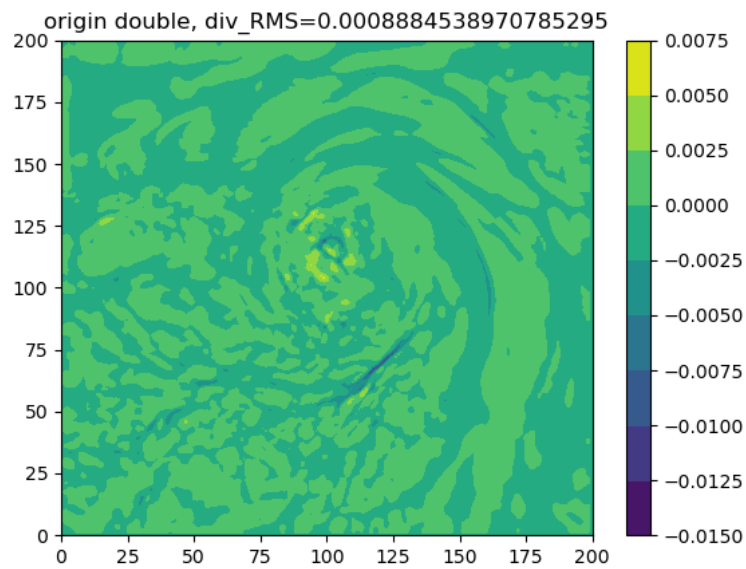
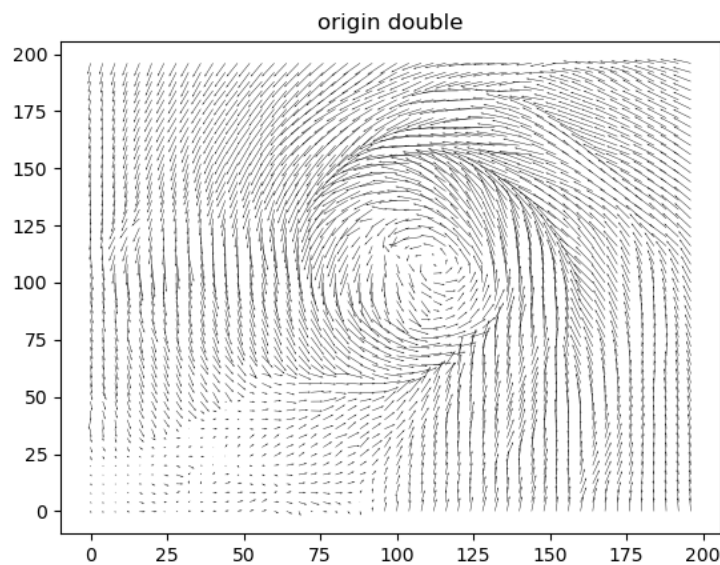


1. Check the magnitude of the averaged divergence. You can use the root-mean-square magnitude.



root-mean-square divergence is 8.8845×10^{-4}

2. Plot the wind field.



3. Use the "correct" scheme to variationally adjust the wind field under **strong constraint**, so that the final wind field becomes completely incompressible. Please repeat this problem twice using "single-precision" and "double-precision" for your computer code, respectively.

高维版 kvs 流程:

给定 u, v ($n \times n$) 可算 $\text{div}(n \times n)$ (忽略内缩 2 圈 $(n-2)(n-2)$)

λ 亦同

$$\int [(u-u')^2 + (v-v')^2 + \lambda(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y})] dx dy \xrightarrow{\text{same}}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \Rightarrow \frac{\lambda_{i+2} - 2\lambda_i + \lambda_{i-2}}{(2\Delta x)^2} + \frac{\lambda_{j+2} - 2\lambda_j + \lambda_{j-2}}{(2\Delta y)^2} = -2 \text{div}_{i,j} \rightarrow \therefore \lambda_{i,j} = \frac{1}{2} \left(\frac{\lambda_{i+1} - \lambda_{i-1}}{2\Delta x} \right) + \tilde{u}_{i,j}$$

$$\Rightarrow \frac{-4\lambda_{i,j}}{(2\Delta x)^2} = -2 \text{div}_{i,j} - \frac{\lambda_{i+2} - 2\lambda_i + \lambda_{i-2}}{(2\Delta x)^2} \Rightarrow \lambda_{i,j} = F_{i,j} = \frac{(2\Delta x)^2}{4} (2 \text{div}_{i,j} - \frac{\lambda_{i+2} - 2\lambda_i + \lambda_{i-2}}{(2\Delta x)^2})$$

$$= 2\Delta x^2 \text{div}_{i,j} + \frac{\lambda_{i+2} - 2\lambda_i + \lambda_{i-2}}{4}$$

$$\Rightarrow \lambda_{i,j}^{\text{new}} = \lambda_{i,j}^{\text{old}} + \epsilon [F_{i,j} - \lambda_{i,j}^{\text{old}}] \text{ 得 } \lambda \text{ map, } \frac{\lambda_{\text{new}} - \lambda_{\text{old}}}{\lambda_{\text{old}}} < \epsilon \text{ for any } i,j$$

$$\Rightarrow \text{can adjust}$$

$$\begin{cases} u_{i,j} = \frac{1}{2} \left(\frac{\lambda_{i+1} - \lambda_{i-1}}{2\Delta x} \right) + \tilde{u}_{i,j} \\ v_{i,j} = \frac{1}{2} \left(\frac{\lambda_{j+1} - \lambda_{j-1}}{2\Delta y} \right) + \tilde{v}_{i,j} \end{cases} \text{ 调整}$$

The source code is attached at the end. (eps=1.5, max_rela_e < 0.0001)

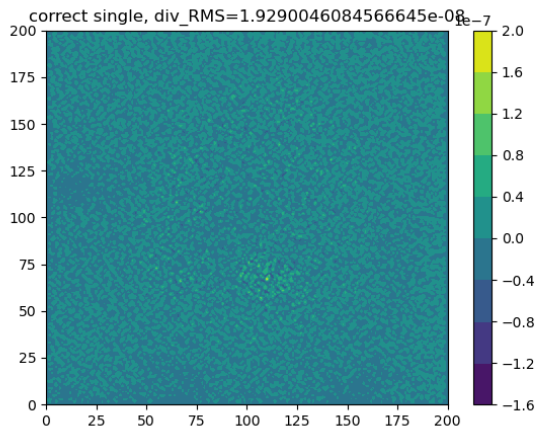
Use python np.array as precision and calculation matrix.

Key lambda renew process :

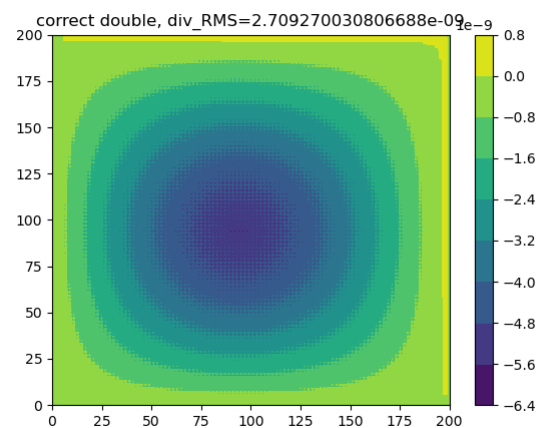
```
F = 2*(resolution**2)*div[i][j] + (lamb[i+2][j]+lamb[i-2][j]+lamb[i][j+2]+lamb[i][j-2])/4
lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])
```

4. Compute the magnitude of the averaged divergence again after the adjustment.

single-precision :



double-precision :



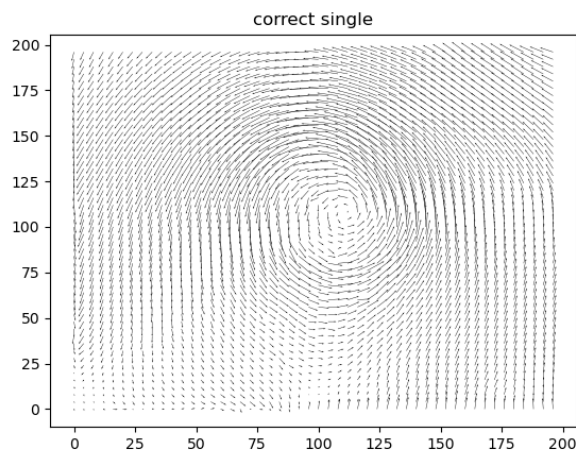
```
origin double divergence_RMS 0.0008884538970785295
correct single divergence_RMS 1.9290046084566645e-08
correct double divergence_RMS 2.709270030806688e-09
```

After adjustment, single-precision root-mean-square divergence is reduced to 1.92×10^{-8} , double-precision root-mean-square divergence is reduced to 2.71×10^{-9} .

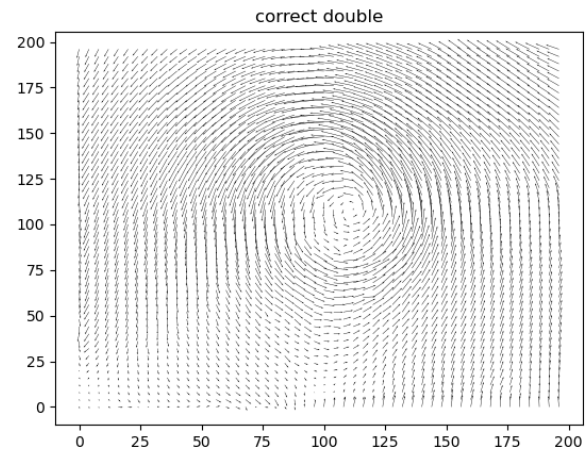
Observing the distribution of divergence in space, we can find that single-precision single-point value jumps more obviously, while double-precision presents a situation where the inner circle deviates from 0.

5. Plot the wind field after the adjustment.

single-precision :



double-precision :



It can be seen that the distribution of the two wind fields is very close, and both are spiral wind fields.

6. Repeat (3) to (5), but use the “wrong” and yet more accurate scheme.

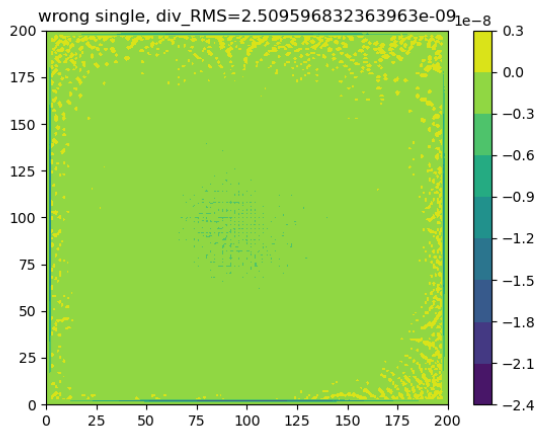
($\text{eps}=1.5$, $\text{max_rela_e} < 0.0001$)

Same as above, but we consider $\text{lamb}[+-1]$ Instead of $\text{lamb}[+-2]$

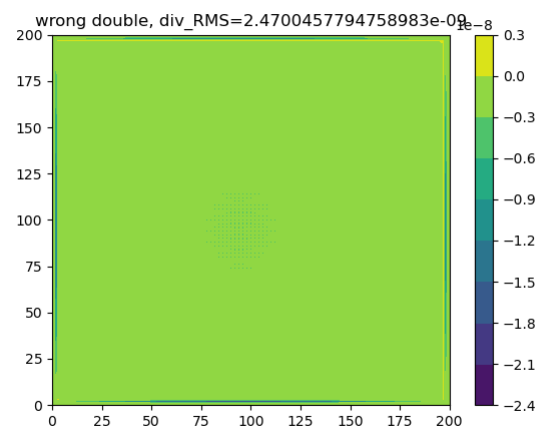
```
F = (resolution**2)*div[i][j]/2 + (lamb[i+1][j]+lamb[i-1][j]+lamb[i][j+1]+lamb[i][j-1])/4
lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])
```

Compute the magnitude of the averaged divergence again after the adjustment.

single-precision :



double-precision :



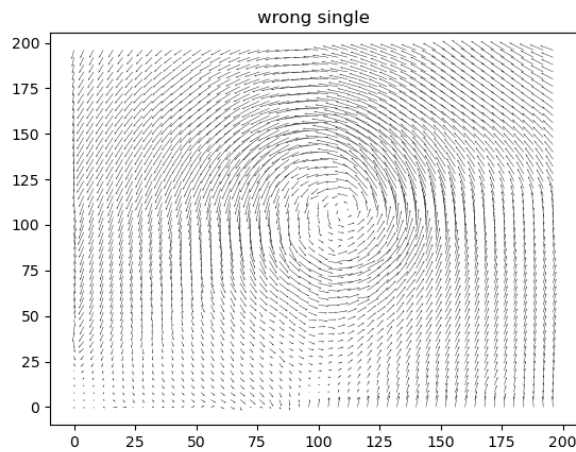
```
origin double divergence_RMS 0.0008884538970785295
correct single divergence_RMS 1.929004608456645e-08
correct double divergence_RMS 2.709270030806688e-09
wrong single divergence_RMS 8.26582341088901e-09
wrong double divergence_RMS 8.096105002240557e-09
```

After adjustment, single-precision root-mean-square divergence is reduced to 8.27×10^{-9} , double-precision root-mean-square divergence is reduced to 8.10×10^{-9} .

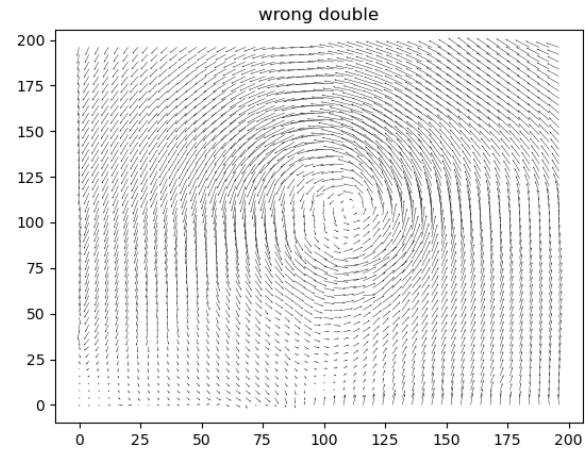
Observing the distribution of divergence in space, we can find that single-precision single-point value jumps more obviously at edge, double-precision is smoother, and there is a larger value of convergence and divergence at the edge.

7. Plot the wind field after the adjustment.

single-precision :



double-precision :



It can be seen that the distribution of the two wind fields is very close, and both are spiral wind fields.

In summary, the variational method and numerical SOR can effectively achieve the constraints we want to complete

In addition, students feel that there is room for improvement on "the relative error of each point of the lambda must be less than the threshold to end the SOR", so they wrote an additional function to change the use of RMS error as the condition to end the SOR process, so that the end when $RMS < 0.01$, And the results are as follows:

```
origin double divergence_RMS 0.0008884538970785295
correct single divergence_RMS 1.9290046084566645e-08
correct double divergence_RMS 2.709270030806688e-09
wrong single divergence_RMS 2.509596832363963e-09
wrong double divergence_RMS 2.4700457794758983e-09
correct test double divergence_RMS 1.0582003325471752e-11
```

Source code : (env:win10, conda4.10.3, python3.8.8, numpy1.19.5)

```
import os
import numpy as np
import matplotlib.pyplot as plt
n = 201
# u, v : n*n
# div, lamb = n*n [usful:(n-4)(n-4)]

# read data
def read_data():
    f = np.loadtxt('data.txt')
    u, v = f[:201], f[201:]
    return u, v

# thinning data for beautiful wind quiver
def thinning(field, thinning_times=5):
    new_field = np.zeros((n//thinning_times, n//thinning_times))
    for i in range(n):
        if i%thinning_times == 0:
            for j in range(n):
                if j%thinning_times == 0 and i//thinning_times <
new_field.shape[0] and j//thinning_times < new_field.shape[1]:
                    new_field[i//thinning_times, j//thinning_times] =
field[i, j]
    return new_field

# Input pre, post, and d and output interpolation differential.
def median_interpolation(front, behind, d):
    return (behind-front)/(2*d)

# double/single version, calculate div_RMS and plot div and savefig
def q1and4_check_averaged_divergence(u, v, title=''): # out 2 lines
    # didn't used, midinter
    if title.split(' ')[-1] == 'double':
        resolution = np.array([2000], dtype=np.float64)[0]
        div = np.zeros((n, n), dtype=np.float64)
        for i in range(2, n-2):
            for j in range(2, n-2):
```

```

        div[i][j] = median_interpolation(u[i][j-1], u[i][j+1],
resolution) + median_interpolation(v[i-1][j], v[i+1][j], resolution)

    div_RMS = 0.0
    for i in range(2, n-2):
        for j in range(2, n-2):
            div_RMS += div[i][j]**2
    div_RMS = (div_RMS/(n-4)**2)**0.5
    print(title+' divergence_RMS', div_RMS)
elif title.split(' ')[-1] == 'single':
    resolution = np.array([2000], dtype=np.float32)[0]
    div = np.zeros((n, n), dtype=np.float32)
    for i in range(2, n-2):
        for j in range(2, n-2):
            div[i][j] = median_interpolation(u[i][j-1], u[i][j+1],
resolution) + median_interpolation(v[i-1][j], v[i+1][j], resolution)

    div_RMS = np.array([0.0], dtype=np.float32)[0]
    for i in range(2, n-2):
        for j in range(2, n-2):
            div_RMS += div[i][j]**2
    div_RMS = (div_RMS/(n-4)**2)**0.5
    print(title+' divergence_RMS', div_RMS)
else:
    print('---q1and4_check_averaged_divergence problem---')
    return

plt.contourf(div)
plt.colorbar()
plt.title(title+', div_RMS='+str(div_RMS))
plt.savefig('5-'+title+'_div')
plt.show()
plt.close()

# plot wind quiver
def q2and5_plot_wind_quiver(u, v, thinning_times=4, title=''): #
thinning and plot

```



```

    thinning_u, thinning_v = thinning(u, thinning_times), thinning(v,
thinning_times)
    x = np.arange(0, 201-thinning_times, thinning_times)
    y = np.arange(0, 201-thinning_times, thinning_times)
    X, Y = np.meshgrid(x, y)
    plt.quiver(X, Y, thinning_u, thinning_v, scale=5, units='xy',
width=0.2) # , headwidth=1, headlength=2
    plt.title(title)
    plt.savefig('5-'+title)
    #plt.show()
    plt.close()

def q3_correct_variationally_adjust(u, v, sd='double'): #強約束風場變分調
整，使風場變得完全不可壓縮。上下左右各兩點
# TODO: threshold/mae/mse? eps<1 or >2?
    if sd == 'double': # 雙精度調整:更新完的 lamb 直接進到下個 lamb 的計算,
eps=1.5 + threshold
        resolution = np.array([2000], dtype=np.float64)[0]
        # check 64bits
        assert type(u[0][0]) == np.float64
        assert type(resolution) == np.float64

        # if lamb has been cal
        filepath = './correct_double_lamb.npy'
        if os.path.isfile(filepath):
            lamb = np.load('correct_double_lamb.npy')
        else:
            # lamb, div init
            lamb = np.zeros((n, n), dtype=np.float64)
            div = np.zeros((n, n), dtype=np.float64)
            for i in range(2, n-2):
                for j in range(2, n-2):
                    div[i][j] = median_interpolation(u[i][j-1],
u[i][j+1], resolution) + median_interpolation(v[i-1][j], v[i+1][j],
resolution)

            # iterate, until every lamb - old_lamb < threshold
            count = 0

```

```

eps = np.array([1.5], dtype=np.float64)[0]
threshold = np.array([10**-3], dtype=np.float64)[0]
while True:
    old_lamb = np.array(lamb)
    count += 1

    for i in range(2, n-2):
        for j in range(2, n-2):
            F = 2*(resolution**2)*div[i][j] +
(lamb[i+2][j]+lamb[i-2][j]+lamb[i][j+2]+lamb[i][j-2])/4
            lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])

    skip_flag = False
    max_rela_e = np.array([0.0], dtype=np.float64)[0]
    for i in range(2, n-2):
        for j in range(2, n-2):
            if old_lamb[i][j] == np.array([0.0],
dtype=np.float64)[0]:
                max_rela_e = 10*threshold # abs fail
                skip_flag = True
            if skip_flag == True:
                break
            max_rela_e = max(max_rela_e, abs((lamb[i][j]-
old_lamb[i][j])/old_lamb[i][j]))
            if skip_flag == True:
                break

    print(count, skip_flag, max_rela_e)

    if max_rela_e < threshold:
        break
    np.save('correct_double_lamb', lamb)
    print('correct double count:', count)

#plt.contourf(lamb)
#plt.colorbar()
#plt.title('lamb')
#plt.show()

```

```

    # adjust
    for i in range(1, n-1):
        for j in range(1, n-1):
            u[i][j] += 0.5*((lamb[i][j+1]-lamb[i][j-
1]))/(2*resolution))
            v[i][j] += 0.5*((lamb[i+1][j]-lamb[i-
1][j]))/(2*resolution))

else:# 單精度調整 # dtype=np.float32
    resolution = np.array([2000], dtype=np.float32)[0]
    # convert and check 32bits
    u = u.astype(np.float32)
    v = v.astype(np.float32)
    assert type(u[0][0]) == np.float32
    assert type(resolution) == np.float32

    # if lamb has been cal
    filepath = './correct_single_lamb.npy'
    if os.path.isfile(filepath):
        lamb = np.load('correct_single_lamb.npy')
    else:
        # lamb, div init
        lamb = np.zeros((n, n), dtype=np.float32)
        div = np.zeros((n, n), dtype=np.float32)
        for i in range(2, n-2):
            for j in range(2, n-2):
                div[i][j] = median_interpolation(u[i][j-1],
u[i][j+1], resolution) + median_interpolation(v[i-1][j], v[i+1][j],
resolution)

        # iterate, until every lamb - old_lamb < threshold
        count = 0
        eps = np.array([1.5], dtype=np.float32)[0]
        threshold = np.array([10**-3], dtype=np.float32)[0]
        while True:
            old_lamb = np.array(lamb)
            count += 1

```

```

        for i in range(2, n-2):
            for j in range(2, n-2):
                F = 2*(resolution**2)*div[i][j] +
(lamb[i+2][j]+lamb[i-2][j]+lamb[i][j+2]+lamb[i][j-2])/4
                lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])

        skip_flag = False
        max_rela_e = np.array([0.0], dtype=np.float32)[0]
        for i in range(2, n-2):
            for j in range(2, n-2):
                if old_lamb[i][j] == np.array([0.0],
dtype=np.float32)[0]:
                    max_rela_e = 10*threshold # abs fail
                    skip_flag = True
                    if skip_flag == True:
                        break
                    max_rela_e = max(max_rela_e, abs((lamb[i][j]-
old_lamb[i][j])/old_lamb[i][j]))
                    if skip_flag == True:
                        break

        print(count, skip_flag, max_rela_e)

        if max_rela_e < threshold:
            break
        np.save('correct_single_lamb', lamb)
        print('correct double count:', count)

    #plt.contourf(lamb)
    #plt.colorbar()
    #plt.title('lamb')
    #plt.show()

    # adjust
    for i in range(1, n-1):
        for j in range(1, n-1):

```

```

        u[i][j] += 0.5*((lamb[i][j+1]-lamb[i][j-
1]))/(2*resolution))
        v[i][j] += 0.5*((lamb[i+1][j]-lamb[i-
1][j]))/(2*resolution))

    return u, v

def q6_wrong_variationally_adjust(u, v, sd='double'): #強約束風場變分調
整，使風場變得完全不可壓縮。上下左右各一點
    if sd == 'double': # 雙精度調整:更新完的 lamb 直接進到下個 lamb 的計算，
eps=1.5 + threshold
        resolution = np.array([2000], dtype=np.float64)[0]
        # check 64bits
        assert type(u[0][0]) == np.float64
        assert type(resolution) == np.float64

        # if lamb has been cal
        filepath = './wrong_double_lamb.npy'
        if os.path.isfile(filepath):
            lamb = np.load('wrong_double_lamb.npy')
        else:
            # lamb, div init
            lamb = np.zeros((n, n), dtype=np.float64)
            div = np.zeros((n, n), dtype=np.float64)
            for i in range(2, n-2):
                for j in range(2, n-2):
                    div[i][j] = median_interpolation(u[i][j-1],
u[i][j+1], resolution) + median_interpolation(v[i-1][j], v[i+1][j],
resolution)

            # iterate, until every lamb - old_lamb < threshold
            count = 0
            eps = np.array([1.5], dtype=np.float64)[0]
            threshold = np.array([10**-3], dtype=np.float64)[0]
            while True:
                old_lamb = np.array(lamb)
                count += 1

```

```

        for i in range(2, n-2):
            for j in range(2, n-2):
                F = (resolution**2)*div[i][j]/2 +
(lamb[i+1][j]+lamb[i-1][j]+lamb[i][j+1]+lamb[i][j-1])/4
                lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])

            skip_flag = False
            max_rela_e = np.array([0.0], dtype=np.float64)[0]
            for i in range(2, n-2):
                for j in range(2, n-2):
                    if old_lamb[i][j] == np.array([0.0],
dtype=np.float64)[0]:
                        max_rela_e = 10*threshold # abs fail
                        skip_flag = True
                    if skip_flag == True:
                        break
                    max_rela_e = max(max_rela_e, abs((lamb[i][j]-
old_lamb[i][j])/old_lamb[i][j]))
                    if skip_flag == True:
                        break

            print(count, skip_flag, max_rela_e)

            if max_rela_e < threshold:
                break
            np.save('wrong_double_lamb', lamb)
            print('wrong double count:', count)

#plt.contourf(lamb)
#plt.colorbar()
#plt.title('lamb')
#plt.show()

# adjust
for i in range(1, n-1):
    for j in range(1, n-1):
        u[i][j] += 0.5*((lamb[i][j+1]-lamb[i][j-
1]))/(2*resolution))

```

```

        v[i][j] += 0.5*((lamb[i+1][j]-lamb[i-1][j])/(2*resolution))

else:# 單精度調整 # dtype=np.float32
    resolution = np.array([2000], dtype=np.float32)[0]
    # convert and check 32bits
    u = u.astype(np.float32)
    v = v.astype(np.float32)
    assert type(u[0][0]) == np.float32
    assert type(resolution) == np.float32

    # if lamb has been cal
    filepath = './wrong_single_lamb.npy'
    if os.path.isfile(filepath):
        lamb = np.load('wrong_single_lamb.npy')
    else:
        # lamb, div init
        lamb = np.zeros((n, n), dtype=np.float32)
        div = np.zeros((n, n), dtype=np.float32)
        for i in range(2, n-2):
            for j in range(2, n-2):
                div[i][j] = median_interpolation(u[i][j-1],
u[i][j+1], resolution) + median_interpolation(v[i-1][j], v[i+1][j],
resolution)

        # iterate, until every lamb - old_lamb < threshold
        count = 0
        eps = np.array([1.5], dtype=np.float32)[0]
        threshold = np.array([10**-3], dtype=np.float32)[0]
        while True:
            old_lamb = np.array(lamb)
            count += 1

            for i in range(2, n-2):
                for j in range(2, n-2):
                    F = (resolution**2)*div[i][j]/2 +
(lamb[i+1][j]+lamb[i-1][j]+lamb[i][j+1]+lamb[i][j-1])/4
                    lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])

```

```

        skip_flag = False
        max_rela_e = np.array([0.0], dtype=np.float32)[0]
        for i in range(2, n-2):
            for j in range(2, n-2):
                if old_lamb[i][j] == np.array([0.0],
dtype=np.float32)[0]:
                    max_rela_e = 10*threshold # abs fail
                    skip_flag = True
                if skip_flag == True:
                    break
                max_rela_e = max(max_rela_e, abs((lamb[i][j]-
old_lamb[i][j])/old_lamb[i][j]))
                if skip_flag == True:
                    break

        print(count, skip_flag, max_rela_e)

        if max_rela_e < threshold:
            break
        np.save('wrong_single_lamb', lamb)
        print('wrong double count:', count)

    #plt.contourf(lamb)
    #plt.colorbar()
    #plt.title('lamb')
    #plt.show()

    # adjust
    for i in range(1, n-1):
        for j in range(1, n-1):
            u[i][j] += 0.5*((lamb[i][j+1]-lamb[i][j-
1]))/(2*resolution))
            v[i][j] += 0.5*((lamb[i+1][j]-lamb[i-
1][j]))/(2*resolution))

    return u, v

```



```

#### test
def q3_cva_test(u, v, sd='double'): # mse test
    if sd == 'double': # 雙精度調整:更新完的 lamb 直接進到下個 lamb 的計算,
eps=1.5 + mse
        resolution = np.array([2000], dtype=np.float64)[0]
        # check 64bits
        assert type(u[0][0]) == np.float64
        assert type(resolution) == np.float64

        # if lamb has been cal
        filepath = './test_correct_double_lamb.npy'
        if os.path.isfile(filepath):
            lamb = np.load('test_correct_double_lamb.npy')
        else:
            # lamb, div init
            lamb = np.zeros((n, n), dtype=np.float64)
            div = np.zeros((n, n), dtype=np.float64)
            for i in range(2, n-2):
                for j in range(2, n-2):
                    div[i][j] = median_interpolation(u[i][j-1],
u[i][j+1], resolution) + median_interpolation(v[i-1][j], v[i+1][j],
resolution)

            # iterate, until every lamb - old_lamb < threshold
            count = 0
            eps = np.array([1.5], dtype=np.float64)[0]
            mse_threshold = np.array([10**-2], dtype=np.float64)[0]
            while True:
                old_lamb = np.array(lamb)
                count += 1

                for i in range(2, n-2):
                    for j in range(2, n-2):
                        F = 2*(resolution**2)*div[i][j] +
(lamb[i+2][j]+lamb[i-2][j]+lamb[i][j+2]+lamb[i][j-2])/4
                        lamb[i][j] = lamb[i][j] + eps*(F-lamb[i][j])

            skip_flag = False

```

```

        mse = np.array([0.0], dtype=np.float64)[0]
        for i in range(2, n-2):
            for j in range(2, n-2):
                if old_lamb[i][j] == np.array([0.0],
dtype=np.float64)[0]:
                    mse = 10*mse_threshold # abs fail
                    skip_flag = True
                    if skip_flag == True:
                        break
                    mse += (lamb[i][j]-old_lamb[i][j])**2
                if skip_flag == True:
                    break

        print(count, skip_flag, mse)

        if mse < mse_threshold:
            break
        #if count > 30:
        #    break
        np.save('test_correct_double_lamb', lamb)
        print('test correct double count:', count)

    #plt.contourf(lamb)
    #plt.colorbar()
    #plt.title('lamb')
    #plt.show()

    # adjust
    for i in range(1, n-1):
        for j in range(1, n-1):
            u[i][j] += 0.5*((lamb[i][j+1]-lamb[i][j-
1]))/(2*resolution))
            v[i][j] += 0.5*((lamb[i+1][j]-lamb[i-
1][j]))/(2*resolution))
        else:
            print(':((')
    return u, v

```

```

if __name__ == '__main__':
    u, v = read_data()
    q1and4_check_averaged_divergence(u, v, 'origin double')
    q2and5_plot_wind_quiver(u, v, 4, 'origin double')

    cva_s_u, cva_s_v = q3_correct_variationally_adjust(u, v, 'single')
    q1and4_check_averaged_divergence(cva_s_u, cva_s_v, 'correct single')
    q2and5_plot_wind_quiver(cva_s_u, cva_s_v, 4, 'correct single')

    cva_d_u, cva_d_v = q3_correct_variationally_adjust(u, v, 'double')
    q1and4_check_averaged_divergence(cva_d_u, cva_d_v, 'correct double')
    q2and5_plot_wind_quiver(cva_d_u, cva_d_v, 4, 'correct double')

    wva_s_u, wva_s_v = q6_wrong_variationally_adjust(u, v, 'single')
    q1and4_check_averaged_divergence(wva_s_u, wva_s_v, 'wrong single')
    q2and5_plot_wind_quiver(wva_s_u, wva_s_v, 4, 'wrong single')

    wva_d_u, wva_d_v = q6_wrong_variationally_adjust(u, v, 'double')
    q1and4_check_averaged_divergence(wva_d_u, wva_d_v, 'wrong double')
    q2and5_plot_wind_quiver(wva_d_u, wva_d_v, 4, 'wrong double')

    cva_d_u_test, cva_d_v_test = q3_cva_test(u, v, 'double')
    q1and4_check_averaged_divergence(cva_d_u_test, cva_d_v_test,
'correct test double')
    q2and5_plot_wind_quiver(cva_d_u_test, cva_d_v_test, 4, 'correct test
double')

```