Classify laterality (left or right sided knee) of the OAI AKOA knee data set

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In this project, I will use a variant VGG model to train and predict the OAI Acelerated Osteoarthritis knee data set. The model contains two VGG blocks and one output block. The final result showed that the accuracy of the model was as high as 0.99%.

```
In [1]:
```

```
gpu_info = !nvidia-smi
gpu_info = '\n'.join(gpu_info)
if gpu_info.find('failed') >= 0:
    print('Select the Runtime > "Change runtime type" menu to enable a GPU acceler
ator, ')
    print('and then re-execute this cell.')
else:
    print(gpu_info)
Sat Nov. 7 02:01:04 2020
```

```
Sat Nov 7 02:01:04 2020
NVIDIA-SMI 455.32.00 Driver Version: 418.67 CUDA Version:
10.1
GPU Name
          Persistence-M Bus-Id
                            Disp.A | Volatile Un
corr. ECC
| Fan Temp Perf Pwr:Usage/Cap| Memory-Usage | GPU-Util C
ompute M.
MIG M.
=======
 0 Tesla V100-SXM2... Off | 00000000:00:04.0 Off |
0 |
| N/A 35C P0 24W / 300W | 0MiB / 16130MiB | 0%
Default |
ERR!
----+
Processes:
 GPU GI CI PID Type Process name
                                         G
PU Memory
       ID
    ID
                                         U
sage
|-----
=======|
 No running processes found
```

First of all, the running environment is based on Google's Colab, the graphics card used is Tesla V100 and has 16GB of video memory, which greatly improves the training speed of the model.

Setup

Import the necessary runtime files, including path recognition and drawing and tensorflow libraries.

```
In [2]:
```

```
from pathlib import Path
from zipfile import ZipFile
from matplotlib import pyplot as plt
import IPython.display as display
import random
import tensorflow as tf
```

Data processing

In this section, the data will be sorted and stored in the left and right folders from the zip file.

OAI Acelerated Osteoarthritis knee data set

OAI Acelerated Osteoarthritis knee data set (18K images) - This is part of the Osteoarthritis Initiative and comes with only labelled laterality (left/right knee labelling) in the filename. The preprocessed version of this data set can be found on the course Blackboard site (under Course Help/Resources).

```
In [3]:
```

```
path = '/content/drive/My Drive/colab/P4/AKOA_Analysis.zip'
raw_file = ZipFile(path)
raw_list = raw_file.namelist()
right_list = filter(lambda x: 'right' in x.lower() or 'r_i_g_h_t' in x.lower() ,
raw_list)
left_list = filter(lambda x: 'left' in x.lower() or 'l_e_f_t' in x.lower() ,raw_list)

for vowel in right_list:
    raw_file.extract(vowel, 'data/right')
for vowel in left_list:
    raw_file.extract(vowel, 'data/left')
```

After finishing the data cleaning, use the following code to show the total number of pictures.

In [4]:

```
def check_photo(data_root):
    data_root = Path(data_root)
    all_image_paths = list(data_root.glob('*/*'))
    all_image_paths = [str(path) for path in all_image_paths]
    random.shuffle(all_image_paths)

    image_count = len(all_image_paths)
    print(image_count)
    print('Total right photo has:')
    check_photo('data/right')
    print('Total left photo has:',)
    check_photo('data/left')
Total right photo has:
10920
```

Extract one of the pictures to get an intuitive impression of the data.

In [5]:

7760

Total left photo has:

```
image_path = '/content/data/left/AKOA_Analysis/OAI9036287_BaseLine_3_de3d1_SAG_3
D_DESS_WE_Left.nii.gz_0.png'
display.display(display.Image(image_path))
```



Create a dataset

In the previous section, the data and were cleaned and classified into two folders on the left and right. In this chapter, I built two classes and some functions to generate tf data streams. The final output is training set, validation set and test set.

Define some parameters for the loader:

In [6]:

```
batch_size = 32
img_height = 224
img_width = 224
```

In [7]:

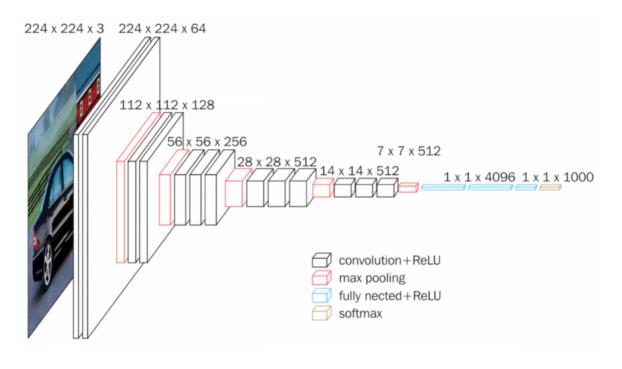
```
AUTOTUNE = tf.data.experimental.AUTOTUNE
class Img dir:
   def init (self, path list):
       self.path dir = tf.data.Dataset.from tensor slices(path list)
   def switch dir(self):
       batch size = round(len(self.path dir) / 3)
       path dir = self.path dir.shuffle(len(self.path dir))
       return path dir.batch(batch size)
class TotalDataset:
   def init (self, left dir, right dir):
        self.left path dir = [ds for ds in Img dir(left dir).switch dir()]
       self.right path dir = [ds for ds in Img dir(right dir).switch dir()]
   def get path label(self, index):
        left xs = self.left path dir[index]
       left ys = tf.zeros(len(left xs), dtype=tf.int64)
       right xs = self.right path dir[index]
       right ys = tf.ones(len(right xs), dtype=tf.int64)
       xs = tf.concat((left xs, right xs), axis=0)
       ys = tf.concat((left_ys, right ys), axis=0)
       ys = tf.one hot(ys, depth=2)
       img paths = tf.data.Dataset.from tensor slices(xs)
        image dir = img paths.map(load and preprocess image)
       label dir = tf.data.Dataset.from tensor slices(ys)
       image label dir = tf.data.Dataset.zip((image dir, label dir))
       return image label dir
   def shuffle buffer(self, image label dir, batch size):
        # 设置一个和数据集大小一致的 shuffle buffer size (随机缓冲区大小) 以保证数据
        # 被充分打乱。
       n = len(image label dir)
       ds = image label dir.shuffle(buffer size=n)
       # ds = ds.repeat()
       ds = ds.batch(batch size)
        # 当模型在训练的时候, `prefetch` 使数据集在后台取得 batch。
       ds = ds.prefetch(buffer_size=AUTOTUNE)
       return ds
   def get train(self, batch size):
       train set = self.get path label(0)
       return self.shuffle buffer(train set, batch size)
   def get val(self, batch size):
       val set = self.get path label(1)
       return self.shuffle buffer(val set, batch size)
   def get_test(self, batch_size):
       test set = self.get path label(2)
       return self.shuffle buffer(test set, batch size)
```

```
def preprocess image(image, img width=224, img height=224):
    image = tf.image.decode jpeg(image, channels=3)
    image = tf.image.resize(image, [img width, img height])
   image /= 255.0 # normalize to [0,1] range
   return image
def load and preprocess image(path):
    image = tf.io.read file(path)
   return preprocess image(image)
def get dir(keyword):
   dir = [path.as posix()
                for path in Path(data root).rglob('**/'+keyword+'/**/*png')]
def get dataset(data root = 'data', batch size = 32):
    left dir = [path.as posix()
                for path in Path(data root).rglob('**/left/**/*png')]
   right dir = [path.as_posix()
                 for path in Path(data root).rglob('**/right/**/*png')]
   data set = TotalDataset(left dir, right dir)
   trainset = data set.get train(batch size)
   valset = data set.get val(batch size)
   testset = data set.get test(batch size)
   return trainset, valset, testset
```

Model building

In this chapter, I constructed a simplified version of VGG that can provide faster training and prediction speeds with the same accuracy.

VGG16 is a convolutional neural network model proposed by K. Simonyan and A. Zisserman of Oxford University in the paper "Very Deep Convolutional Networks for Large-scale Image Recognition". It is one of the famous models submitted to ILSVRC-2014. By replacing the large kernel size filters (11 and 5 in the first and second convolutional layers respectively) with multiple 3×3 kernel size filters,



In [8]:

```
trainset, valset, testset = get_dataset(data_root = 'data/')
```

In [15]:

```
model = tf.keras.models.Sequential()
# 1 VGG Blocks
model.add(tf.keras.layers.Conv2D(filters=64,kernel size=3, activation='relu', pa
dding='same', input_shape=(224, 224, 3)))
model.add(tf.keras.layers.Conv2D(filters=64,kernel size=2,activation='relu'))
# model.add(tf.keras.layers.MaxPooling2D((2, 2), strides=2, padding='same'))
model.add(tf.keras.layers.Dropout(0.2))
# 2 VGG Blocks
model.add(tf.keras.layers.Conv2D(filters=64,kernel size=3, activation='relu', pa
dding='same', input shape=(224, 224, 3)))
model.add(tf.keras.layers.Conv2D(filters=64,kernel size=2,activation='relu'))
# model.add(tf.keras.layers.MaxPooling2D((2, 2), strides=2, padding='same'))
model.add(tf.keras.layers.Dropout(0.2))
model.add(tf.keras.layers.Flatten())
model.add(tf.keras.layers.Dropout(0.7))
model.add(tf.keras.layers.Dense(2, activation='softmax'))
model.summary()
```

Model: "sequential 2"

Layer (type)	Output Shape	Param #
conv2d_3 (Conv2D)	(None, 224, 224, 64)	1792
conv2d_4 (Conv2D)	(None, 223, 223, 64)	16448
dropout_2 (Dropout)	(None, 223, 223, 64)	0
flatten_2 (Flatten)	(None, 3182656)	0
dropout_3 (Dropout)	(None, 3182656)	0
dense_3 (Dense)	(None, 2)	6365314

Total params: 6,383,554
Trainable params: 6,383,554
Non-trainable params: 0

The input of the cov1 layer has a fixed size 224 x 224 image. The image passes through a stack of convolution (convolution) layers. In one configuration, it also uses 64 convolution filters). The convolution stride is fixed at 1 pixel; the converted space filling layer input preserves the spatial resolution after convolution. All hidden layers have rectification (ReLU) nonlinear characteristics. This structure will improve the performance of the ILSVRC data set, and also save memory consumption and calculation time.

In [26]:

```
Epoch 1/15
1372 - accuracy: 0.9865 - val loss: 5.4412e-04 - val accuracy: 1.000
Epoch 2/15
9412e-05 - accuracy: 1.0000 - val loss: 1.5971e-04 - val accuracy:
1.0000
Epoch 3/15
195/195 [============= ] - 46s 236ms/step - loss: 1.
5178e-05 - accuracy: 1.0000 - val loss: 6.8459e-05 - val accuracy:
1.0000
Epoch 4/15
5823e-06 - accuracy: 1.0000 - val loss: 3.2114e-05 - val accuracy:
1.0000
Epoch 5/15
1083e-06 - accuracy: 1.0000 - val loss: 1.3409e-04 - val accuracy:
1.0000
Epoch 6/15
3576e-06 - accuracy: 1.0000 - val loss: 2.9248e-05 - val accuracy:
1.0000
Epoch 7/15
3120e-06 - accuracy: 1.0000 - val loss: 2.1438e-05 - val accuracy:
1.0000
Epoch 8/15
195/195 [============= ] - 46s 235ms/step - loss: 1.
6847e-06 - accuracy: 1.0000 - val loss: 3.4339e-05 - val accuracy:
1.0000
Epoch 9/15
195/195 [============= ] - 41s 210ms/step - loss: 1.
3197e-06 - accuracy: 1.0000 - val loss: 6.3285e-05 - val accuracy:
1.0000
Epoch 10/15
0510e-06 - accuracy: 1.0000 - val loss: 6.2886e-05 - val accuracy:
1.0000
Epoch 11/15
195/195 [============= ] - 38s 197ms/step - loss: 6.
9197e-07 - accuracy: 1.0000 - val loss: 1.2744e-05 - val accuracy:
1.0000
Epoch 12/15
9604e-06 - accuracy: 1.0000 - val loss: 4.7944e-05 - val accuracy:
1.0000
Epoch 13/15
0919e-06 - accuracy: 1.0000 - val loss: 3.8072e-05 - val accuracy:
1.0000
Epoch 14/15
1314e-07 - accuracy: 1.0000 - val loss: 3.0530e-05 - val accuracy:
1.0000
Epoch 15/15
6851e-07 - accuracy: 1.0000 - val_loss: 4.2685e-05 - val_accuracy:
1.0000
```

Evaluation and prediction

In [30]:

```
acc = history.history['accuracy']
val acc = history.history['val accuracy']
loss = history.history['loss']
val loss = history.history['val loss']
epochs range = range(15)
plt.figure(figsize=(8, 8))
plt.subplot(1, 2, 1)
plt.plot(epochs range, acc, label='Training Accuracy')
plt.plot(epochs_range, val_acc, label='Validation Accuracy')
plt.legend(loc='lower right')
plt.title('Training and Validation Accuracy')
plt.subplot(1, 2, 2)
plt.plot(epochs range, loss, label='Training Loss')
plt.plot(epochs range, val loss, label='Validation Loss')
plt.legend(loc='upper right')
plt.title('Training and Validation Loss')
plt.show()
```



The Test accuracy is:

```
In [31]:
```

Conclusion

From the above training structure, it can be found that the variant VGG model has a high accuracy (infinitely close to one) for the classification of Classify laterality (left or right sided knee) of the OAI AKOA knee data set. Performance in the test set and validation set Consistently, no overfitting occurred. However, like VGGNet, it has two main disadvantages: despite the optimization and streamlining of the model, the training time is still very slow, and the network architecture weight itself is very large (with regard to disk/bandwidth).