Bayesian Non Parametric and its Inference

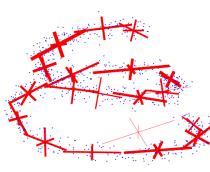
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Dirichlet Process: A diagrammatic representation

Rasmussen, Infinite Gaussian Mixture Model (1999):



For a mixture model: Let $\mathbf{X} = x_1, \dots, x_N$:

$$P(\mathbf{X}|\theta_1,\ldots\theta_K,w_1,\ldots w_K) = \sum_{l=1}^K w_l f(\mathbf{X}|\theta_l)$$

where
$$\sum_{l=1}^{K} w_l = 1$$

If we allow K to also vary, what happens if you want to:

$$\underset{\theta_1,\ldots\theta_K,w_1,\ldots,w_K,K}{\arg\max} P(\mathbf{X}|\theta_1,\ldots\theta_K,w_1,\ldots w_K,K)?$$

K = N for Gaussian case. Of course it's not desirable!



Dirichlet Process: Motivation

- For data x_1, \ldots, x_N , each x_i is associating with a parameter θ_i
- ▶ We need to a good prior for $Pr(\theta_1 \dots \theta_N)$:
- You also want K potentially be infinite
- ightharpoonup A "clustering" property, controllable through a single parameter lpha
- Let's define it using Hierarchical prior, its marginal is:

$$p(\theta_1, \dots \theta_n) = \int_{\mathcal{G}} \Pr(\theta_1, \dots, \theta_n | \mathcal{G}) \mathbf{p}(\mathbf{G})$$

So, we are interested in the property of G:

- ▶ *G* needs to be **discrete** random distribution.
- Perhaps it should also some resemblence with some basic distribution H.

Dirichlet Process Definition

We say G is a Dirichlet process, distributed with base distribution H and concentration parameter α:

$$\label{eq:Galling} \textit{G} \sim \textit{DP}(\alpha, \textit{H}), \text{if} \\ (\textit{G}(\textit{A}1), ..., \textit{G}(\textit{A}\textit{r})) \sim \textit{Dir}(\alpha \textit{H}(\textit{A}1), ..., \alpha \textit{H}(\textit{A}\textit{r}))$$

- for every finite measurable partition $A_1, ..., A_r$ of Θ .
- ▶ What does this all mean? Let's visualise it!
- ▶ note $(A_1 \cup A_2 \cup \cdots \cup A_r) \subseteq \Omega$, this can be seen from the fact that:

$$(x_1, \dots, x_k, \dots, x_K) \sim \operatorname{Dir}(\alpha_1, \dots, \alpha_k, \dots, \alpha_K)$$

$$\implies \left(\frac{x_1}{1 - x_k}, \dots, \frac{x_{k-1}}{1 - x_k}, \frac{x_{k+1}}{1 - x_k}, \dots, \frac{x_K}{1 - x_k}\right) \sim \operatorname{Dir}(\alpha_1, \alpha_{k-1}, \alpha_{k+1}, \alpha_K)$$

You need both the posterior and predictive distribution of Multinomial-Dirichlet:

Posterior Marginal

$$P(p_{1}, \dots, p_{k} | n_{1}, \dots, n_{k})$$

$$\propto \frac{\Gamma\left(\sum_{i=1}^{k} \alpha_{i}\right)}{\prod_{i=1}^{k} \Gamma(\alpha_{i})} \prod_{i=1}^{k} p_{i}^{\alpha_{i}-1} \underbrace{\frac{n!}{n_{1}! \dots n_{k}!} \prod_{i=1}^{k} p_{i}^{n_{i}}}_{\text{Mult}(n_{1}, \dots, n_{k} | p_{1}, \dots p_{k})} = \frac{\Gamma\left(\sum_{i=1}^{k} \alpha_{i}\right)}{\prod_{i=1}^{k} \Gamma(\alpha_{i})} \frac{n!}{n_{1}! \dots n_{k}!} \int_{p_{1}, \dots, p_{k}} \prod_{i=1}^{k} p_{i}^{n_{i}}$$

$$\propto \prod_{i=1}^{k} p_{i}^{\alpha_{i}-1} \prod_{i=1}^{k} p_{i}^{n_{i}} = \prod_{i=1}^{k} p_{i}^{\alpha_{i}-1+n_{i}}$$

$$= \frac{N!}{n_{1}! \dots n_{k}!} \times \frac{\Gamma\left(\sum_{i=1}^{k} \alpha_{i}\right)}{\prod_{i=1}^{k} \Gamma(\alpha_{i})} \times \frac{\prod_{i=1}^{k} \Gamma(\alpha_{i}+n_{i})}{\Gamma\left(N+\sum_{i=1}^{k} \alpha_{i}\right)}$$

$$= \text{Dir}(p_{1}, \dots, p_{k} | \alpha_{i} + n_{i}, \dots, \alpha_{k} + n_{k})$$

Expectation

- ▶ for any measurable set $A_i \in \Omega$: we have $\mathbb{E}[G(A_i)] = H(A_i)$, why?
- for a dirichlet distribution:

$$f(x_1,\ldots,x_K|\alpha_1,\ldots,\alpha_K) = \frac{\Gamma\left(\sum_{i=1}^K \alpha_i\right)}{\prod_{i=1}^K \Gamma(\alpha_i)} \prod_{i=1}^K x_i^{\alpha_i-1}$$

- the expectation: $E[X_i] = \frac{\alpha_i}{\sum_k \alpha_k}$
- ▶ Therefore:

$$\mathbb{E}[G(A_i)] = \frac{\alpha H(A_i)}{\sum_i \alpha H(A_i)} = \frac{\alpha H(A_i)}{\alpha \sum_i H(A_i)} = H(A_i)$$

lacktriangle note that the expectation is **independent of** lpha



Variances

Variances for Dirichlet Distribution:

$$VAR[X_i] = \frac{\alpha_i \left(\left(\sum_{i=1}^{K} \alpha_{i=1} \right) - \alpha_i \right)}{\left(\sum_{i=1}^{K} \alpha_{i=1} \right)^2 \left(\sum_{i=1}^{K} \alpha_{i=1} + 1 \right)}$$

▶ substitute $\alpha \to \alpha H(A_i)$:

$$VAR(G(A_i)) = \frac{\alpha H(A_i) (\alpha - \alpha H(A_i))}{\alpha^2 (\alpha + 1)}$$
$$= \frac{H(A_i) (1 - H(A_i))}{(\alpha + 1)}$$

• when $\alpha = 0$:

$$\mathbb{VAR}(\textit{G}(\textit{A}_{\textit{i}})_{\alpha=0}) = \textit{H}(\textit{A}_{\textit{i}})(1 - \textit{H}(\textit{A}_{\textit{i}}))$$



Posterior

from multinomial-dirichlet conjugacy, we have:

$$G' = G(A_1), \ldots, G(A_r)|\theta_1, \ldots, \theta_n \sim \text{Dir}(\alpha H(A_1) + n_1, \ldots, \alpha H(A_k) + n_k)$$

DP provides a conjugate family of priors over distributions that is closed under posterior updates given observations:

$$\begin{split} \mathbf{G}' &\sim \mathsf{DP}\left(\alpha + \mathbf{n}, \frac{\alpha H + \sum_{i=1}^n \delta_{\theta_i}}{\alpha + \mathbf{n}}\right), \text{ or } \\ \mathbf{G}' &\sim \mathsf{DP}\left(\alpha + \mathbf{n}, \frac{\alpha}{\alpha + \mathbf{n}} H + \frac{\sum_{i=1}^n \delta_{\theta_i}}{\alpha + \mathbf{n}}\right) \end{split}$$

another way of specifying this is:

$$G_u \sim \mathsf{DP}(\alpha, H)$$
 $G' = \frac{1}{\alpha + n} \sum_{i=1}^n \delta_{\theta_i} + \frac{\alpha}{\alpha + n} G_u$

In words: posterior of $\mathsf{DP}(\alpha,H)$ is to squash $\mathsf{DP}(\alpha,H)$ to a total mass of $\frac{\alpha}{\alpha+n}$ remaining mass was assigned to discrete points $\sum_{i=1}^n \delta_{\theta_i}$.



▶ Let $P(\theta_{n+1} \in A|G) = G(A)$:

$$P(\theta_{n+1} \in A | \theta_1, \dots, \theta_n) = \int_G P(\theta_{n+1} \in A | G) P(G | \theta_1, \dots, \theta_n) dG$$
$$= \mathbb{E}(G(A) | \theta_1, \dots, \theta_n)$$
$$= \mathbb{E}(G'(A))$$

▶ We know that:

$$\mathbb{E}(G(A)) = H(A) \implies \mathbb{E}(G'(A)) = \frac{\alpha}{\alpha + n} H(A) + \frac{\sum_{i=1}^{n} \delta_{\theta_i}}{\alpha + n}$$



Stick-Breaking construction

- $ightharpoonup v_k \sim \mathsf{Beta}(1, \alpha)$
- $ightharpoonup \pi_k = v_k \prod_{l=1}^{k-1} (1 v_l)$
- \bullet $\theta_k \sim H$
- $\blacktriangleright G_0 = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}$



posterior sampling of π

- \triangleright $v_k \sim \text{Beta}(1, \alpha)$
- \bullet $\pi_k = v_k \prod_{l=1}^{k-1} (1 v_l)$
- given samples $\theta_1, \ldots, \theta_N$ with k distinct values having n_1, \ldots, n_K counts

$$G' = G(A_1), \dots, G(A_K)|\theta_1, \dots, \theta_n$$

$$\sim \mathsf{Dir}(\alpha H(A_1) + n_1, \dots, \alpha H(A_K) + n_k)$$

$$\sim \mathsf{Dir}\left(\delta_{\theta_1 \in B_1} n_1, \dots, \delta_{\theta_K \in B_K} n_K, \alpha H(\Omega \setminus \{\mathsf{d}B_1, \dots \mathsf{d}B_K\}_{\|\mathsf{d}B_k\| \to 0 \ \forall k})\right)$$

$$\implies (\pi_1, \dots, \pi_k, \pi_n) \sim \mathsf{Dir}(n_1, n_2, \dots n_K, \alpha)$$

• where π_u are all the probability mass assign to $\theta_{K+1}, \ldots, \theta \infty$

Let $\alpha_i = \frac{\alpha}{k}$: compute the density of t^{th} data belonging to existing component m.

$$\Pr(z_{i} = m | \mathbf{z}_{-1}) = \int_{p_{1}, \dots, p_{k}} P(z_{i} = m | p_{1}, \dots, p_{k}) P(p_{1}, \dots, p_{k} | n_{1, -i}, \dots, n_{k, -i}) \\
= \frac{\int_{p_{1}, \dots, p_{k}} P(z_{i} = m | p_{1}, \dots, p_{K}) P(n_{1, -i}, \dots, n_{k, -i} | p_{1}, \dots, p_{K}) P(p_{1}, \dots, p_{K})}{P(n_{1, -i}, \dots, n_{k, -i})} \\
= \frac{\int_{p_{1}, \dots, p_{k}} P(z_{i} = m | p_{1}, \dots, p_{K}) P(n_{1, -i}, \dots, n_{k, -i} | p_{1}, \dots, p_{K}) P(p_{1}, \dots, p_{K})}{\int_{p_{1}, \dots, p_{K}} P(n_{1}^{-i}, \dots, n_{K}^{-i} | p_{1}, \dots, p_{K}) P(p_{1}, \dots, p_{K})} \\
= \frac{\Gamma(\frac{\alpha}{k} + n_{m, -i} + 1) \prod_{l=1, l \neq m}^{k} \Gamma(\frac{\alpha}{k} + n_{l, -i})}{\Gamma(N + \alpha)} \times \frac{\Gamma(N - 1 + \alpha)}{\prod_{l=1}^{k} \Gamma(\frac{\alpha}{k} + n_{l, -1})} \\
= \frac{\frac{\alpha}{k} + n_{m, -i}}{N + \alpha - 1} \quad \text{Let } k \to \infty = \frac{n_{m, -i}}{N + \alpha - 1}$$

$$\Pr(z_i = \text{new}) = \frac{\alpha}{N + \alpha - 1}$$
.

Chinese Restaurant Sampling algorithm 中国餐馆过程的采样算法 (1)

▶ conditional density, i.e., to determine which table customer i sit based on seating of the previous customers 1,...,i-1: 假若我们知道第 1 到第 n-1 的人坐的桌子是什么,那第 n 个人坐的桌子的条件概率是:

$$\Pr(\mathbf{z}_i = m | \mathbf{z}_{-i}, \alpha) \propto \left\{ egin{array}{ll} rac{n_m^{-i}}{N + \alpha - 1} & \qquad \qquad m^{ ext{th}} \; ext{existing table} \; (坐第 m 张有人坐的桌子) \\ rac{lpha}{N + \alpha - 1} & \qquad \qquad ext{new table} \; (坐新的桌子) \end{array}
ight.$$

where n_m^{-i} is number of customers exclude customer i, sit in table m n_m^{-i} 指的是第 m 张桌子坐了几个人(除了第 i 个人以外)

- using above conditional density $\Pr(z_i = m | \mathbf{z}_{-i}, \alpha)$, sampling of joint density $\Pr(z_n, z_1, \dots z_n)$ may be:
 - sample from joint density directly: 直接从联合分布中采样

$$(z_1,z_2,\ldots,z_n) \sim \big(\Pr(z_1)\Pr(z_2|z_1)\ldots\Pr(z_n|z_1,\ldots z_{n-1}) \equiv \Pr(z_n,z_1,\ldots z_n)\big)$$

 sample from joint density: Pr(z_n, z₁,...z_n) using Gibbs sampling 用吉布斯采样从联合分布中采样



Chinese Restaurant Sampling algorithm 中国餐馆过程的采样算法 (2)

Algorithm 1 direct sampling

Algorithm 2 Gibbs sampling

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Require: N = number of customer Require: T = number of iterations Require: T = number of iterations Require: t = DP concentration Require: t = DP concentration t = Start with one joint sample, e.g., (z_1^{(0)} = 1, \ldots, z_N^{(0)} = 1) for t = 1, \ldots, N do  z_1^{(t)} \sim \Pr\left(z_1 | z_2^{(t-1)}, z_3^{(t-1)}, \ldots, z_N^{(t-1)}, \alpha\right)   z_2^{(t)} \sim \Pr\left(z_2 | z_1^{(t)}, z_3^{(t-1)}, \ldots, z_N^{(t-1)}, \alpha\right)   \ldots   z_i^{(t)} \sim \Pr\left(z_i | z_1^{(t)}, \ldots, z_{i-1}^{(t)}, z_{i+1}^{(t-1)}, \ldots, z_N^{(t-1)}, \alpha\right)   \ldots   z_N^{(t)} \sim \Pr\left(z_N | z_1^{(t)}, z_2^{(t)}, \ldots, z_{N-1}^{(t)}, \alpha\right)  end for generated a sample: \mathbf{Z}^{(t)} \equiv (z_1^{(t)}, \ldots, z_N^{(t)})  end for return the last T samples after discard burn-in:
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how can we know samples are drawn correctly?, we can check theoretical vs empirical for:

- ► Expected number of tables, K 被占桌子个数 K 的期望
- **Probability** over the numbers of occupied tables $\Pr(K = k)$ 被占桌子个数 $\Pr(K = k)$ 的概率



 $(\mathbf{z}^{(1+b)}, \dots, \mathbf{z}^{(T+b)})$

How to compute expected number of occupied tables $\mathbb{E}(K)$ (被占桌子个数的期望怎么求呢?) (1)

- ▶ Question is: if customers sit according to a Chinese Restaurant Process, then what is the average number of tables to have at least one customer?
 假若人按照狄利克雷过程(或中国餐馆过程)坐的话,那平均有几张被占的桌子呢?
- ▶ We know for expectation, $\mathbb{E}(X+Y)=\mathbb{E}(X)+\mathbb{E}(Y)$ for any two random variables X and Y regardless of whether they are independent or not 我们都知对于期望来说 $\mathbb{E}(X+Y)=\mathbb{E}(X)+\mathbb{E}(Y)$ 不管随机变量 X 和 Y 是否独立
- ▶ BTW, what happens to variance of sum of random variables? 顺便说一下,方差的值可是和变量之间是否独立有关哟!

$$\begin{split} \mathbb{VAR}\bigg(\sum_{i=1}^n a_i X_i\bigg) &= \mathbb{E}\bigg[\bigg(\sum_{i=1}^n a_i X_i\bigg)^2\bigg] - \bigg(\mathbb{E}\bigg[\sum_{i=1}^n a_i X_i\bigg]\bigg)^2 = \mathbb{E}\bigg[\sum_{i=1}^n \sum_{j=1}^n a_i a_j X_i X_j\bigg] - \bigg(\mathbb{E}\bigg[\sum_{i=1}^n a_i X_i\bigg]\bigg)^2 \\ &= \sum_{i=1}^n \sum_{j=1}^n a_i a_j \mathbb{E}[X_i X_j] - \bigg(\sum_{i=1}^n a_i \mathbb{E}[X_i]\bigg)^2 \\ &= \sum_{i=1}^n \sum_{j=1}^n a_i a_j \mathbb{E}[X_i X_j] - \sum_{i=1}^n \sum_{j=1}^n a_i a_j \mathbb{E}[X_i] \mathbb{E}[X_j] \\ &= \sum_{i=1}^n \sum_{j=1}^n a_i a_j \bigg(\mathbb{E}[X_i X_j] - \mathbb{E}[X_i] \mathbb{E}[X_j]\bigg) \\ &= \sum_{i=1}^n \sum_{j=1}^n a_i a_j \mathbb{COV}(X_i, X_j) = \sum_{i=1}^n a_i^2 \mathbb{VAR}(X_i) + 2 \sum_{i=1}^n \sum_{j>i}^n a_i a_j \mathbb{COV}(X_i, X_j) \end{split}$$

Expected number of occupied tables $\mathbb{E}(K)$ (被占桌子个数的期望) (2)

- ▶ think the problem as: if N customer occupies K tables, then K must be the sum of "fraction of new table that each customer occupies" 我们可以把这个问题看成: 如果有 N 个顾客霸占了 K 个的桌子, 那 K 一定是 "每个顾客占新桌子的份额" 的总和
- ► K can be a decimal point number K 当然是可以是小数点的值
- we let k_i^{new} to be the random variable indicate what "fraction" of **new table** customer i occupies, obviously, $k_i^{\text{new}} \leq 1$ 我们让 k_i^{new} 作为随机变量,告诉我们第 i 个人占多少新桌子的份额,当然 $k_i^{\text{new}} \leq 1$ 显然一个人是不肯能占超过一张桌子的
- then:

$$\mathbb{E}(\# \text{ of occupied tables}) = \ \mathbb{E}\bigg(\sum_{i=1}^N k_i^{\mathsf{new}}\bigg) = \sum_{i=1}^N \mathbb{E}(k_i^{\mathsf{new}})$$

Expected number of occupied tables $\mathbb{E}(K)$ (被占桌子个数的期望) (3)

$$\mathbb{E}(\# \text{ of occupied tables}) = \ \mathbb{E}\bigg(\sum_{i=1}^N k_i^{\mathsf{new}}\bigg) = \sum_{i=1}^N \mathbb{E}(k_i^{\mathsf{new}})$$

- k_i^{new} is a random variable indicate the "fraction of a table" occupied by person i.
- Let $P(k_i^{\text{new}} = 1(\text{occupied})) = t \implies \mathbb{E}(k_i^{\text{new}}) = t$
- ▶ for Bernoulli distribution that $\mathbb{E}(X)$ and P(X=1) has the same value 在伯努利分布上,期望 $\mathbb{E}(X)$ 和概率 P(X=1) 值都是一样的
- ▶ independent case when $P(K_i|K_{i-1}) = P(K_i)$

$$\mathbb{E}(\# \text{ of occupied tables}) = \ \mathbb{E}\bigg(\sum_{i=1}^N k_i^{\text{new}}\bigg) = \sum_{i=1}^N \mathbb{E}(k_i^{\text{new}}) = \textit{Nt}$$

expected value of binomial distribution

- **b** dependent case $P(k_i^{\text{new}}|k_{i-1}^{\text{new}}) \neq P(k_i^{\text{new}})$
 - ▶ in Dirichlet Process: $P(k_i^{\text{new}})$ is **independent** of the value of previous $\{k_t^{\text{new}}\}_{t=1}^{i-1}$, i.e., **independent** of existing seating arrangement.
 - \blacktriangleright However, it does depend on how many people are in the restaurant, i.e., value of i-1.



Expected number of occupied tables $\mathbb{E}(K)$ (被占桌子个数的期望) (4)

▶ we know each th new person has ¹⁄_{a+i} probability of occupying a new table: 我们知道第 i 个新进来的人有 ¹⁄_{a+i} 概率坐新的桌子

$$\begin{split} \mathbb{E}(\# \text{ of occupied tables}) &= \mathbb{E}(K) = \ \mathbb{E}\bigg(\sum_{i=1}^N k_i^{\text{new}}\bigg) = \sum_{i=1}^N \mathbb{E}(k_i^{\text{new}}) \\ &= \sum_{i=1}^N \frac{1}{\alpha+i-1} = \sum_{i=0}^{N-1} \frac{1}{\alpha+i} \\ \text{using following relations:} \qquad \psi(\mathbf{x}+\mathbf{N}) - \psi(\mathbf{x}) = \sum_{k=0}^{N-1} \frac{1}{\mathbf{x}+k} \\ &= \alpha \big(\psi(\alpha+\mathbf{N}) - \psi(\alpha)\big) \end{split}$$

where

$$\Gamma(z) = \int_0^\infty x^{z-1} e^{-x} dx \qquad \qquad \psi(x) = \frac{d}{dx} \ln \left(\Gamma(x) \right) = \frac{\Gamma'(x)}{\Gamma(x)}$$

Homework to also prove:

$$\mathbb{VAR}(\# \text{ of occupied tables}) = \alpha \bigg(\psi(\alpha + \textit{n}) - \psi(\alpha) \bigg) + \alpha^2 \big(\psi'(\alpha + \textit{n}) - \psi'(\alpha) \big)$$



probability of the number of occupied tables Pr(K = k)

- ▶ we already know how to compute the expectation of occupied table, but what about the probability of a particular number of occupied tables? 我们已然知道怎样计算被占桌子的个数的均值,那么,被占桌子的概率是什么呢?
- ► K is a random variable indicating "number of times customers sit at new tables" 我们让 K 作为被占桌子的随机变量
- ▶ say we are interested in $\Pr(K=3)$, then: 假设我们想要知道 K=3 的概率
 - 1st, 2nd, 3rd customer sit at new tables, or
 1st, 6th, 9th customer sit at new tables
 - can both contribute to Pr(K=3) 以上的两种情况都会成为 Pr(K=3) 的一部分
- ▶ the question is what are the combinations (i.e, coefficient) for each Pr(K)?
 所以每个 Pr(K = k) 应该有个概率集的组合,也就是系数。我们看下如何得到它?

"binomial coefficient" vs "Stirling number of the first kind" "二项式系数"和"第一种 Stirling 数值"

▶ in binomial expansion, fixed y:在二项式展开中,y 值是固定的

$$(x+y)^n = \underbrace{(x+y)(x+y)\dots(x+y)}_{n \text{ identical terms}} = \sum_{k=0}^n \binom{n}{k} x^k y^{n-k}$$

in terms of probability distribution:将总数为 1 的概率分散在值 = K 的各项当中

$$1 = \left(\underbrace{p}_{x} + \underbrace{(1-p)}_{y}\right)^{n} = \sum_{k=0}^{n} \binom{n}{k} p^{k} (1-p)^{n-k}$$

▶ instead of fix y, increase y by one in each term: ∏_{y=0}ⁿ(x + y) 现在我们需要 y 值每次都增加 1 所以肯定不能用二项式展开:

$$\prod_{y=0}^{n} (x+y) = (x+0)(x+1)(x+2)\dots(x+n) = \sum_{k=0}^{n} {n \brack k} x^{k}$$

 ${n\brack k}$ is called **Stirling number of the first kind**: ${n\brack k}$ 系数叫做 "第一种 Stirling 数值"

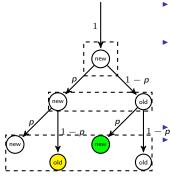
in terms of probability distribution:将总数为 1 的概率分散在值 = K 的各项当中

$$\mathbf{1} = \frac{(x+0)(x+1)(x+2)\dots(x+n)}{(x+0)(x+1)(x+2)\dots(x+n)} = \frac{\sum_{k=0}^{n} {n \brack k} x^k}{(x+0)(x+1)(x+2)\dots(x+n)}$$

▶ let's see which of these probability distribution that Chinese Restaurant Process falls under 我们看下 CRP 到底需要什么样的展开



probability of the number of tables $\Pr(K)$ - independent probabilities



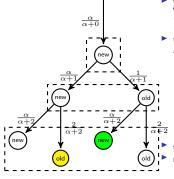
- ▶ first person always occupies the first table with probability of 1; therefore, when computing Pr(K = k|N), we can only assign N 1 to k 1 tables: 第一个人总是坐一张新桌子,所以当我们计算 Pr(K = k|N) 时,我们只能对剩下 N 1 人进行 k 1 新桌子的分配
- **b** for example, N=3, $\Pr(K=2|N=3)$ requires total of $\binom{N-1}{2-1}=2$ paths, and the sum of these two paths are: 以上概率会有 2 条路径,他们的概率总和是:

$$Pr(K = 2|N = 3) = \underbrace{1}_{first} \times \left[p(1-p) + (1-p)p \right]$$
$$= \underbrace{2(1-p)p}$$

sum of probabilities of all paths must equal 1 所有路径概率的总和加起来等于 1 probability distribution for each K=k 用独立坐位于概率分配是:

$$\underbrace{\frac{1}{\text{first}}}_{\text{XWbequent}} \times \underbrace{\frac{\left(\rho + (1-\rho)\right)^{N-1}}{\text{Subsequent}}}_{\text{Subsequent}} = 1 \times \left[\sum_{i=0}^{2} \binom{2}{i} \rho^{i} (1-\rho)^{2-i} \right]$$
$$= 1 \times \left[\underbrace{\binom{2}{2} \rho^{2}}_{K=3} + \underbrace{\binom{2}{1} \rho (1-\rho)}_{K=2} + \underbrace{\binom{2}{0} (1-\rho)^{2}}_{K=1} \right]$$
$$= 1 \times \left[\rho^{2} + 2\rho(1-\rho) + (1-\rho)^{2} \right]$$

probability of the number of tables $\Pr(\mathcal{K})$ - Chinese Restaurant Process



- first person always occupies the first table with probability of 1; therefore, when computing $\Pr(K=k|N,\alpha)$, we can only assign N-1 to k-1 tables: 第一个人总是坐一张斯京子,所以当我们计算 $\Pr(K=k|N)$ 时,我们只能对剩下 N-1 人进行 k-1 都菜于的分配
- **b** for example, N=3, $\Pr(K=2|N=3,\alpha)$ requires total of $\binom{N-1}{2-1}=2$ paths, and the sum of these two paths are: 以上概率会有 2 条路径,他们的概率总和是:

$$\Pr(K = 2 | N = 3, \alpha) = \underbrace{\frac{\alpha}{(\alpha + 0)}}_{\text{fixed}} \frac{\alpha}{(\alpha + 1)} \frac{2}{(\alpha + 2)} + \underbrace{\frac{\alpha}{(\alpha + 0)}}_{\text{fixed}} \frac{1}{(\alpha + 1)} \frac{\alpha}{(\alpha + 2)}$$

sum of probabilities of all paths must equal 1 所有路径概率的总和加起来等于 1 probability distribution for each K=k用 CRP 的概率分配是:

$$1 = \frac{(\alpha+0)(\alpha+1)(\alpha+2)}{(\alpha+0)(\alpha+1)(\alpha+2)} = \frac{\alpha^3 + \frac{3}{2}\alpha^2 + \frac{3}{1}\alpha}{(\alpha+0)(\alpha+1)(\alpha+2)}$$
$$= \frac{\alpha^3 + 3\alpha^2 + 2\alpha}{(\alpha+0)(\alpha+1)(\alpha+2)}$$
$$= \frac{\Gamma(\alpha)[\alpha^3 + 3\alpha^2 + 2\alpha]}{\Gamma(\alpha+3)}$$

for an individual probability: $\Pr(K = k | N, \alpha) = {N \choose k} \alpha^k \frac{\Gamma(\alpha)}{\Gamma(\alpha + N)}$:



Partition Model (划分模型)

- ▶ problem when there are N customers, one may potentially assign them to k ∈ {1,..., N} tables; what is probability of a partition having {n₁, n₂,..., n_K} customers: 划分模型的问题是,当有 N 个人的时候,可以把他们划分在 k ∈ {1,..., N} 的桌子中。假若某种划分结果是有 K 个桌子,每个桌子有 {n₁, n₂,..., n_K} 个顾客,那这样划分的概率是什么?
- let $K \equiv n(\Pi)$, number of tables for a particular partition:
- ▶ one may have the following two"partitions": 以下的两种划分都是等价的

$$\{3, 1, 2, 3, 2, 3, 2, 3\} \implies \{n_1 = 1, n_2 = 3, n_3 = 4\}$$

 $\{3, 3, 3, 2, 1, 1, 1, 1\} \implies \{n_1 = 4, n_2 = 1, n_3 = 3\}$

they are equivalent:

- in words: for all partitions of 8 customers having:
 - "4 customers sit one of the table, 3 sit one of the table and 1 customer sit on one table" then these partitions should be treated **equivalently**, i.e., it does **not** matter which particular table has 4 customers
- obviously, different process in generate customers seating result in different probabilities of partitions



Partition Model using CRP (用中国餐馆过程做划分模型)

• we know the conditional density $\Pr(z_i = m | z_{i-1}, \dots z_1) \equiv \Pr(z_i = m | \mathbf{z}_{-i}, \alpha)$

$$\Pr(\mathbf{z}_i = \mathbf{m} | \mathbf{z}_{-i}, \alpha) \propto \left\{ \begin{array}{ll} \frac{n_{m,-i}}{N + \alpha - 1} & \text{for existing cluster } \mathbf{m} \\ \frac{N + \alpha - 1}{N + \alpha - 1} & \text{for new cluster} \end{array} \right.$$

using DP, the probability on a partition is:

$$\pi(\Pi_N) = \frac{\alpha^k \prod_{l=1}^k \Gamma(n_l)}{\prod_{i=1}^n (\alpha + i - 1)}$$

- $k \equiv n(\Pi)$: number of tables (clusters)
- n_I: number of customers in a table I (number data in a cluster)

Partition Model uisng CRP

probability of a cluster C_j taking value m: $\Pr(C_j = m | \Pi_{-n_i}, \alpha)$ for example, let j = 2:

$$\{3, 1, ?, 1, ?, 3, 3, 3\} \implies \underbrace{\{n_1 = 2, \mathbf{n_2} = ?, n_3 = 4\}}_{\Pi_{-n_2}}$$

- knowing **joint** probability of a partition is $\pi(\Pi_N) = \frac{\alpha^k \prod_{l=1}^k \Gamma(n_l)}{\prod_{l=1}^n (\alpha+i-1)}$:
- sampling of a conditional can be achieved in the following fashion: (canceling denominator):

$$\Pr(\textit{C}_2 = \textit{m}|\Pi_{-\textit{n}_2}, \alpha) \propto \begin{cases} \underbrace{\begin{bmatrix} \alpha\Gamma(\textit{n}_1 + \mathbf{n}_2) \\ \alpha\Gamma(\textit{n}_1) \end{bmatrix} \begin{bmatrix} \alpha\Gamma(\textit{n}_3) \\ \alpha\Gamma(\textit{n}_1) \end{bmatrix} \begin{bmatrix} \alpha\Gamma(\textit{n}_3 + \mathbf{n}_2) \end{bmatrix}}_{\left[\alpha\Gamma(\textit{n}_1) \right] \begin{bmatrix} \alpha\Gamma(\textit{n}_2) \end{bmatrix} \begin{bmatrix} \alpha\Gamma(\textit{n}_3) \end{bmatrix}} & \textit{m} = 1, \text{ i.e., existing} \\ \textit{m} = 3, \text{ i.e., existing} \\ \underbrace{\begin{bmatrix} \alpha\Gamma(\textit{n}_1) \end{bmatrix} \begin{bmatrix} \alpha\Gamma(\textit{n}_2) \end{bmatrix} \begin{bmatrix} \alpha\Gamma(\textit{n}_3) \end{bmatrix}}_{\left[\alpha\Gamma(\textit{n}_3) \right]} & \textit{m} = 2, \text{ i.e., new} \end{cases}$$

omit the case of m=1, as it's in the same form as any other existing component indices m=3:

$$\Pr(\mathbf{C_2} = m | \Pi_{-n_2}, \alpha) \propto \begin{cases} \frac{\alpha^2 \Gamma(n_1) \Gamma(n_3 + \mathbf{n_2})}{\alpha^3 \Gamma(n_1) \Gamma(\mathbf{n_2}) \Gamma(n_3)} & m = 3, \text{ i.e., existing} \\ \frac{\alpha^3 \Gamma(n_1) \Gamma(\mathbf{n_2}) \Gamma(n_3)}{n_1 - n_2} & m = 2, \text{ i.e., new} \end{cases}$$

after cancellation and write it out generally:

$$\Pr(\mathbf{C_j} = m | Pi_{-n_j}, \alpha) \propto \begin{cases} \frac{\Gamma(n_i + \mathbf{n_j})}{\Gamma(n_i)} & m = t, \text{ i.e., existing} \\ \alpha \Gamma(\mathbf{n_j}) & m = \text{new} \end{cases}$$

in the case of $n_i = 1$, we get Chinese Restaurant Process:

$$\Pr(\mathbf{z_j} = m | \Pi_{-n_2}, \alpha) \propto \begin{cases} \frac{\Gamma(n_t + 1)}{\Gamma(n_t)} \\ \alpha \Gamma(\mathbf{1}) \end{cases} = \begin{cases} n_t & m = t, \text{ i.e., existing} \\ \alpha & m = \text{new} \end{cases}$$

Slice sampling for Dirichlet Process

an infinite mixture density (e.g. Gaussian) can be written as:

$$f_{\pi,\theta}(y) = \sum_{j=1}^{\infty} \pi_{j=1} \mathcal{N}(y|\theta_j)$$
 where $\theta = (\mu, \sigma^2)$

adding slice variable u:

$$f_{\pi,\theta}(y,u) = \sum_{j=1}^{\infty} \mathbf{1}(u < \pi_j) \mathcal{N}(y|\theta_j)$$

to ensure marginal is invariant:

$$\int f_{\pi,\theta}(y,u) du = \int_0^{\pi_j} \sum_{j=1} \mathbf{1}(u < \pi_j) \mathcal{N}(y|\theta_j) du$$

$$= \sum_{j=1}^{\infty} \mathcal{N}(y|\theta_j) \int_0^{\pi_j} \mathbf{1}(u < \pi_j) du$$

$$= \sum_{j=1}^{\infty} \mathcal{N}(y|\theta_j) \times \pi_j$$

$$= f_{\pi,\theta}(y)$$

note this is in the absence of latent variable z_i (later slides)



Slice variable u

$$\begin{aligned} & \text{finite model:} \qquad P(y|\pi,\theta) = \frac{1}{K} \sum_{j \in \{1...K\}} \mathcal{N}(y|\theta_j) \\ & \text{infinite model:} \qquad P(y|\pi,\theta,u) \equiv f_{\pi,\theta}(y|u) = \underbrace{\frac{1}{\#\{A_\pi(u)\}}}_{f_\pi(u)} \sum_{j \in A_\pi(u)} \mathcal{N}(y|\theta_j) = \frac{1}{f_\pi(u)} \sum_{j \in A_\pi(u)} \mathcal{N}(y|\theta_j) \end{aligned}$$

 $ightharpoonup f_{\pi}(u)$ is a a random integer

$$\begin{split} f_{\pi}(u) &= \sum_{j=0}^{\infty} \mathbf{1}(u < \pi_j) \\ &= \sum_{j=0}^{\infty} \pi_j \mathcal{U}(u|0, \pi_j) \qquad \text{where } \mathcal{U}(u|0, \pi_j) = \begin{cases} \frac{1}{\pi_j}, & u < \pi_j \\ 0, & u > \pi_j \end{cases} \end{split}$$



Latent variable z_i

▶ latent variable *z* identify the component which *y* is to be taken:

$$f_{\pi,\theta}(u,z,y) = \mathcal{N}(y|\theta_z)\mathbf{1}(z \in A(u))$$

- ▶ for example, $u_6 = 0.15$ and $A(u_6) = \{2, 4, 5, 6\}, k_6 = 4 \in A(u_6) \implies \pi_4 > 0.15$
- ▶ If there are *n* samples, complete data likelihood:

$$\mathcal{L}_{\pi,\theta}(\{y_i, u_i, z_i\}_{i=1}^n) = \prod_{i=1}^n \mathcal{N}(y_i | \theta_{z_i}) \mathbf{1}(u_i < \pi_{z_i})$$



sampling algorithm

- 1. $u_i \sim U(0, \pi_{z_i})$
- 2. $f(\theta_j|\cdots) \propto H(\theta_j) \prod_{z_i=j} \mathcal{N}(y_i|\theta_j)$ If there are no $z_i=j$, then $f(\theta_j|\cdots) = H(\theta_j)$
- 3. $f(v|\cdots) \propto \pi(v) \prod_{i=1}^{n} \mathbf{1}(\pi_{z_i} > u_i)$

$$f(v|\cdots) \propto \pi(v) \prod_{i=1}^{n} \mathbf{1}(\pi_{z_i} > u_i) = \pi(v) \prod_{i=1}^{n} \mathbf{1}\left(\underbrace{v_{z_i} \prod_{l < z_i} (1 - v_l)}_{\pi_{z_i}} > u_i\right)$$

$$= \underbrace{\pi(v)}_{\text{beta}(1,\alpha)} \prod_{i=1}^{n} \mathbf{1}\left(\underbrace{v_{z_i} \prod_{l < z_i} (1 - v_l) > u_i}_{\gamma_j < v_j < \beta_j}\right)$$

- the above only applies when $j \leq z^*$, where z^* is the maximum of $\{z_1, \ldots, z_n\}$
- \triangleright for γ_i and β_i must be a function of u_i and α



lower bound γ_j

$$\mathit{f}(\mathit{v}|\cdots) = \underbrace{\pi(\mathit{v})}_{\mathsf{beta}(1,\alpha)} \prod_{i=1}^{n} \mathbf{1} \left(\underbrace{v_{\mathit{k}_i} \prod_{l < \mathit{z}_i} (1 - \mathit{v}_l) > \mathit{u}_i}_{\gamma_j < \mathit{v}_j < \beta_j} \right)$$

- **lower bound** means how low you can reduce v_j to
- ightharpoonup reduce $v_j \implies$ reduce π_j
- ▶ therefore, one needs to ensure all: $\{\pi_{z_i=j}\} > u_i$:

$$\begin{split} v_{z_i} \prod_{l < z_i} (1 - v_l) &> \max_{\{i: z_i = j\}} (u_i) \\ &\implies v_{z_i} > \frac{\max_{\{z_i = j\}} (u_i)}{\prod_{l < z_i} (1 - v_l)} \\ &\implies v_{z_i} > \underbrace{\max_{\{z_i = j\}} \left(\frac{u_i}{\prod_{l < z_i} (1 - v_l)} \right)}_{\gamma_i} \end{split}$$

- $ightharpoonup \pi_{j+1}, \pi_{j+2}, \ldots$ will **increase**: there is more to share now but not affected by lower bound
- \blacktriangleright π_1, \ldots, π_{j-1} will **not** be affected



upper bound β_j

$$\mathit{f}(\mathsf{v}|\cdots) = \underbrace{\frac{\pi(\mathsf{v})}{\mathsf{beta}(1,\alpha)} \prod_{i=1}^{n} \mathbf{1} \bigg(\underbrace{\mathsf{vz}_{i} \prod_{l < z_{i}} (1-\mathsf{v}_{l}) > u_{i}}_{\gamma_{j} < \nu_{j} < \beta_{j}} \bigg)$$

- ightharpoonup increase $\pi_j \implies$ reduce $\pi_{j+1}, \pi_{j+2}, \ldots$
- ▶ therefore, one needs to ensure all: $\{\pi_{k_i>i}\}>u_i$
- **a** as an **illustrative example**, we let (j = 3) and a particular $(z_i = 5)$:

$$\pi_{z_i=5} > u_i$$

$$\implies (1 - v_1)(1 - v_2)(1 - v_3)(1 - v_4)v_5 > u_i$$

$$\implies (1 - v_1)(1 - v_2)(1 - v_4)v_5 - v_3(1 - v_1)(1 - v_2)(1 - v_4)v_5 > u_i$$

$$\implies v_3(1 - v_1)(1 - v_2)(1 - v_4)v_5 < (1 - v_1)(1 - v_2)(1 - v_4)v_5 - u_i$$

$$\implies v_3 < 1 - \frac{u_i}{(1 - v_1)(1 - v_2)(1 - v_4)v_5}$$

however, one needs to ensure v_3 (or v_j in general) satisfies: $\{\forall z_i > j\}$, write it generally:

$$\begin{aligned} v_j &< \min_{\{z_i > j\}} \left(1 - \frac{u_i}{v_{z_j} \prod_{l < z_i, l \neq j} (1 - v_l)} \right) \\ \Longrightarrow v_j &< \underbrace{1 - \max_{\{z_i > j\}} \left(\frac{u_i}{v_{z_j} \prod_{l < z_i, l \neq j} (1 - v_l)} \right)}_{\beta_j} \end{aligned}$$

 \blacktriangleright π_1, \ldots, π_{j-1} and π_j will **not** be affected



sampling via inverse CDF of v_j

We can define the truncated CDF distribuiton of v:

$$\begin{split} F(\mathbf{v}) &= \frac{1}{C} \int_{\gamma_j}^{\mathbf{v}} f(\mathbf{v}|\cdots) \mathrm{d}\mathbf{v} \\ &= \frac{\int_0^{\mathbf{v}} \mathsf{beta}(\mathbf{v}|1,\alpha) \mathbf{1}(\gamma_j < \mathbf{v} < \beta_j) \mathrm{d}\mathbf{v}}{\int_0^1 \mathsf{beta}(\mathbf{v}|1,\alpha) \mathbf{1}(\gamma_j < \mathbf{v} < \beta_j) \mathrm{d}\mathbf{v}} = \frac{\int_{\gamma_j}^{\mathbf{v}} \mathsf{beta}(\mathbf{v}|1,\alpha) \mathrm{d}\mathbf{v}}{\int_{\gamma_j}^{\beta_j} \mathsf{beta}(\mathbf{v}|1,\alpha) \mathrm{d}\mathbf{v}} \end{split}$$

looking at the property of beta distribution:

$$\begin{split} \int_{\gamma_j}^{\nu_j} \mathsf{beta}(\mathbf{v}|1,\alpha) \mathsf{d}\mathbf{v} &= \int_{\gamma_j}^{\nu_j} \frac{\Gamma(1+\alpha)}{\Gamma(1)\Gamma(\alpha)} \mathbf{v}^{1-1} (1-\mathbf{v})^{\alpha-1} \mathsf{d}\mathbf{v} \\ &= \alpha \int_{\gamma_j}^{\nu_j} (1-\mathbf{v})^{\alpha-1} \mathsf{d}\mathbf{v} \\ &= (1-\gamma_j)^{\alpha} - (1-\mathbf{v}_j)^{\alpha} \end{split}$$

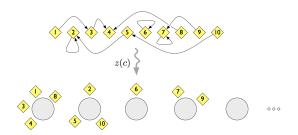
► So, we can prove that:

$$F(v_j) = \frac{(1 - \gamma_j)^{\alpha} - (1 - v_j)^{\alpha}}{(1 - \gamma_i)^{\alpha} - (1 - \beta_i)^{\alpha}}$$

▶ this is where inverse CDF becomes useful



dd-CRP



instead of sample class variable for nodes, it samples links:

$$\Pr(c_i = j | D, \alpha) \propto \begin{cases} f(d_{ij}) & \text{if } j \neq i \\ \alpha & \text{else} \end{cases}$$

MATLAB code download: http://www-staff.it.uts.edu.au/~ydxu/software1.htm

