

# Final exam for GRA4153

2025

This exam is to be completed individually. The page limit is 15 pages; this is an exaggerated upper limit and not a suggestion. You may freely refer to results from the lecture notes, slides and exercises (including solutions). You may also use other resources (e.g. books, internet resources), but – similarly – you *must* cite them if you do so.<sup>1</sup> All code must be in Python.

Each question is worth 1/3 of the total grade. Questions 1 & 2 are equally weighted. The individual parts of Question 3 display their relative weight (e.g. part (i) is worth 5% of the total grade for Question 3). Partial credit is always given if a partially correct answer is provided. Please provide a typed set of solutions as a pdf.<sup>2</sup> Your solutions must be submitted online by 12:00 on 5 December 2025.

## Question 1

Consider the linear regression model in matrix form:

$$y = X\beta + \epsilon,$$

where we assume that  $X$  has full column rank and

$$\mathbb{E}[\epsilon|X] = 0, \quad \mathbb{E}[\epsilon\epsilon'|X] = \sigma^2 I.$$

Often the data we observe is measured with error; in this question you will explore the effect of this on the OLS estimator.

- (i) Suppose that instead of  $(y, X)$  you observe  $(y^*, X)$  where  $y^* = y + \nu$  for a random vector  $\nu$  independent of  $(X, \epsilon)$  with  $\mathbb{E}[\nu] = 0$  and  $\text{Var}(\nu) = \varsigma^2 I$ . Is the OLS estimator  $\hat{\beta}^* = (X'X)^{-1}X'y^*$  unbiased? What is the variance of  $\hat{\beta}^*$ ?
- (ii) Suppose that instead of  $\beta$ ,  $y = X\beta^* + \epsilon$ , where  $\beta^* = \beta + \nu$ , with  $\nu$  a random vector independent of  $(X, \epsilon)$  and  $\mathbb{E}\nu = 0$ ,  $\text{Var}(\nu) = \varsigma^2 I$ . Calculate  $\mathbb{E}[y|X]$  and  $\text{Var}(y|X)$ .

Now we will consider some large sample (asymptotic) results. Instead of the assumptions above now assume that  $(y_i, X_i)$  for  $i = 1, \dots, n$  are i.i.d. and such that

$$\mathbb{E}\|X_i\epsilon_i\| < \infty \quad \text{with} \quad \mathbb{E}[X_i\epsilon_i] = 0 \quad \text{for each } i = 1, \dots, n,$$

---

<sup>1</sup>Of course, if you are asked to “derive”, “show”, “demonstrate” or “prove” something (or similar) you have to do so.

<sup>2</sup>How you produce the document is up to you. One good option is L<sup>A</sup>T<sub>E</sub>X; [overleaf](#) is a collaborative web based L<sup>A</sup>T<sub>E</sub>X editor. Another option is to use a jupyter notebook and use markdown cells to write your solutions; a markdown cheat sheet is [here](#) and a tutorial about how to write mathematics in markdown is [here](#).

$Q := \mathbb{E}X_1X_1'$  and  $\Sigma := \text{Var}(X_i\epsilon_i)$  exist and are positive definite.

Suppose that instead of  $(y_i, X_i)$  you observe  $(y_i^*, X_i)$  where  $y_i^* = y_i + \nu_i$  for a random variable  $\nu_i$  where  $(\nu_i)_{i \in \mathbb{N}}$  is i.i.d. and independent of  $(X_i, \epsilon_i)$  with  $\mathbb{E}[\nu_i] = 0$  and  $\text{Var}(\nu_i) = \varsigma^2$ . Let  $\hat{\beta}^*$  be the OLS estimator based on  $(y_i^*, X_i)$ .

(iii) Is  $\hat{\beta}^*$  consistent for  $\beta$ ?

(iv) Derive the asymptotic distribution of  $\hat{\beta}^*$ . Comment on the result.

## Question 2

This question reviews the concept of stationarity of a time series.

- (i) Let  $(X_t)_{t \in \mathbb{Z}}$  be given by  $X_t = \epsilon_t \epsilon_{t-1}$  where  $\epsilon_t \stackrel{iid}{\sim} \text{WN}(0, \sigma^2)$ . Is  $(X_t)_{t \in \mathbb{Z}}$  covariance stationary? Is it white noise?
- (ii) Let  $(X_t)_{t \in \mathbb{Z}}$  be given by  $X_t = Y \cos(at) + Z \sin(at)$  where  $Y, Z$  are uncorrelated random variables with mean zero and variance  $\sigma^2$  and  $a \in \mathbb{R}$  is non-random. Is  $(X_t)_{t \in \mathbb{Z}}$  covariance stationary? Is it white noise?<sup>3</sup>
- (iii) Let  $(X_t)_{t \in \mathbb{Z}}$  be given by  $X_t = Z_t \cos(at) + Z_{t-1} \sin(at)$  where  $(Z_t)_{t \in \mathbb{Z}}$  is a covariance stationary process and  $a \in \mathbb{R}$  is non-random. Is  $(X_t)_{t \in \mathbb{Z}}$  covariance stationary? Is it white noise?

## Question 3

In this exercise you will analyse a time series of industrial production and forecast its future values. The data set is `INDPRO.csv` and is available on `wiseflow`.

- (i) (5%) Select the sample from 1970-01-01 to 2015-12-01 and plot the sample.
- (ii) (15%) Test for a unit root (i.e. nonstationarity) using `sm.tsa.stattools.adfuller`; what is your conclusion?
- (iii) (5%) Based on the result of the test in part (ii), you may or may not want to transform the series in some way. Let  $X_t$  be the series following any (or no) transform you perform.
- (iv) (15%) Plot the sample ACF and PACF for  $X_t$ . Can you conclude anything about an appropriate ARMA model order?
- (v) (20%) Fit  $\text{ARMA}(p, q)$  models for  $p, q$  up to 4 to  $X_t$  and select an appropriate model order using AICC and BIC. What order do you find? Do the two criteria lead to the same conclusion? If not, pick a model and justify your choice.
- (vi) (20%) Estimate the model you picked in the preceding section. Interpret the results.
- (vii) (20%) Forecast  $X_t$  4 periods ahead and plot  $X_t$  and your forecast.

---

<sup>3</sup>Hint:  $\cos(a) \cos(b) + \sin(a) \sin(b) = \cos(a - b)$ .