

**PWM Driver  
User Guide  
V1.00.01**

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1. Constant Definition .....	3
2. Functions.....	4
<i>DrvPWM_IsTimerEnabled</i> .....	4
<i>DrvPWM_SetTimerCounter</i> .....	4
<i>DrvPWM_GetTimerCounter</i> .....	5
<i>DrvPWM_EnableInt</i> .....	5
<i>DrvPWM_DisableInt</i> .....	6
<i>DrvPWM_ClearInt</i> .....	6
<i>DrvPWM_GetIntFlag</i> .....	7
<i>DrvPWM_GetRisingCounter</i> .....	7
<i>DrvPWM_GetFallingCounter</i> .....	8
<i>DrvPWM_GetCaptureIntStatus</i> .....	8
<i>DrvPWM_ClearCaptureIntStatus</i> .....	9
<i>DrvPWM_Open</i> .....	9
<i>DrvPWM_Close</i> .....	10
<i>DrvPWM_EnableDeadZone</i> .....	10
<i>DrvPWM_Enable</i> .....	10
<i>DrvPWM_SetTimerClk</i> .....	11
<i>DrvPWM_SetTimerIO</i> .....	12
<i>DrvPWM_SelectClockSource</i> .....	13
<i>DrvPWM_GetVersion</i> .....	13
2. Revision History.....	15

## 1. Constant Definition

Name	Value	Description
DRVPWM_TIMER0	0x00	PWM Timer 0
DRVPWM_TIMER1	0x01	PWM Timer 1
DRVPWM_CAP0	0x10	PWM Capture 0
DRVPWM_CAP1	0x11	PWM Capture 1
DRVPWM_CAP_ALL_INT	3	PWM Capture Rising and Falling Interrupt
DRVPWM_CAP_RISING_INT	1	PWM Capture Rising Interrupt
DRVPWM_CAP_FALLING_INTERRUPT	2	PWM Capture Falling Interrupt
DRVPWM_CAP_RISING_FLAG	6	Capture rising interrupt flag
DRVPWM_CAP_FALLING_FLAG	7	Capture falling interrupt flag
DRVPWM_CLOCK_DIV_1	4	Input clock divided by 1
DRVPWM_CLOCK_DIV_2	0	Input clock divided by 2
DRVPWM_CLOCK_DIV_4	1	Input clock divided by 4
DRVPWM_CLOCK_DIV_8	2	Input clock divided by 8
DRVPWM_CLOCK_DIV_16	3	Input clock divided by 16
DRVPWM_TOGGLE_MODE	1	PWM Timer Toggle mode
DRVPWM_ONE_SHOT_MODE	0	PWM Timer One-shot mode
DRVPWM_10K	0	clock source from internal 10 kHz oscillator
DRVPWM_32K	1	clock source from external 32kHz crystal clock
DRVPWM_HCLKK	2	clock source from HCLK
DRVPWM_48M	3	clock source from internal OSC48M oscillator clock

## 2. Functions

### ***DrvPWM\_IsTimerEnabled***

#### **Prototype**

```
int32_t DrvPWM_IsTimerEnabled(uint8_t u8Timer);
```

#### **Description**

This function is used to get PWM specified timer enable/disable state

#### **Parameter**

**u8Timer [in]**

Specify the timer.

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

1: The specified timer is enabled.

0: The specified timer is disabled.

### ***DrvPWM\_SetTimerCounter***

#### **Prototype**

```
void DrvPWM_SetTimerCounter(uint8_t u8Timer, uint16_t u16Counter);
```

#### **Description**

This function is used to set the PWM specified timer counter.

#### **Parameter**

**u8Timer [in]**

Specify the timer.

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

**u16Counter [in]**

Specify the timer value. (0~65535)

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

None

**Note** If the counter is set to 0, the timer will stop.

## ***DrvPWM\_GetTimerCounter***

### **Prototype**

```
uint32_t DrvPWM_GetTimerCounter(uint8_t u8Timer);
```

### **Description**

This function is used to get the PWM specified timer counter value

### **Parameter**

**u8Timer [in]**

Specify the timer.

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

### **Include**

Driver/DrvPWM.h

### **Return Value**

The specified timer counter value.

## ***DrvPWM\_EnableInt***

### **Prototype**

```
void DrvPWM_EnableInt(uint8_t u8Timer, uint8_t u8Int,  
PFN_DRV_PWM_CALLBACK pfncallback);
```

### **Description**

This function is used to enable the PWM timer/capture interrupt and install the call back function.

### **Parameter**

**u8Timer [in]**

Specify the timer

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

or the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**u8Int [in]**

Specify the capture interrupt type (The parameter is valid only when capture function)

DRV\_PWM\_CAP\_RISING\_INT: The capture rising interrupt.

DRV\_PWM\_CAP\_FALLING\_INT: The capture falling interrupt.

DRVPWM\_CAP\_ALL\_INT: All capture interrupt.

**pfncallback [in]** The pointer of the callback function for specified timer / capture.

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

None

### ***DrvPWM\_DisableInt***

#### **Prototype**

```
void DrvPWM_DisableInt(uint8_t u8Timer);
```

#### **Description**

This function is used to disable the PWM timer/capture interrupt.

#### **Parameter**

##### **u8Timer [in]**

Specify the timer

DRVPWM\_TIMER0: PWM timer 0.

DRVPWM\_TIMER1: PWM timer 1.

or the capture.

DRVPWM\_CAP0: PWM capture 0.

DRVPWM\_CAP1: PWM capture 1.

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

None

### ***DrvPWM\_ClearInt***

#### **Prototype**

```
void DrvPWM_ClearInt(uint8_t u8Timer);
```

#### **Description**

This function is used to clear the PWM timer/capture interrupt.

#### **Parameter**

##### **u8Timer [in]**

Specify the timer

DRVPWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

or the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**Include**

Driver/DrvPWM.h

**Return Value**

None

***DrvPWM\_GetIntFlag*****Prototype**

```
int32_t DrvPWM_GetIntFlag(uint8_t u8Timer);
```

**Description**

This function is used to get the PWM timer/capture interrupt flag

**Parameter**

**u8Timer [in]**

Specify the timer

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

or the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**Include**

Driver/DrvPWM.h

**Return Value**

1: The specified interrupt occurs.

0: The specified interrupt doesn't occur.

***DrvPWM\_GetRisingCounter*****Prototype**

```
uint16_t DrvPWM_GetRisingCounter(uint8_t u8Capture);
```

**Description**

This function is used to get value which latches the counter when there is a rising transition.

**Parameter****u8Capture [in]**

Specify the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**Include**

Driver/DrvPWM.h

**Return Value**

The value which latches the counter when there is a rising transition.

***DrvPWM\_GetFallingCounter*****Prototype**

```
uint16_t DrvPWM_GetFallingCounter(uint8_t u8Capture);
```

**Description**

This function is used to get value which latches the counter when there's a falling transition.

**Parameter****u8Capture [in]**

Specify the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**Include**

Driver/DrvPWM.h

**Return Value**

The value which latches the counter when there's a falling transition

***DrvPWM\_GetCaptureIntStatus*****Prototype**

```
int32_t DrvPWM_GetCaptureIntStatus(uint8_t u8Capture, uint8_t u8IntType);
```

**Description**

Check if there's a rising / falling transition

**Parameter****u8Capture [in]**

Specify the capture.

DRV\_PWM\_CAP0: PWM capture 0.





DRV\_PWM\_CAP1: PWM capture 1.

**u8IntType [in]**

Specify the capture.

DRV\_PWM\_CAP\_RISING\_FLAG: The capture rising interrupt flag.

DRV\_PWM\_CAP\_FALLING\_FLAG: The capture falling interrupt flag.

**Include**

Driver/DrvPWM.h

**Return Value**

TRUE: The specified interrupt occurs.

FALSE: The specified interrupt doesn't occur.

### ***DrvPWM\_ClearCaptureIntStatus***

**Prototype**

```
void DrvPWM_ClearCaptureIntStatus(uint8_t u8Capture, uint8_t u8IntType);
```

**Description**

Clear the rising / falling transition interrupt flag

**Parameter**

**u8Capture [in]**

Specify the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**u8IntType [in]**

Specify the capture.

DRV\_PWM\_CAP\_RISING\_FLAG: The capture rising interrupt flag.

DRV\_PWM\_CAP\_FALLING\_FLAG: The capture falling interrupt flag.

**Include**

Driver/DrvPWM.h

**Return Value**

None

### ***DrvPWM\_Open***

**Prototype**

```
void DrvPWM_Open(void);
```

**Description**

Enable PWM engine clock and reset PWM.

### Include

Driver/DrvPWM.h

### Return Value

None

## ***DrvPWM\_Close***

### Prototype

```
void DrvPWM_Close(void);
```

### Description

Disable PWM engine clock and the I/O enable

### Include

Driver/DrvPWM.h

### Return Value

None

## ***DrvPWM\_EnableDeadZone***

### Prototype

```
void DrvPWM_EnableDeadZone(uint8_t u8Length, int32_t  
i32EnableDeadZone);
```

### Description

This function is used to set the dead zone length and enable/disable Dead Zone function.

### Parameter

**u8Length [in]**

Specify Dead Zone Length : 0~255.

**i32EnableDeadZone [in]**

Enable DeadZone (1) / Diasble DeadZone (0)

### Include

Driver/DrvPWM.h

### Return Value

None

## ***DrvPWM\_Enable***

### Prototype



```
void DrvPWM_Enable(uint8_t u8Timer, int32_t i32Enable);
```

### Description

This function is used to enable PWM timer / capture function

### Parameter

#### **u8Timer [in]**

Specify the timer

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

or the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

#### **i32Enable [in]**

Enable (1) / Disable (0)

### Include

Driver/DrvPWM.h

### Return Value

None

## ***DrvPWM\_SetTimerClk***

### Prototype

```
uint32_t DrvPWM_SetTimerClk(uint8_t u8Timer,  
S_DRV_PWM_TIME_DATA_T *sPt);
```

### Description

This function is used to configure the frequency/pulse/mode/inverter function.

### Parameter

#### **u8Timer [in]**

Specify the timer

DRV\_PWM\_TIMER0: PWM timer 0.

DRV\_PWM\_TIMER1: PWM timer 1.

or the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

#### **\*sPt [in]**

It includes the following parameter

***u8Frequency***: The timer/capture frequency

***u8HighPulseRatio***: High pulse ratio

***u8Mode:*** DRV\_PWM\_ONE\_SHOT\_MODE / DRV\_PWM\_TOGGLE\_MODE

***Inverter:*** Inverter Enable (1) / Inverter Disable (0)

***u8ClockSelector:*** Clock Selector

DRV\_PWM\_CLOCK\_DIV\_1:

DRV\_PWM\_CLOCK\_DIV\_2:

DRV\_PWM\_CLOCK\_DIV\_4:

DRV\_PWM\_CLOCK\_DIV\_8:

DRV\_PWM\_CLOCK\_DIV\_16:

(The parameter takes effect when u8Frequency = 0)

***u8PreScale:*** Prescale (2 ~ 256)

(The parameter takes effect when u8Frequency = 0)

***u32Duty:*** Pulse duty

(The parameter takes effect when u8Frequency = 0 or u8Timer =

DRV\_PWM\_CAP0/DRV\_PWM\_CAP1)

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

The actual frequency.

#### **Note**

1. The function will set the frequency property automatically when user set a nonzero frequency value
2. When setting the frequency value to zero, user also can set frequency property (Clock selector/Prescale/Duty) by himself.
3. The function can set the proper frequency property (Clock selector/Prescale) for capture function and user needs to set the proper pulse duty by himself.

### ***DrvPWM\_SetTimerIO***

#### **Prototype**

```
void DrvPWM_SetTimerIO(uint8_t u8Timer, int32_t i32Enable);
```

#### **Description**

This function is used to enable/disable PWM timer/capture I/O function

#### **Parameter**

**u8Timer [in]**

Specify the timer

DRV\_PWM\_TIMER0: PWM timer 0.



DRV\_PWM\_TIMER1: PWM timer 1.

or the capture.

DRV\_PWM\_CAP0: PWM capture 0.

DRV\_PWM\_CAP1: PWM capture 1.

**i32Enable [in]**

Enable (1) / Disable (0)

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

None

### ***DrvPWM\_SelectClockSource***

#### **Prototype**

```
void DrvPWM_SelectClockSource(uint8_t u8Timer, uint8_t
u8ClockSourceSelector);
```

#### **Description**

This function is used to select PWM0/PWM1 engine clock source.

#### **Parameter**

**u8Timer [in]**

Specify the timer

DRV\_PWM\_TIMER0/DRV\_PWM\_TIMER1: PWM timer 0 or PWM timer 1.

**u8ClockSourceSelector [in]**

DRV\_PWM\_10K/DRV\_PWM\_32K/DRV\_PWM\_HCLK/DRV\_PWM\_48M

DRV\_PWM\_10K: internal 10 KHz crystal clock

DRV\_PWM\_32K: external 32 KHz crystal clock

DRV\_PWM\_HCLK: HCLK

DRV\_PWM\_48M: internal OSC48 MHz crystal clock

#### **Include**

Driver/DrvPWM.h

#### **Return Value**

None

### ***DrvPWM\_GetVersion***

#### **Prototype**

```
int32_t DrvPWM_GetVersion (void);
```

### Description

Return the current version number of driver.

### Include

Driver/DrvPWM.h

### Return Value

Version number :

31:24	23:16	15:8	7:0
00000000	MAJOR_NUM	MINOR_NUM	BUILD_NUM

## 2. Revision History

Version	Date	Description
1.00.01	Mar. 2011	Preliminary PWM Driver User Guide of ISD9160