DNN_05

Convolutional Neural Network-2

Internal

Why Convolution?

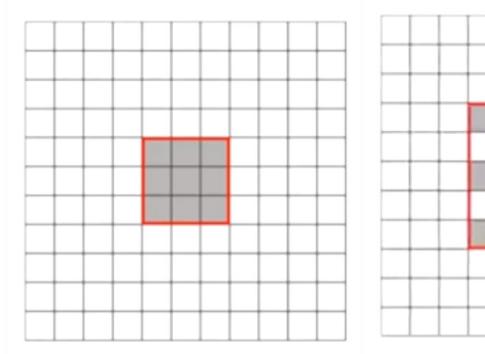
- Parameter sharing.
- Retain Spatial Information.
- Can be scaled for larger Input dimension.
- Can support multiple dimension of Input Image.

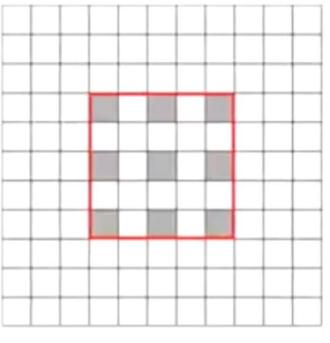
Dilated Convolution

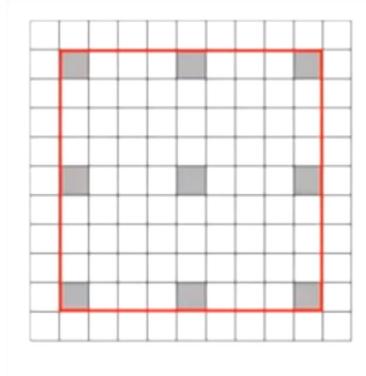
Dilated convolution is just a convolution applied to input with defined gaps. It is a way of increasing receptive field (global view) of a filter.

- Increase Receptive Field of a Filter
- Effective when used in Semantic Segmentation
- Capturing fine Details by processing inputs in higher resolutions.
- Faster Runtime

Dilated Convolution







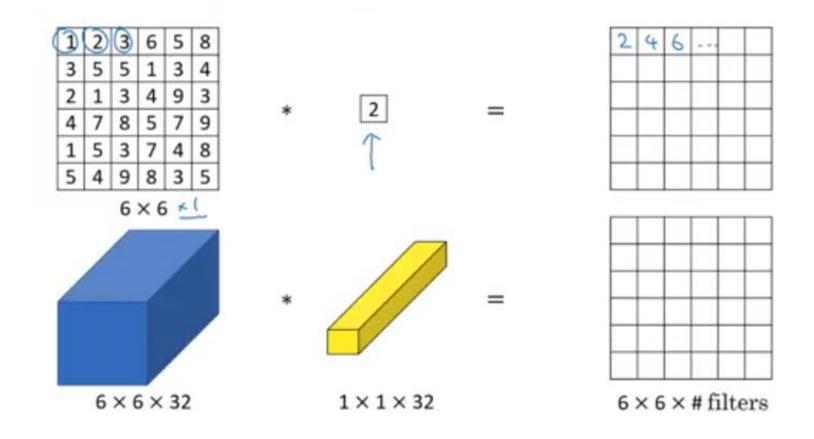
Simple Convolution Receptive Field: 3*3

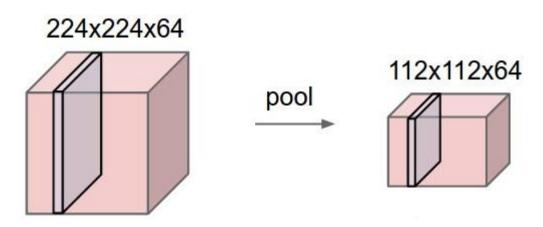
Dilation rate l= 2
Receptive Field 5*5**

Dilation rate l= 4 Receptive Field 9*9

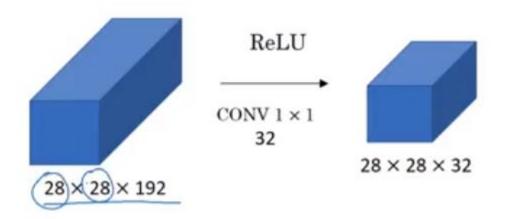
- L=1 -> Standard Convolution
- L=2 -> Skipping one pixel per input
- L=4 -> Skipping three pixels per input

- Also called as Network in Network
- Reduce Number of channel
- Can be used to replace Fully connected Layer
- Reduce Computational Cost





Pooling: Reduce the dimension (W, H)

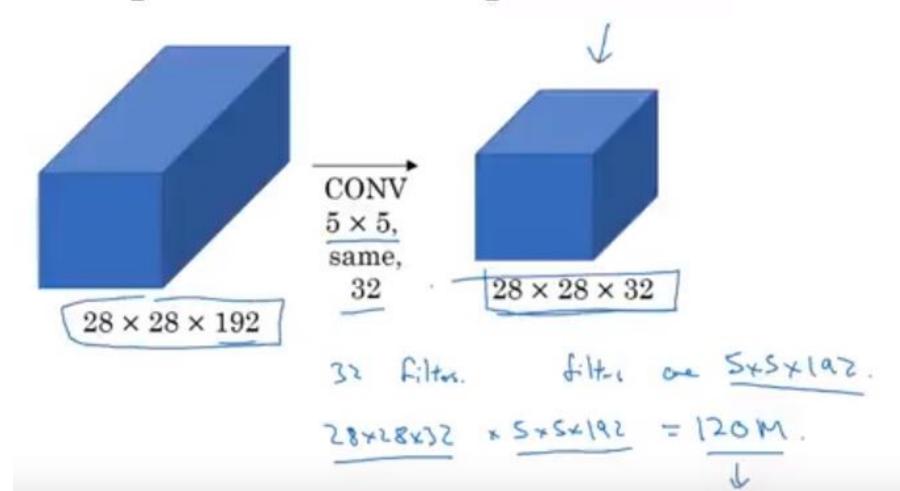


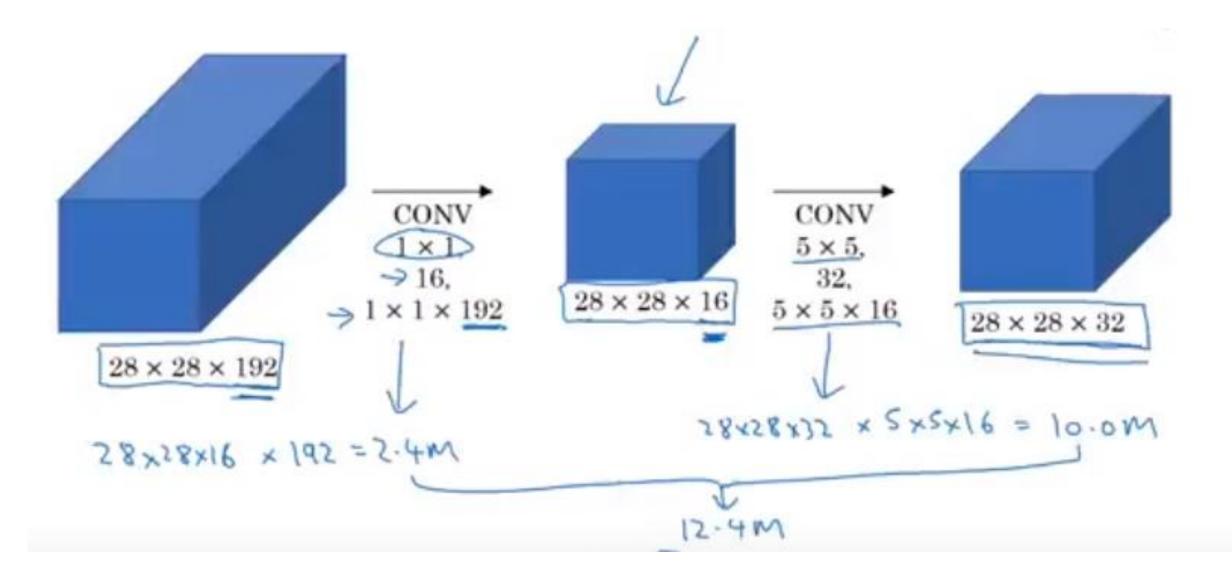
1 x 1 Convolution : Reduce number of channels

Internal

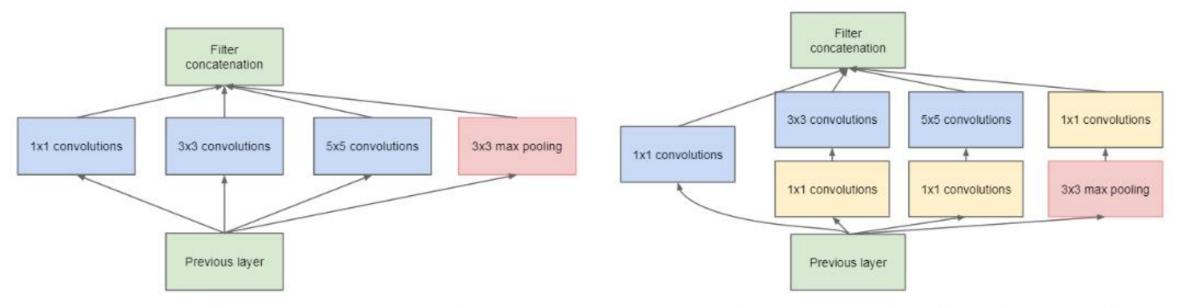
- Pooling layer Reduces the dimension (W and H)
- 1 x 1 Convolution reduces the number of channels

The problem of computational cost





One by One [1 x 1] Convolution in Inception



(a) Inception module, naïve version

(b) Inception module with dimension reductions

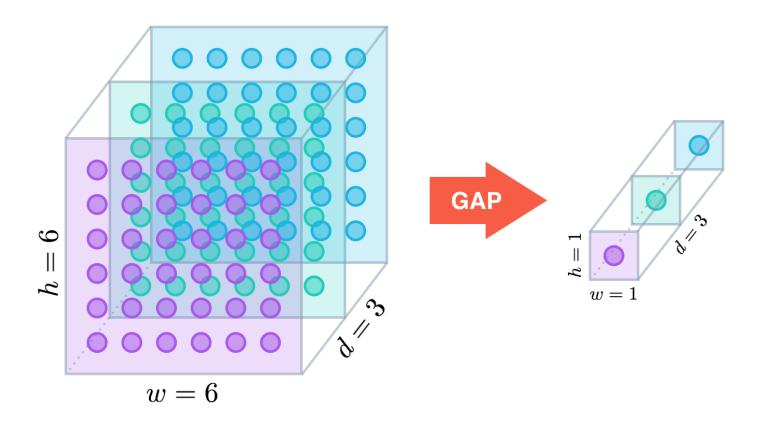
1x1 convolutions in GoogLeNet

Global Average Pooling

- Traditional we use fully connected layers in CNN as the final layer and apply softmax over it.
- The fully connected layers are prone to overfitting and heavily depend on dropout regularization
- global average pooling is itself a structural regularizer, which natively prevents overfitting for the overall structure.

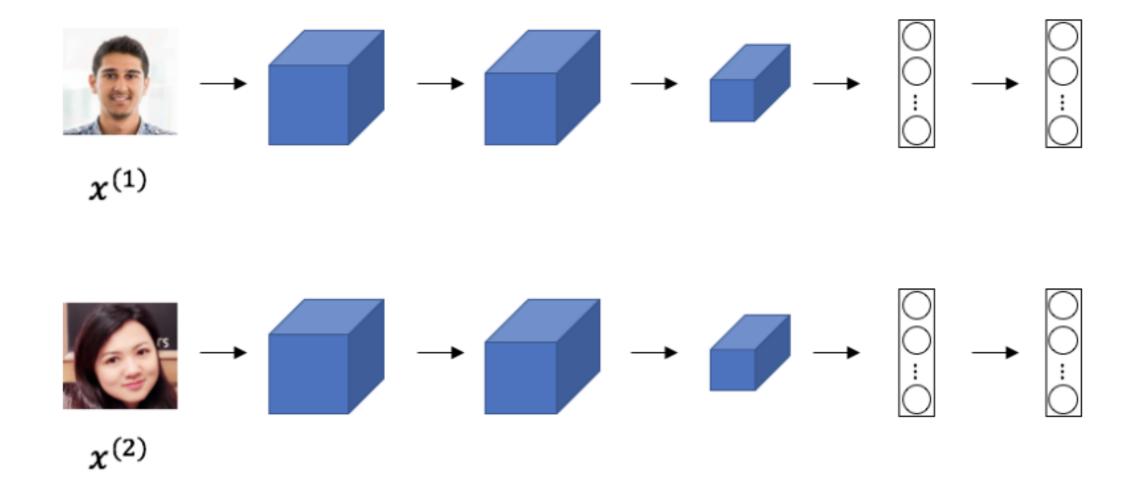
Interna

Global Average Pooling



```
[convolutional]
batch_normalize=1
filters=1024
size=3
stride=1
pad=1
activation=leaky
[shortcut]
from=-3
activation=linear
[avgpool]
[convolutional]
filters=1000
size=1
stride=1
pad=1
activation=linear
[softmax]
groups=1
```

Siamese Network (One-Shot Learning)



Siamese Network

Triplet Loss



Anchor



Positive



Anchor



Negative

$$\mathcal{L} = max(d(a,p) - d(a,n) + margin, 0)$$

Reference

• DeepLearning.ai

Internal