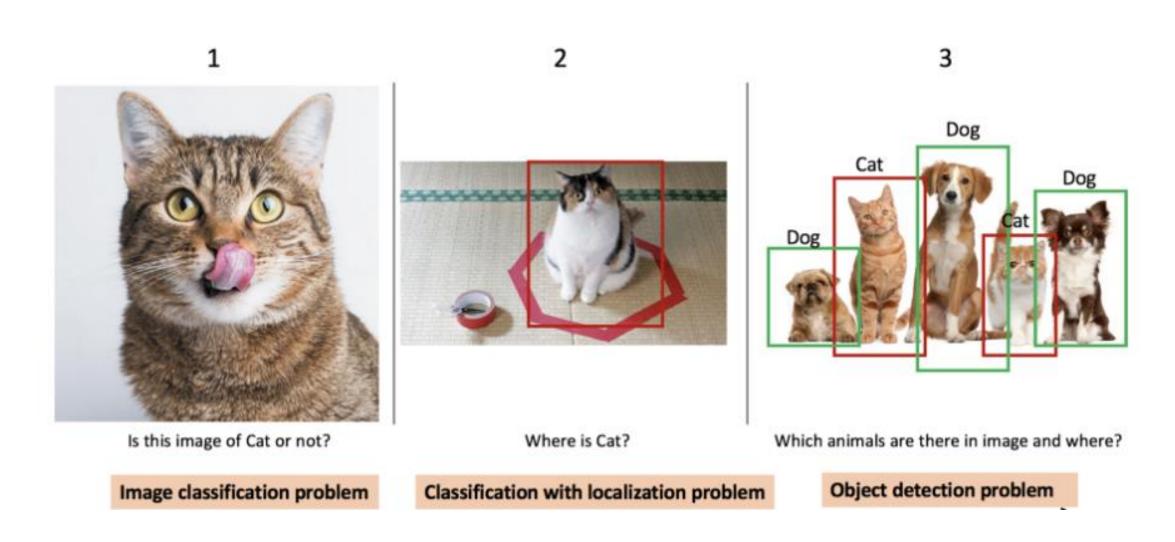
DNN_8.1

Object Detection

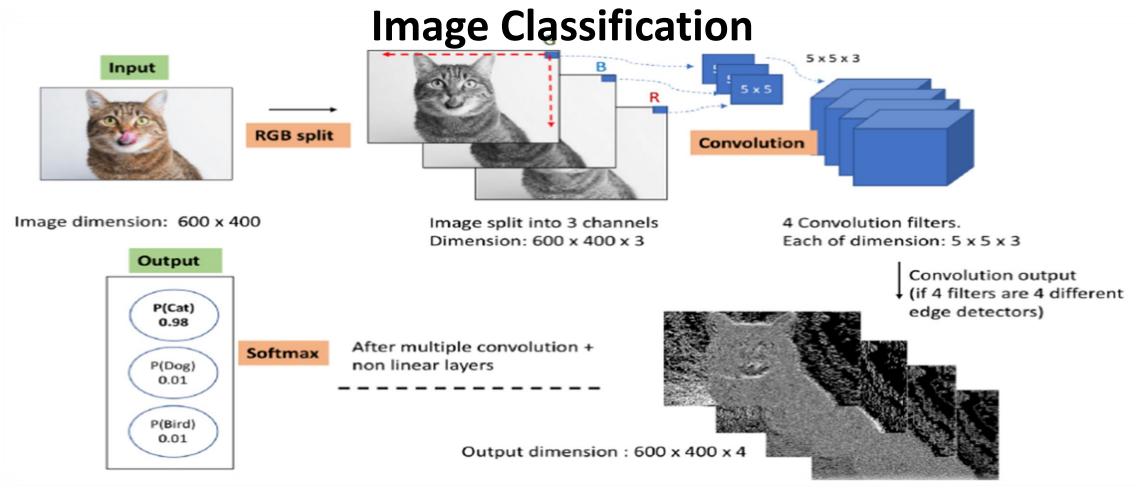
Table of Content

- Object Detection
- History of Object Detection
- RCNN

Computer Vision Tasks



Computer Vision Tasks



Input : Image

Output: class label

Evaluation: Accuracy

Computer Vision Tasks Object Classification and Localization

Cat/ Dog/ Bird classifier and localizer

Output

(Object)

Bx

By

Bw

Bh

P (Cat)

P (Dog)

P (Bird)

0.6

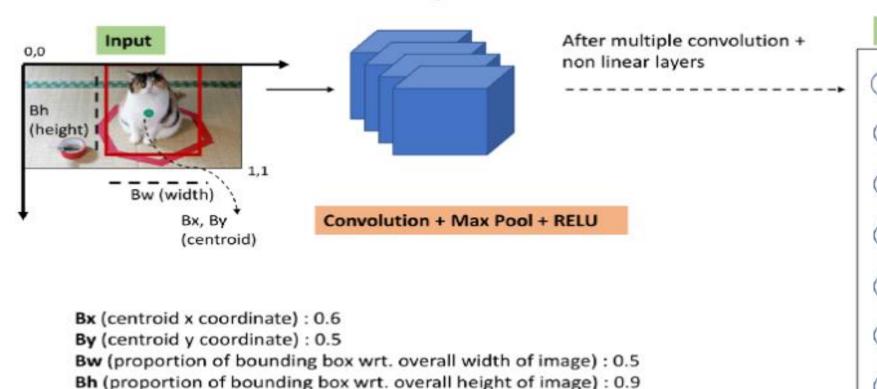
0.5

0.5

0.9

1

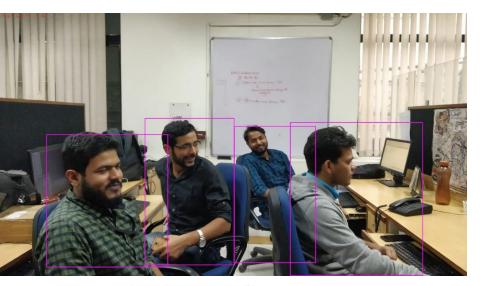
0



Input:image

Output: class label Evaluation: Accuracy

Multiple objects detection and localization



Person, (x, y, w, h)



DOG, DOG, CAT

Dog, (x, y, w, h) Dog, (x, y, w, h)

Cat , (x, y, w, h)

Each image needs a different number of outputs!

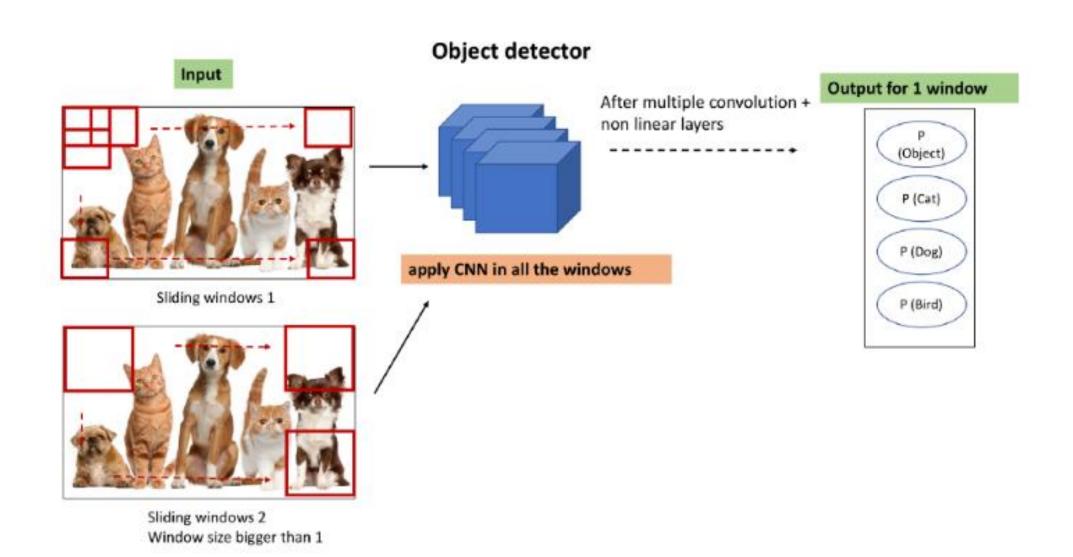


Multiple objects detection and localization

Problems

- Object in image can have different scale.
- Different Aspect ratio.
- Object can be present at any spatial location.

Object detection as Classification: Sliding Window



Object detection as Classification: Sliding Window

- Feature can also be extracted using HOG, LBP, Haar Cascade and can be feed to any M.L model (ex – Face Detection, Pedestrian detection).
- A neural network can be used as a feature extractor and SVM as a classifier.
- Need to apply CNN to huge number of scales and location, Computationally very expensive.
- Object can have different aspect ratio, therefore it generate inaccurate bounding box.

- RCNN uses selective search to extract bounding boxes(regions of Interest) where objects may be present.
- Selective search produces (~2K propsoals) on which we apply CNN for classification.



Selective Search

There are basically four regions that can form and differentiate between objects.

- Varying Scales
- Varying Colors
- Varying textures
- Enclosures(edges).

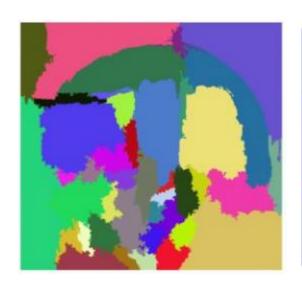
Selective Search proposes various regions based on above properties.

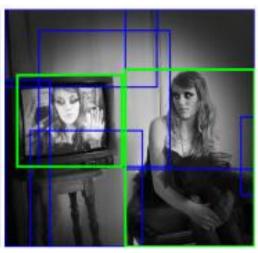
Selective Search

- Generates initial sub-segmentations so that we have multiple regions from this image
- Combines the similar regions to form a larger region (based on color similarity, texture similarity, size similarity, and shape compatibility)
- Finally, these regions then produce the final object locations (Region of Interest).

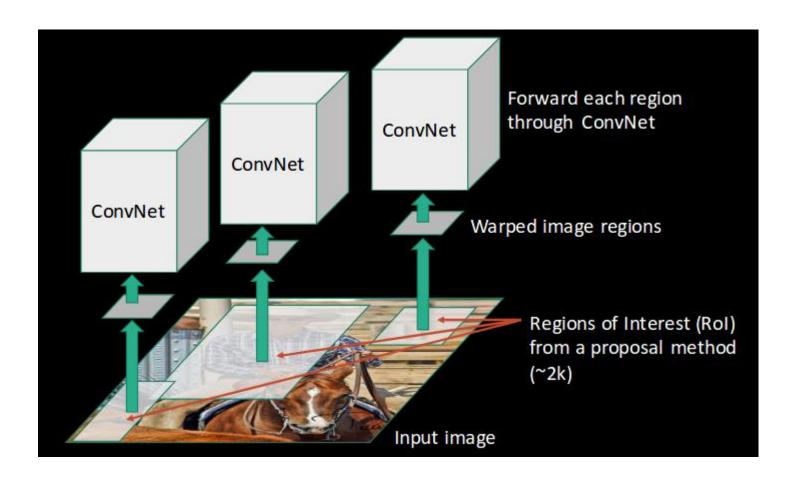


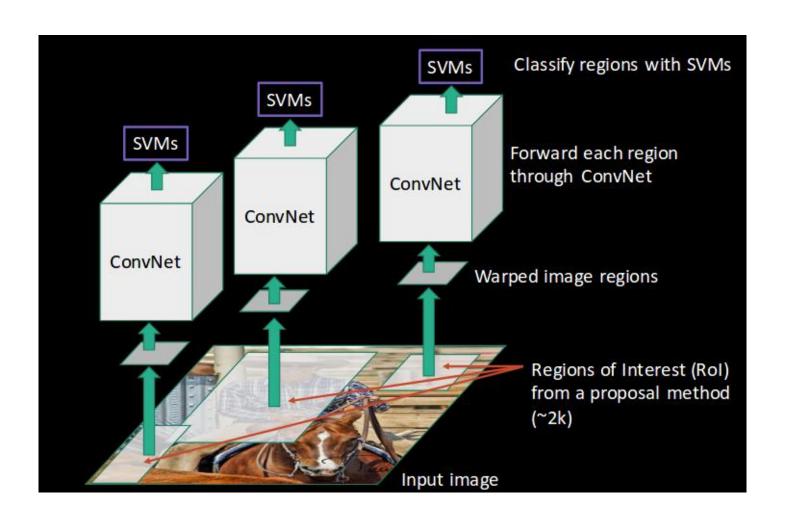


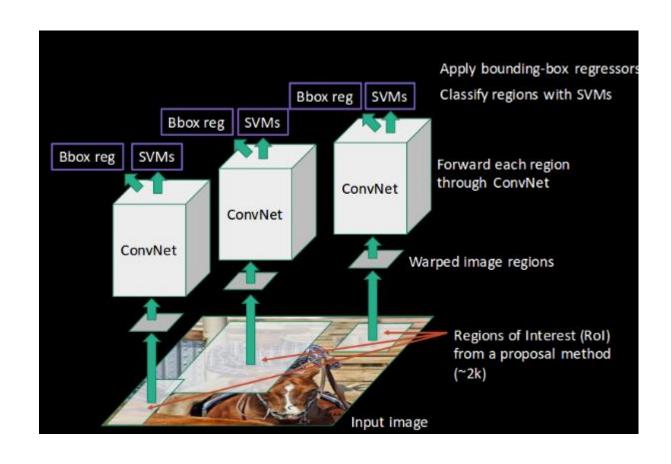












Problems

- Extracting 2,000 regions for each image based on selective search
- Extracting features using CNN for every image region. Suppose we have N images, then the number of CNN features will be N*2,000
- Training is slo
- Inference (detection) is slow 47s / image with VGG16

Fast R-CNN

