third Year B. Tech., Sem V											
Cours	Course Code 6EL324											
Cours	e Na	ame	Energy Audit an	d Management								
Desire	ed R	equisites:	Nil									
	Tea	ching Scheme		Examination Scheme	e (Marks)							
Lectu	re	3 Hrs/wee	ESE	Total								
Tutor	ial	50	100									
				Credits: 3								
			Cours	e Objectives								
1	_			nergy conservation and its								
2	То			nergy management in indu		ment						
A t tha	and		tudents will be able to	with Bloom's Taxonomy	Level							
At the	ena	of the course, the s	tudents will be able to	0,	Bloom's	Bloom's						
co		Co	urse Outcome State	ment/s	Taxonomy	Taxonomy						
				Le								
CO1		<b>xplain</b> energy cor ergy audit.	servation, its impor	rtance and necessity of	II	Understanding						
CO2			al analysis for energy	economics.	III	Applying						
CO3	Ar	nalyse Energy Effic	eiency in Electrical an	d Thermal Utilities	IV	Analysing						
Modu	ıle			Contents		Hours						
I		Energy Conservation Ac Conservation Ac Reforms, Energy Principles of Ener	t2001 and its featu And Environmen	ent ace, Energy strategy for f ares, Energy Pricing, E t, Energy Security, Ob	nergy Sector	7						
Energy Audit Energy audit Definition as per EC-act 2001, Need of Energy Audit, Types of Energy Audit, Energy Audit Reporting Format, Understanding Energy and Costs, Benchmarking, Energy Performance, Energy Audit Instruments, Duties and Responsibilities of Energy Auditor.												
Energy Action Planning, Monitoring And Targeting Energy action Planning Steps, Top Management Support, Energy Manager  III Duties & responsibilities, Evaluating Energy Performance, Energy monitoring & Targeting — Set up, Key Elements, Data & Information Analysis, Relating Energy Consumption & Production, CUSUM Technique, Case Study												
IV		<b>Energy Economi</b> Financial Analysi	cs s Techniques – Pay I ternal Rate Of Retur	Back Period, Net Present rn, Time Value Of Money	Value, Returr	1 0						

Risk & Sensitivity analysis.

	Energy Efficiency in Electrical Utilities	
	Electricity Billing, Electrical Load Management and Maximum Demand	
V	Control, Power Factor Improvement & Benefits, Assessment of Transmission	
V	and Distribution Losses, Estimation Of Technical Losses in Distribution	7
	System, Commercial Losses, Demand Side Management, Energy Saving	
	Opportunities With Pumps and Fans.	
	Energy Efficiency in Thermal Utilities	
	Energy Conservation in Boilers, Steam Turbine, Industrial Heating System,	
VI	Heat Exchangers, Heat Pumps, Efficiency Improvement, Energy Conservation	5
	in Buildings, Climate responsive Buildings, Thermal load modelling in	]
	Building	
	Textbooks	
1	Amlan Chakrabarti, "Energy Engineering and Management", PHI, 2011.	
	References	
1	Bureau of Energy Efficiency, "General Aspects of Energy Management & Energy	gy Audit1.1, 1.2
1	&1.3", BEE, e-books.	
	Useful Links	
1	https://beeindia.gov.in/content/energy-auditors	

	CO-PO Mapping													
		Programme Outcomes (PO)											PS	<b>SO</b>
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1							2							
CO2	2													
CO3		2												

#### Assessment

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ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

# Professional Core (Lab)

(Government Aided Autonomous Institute)

#### AY 2023-24

#### Course Information

	Course information									
Programme B. Tech. (Electrical Engineering)										
Class, Semester Third Year B. Tech., Sem VI										
Course Code 6EL371										
Course Name	Power System Protection Lab									

Desired Requisites: Power System Engineering

Teaching Scheme		Examination Scheme (Marks)						
Practical	2 Hrs/ Week	LA1	LA2	Lab ESE	Total			
Interaction	-	30	30	40	100			
		Credits: 1						

#### **Course Objectives**

- To develop hands on skills to test and verify protective relay operation, used in power system protection
- 2 To demonstrate electromagnetic and digital relays to illustrate their operating characteristics
- To experience to use power system analysis software for developing protection schemes for simple electrical systems.

#### Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

СО	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	<b>Demonstrate</b> the working of over current, earth fault relays and plot the I-t characteristics	III	Applying
CO2	<b>Execute</b> experimental study of a microcontroller based relays.	III	Applying
CO3	<b>Design</b> a scheme for over current relay co-ordination using simulation software / hardware.	VI	Creating

#### List of Experiments / Lab Activities/Topics

#### **List of Experiments:**

- 1. Arrange the set-up & perform an experiment to verify the Current-Time characteristics of a shaded pole type over current relay.
- 2. Arrange the set-up & perform an experiment to verify the Current-Time characteristics of a shaded pole type earth fault relay.
- 3. Arrange the set-up & perform an experiment to demonstrate the operation & use of Directional over current relay.
- 4. Assemble a circuit to obtain & verify various Current-Time curves for Digital over Current Relay.
- 5. Demonstrate the application of Quadrilateral Distance relay for detection of fault on transmission lines.
- 6. Conduct a simulation study to develop relay co-ordination scheme of over current relays for a simple radial feeder system.
- 7. Conduct an experiment to illustrate the over current relay co-ordination on the Transmission Line Simulator.
- 8. Conduct a simulation study to explain the Circuit Breaker operation under fault condition.

	Textbooks						
1	S.S. Rao, "Switchgear & Protection", Khanna Pub., XI edition, 2005						
2	B.Ram and Vishwakarma, "Power System Protection & Switchgear", TMH Pub., III edition, 2008.						
	References						
1	Oza, Nair, Mehta and Makwana, "Power System Protection and Switchgear", MGH pub., 2011.						
2	C.R. Mason, "Art and Science of Protective Relaying", GE e-book.						
3	Y.G. Paithankar and S.R. Bhide, "Fundamentals of Power System Protection", PHI pub., I edition, 2004.						
	Useful Links						
1	https://nptel.ac.in/courses/108/101/108101039/						

	CO-PO Mapping													
		Programme Outcomes (PO)								PSO				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	1													
CO2	3	3												
CO3		2												

The strength of mapping is to be written as 1,2,3; where, 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO, and preferably to only one PO.

#### Assessment

There are three components of lab assessment, LA1, LA2 and Lab ESE.

IMP: Lab ESE is a separate head of passing.(min 40 %), LA1+LA2 should be min 40%

Assessment	Based on	Conducted by	Typical Schedule	Marks
	Lab activities,		During Week 1 to Week 8	
LA1	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 8	
	Lab activities,		During Week 9 to Week 16	
LA2	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 16	
	Lab activities,	Lab Course Faculty and	During Week 18 to Week 19	
Lab ESE	journal/	External Examiner as	Marks Submission at the end of	40
	performance	applicable	Week 19	

Week 1 indicates starting week of a semester. Lab activities/Lab performance shall include performing experiments, mini-project, presentations, drawings, programming, and other suitable activities, as per the nature and requirement of the lab course. The experimental lab shall have typically 8-10 experiments and related activities if any.

(Government Aided Autonomous Institute)

#### AY 2022-23

Course Information						
Programme B.Tech. (Electrical Engineering)						
Class, Semester Third Year B. Tech., Sem VI						
Course Code	6EL372					
Course Name Industrial Drives and Control Lab						
Desired Requisites:	DC Machines and Transformer, AC Machines and Power Electronics					

Teaching Scheme		Examination Scheme (Marks)							
Practical	2 Hrs/ Week	LA1	LA1 LA2 Lab ESE Total						
Interaction	-	30	30	40	100				
		Credits: 1							

#### **Course Objectives**

- To impart knowledge on performance of the fundamental control practices associated with AC and 1 DC machines (starting, reversing, braking, plugging, etc.) using solid state converters.
  - To develop the skills for the use of computer-based analysis tools to review the major classes of 2 machines and their physical basis for operation and suitability for a particular operation
  - 3 4

#### Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

СО	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	<b>Demonstrate</b> experiments on basics of DC and AC drives.	III	Applying
CO2	<b>Analyze</b> the performance of drives using hardware circuits and simulation.	IV	Analysing
CO3	<b>Evaluate</b> performance of drives using hardware circuits and simulation.	VI	Evaluating

#### List of Experiments / Lab Activities/Topics

#### **List of Lab Activities:**

- 1. Verify Speed Torque characteristics of chopper fed D. C. series motor. (Hardware)
- 2. Analyze the performance of chopper fed D. C. drive for closed loop speed control (simulation).
- 3. Demonstrate operation and application of single-phase full wave, half controlled converter for open loop speed control of D. C. shunt motor. (Hardware).
- 4. Demonstrate operation and application of single-phase full wave, full controlled converter for open loop speed control of D. C. shunt motor. (Hardware).
- 5. Analyze the performance of converter fed D. C. drive for closed loop speed control. (Simulation).
- 6. Study the operation of two quadrant single phase converter fed 5 HP DC drive (Simulation).
- 7. Study the four-quadrant operation of 5 HP DC motor using single phase converter. (Simulation).
- 8. Study the operation of four quadrant chopper fed DC drive (simulation).
- 9. Assess the performance of rotor resistance control method for speed control of Slip Ring Induction motor. (Simulation)
- 10. Demonstrate speed control of Induction motor using V/f method. (Hardware)
- 11. Analyze the operation of Induction motor drive with Six step VSI control (Simulation).
- 12. Demonstrate the operation of brushless DC motor drive with software Simulation. (Simulation)
- 13. Demonstrate speed control of Induction motor using Kramer speed control method. (Hardware)

	Textbooks					
1	"Fundamentals of Electrical Drives", G. K. Dubey, Narosa publication, 2nd edition.					
	References					
1	"Modern Power Electronics and AC drives" by B. K. Bose, Prentice Hall of India Pvt. India					
2	"Power Electronics - Converter application" By N. Mohan T.M. Undeland and W. P. Robbins,					
<i>L</i>	John Wiley and sons					
3	"Electrical Drives - Concept and application" Vedam Subramanyam.					
	Useful Links					
1	https://nptel.ac.in/courses/108/104/108104140/					

	CO-PO Mapping													
				]	Progra	mme C	Outcom	es (PO	)				PSO	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1		3												
CO2		2												2
CO3			2											2
CO4														

The strength of mapping is to be written as 1,2,3; where, 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO, and preferably to only one PO.

#### Assessment

There are three components of lab assessment, LA1, LA2 and Lab ESE.

IMP: Lab ESE is a separate head of passing.(min 40 %), LA1+LA2 should be min 40%

Assessment	Based on	Conducted by	Typical Schedule	Marks
	Lab activities,		During Week 1 to Week 8	
LA1	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 8	
	Lab activities,		During Week 9 to Week 16	
LA2	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 16	
	Lab activities,	Lab Course Faculty and	During Week 18 to Week 19	
Lab ESE	journal/	External Examiner as	Marks Submission at the end of	40
	performance	applicable	Week 19	

Week 1 indicates starting week of a semester. Lab activities/Lab performance shall include performing experiments, mini-project, presentations, drawings, programming, and other suitable activities, as per the nature and requirement of the lab course. The experimental lab shall have typically 8-10 experiments and related activities if any.

(Government Aided Autonomous Institute)

#### AY 2023-24

Course Information						
Programme B.Tech. (Electrical Engineering)						
Class, Semester Third Year B. Tech., Sem VI						
Course Code	6EL373					
Course Name Microcontroller and Applications Lab						
Desired Requisites: Analog and Digital Circuits Lab						

Teaching	Scheme	Examination Scheme (Marks)								
Practical	2 Hrs/Week	LA1	LA2	Lab ESE	Total					
Interaction	-	30	30	40	100					
			Credits: #							

	Course Objectives								
	1	To develop the necessary skills required for programming 8051 and Arduino microcontroller implement real world applications.							
Г	2	To understand the practical problems in electrical systems and implement programs for same.							
	3	3 To introduce various programming softwares and implement microcontroller based applications.							

#### Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

СО	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	Use simulation tools to analyze microcontroller based systems.	III	Applying
CO2	<b>Apply</b> programming techniques to implement counters, timers, interrupts and other peripherals.	III	Applying
CO3	<b>Execute</b> programs to interface microcontrollers with electrical and electronics systems.	III	Applying
CO4	<b>Construct</b> programs for electrical applications using microcontrollers.	III	Applying

#### List of Experiments / Lab Activities/Topics

#### **List of Lab Activities:**

- 1. Introduction to different Development Boards, Keil/Arduino IDE, Using Keil/Arduino IDE to assemble a program, Hex file format, Downloading and running the program
- 2. Demonstrate the flashing of GPIO ports of using delay.
- 3. Implement a 8-bit up and down counter using microcontroller.
- 4. Devise a running light scheme using GPIO pins of microcontroller.
- 5. Demonstrate the process of serial communication using 8051 and Arduino microcontroller
- 6. Construct a C program using 8051 to generate pulses using various timer modes
- 7. Execute programs to demonstrate interrupts for 8051.
- 8. Construct a C program to interface LCD with Arduino.
- 9. Devise a Arduino based relay control for single phase ac loads.
- 10. Construct a C program to interface stepper motor with Arduino.
- 11. Construct a temperature control system using Arduino
- 12. Demonstration of Hardware-in-loop simulation using Arduino and Matlab /Simulink

	Textbooks									
1	Muhammad Mazidi, Janice Mazidi and Rolin McKinlay, "The 8051 Microcontroller and									
1	Embedded systems using Assembly and C", Pearson Education, 2nd Edition, 2007									
2	Kenneth Ayala, "8051 Architecture, Programming and Applications", 3rd Edition, 2007									
3	Massimo Banzi and Michael Shiloh, Make: Getting Started With Arduino - The Open Source									
3	Electronics Prototyping Platform, Shroff/Maker Media; 3rd edition, 2014									
	References									
1	Subrata Ghoshal, "Embedded Systems and Robots- Projects using the 8051 Microcontroller",									
1	Cengage Learning, 1st Edition, 2009									
2	Michael Margolis, "Arduino Cookbook", Shroff/ O'Reilly,2nd Edition,2012									
3	Mazidi, RolinMc Kinlay and Danny Causey, "PIC Microcontroller and Embedded Systems using									
3	Assembly and C for PIC18", Pearson Education.									
	Useful Links									
1	https://nptel.ac.in/courses/106/108/106108100/									
2	https://nptel.ac.in/courses/117/104/117104072/									
3	https://nptel.ac.in/courses/108/102/108102045/									

	CO-PO Mapping													
		Programme Outcomes (PO)										PSO		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1			3											
CO2					3									
CO3					3									
CO4			3											

The strength of mapping is to be written as 1,2,3; where, 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO, and preferably to only one PO.

#### Assessment

There are three components of lab assessment, LA1, LA2 and Lab ESE.

IMP: Lab ESE is a separate head of passing.(min 40 %), LA1+LA2 should be min 40%

Assessment	Based on	Conducted by	Typical Schedule	Marks
	Lab activities,		During Week 1 to Week 8	
LA1	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 8	
	Lab activities,		During Week 9 to Week 16	
LA2	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 16	
	Lab activities,	Lab Course Faculty and	During Week 18 to Week 19	
Lab ESE	journal/	External Examiner as	Marks Submission at the end of	40
	performance	applicable	Week 19	

Week 1 indicates starting week of a semester. Lab activities/Lab performance shall include performing experiments, mini-project, presentations, drawings, programming, and other suitable activities, as per the nature and requirement of the lab course. The experimental lab shall have typically 8-10 experiments and related activities if any.

(Government Aided Autonomous Institute)

#### AY 2023-24

#### Course Information

	Course Information						
Programme B.Tech. (Electrical Engineering)							
Class, Semester	Third Year B. Tech., Sem VI						
Course Code	6EL341						
Course Name	Mini-Project-3						

**Desired Requisites:** 

Teaching	Scheme	Examination Scheme (Marks)								
Practical	2 Hrs/ Week	LA1	LA2	Lab ESE	Total					
Interaction		30	30	40	100					
			Credits: 1							

#### **Course Objectives**

- 1 To acquire the skills of electrical and electronic circuit design and assembly.
- To develop the skills of analysis and fault diagnosis of the electrical and electronic circuit as per design.
- 3 To test the electrical and electronic circuit assembly.

#### Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

СО	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	Understand the basics concepts used in Mini Project.	III	Understanding
CO2	Analyse and infer the reference literature critically and efficiently.	IV	Analysing
CO3	Construct the model of the project.	VI	Creating
CO4	<b>Evaluate</b> the performance of the project.	V	Evaluating
CO5	Write and Present the report of the project.	VI	Creating

#### **List of Experiments / Lab Activities/Topics**

#### **List of Lab Activities:**

- 1. Visit to a local industry or search for the study of problems of industry.
- 2. Prepare the problem based hardware Mini project.
- 3. Evaluate the performance of project.
- 4. Prepare a report on the same.

#### Note:

Student will have to perform a group project based on above points which will be evaluated as In Semester Examination (LA1, LA2 and Lab ESE).

#### Textbooks

#### References

#### **Useful Links**

	CO-PO Mapping													
		Programme Outcomes (PO)											PSO	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1						3			1					
CO2		3							3					
CO3	1		3											
CO4				2	3									
CO5									3					

The strength of mapping is to be written as 1,2,3; where, 1: Low, 2: Medium, 3: High Each CO of the course must map to at least one PO, and preferably to only one PO.

#### Assessment

There are three components of lab assessment, LA1, LA2 and Lab ESE.

IMP: Lab ESE is a separate head of passing.(min 40 %), LA1+LA2 should be min 40%

Assessment	Based on	Conducted by	Typical Schedule	Marks
	Lab activities,		During Week 1 to Week 8	
LA1	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 8	
	Lab activities,		During Week 9 to Week 16	
LA2	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 16	
	Lab activities,	Lab Course Faculty and	During Week 18 to Week 19	
Lab ESE	journal/	External Examiner as	Marks Submission at the end of	40
	performance	applicable	Week 19	

Week 1 indicates starting week of a semester. Lab activities/Lab performance shall include performing experiments, mini-project, presentations, drawings, programming, and other suitable activities, as per the nature and requirement of the lab course. The experimental lab shall have typically 8-10 experiments and related activities if any.

## **Professional Elective-2**

#### Walchand College of Engineering, Sangli (Government Aided Autonomous Institute) AY 2022-23 **Course Information** B.Tech. (Electrical Engineering) **Programme** Class, Semester Third Year B.Tech., Sem VI **Course Code** 6EL331 **Course Name** Professional Elective II: ANN and Fuzzy Control **Desired Requisites:** Nil **Teaching Scheme Examination Scheme (Marks)** Lecture 3 Hrs/week **MSE ISE ESE Total Tutorial** 30 20 50 100 Credits: 3 **Course Objectives** To make students understand operation and performance of ac and dc machines. 1 2 To make students learn characteristics of ac and dc machines. 3 To develop skills to choose ratings of ac and dc machines for various applications. Course Outcomes (CO) with Bloom's Taxonomy Level At the end of the course, the students will be able to, Bloom's Bloom's $\mathbf{CO}$ **Course Outcome Statement/s Taxonomy Taxonomy Description** Level Explain the architecture and features of neural networks Understanding CO<sub>1</sub> II Explain programming techniques to implement neural networks Ш Understanding CO<sub>2</sub> Implement the applications related to electrical and electronics IV CO<sub>3</sub> Applying

Module	Module Contents	Hours
I	Neural Networks and Architecture Fundamentals of Neural Networks: What is Neural Network, Model of Artificial Neuron, Learning rules and various activation functions, Single layer Feed-forward networks, Perceptron learning, MLP structures.	7
II	Back propagation Networks  Delta and LMS rules, Back propagation Networks, Architecture of Back- propagation (BPN) Networks, Back-propagation Learning, Variation of Standard Back propagation algorithms.	7
III	Unsupervised networks Associative Memory: Auto correlators, Heterocorrelators, Multiple Training Encoding Strategy, Exponential BAM, and Associative Memory for Real coded pattern pairs, Applications	7
IV	Adaptive Resonance Networks Adaptive Resonance Theory: Cluster Structure, Vector Quantization, Classical ART Network, Simplified ART Architecture, ART1 and ART2 Architecture and algorithms, Applications, Sensitivities of ordering of data.	6
V	Radial and Convolution Networks Convolution networks, pooling, working and design, Radial basis function network, working	6
VI	Application to Electrical  Control system design with neural network- controller design, tuning and learning, Power system applications, Load forecasting and fault analysis	6

	Textbooks
1	Simon Haykin, "Neural Network", Pearson Publications, 2005.
2	Bishop, C. M., "Neural Networks for Pattern Recognition", Oxford University Press. 1995.
3	S.Rajasekaran and G.A. Vijayalakshmi Pai., "Neural Networks, Fuzzy Logic and Genetic Algorithms", PHI publications, 2012.
	References
1	Chin Teng Lin, C. S. George Lee, "Neuro-Fuzzy Systems", PHI.pub. 2007.
	Useful Links
1	https://onlinecourses.nptel.ac.in/noc21_ge07/preview

					(	CO-PC	Марр	ping						
				I	Progra	mme C	utcom	es (PO	)				PS	SO
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	3												2	
CO2			2										2	
CO3					2								2	

#### Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

(Government Aided Autonomous Institute)

#### AY 2023-24

Course Information							
Programme	B.Tech. (Electrical Engineering)						
Class, Semester	Third Year B. Tech., Sem VI						
Course Code	6EL332						
Course Name	Professional Elective II: Nonlinear and Digital Control System						
Desired Requisites:	Control System Engineering						

Teaching	Scheme	Examination School	Examination Scheme (Marks)						
Lecture	3 Hrs/week	MSE	ISE	ESE	Total				
Tutorial	-	30	20	50	100				
			Credits: 3						

## Course Objectives 1 To make students identify various characteristics of nonlinear systems. 2 To develop skills for analyzing nonlinear systems. 3 To make students familiar with digital control system.

#### Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

со	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	Construct mathematical models of digital control system.	III	Applying
CO2	Analyze the nonlinear systems using various basic and commonly used tools.	IV	Analysing
CO3	Calculate the compensators and controllers for digital control system.	V	Evaluating

Module	Module Contents	Hours
I	Nonlinear System Properties of nonlinear system, Multiple Equilibrium States, Chaos, Sensitive to input amplitude, Limit Cycle, Bifurcation, Jump Phenomenon, Common Physical Nonlinearities, Dead Zone, Saturation, Hysteresis, Backlash, Classification of Nonlinearities	5
II	Analysis of Nonlinear System Linearization, Phase Plane Analysis, Classification of Equilibrium States, Node, Focus, Saddle Point, Centre, Prediction of Limit Cycle using Phase Plane, Describing Function Method, Lyapunov Stability for Non-linear and Linear Systems.	7
III	Digital Control System Review of Z transforms, Z transform method for solving difference equation, Impulse Sampling and Data Hold, Pulse Transfer Function, Sampling Theorem, Mapping between S Plane and Z Plane, Stability Analysis, Transient and SteadyState Analysis.	7
IV	Design of Digital Control System  Construction of Root Locus, Design based on Root Locus, P,PI,PD,PID  Controllers, Lead, Lag, Lead-Lag Compensators, Frequency Response  Analysis, Bode Diagram.	8

State Space Analysis of Digital Control System State Space representation of Digital System, Controllable Canonical form, Observable Canonical form, Diagonal form, Jordan form, Solving State Space Equations, State Transition Matrix, Properties of State Transition Matrix, Pulse Transfer Function Matrix. Discretization of Continuous Time State Space Equation.  State Space Design of Digital Control System Controllability, Controller Design in State Space, Design via Pole Placement for Controller Design, Ackermann's Formula for Controller Design, Observability, Observer Design, Design via Pole Placement for Observer Design, Ackermann's Formula for Observer Design, Deadbeat Design, Design for Deadbeat Response  Textbooks  K. Ogata, "Discrete Time Control Systems", Second Edition, Pearson Education, 2005, ISBN: 9788120327603  C.L. Phillips, J.M. Parr, "Feedback Control Systems", Fifth Edition, Pearson Education, 20 ISBN: 9789332507609  References  I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition, 2018, ISBN: 9789386070111			
VI State Space Design of Digital Control System Controllability, Controller Design in State Space, Design via Pole Placement for Controller Design, Ackermann's Formula for Controller Design, Observability, Observer Design, Design via Pole Placement for Observer Design, Ackermann's Formula for Observer Design, Deadbeat Design, Design for Deadbeat Response  Textbooks  1 K. Ogata, "Discrete Time Control Systems", Second Edition, Pearson Education, 2005, ISBN: 9788120327603  2 C.L. Phillips, J.M. Parr, "Feedback Control Systems", Fifth Edition, Pearson Education, 20 ISBN: 9789332507609  References  I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition,	V	State Space representation of Digital System, Controllable Canonical form, Observable Canonical form, Diagonal form, Jordan form, Solving State Space Equations, State Transition Matrix, Properties of State Transition Matrix, Pulse Transfer Function Matrix. Discretization of Continuous Time	6
1 K. Ogata, "Discrete Time Control Systems", Second Edition, Pearson Education, 2005, ISBN: 9788120327603 2 C.L. Phillips, J.M. Parr, "Feedback Control Systems", Fifth Edition, Pearson Education, 20 ISBN: 9789332507609  References  I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition,	VI	State Space Design of Digital Control System Controllability, Controller Design in State Space, Design via Pole Placement for Controller Design, Ackermann's Formula for Controller Design, Observability, Observer Design, Design via Pole Placement for Observer Design, Ackermann's Formula for Observer Design, Deadbeat Design,	6
1 K. Ogata, "Discrete Time Control Systems", Second Edition, Pearson Education, 2005, ISBN: 9788120327603 2 C.L. Phillips, J.M. Parr, "Feedback Control Systems", Fifth Edition, Pearson Education, 20 ISBN: 9789332507609  References  I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition,			
ISBN: 9788120327603  C.L. Phillips, J.M. Parr, "Feedback Control Systems", Fifth Edition, Pearson Education,20 ISBN: 9789332507609  References  I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition,		Textbooks	
ISBN: 9789332507609  References  I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition,	1		2005,
I.J. Nagrath, M.Gopal "Control Systems Engineering", New Age International, Sixth Edition,	2		cation,2013,
1 Edition,		References	
2016, ISDN. 9769360070111	1		al, Sixth
B.C. Kuo, "Digital Control Systems", Oxford University Press, Second Edition, 2012, ISBN: 9780198083542	2		2012,
Useful Links		Useful Links	
1 https://nptel.ac.in/courses/108/106/108106162/	1	https://nptel.ac.in/courses/108/106/108106162/	
2 https://nptel.ac.in/courses/108/102/108102113/	2	https://nptel.ac.in/courses/108/102/108102113/	

	CO-PO Mapping													
	Programme Outcomes (PO)											PSO		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	3													
CO2		2												
CO3			2											

#### Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

		Walc	hand College	of Engineering, Sa	ngli	
				l Autonomous Institute)	•	
			AY	2023-24		
			Course 1	Information		
Progra	amme		B.Tech. (Electrical	al Engineering)		
	Semester		Third Year B. Te	ch., Sem VI		
	e Code		6EL333			
Cours	e Name		Professional Elec	tive III: Introduction to	Electric Vehicl	le
Desire	d Requisi	tes:		nes, Power Electronics		
2 03110	21040251					
	Teaching	Scheme		<b>Examination Schem</b>	e (Marks)	
Lectur		3 Hrs/week	MSE	ISE	ESE	Total
Tutori			30	20	50	100
Tutori			30	Credits: 3		100
		<u>I</u>	<u> </u>	Cituis. 2		
			Course	Objectives		
1	To devel	on basic knowle		itecture of Electric Vehi	clas	
2			<u> </u>	ects and dynamics of Electric Vehicle		
				erstand the motor specif		narging
3		for Electric vel				88
	'	Course	Outcomes (CO) w	ith Bloom's Taxonomy	Level	
At the	end of the	course, the stud	ents will be able to	,		
CO		Course	e Outcome Statem	ent/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	Explain	the architectur	e and features of	Electric Vehicles	II	Understanding
CO2		t the topologies		gn considerations for	II	Understanding
CO3			e dynamics for	Electric propulsion	III	Applying
	systems					
Modu	ile		Module C	ontents		Hours
	Intro	duction to Elect	tric Vehicles	etric Vehicle System, Co	omponents of	
I	Elect	ric Vehicles, A	dvantages of Elec	etric Vehicles, Efficien Fundamentals of Electr	cy, Pollution	6
			chicles and Archite c, Hybrid and I		cles, Typical	
II	II  Concept of Electric, Hybrid and Plug-in Electric Vehicles, Typical configuration of Hybrid Electric Vehicle, Topologies of HEVs: Series, Parallel and Series-Parallel Configuration, Topologies of Plug-in Hybrid Electric Vehicles, Fuel Cell Electric Vehicles, Solar Powered Electric					7
	Vehic	eles			Cied Electric	
	_	•	ons for Electric Ve		Consideration	
III	Rollii Basic	ng resistance, T	ransmission efficie	entals, Aerodynamic Cency, Consideration of ody design, general issu	vehicle mass,	6

IV	Vehicle Dynamics Roadway fundamentals, Vehicle Kinetics, Dynamics of Vehicle Motion, Propulsion power: Force velocity characteristics, Vehicle gradability, Velocity and Acceleration: Velocity Profile, Distance traversed, tractive power, Energy Required, Propulsion System Design for EV systems	7
V	EV Drive systems Types of motors used in EV, Requirements of EV drive systems, Series Hybrid Electric Drive Train - Operation Patterns, Control Strategies, Parallel Hybrid Electric Drive Train - Operation Pattern, Control Strategies	7
VI	Electric Vehicle Chargers and Charging Standards EV charging: requirements and Classification, Charging standards for Electric vehicles, Introduction to AC and DC chargers for EV systems, Working of Electric Vehicle Supply Equipment (EVSE), Fast Chargers for EV systems, ARAI Testing standards for Electric Vehicles	6
	· •	
	Textbooks	
1	Iqbal Husain, 'Electric and Hybrid Vehicles: Design Fundamentals', CRC Pro-	
2	James Larminie, John Lowry, "Electric Vehicle Technology Explained", Wil 2012	ey, 2nd edition,
	References	
1	Sheldon Williamson, 'Energy Management Strategies for Electric and Plug-in Vehicles', Springer-Verlag, 2012	Hybrid Electric
2	M. Ehsani, Y. Gao, S. Gay and A. Emadi, Modern Electric, Hybrid Electric Vehicles, CRC Press, 2005.	c, and Fuel Cell
	Useful Links	
1	https://nptel.ac.in/courses/108/103/108103009/	
2	https://nptel.ac.in/courses/108/102/108102121/	
3	https://nptel.ac.in/courses/108/106/108106170/	

					(	CO-PC	) Mapp	oing						
				I	Progra	mme C	Outcom	es (PO	)				PS	SO
	1	2	3	4	5	6	7	8	9	10	11	12	1	2
CO1	3													
CO2		3												
CO3		3												

#### Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISE shall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

## **Open Elective 2**

		Wal		of Engineering, Sand Autonomous Institute)	ıngli			
			AY	2022-23				
			Course	Information				
Progra	amme		B.Tech. (Electrica	al Engineering)				
Class,	Semester		Third Year B. Ted	ch., Sem VI				
Cours	se Code		6OE350					
Cours	se Name		Open Elective 2:	Industrial Automation				
Desired Requisites: Basic Electrical Engineering, Basic Mechanical Engineering								
			<u> </u>	<u> </u>				
	Teaching	Scheme		Examination Schen	ne (Marks)			
Lectu		3 Hrs/week	MSE	ISE	ESE	Total		
Tutori		_	30	100				
				20 Credits: 3	50			
		I	I	0.2 0 00.200				
			Course	e Objectives				
1	This cou	rse intends to de		der logic programming fo	or PLC			
2			n level knowledge o		1120.			
3	<u> </u>			ler for closed loop contro	ol.			
4				drives in industries.				
		Course	e Outcomes (CO) v	vith Bloom's Taxonom	Level			
At the	end of the	course, the stud	ents will be able to	,				
					Bloom's	Bloom's		
CO		Cours	se Outcome Staten	nent/s	Taxonomy	Taxonomy		
CO1	Evnloin	the working o	f various types of	measuring instruments,	Level	<b>Description</b> Understanding		
COI	controlle			entation in industrial	II	Understanding		
			tors for implem	chiation in maastrar				
CO2	automation.							
	Identify		us actuators in indu	strial automation	III	Applying		
CO2		the use of vario	us actuators in indu of PLC and S			Applying Applying		
		the use of vario		strial automation SCADA for Industrial	III	Applying Applying		
	Apply Automat	the use of vario the knowledge ion.	of PLC and S					
CO3	Apply Automat Explore	the use of vario the knowledge ion.	of PLC and Stole speed drives for	SCADA for Industrial Industrial Automation.	III	Applying Applying		
CO3	Apply Automat Explore	the use of vario the knowledge ion. the use of varial	of PLC and Sole speed drives for Module C	SCADA for Industrial Industrial Automation. Contents	III	Applying		
CO3	Apply Automat Explore  Ile Mea	the use of vario the knowledge ion. the use of varial surement of Va	of PLC and Sole speed drives for  Module Crious Process Para	SCADA for Industrial Industrial Automation. Contents meters	III	Applying Applying		
CO3	Apply Automat Explore  Measure	the use of varion the knowledge ion. the use of varial surement of Varience to the use of quarter than the use of quarter than the use of quarter than the use of variance that the use of variance	of PLC and Sole speed drives for  Module Crious Process Parantities such as temp	Industrial Automation.  Contents Derature, pressure, force,	III	Applying Applying		
CO3 CO4 Modu	Apply Automat Explore  Meas Meas displ	the use of vario the knowledge ion. the use of varial surement of Va surement of qua- acement, speed,	of PLC and Sole speed drives for  Module Crious Process Parantities such as tempflow, level, humidi	SCADA for Industrial Industrial Automation. Contents meters	III	Applying Applying Hours		
CO3 CO4 Modu	Apply Automat Explore  Meas Meas displ estim	the use of varion the knowledge ion. the use of varial surement of Variancement, speed, aation of errorsa	of PLC and Sole speed drives for  Module Crious Process Parantities such as temp flow, level, humiding calibration.	Industrial Automation.  Contents meters perature, pressure, force, ity, pH etc., signal cond	III	Applying Applying Hours		
CO3 CO4 Modu	Apply Automat Explore  Meas Meas displ estim	the use of various the knowledge ion. the use of varial surement of Variancement, speed, accement, speed, accement, accement accement of errors access Control and	of PLC and Sole speed drives for Module Crious Process Parantities such as temp flow, level, humiding calibration.	Industrial Automation.  Contents meters perature, pressure, force, ity, pH etc., signal conders	III III ationing,	Applying Applying Hours		
CO3 CO4 Modu	Apply Automat Explore  Meas displ estim Proc	the use of varion the knowledge ion. the use of varial surement of Variancement, speed, accement, speed, accement, speed, accement of errors are control and duction to proceed.	of PLC and Sole speed drives for Module Crious Process Parantities such as temp flow, level, humiding calibration.  I Various Controllers control, PID c	Industrial Automation.  Contents meters perature, pressure, force, ity, pH etc., signal conders ontroller and tuning, vi	III III ationing,	Applying Applying Hours		
CO3 CO4 Modu	Apply Automat Explore  Meas displ estim Proc Intro confi	the use of varion the knowledge ion. the use of varial surement of Variancement, speed, accement, speed, accement, speed, accement of errorsa the control and duction to proceed gurations such a sure in the work of the control and the cont	of PLC and Sole speed drives for Module Crious Process Parantities such as temp flow, level, humiding calibration.  I Various Controllers control, PID c	Industrial Automation.  Contents meters perature, pressure, force, ity, pH etc., signal conders ontroller and tuning, valued feed forward control, sp	III III ationing,	Applying Applying Hours		
CO3 CO4 Modu	Apply Automat Explore  Meas displ estim Proc Intro confi contr Actu	the use of varion the knowledge ion. the use of varial surement of Variancement, speed, nation of errorsa ess Control and duction to procedurations such a ol, ratio control, ators	of PLC and Sole speed drives for  Module Crious Process Parantities such as tempflow, level, humiding calibration.  Various Controllers control, override control and control	Industrial Automation.  Contents meters perature, pressure, force, ity, pH etc., signal cond  ers ontroller and tuning, valued forward control, specific displayed selective control.	tioning, arious control	Applying Applying Hours 6		
CO3 CO4 Modu	Apply Automat Explore  Meas Meas displ estim Proc Intro confi contr Actu	the use of varion the knowledge ion. the use of varial surement of Variancement, speed, nation of errors a duction to proceed gurations such a col, ratio control, ators duction to varion to varion to varion to varion to varion the knowledge of the varion to varion the knowledge of the varion to varion the knowledge of varion to varion the varion to varion the varion the varion to varion the va	of PLC and Sole speed drives for  Module Crious Process Parantities such as temp flow, level, humiding calibration.  Various Controllers control, PID cas cascade control, override control and us actuators such as	Industrial Automation.  Contents  meters perature, pressure, force, ity, pH etc., signal cond  ers ontroller and tuning, valued forward control, spid selective control.  as flow control valves,	tioning, arious control	Applying Applying Hours		
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	SCADA for Industrial Automation							
V	Components of SCADA systems, functions, classification of SCADA,	7						
	networking and communication protocols.							
	Variable Speed Drives							
VI	Role of variable speed drives in automation, DC drives, AC drives and	7						
	synchronous motor drives applications of variable speed drives.							
	Textbooks							
1	John W. Webb, Ronald A. Reis "Programmable logic controllers, principles & appli by PHI publication, Eastern Economic Edition.							
1								
2	C. D. Johnson, "Process control & instrumentation techniques". Pearson Education							
	References							
1	George Stephanopoulos, "Chemical Process Control - An introduction to	Theory and						
1	Practice", Prentice-Hall of India, 1st Edition 1984.							
2	2 "Fundamentals of Electrical Drives", G. K. Dubey, Narosa publication, 2nd edition.							
	Useful Links							
1	https://nptel.ac.in/courses/108105063							
2	https://archive.nptel.ac.in/courses/108/106/108106022/							

CO-PO Mapping															
		Programme Outcomes (PO)											PSO		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1		2													
CO2		2			2										
CO3						2								2	

#### Assessment

The assessment is based on MSE, ISE and ESE.

MSE shall be typically on modules 1 to 3.

ISEshall be taken throughout the semester in the form of teacher's assessment. Mode of assessment can be field visit, assignments etc. and is expected to map at least one higher order PO.

ESE shall be on all modules with around 40% weightage on modules 1 to 3 and 60% weightage on modules 4 to 6.

(Government Aided Autonomous Institute)

#### AY 2023-24

Course Information								
Programme B.Tech. (Electrical Engineering)								
Class, Semester	Third Year B. Tech., Sem VI							
Course Code	6EL375							
Course Name	Humanities 2- Project Management (Universal values, ethics)							

B.Tech. (Electrical Engineering) **Desired Requisites:** 

Teaching	Scheme	<b>Examination Scheme (Marks)</b>								
Practical	-	LA1	LA2	Lab ESE	Total					
Interaction	2 Hrs/ Week	30	100							
		Credits: 2								

#### **Course Objectives**

- To prepare the students to manage projects by exploring both technical and managerial 1 challenges and preparing the budget.
- To make aware the students about leadership and ethical qualities in dealing with real life 2 Project
- To induce qualities for working in interdisciplinary and cross functional teams with effective 3 Communication skills, economical and managerial challenges and commercial management.

#### Course Outcomes (CO) with Bloom's Taxonomy Level

At the end of the course, the students will be able to,

СО	Course Outcome Statement/s	Bloom's Taxonomy Level	Bloom's Taxonomy Description
CO1	Grasp and perceive the project activities with respect to		Understanding
	resources required and the constraint for feasibility or completion within time	II	
CO2	Estimate and prepare budget for project completion, Understand commercial management	IV	Analyzing
CO3	Figure out and schedule the project and assess for controlling critical path networks	V	Evaluating

#### List of Experiments / Lab Activities/Topics

#### **List of Topics(Applicable for Interaction mode):**

- 1. Introduction to Project Management.
- 2. Project Cost, Planning, feasibility, risk.
- 3. Critical Path Networks Principles of Resource Scheduling.
- 4. Executing and Controlling.
- 5. Commercial Management and various regulations.
- 6. Study and use of software related to Project Management System.
- 7. Universal values and ethics in regards to project management.

	Textbooks										
1	Dennis Lock, "Project Management", Gower Publishing Limited, 2013										
2	Samuel J. Mantel, Jr., Jack R. Meredith, Scott M. Shafer, Margaret M. Sutton, "Project Management in Practice", John Wiley & Sons, Inc., 2011										

3	B.C. Punmia and Khandelwal, "Project Planning and Control with PERT and CPM", Lakshmi Publications Pvt. Ltd., 2001								
4	Horald Kerzner, "Project Management: A systems approach to planning, scheduling and								
4	Controlling", John Wiley & Sons Inc., 2009								
5	Meri Williams, "The Principles of Project Management", Sitepoint Pvt Ltd., 2008.								
	References								
1	K. Nagarajan, "Project Management", New Age Int., 2nd ed. 2004.								
2	B.M.Naik, "Project Management-Scheduling and Monitoring by PERT/CPM", 1984								
3	William R Duncan, "A guide to the project management body of knowledge", PMI								
3	Publications, 1996								
	Useful Links								
1	https://www.apm.org.uk/resources/what-is-project-management/								
2	https://www.projectmanager.com/project-management								

CO-PO Mapping															
		Programme Outcomes (PO)											PSO		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1								1					1	1	
CO2									2					2	
CO3							1						2		

#### Assessment

There are three components of lab assessment, LA1, LA2 and Lab ESE.

IMP: Lab ESE is a separate head of passing.(min 40 %), LA1+LA2 should be min 40%

Assessment	Based on	Conducted by	Typical Schedule	Marks
	Lab activities,		During Week 1 to Week 8	
LA1	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 8	
	Lab activities,		During Week 9 to Week 16	
LA2	attendance,	Lab Course Faculty	Marks Submission at the end of	30
	journal		Week 16	
	Lab activities,	Lab Course Faculty and	During Week 18 to Week 19	
Lab ESE	journal/	External Examiner as	Marks Submission at the end of	40
	performance	applicable	Week 19	

Week 1 indicates starting week of a semester. Lab activities/Lab performance shall include performing experiments, mini-project, presentations, drawings, programming, and other suitable activities, as per the nature and requirement of the lab course. The experimental lab shall have typically 8-10 experiments and related activities if any.