

Vision & Learning Lab

Multimodal Compact Bilinear Pooling

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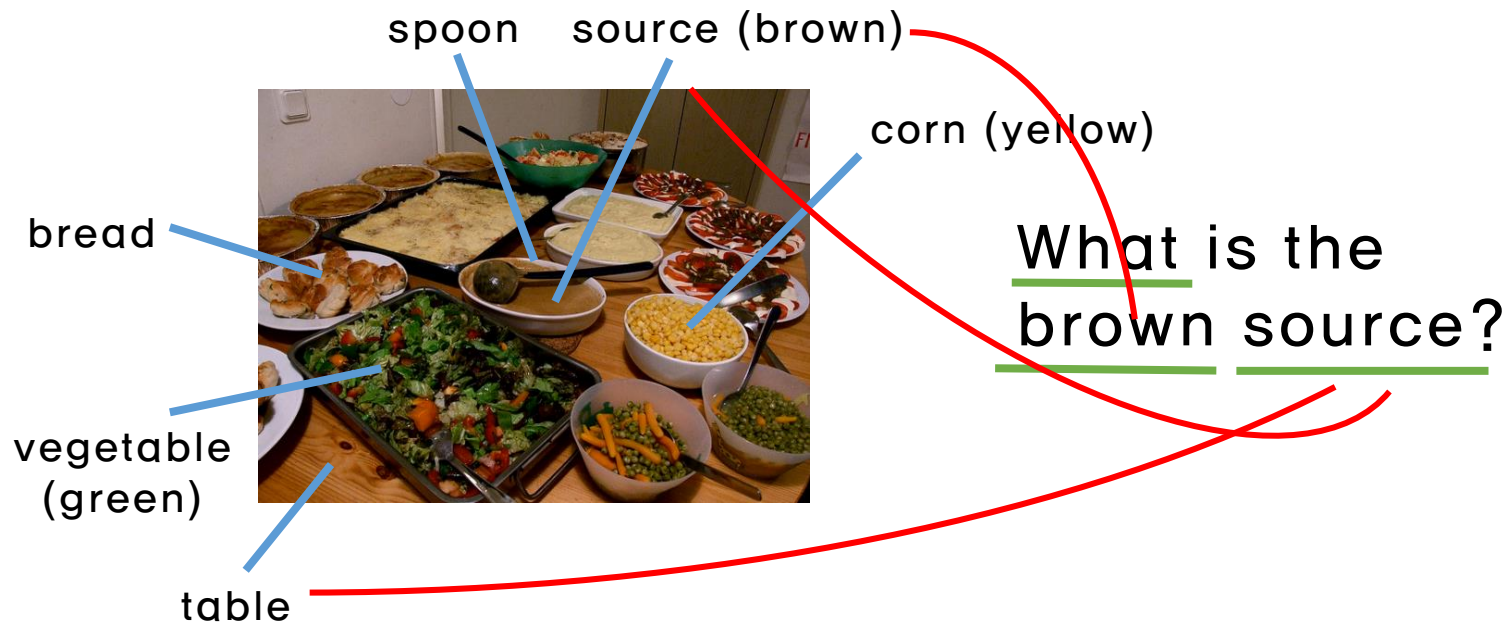
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II . Compact bilinear pooling

III . Models for Visual QA & Visual grounding

IV . Results

Topic

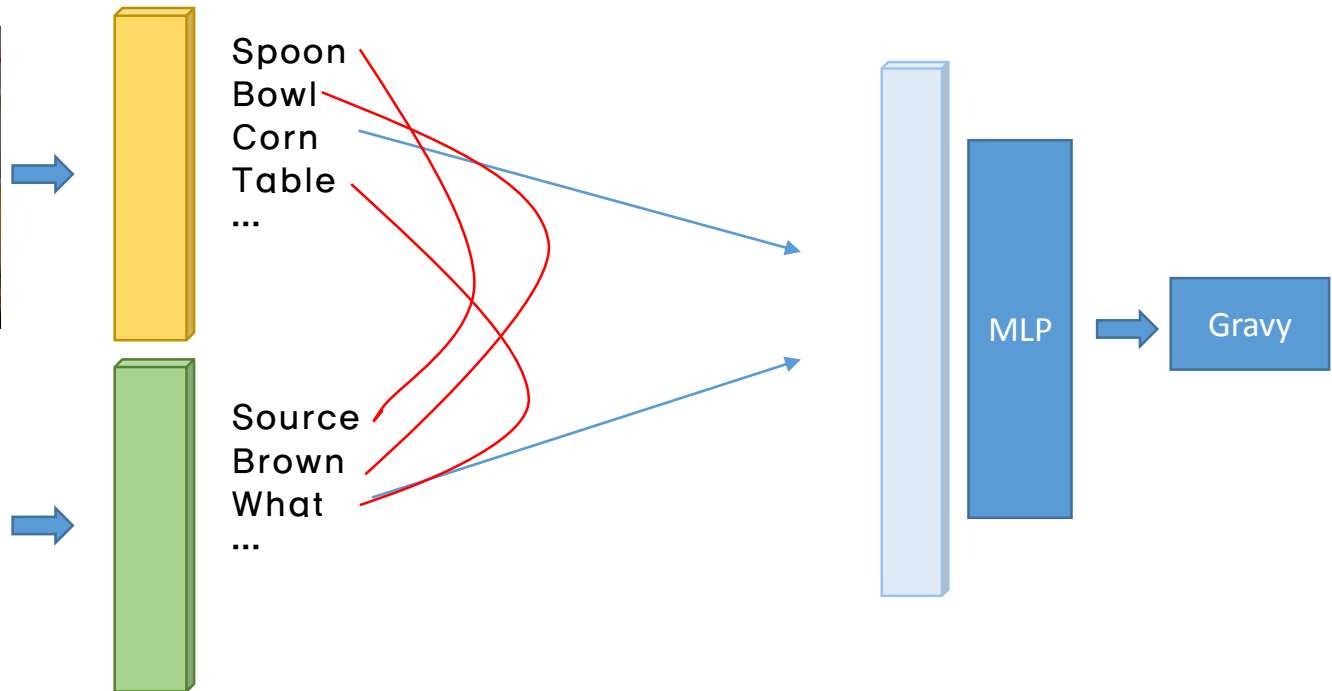


Gravy

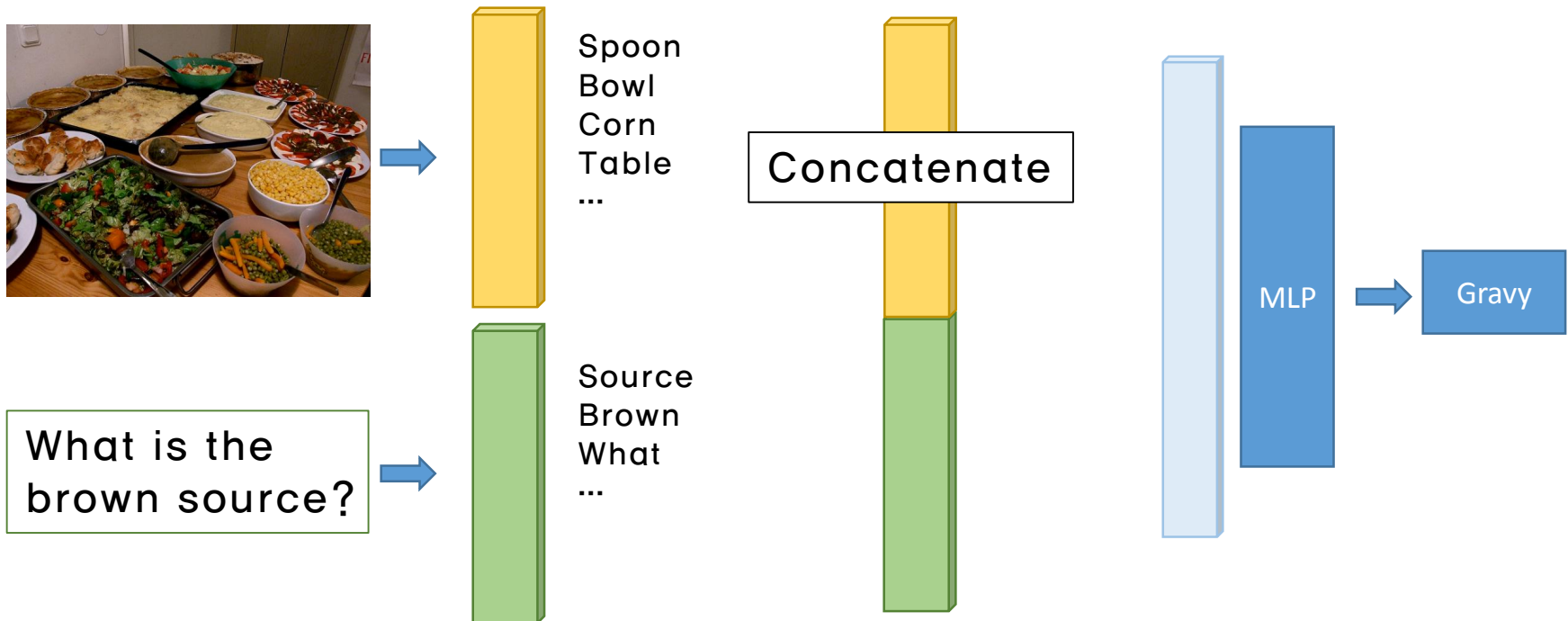
Topic



What is the
brown source?

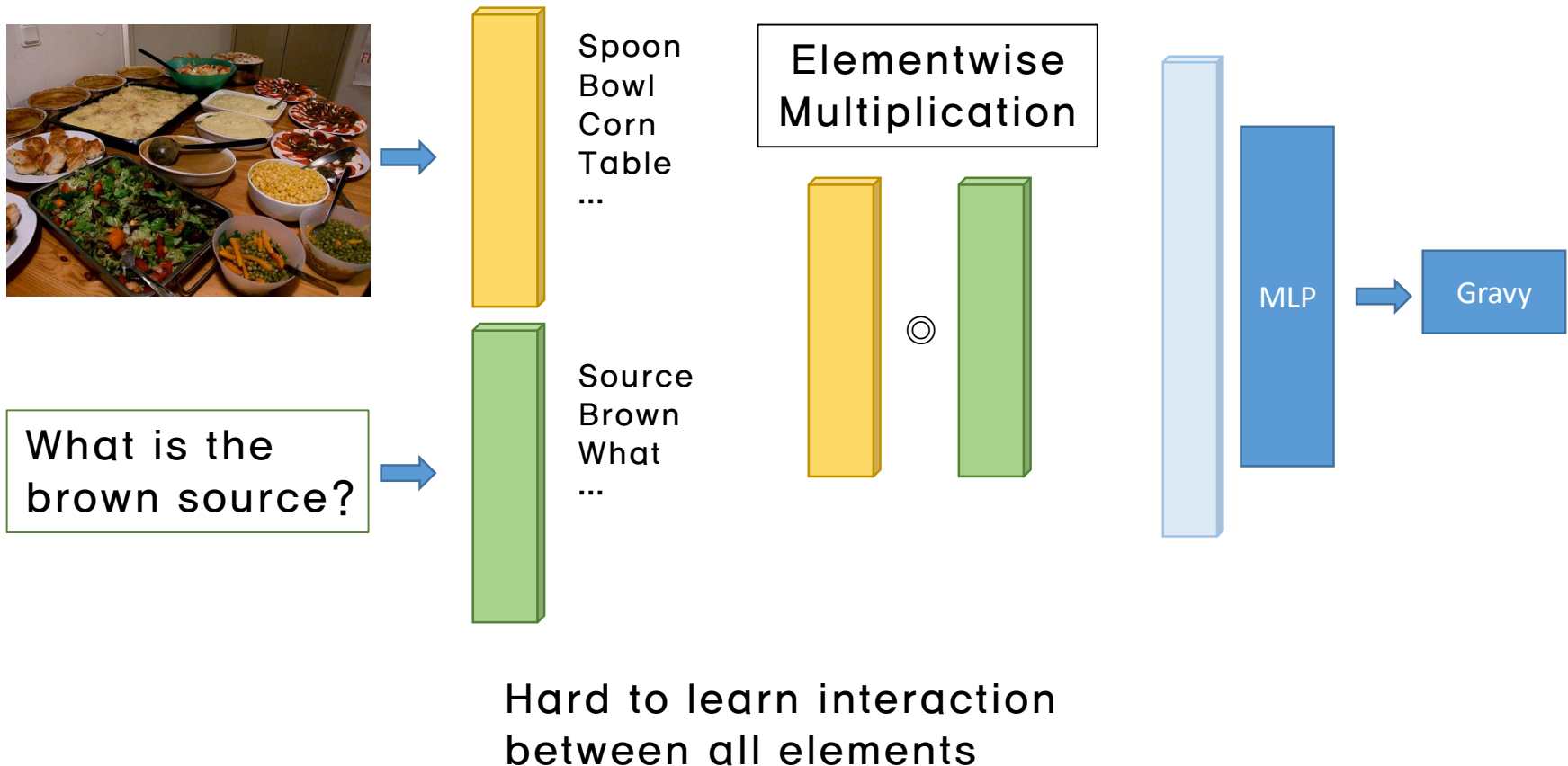


Bilinear Model

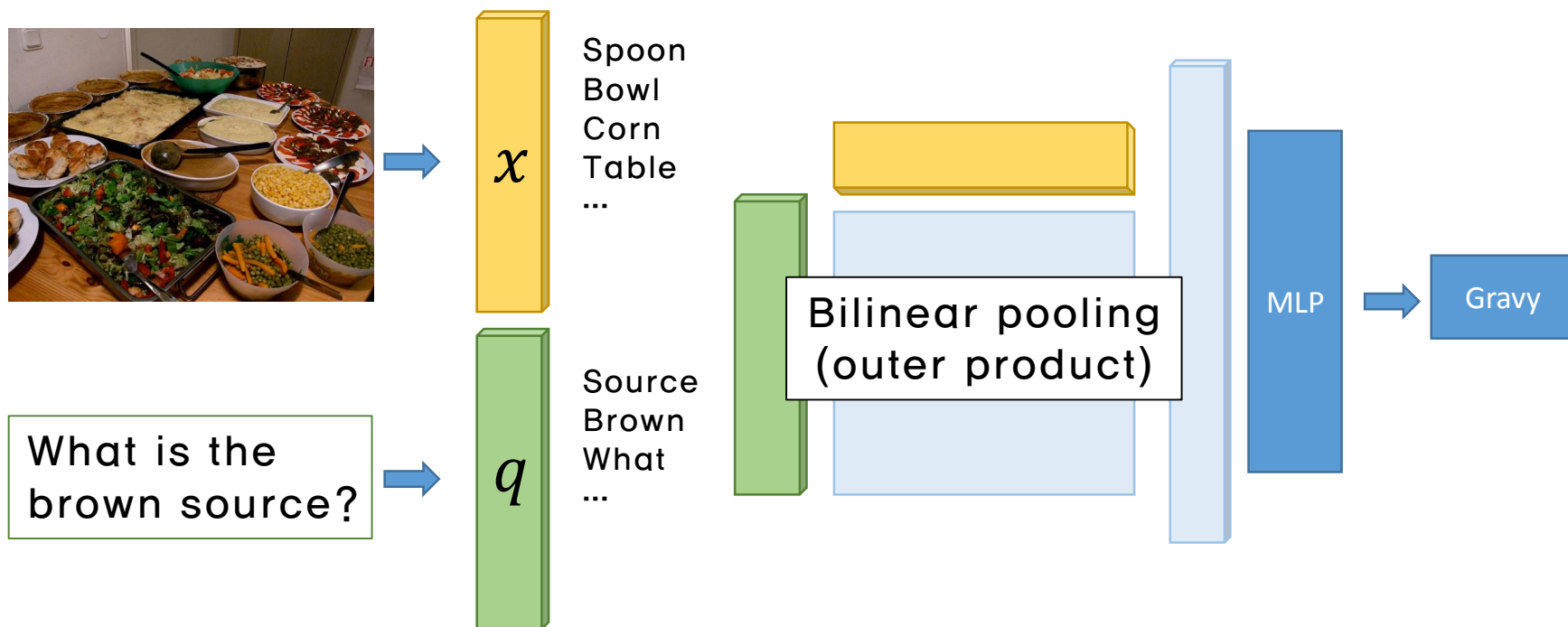


Hard to learn multiplicative interaction
between elements of two vectors

Bilinear Model



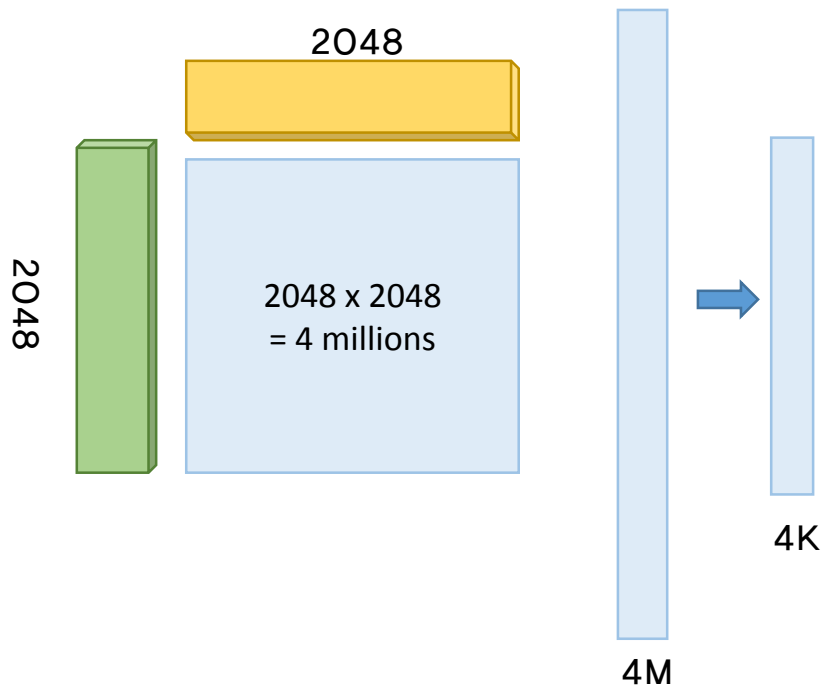
Bilinear Model



$$B(X) = \sum_{s \in S} x_s \cdot q_s^T = \sum_{s \in S} x_s \times q_s$$

(sum pooling)

Compact Bilinear Pooling



$$B(X) = \sum_{s \in S} x_s \times q_s \quad : c \text{ dimension}$$



$$C(X) = ? \quad : d \text{ dimension}$$

$$(X = \{x_1, x_2, \dots, x_{|S|}, q_1, q_2, \dots, q_{|S|}\})$$

Random
Maclaurin

Tensor
Sketch

Compact Bilinear Pooling

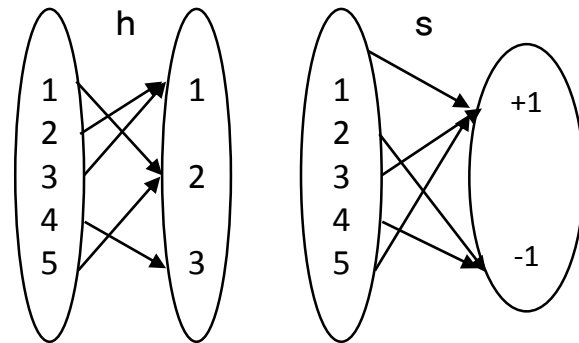
Count Sketch

Random projection

Given hash functions $h : [c] \rightarrow [d]$, $s : [c] \rightarrow \{+1, -1\}$,
Count sketch of the point $x = \{x_1, x_2, \dots, x_c\} \in R^c$ is

$$\Psi(x, h, s) = \{y_1, y_2, \dots, y_d\} \in R^d,$$

where $y_j = \sum_{i:h(i)=j} s(i)x_i$



$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \rightarrow \Psi(x, h, s) = \begin{bmatrix} -x_2 + x_3 \\ x_1 + x_5 \\ -x_4 \end{bmatrix}$$

Compact Bilinear Pooling

Count Sketch

$$1) \langle u, v \rangle \approx \langle \Psi(u, h, s), \Psi(v, h, s) \rangle$$

$$E[\langle \Psi(u, h, s), \Psi(v, h, s) \rangle] = \langle u, v \rangle$$

$$\text{Var}[\langle \Psi(u, h, s), \Psi(v, h, s) \rangle] = \frac{1}{d} (\sum_{i \neq j} (u_i^2 v_j^2 + u_i v_i u_j v_j))$$

pf)

$$\text{let } \langle \psi(u, h, s), \psi(v, h, s) \rangle = \langle u, v \rangle_\psi$$

$$\begin{aligned} E_\psi[\langle u, v \rangle_\psi] &= E_h[E_s[\langle u, v \rangle_\psi]] = E_h[E_s[\sum_{i,j} s(i)s(j)u_i v_j \delta_{h(i),h(j)}]] \\ &= \sum_{i,j} u_i v_j \quad (\because E_s[\sum_{i \neq j} s(i)s(j)] = 0) \\ &= \langle u, v \rangle \end{aligned}$$

$$\begin{aligned} E_\psi[\langle u, v \rangle_\psi^2] &= E_\psi[\sum_{i,j,k,l} s(i)s(j)s(k)s(l)u_i v_j u_k v_l \delta_{h(i),h(j)} \delta_{h(k),h(l)}] \\ &= \sum_{i,k} u_i v_i u_k v_k + \sum_{i \neq j} u_i^2 v_j^2 E_h[\delta_{h(i),h(j)}] + \sum_{i \neq j} u_i v_i u_j v_j E_h[\delta_{h(i),h(j)}] \\ &= \langle u, v \rangle^2 + \frac{1}{d} \left(\sum_{i \neq j} u_i^2 v_j^2 + u_i v_i u_j v_j \right) \end{aligned}$$

Compact Bilinear Pooling

Count Sketch

$$1) \langle u, v \rangle \approx \langle \Psi(u, h, s), \Psi(v, h, s) \rangle$$

$$E[\langle \Psi(u, h, s), \Psi(v, h, s) \rangle] = \langle u, v \rangle$$

$$\text{Var}[\langle \Psi(u, h, s), \Psi(v, h, s) \rangle] = \frac{1}{d} (\sum_{i \neq j} (u_i^2 v_j^2 + u_i v_i u_j v_j))$$

pf)

$$\text{Var}_{\psi}[\langle u, v \rangle_{\psi}] = \mathbf{E}_{\psi}[\langle u, v \rangle_{\psi}^2] - \mathbf{E}_{\psi}[\langle u, v \rangle]^2 = \frac{1}{d} \left(\sum_{i \neq j} u_i^2 v_j^2 + u_i v_i u_j v_j \right)$$

Relative error bound (Chebyshev's inequality)

$$\begin{aligned} \mathbf{P} \left[\left| \frac{\langle u, v \rangle_{\psi} - \langle u, v \rangle}{\langle u, v \rangle} \right| \geq \epsilon \right] &\leq \frac{\text{Var}_{\psi}[\langle u, v \rangle_{\psi}]}{\epsilon^2 \mathbf{E}_{\psi}[\langle u, v \rangle]^2} \\ &\leq \frac{2}{d \epsilon^2} \left(\frac{1}{\cos \theta_{xy}} \right)^2 \end{aligned}$$

Compact Bilinear Pooling

Count Sketch

2) Given $x, y \in R^c$, 2-wise independent hash functions h_1, h_2, s_1, s_2 ,

$$\Psi(x \times y, h, s) = FFT^{-1}(FFT(\Psi(x, h_1, s_1)) \odot FFT(\Psi(y, h_2, s_2)))$$

$$\equiv \Psi(x, h_1, s_1) * \Psi(y, h_2, s_2)$$

$$h(i, j) = h_1(i) + h_2(j), \text{ mod } d, s(i, j) = s_1(i)s_2(j)$$

Compact Bilinear Pooling

$$\Psi(x \times y, h, s) = \text{FFT}^{-1}(\text{FFT}(\Psi(x, h_1, s_1)) \odot \text{FFT}(\Psi(y, h_2, s_2)))$$

pf)

Count Sketch $\Psi(x, h, s)$ of d dimension can be represented as a polynomial of $d-1$ dimension

$$p_x^{h,s}(w) = \sum_{i=1}^c S(i) x_i w^{h(i)}$$

(basis of d dimension: $[p_x^{h,s}(w^{*0}), p_x^{h,s}(w^{*1}), \dots, p_x^{h,s}(w^{*d-1})]$ where $w^{*d} = 1$)

$$\text{Then, } \Psi(x, h_1, s_1) \rightarrow p_x^{h_1, s_1}(w) = \sum_{i=1}^c S_1(i) x_i w^{h_1(i)}$$

$$\Psi(y, h_2, s_2) \rightarrow p_y^{h_2, s_2}(w) = \sum_{j=1}^c S_2(j) y_j w^{h_2(j)}$$

$$\Psi(x \times y, h, s) \rightarrow p_{xy}^{h,s}(w) = \sum_{i,j=1}^c S(i,j) x_i y_j w^{H(i,j)}$$

$$= \sum_{i,j=1}^c S_1(i) S_2(j) x_i y_j w^{h_1(i)} w^{h_2(j)}$$

$$= p_x^{h_1, s_1}(w) \cdot p_y^{h_2, s_2}(w)$$

$$= \text{FFT}^{-1}(\text{FFT}(p_x^{h_1, s_1}(w)) \odot \text{FFT}(p_y^{h_2, s_2}(w)))$$

Y. Gao et al. Compact bilinear pooling. 2016.

N. Pham and R. Pagh. Fast and scalable polynomial kernels via explicit feature maps. 2013.

R. Pagh. Compressed matrix multiplication. 2012.

Compact Bilinear Pooling

Compact bilinear pooling using Tensor sketch

$$1) \langle u, v \rangle \approx \langle \Psi(u, h, s), \Psi(v, h, s) \rangle$$

$$2) \Psi(x \times y, h, s) = \Psi(x, h_1, s_1) * \Psi(y, h_2, s_2)$$

$$B(X) = \sum_{s \in S} x_s \times q_s \quad (X = \{x_1, x_2, \dots, x_{|S|}, q_1, q_2, \dots, q_{|S|}\})$$

$$C(X) = \sum_{s \in S} \Psi(x_s, h_1, s_1) * \Psi(q_s, h_2, s_2)$$

Given $X = \{x, q\}, Y = \{y, r\}$,

$$\langle B(X), B(Y) \rangle = \sum_{s \in S} \sum_{u \in U} \langle x_s \times q_s, y_u \times r_u \rangle$$

$$\approx \sum_{s \in S} \sum_{u \in U} \langle \Psi(x_s \times q_s, h, s), \Psi(y_u \times r_u, h, s) \rangle$$

$$= \sum_{s \in S} \sum_{u \in U} \langle \Psi(x_s, h_1, s_1) * \Psi(q_s, h_2, s_2), \Psi(y_u, h_1, s_1) * \Psi(r_u, h_2, s_2) \rangle$$

$$= \langle C(X), C(Y) \rangle$$

Compact Bilinear Pooling



Spoon
Bowl
Corn
Table
...

Count
sketch

FFT

FFT^{-1}



Gravy

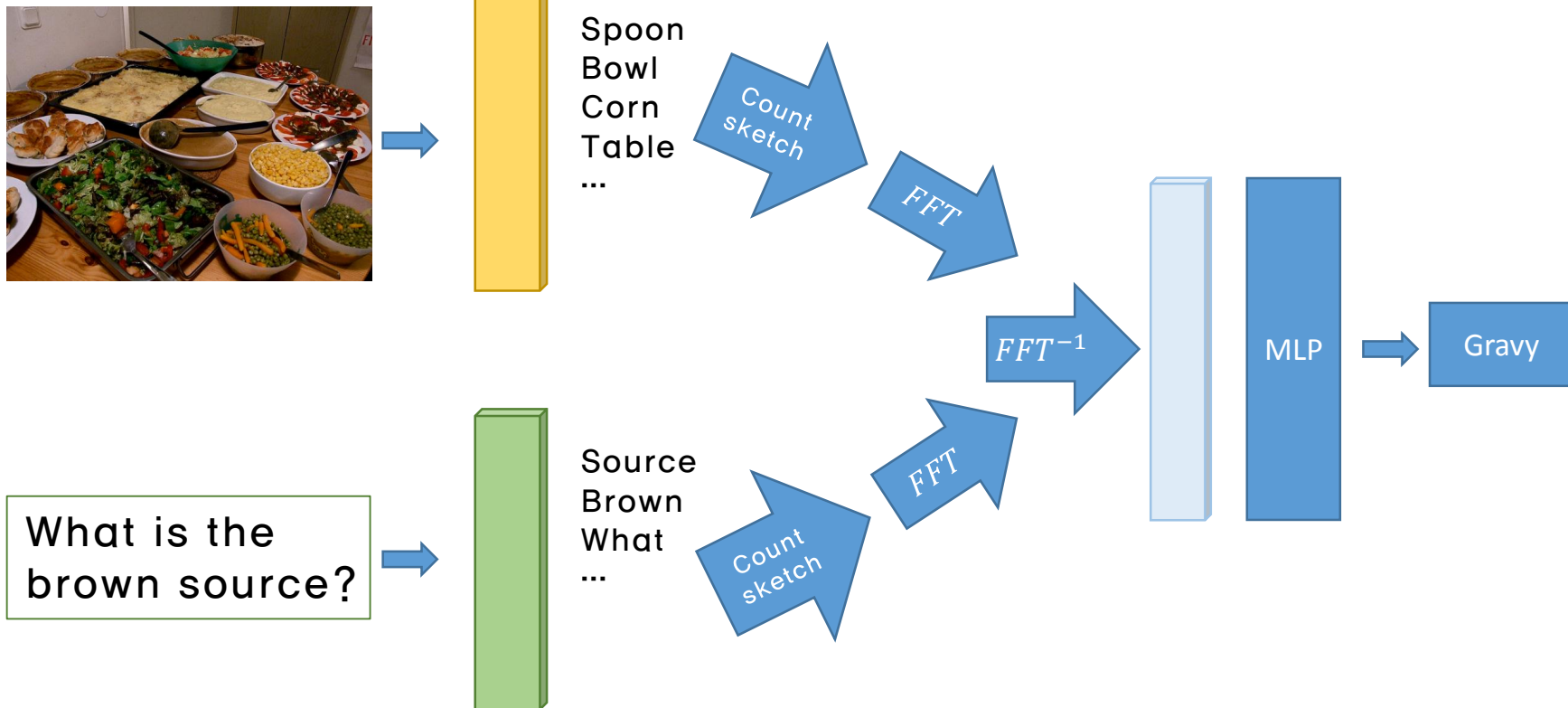
What is the
brown source?



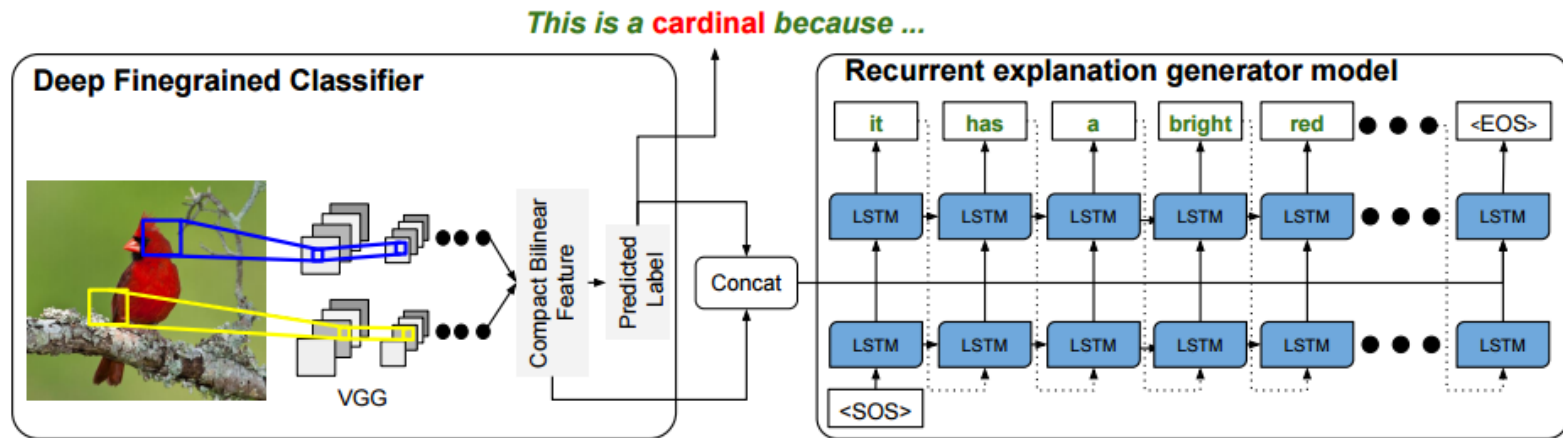
Source
Brown
What
...

Count
sketch

FFT



Models



Visual QA

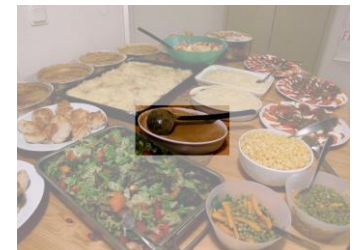
What is the brown source?



Gravy

Visual Grounding

The bowl with the brown source



QA Models

1) Visual QA without Attention

Feature extraction

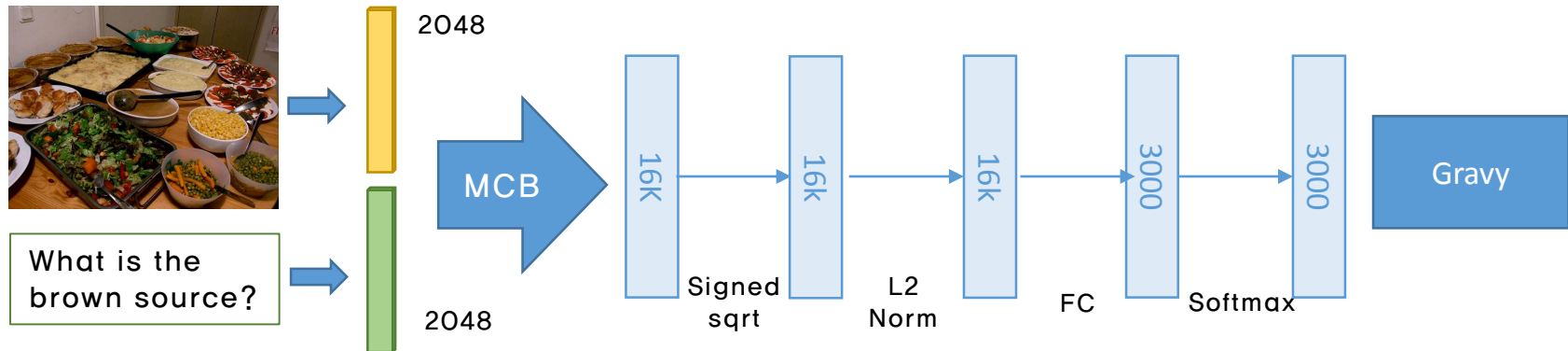
image : ResNet 152 (Before FC)

Question : 2-layer LSTM with output size 1024

(embedding words 13k–20k, embedding size 300)

Answer decoding

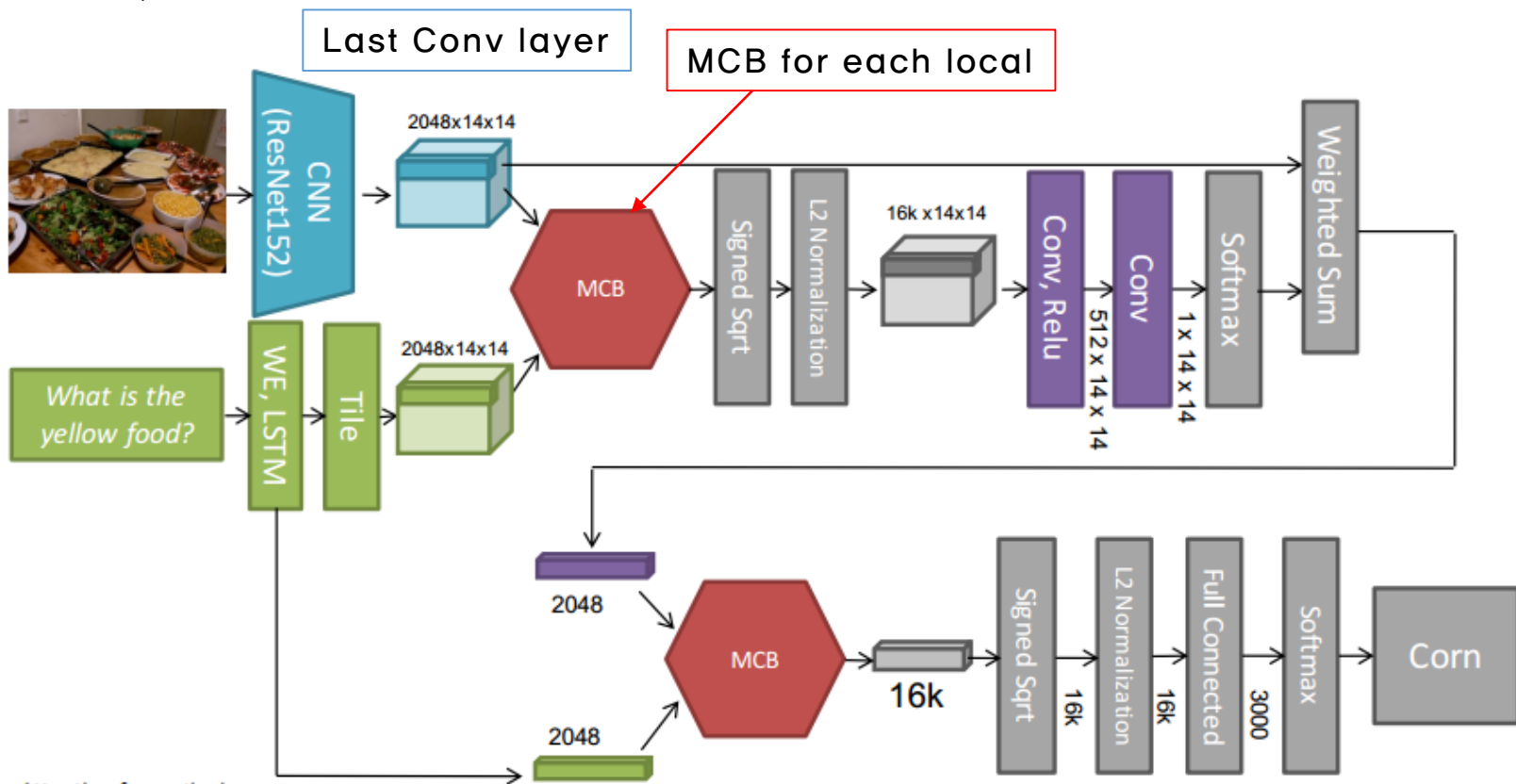
3000 most frequent answers on train



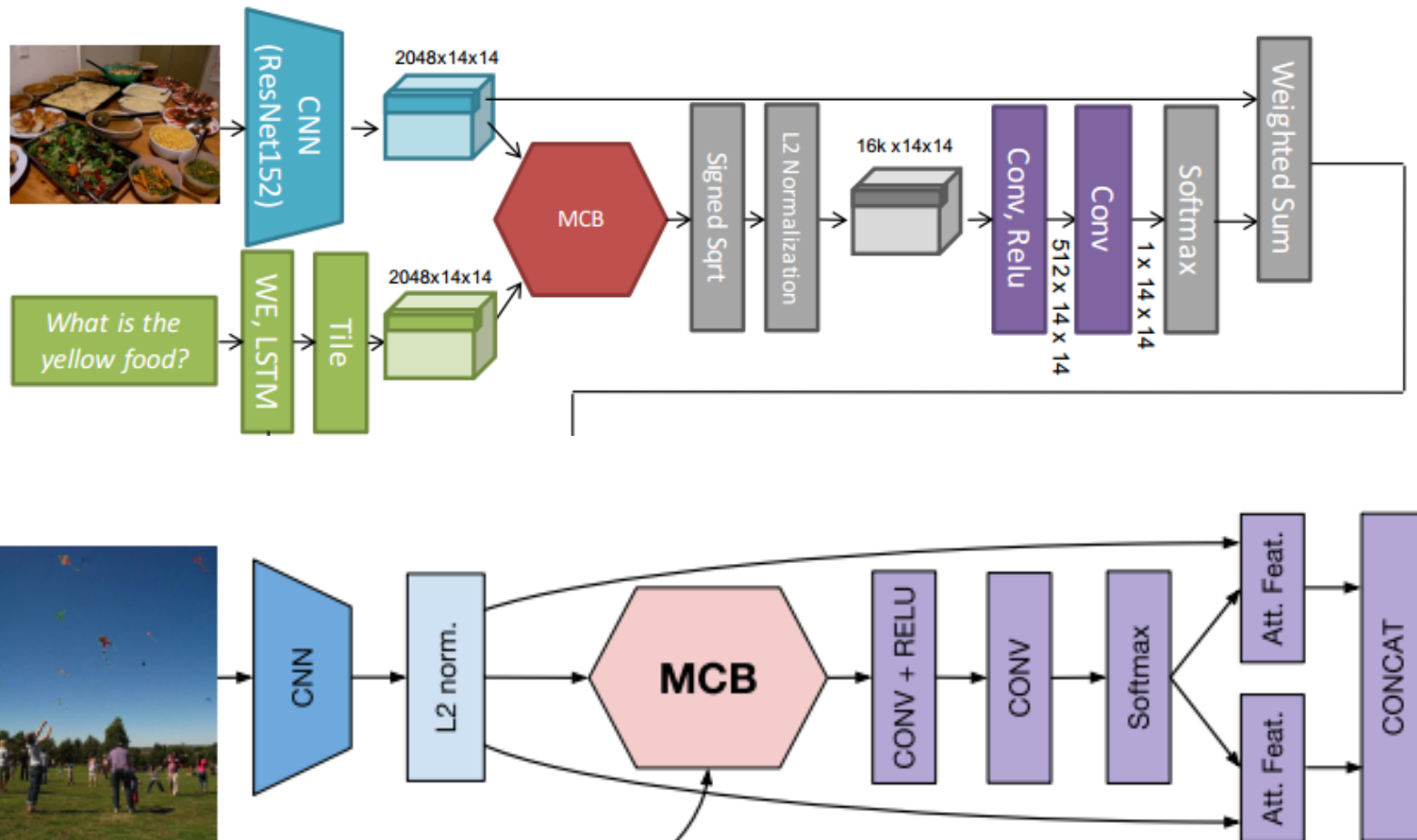
QA Models

2) Visual QA with Attention

2 MCB, Multiple attentions



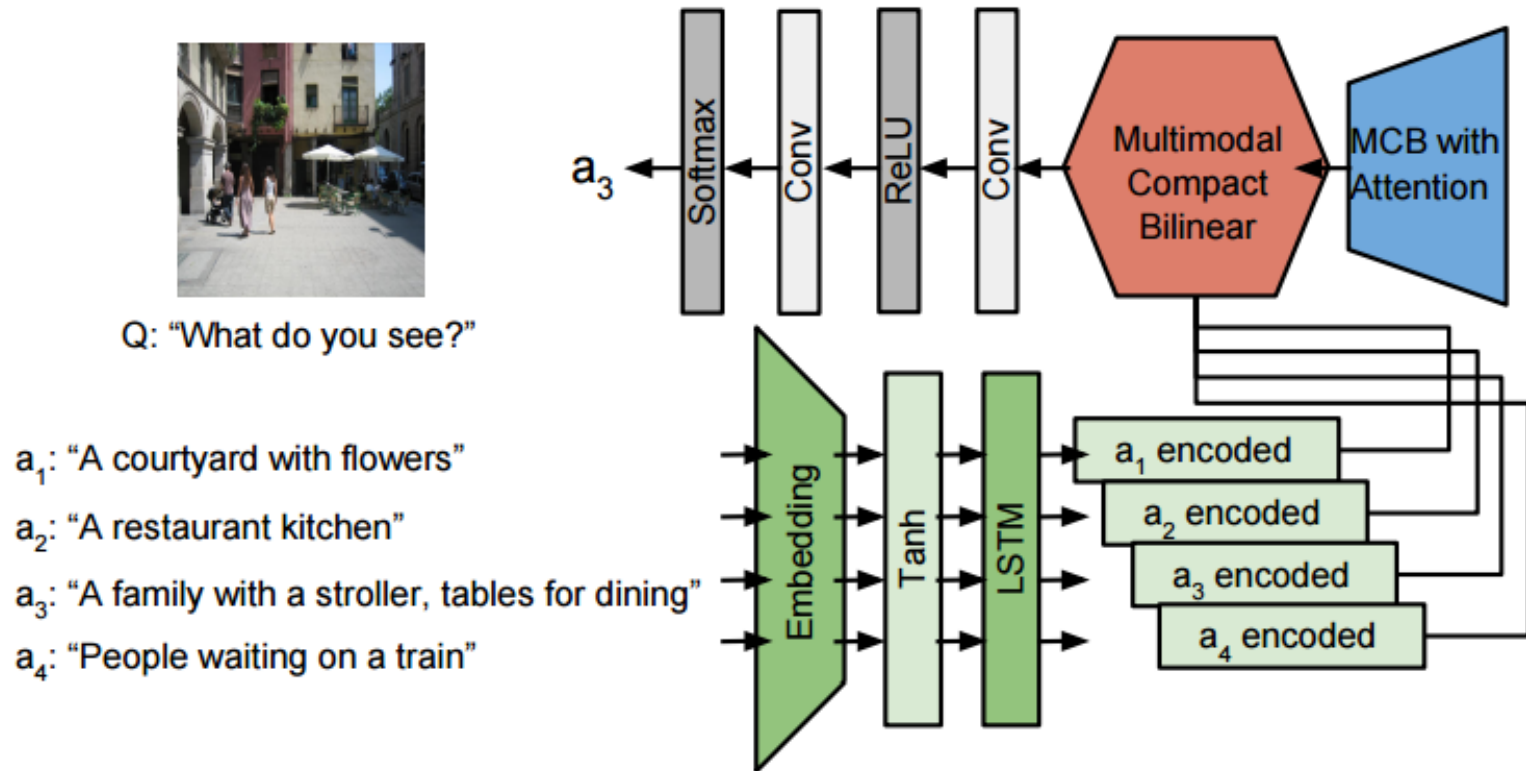
QA Models



QA Models

3) Visual QA (Multiple choices)

Extra embedding for answer candidates (share parameters)



QA Datasets

1) Visual Question Answering real-image dataset

- Approximately 200K MSCOCO images (train 80K, valid 40K, test 80K)
- 3 questions/image, 10 answers/question
- Evaluation : accuracy = $\min(\frac{\text{\# human provided that answer}}{3}, 1)$

2) Visual7W

- Part of the Visual Genome (6W + 7th which question)
- 47300 images from MSCOCO, 139868 QA pairs
- Multiple choice, 4 answer candidates / question
- More balanced distribution of 6W question types, longer question and answers

QA Results

Non-bilinear vs bilinear
with same number of parameters

$$4096^2 + 4096^2 + 4096 \times 3000 \approx 46 \text{ million}$$

$$16000 \times 3000 = 48 \text{ million}$$

Full bilinear vs Compact bilinear

Better regardless of CNN

Better with attention

Method	Accuracy
Eltwise Sum	56.50
Concat	57.49
Concat + FC	58.40
Concat + FC + FC	57.10
Eltwise Product	58.57
Eltwise Product + FC	56.44
Eltwise Product + FC + FC	57.88
MCB ($2048 \times 2048 \rightarrow 16K$)	59.83
Full Bilinear ($128 \times 128 \rightarrow 16K$)	58.46
MCB ($128 \times 128 \rightarrow 4K$)	58.69
Eltwise Product with VGG-19	55.97
MCB ($d = 16K$) with VGG-19	57.05
Concat + FC with Attention	58.36
MCB ($d = 16K$) with Attention	62.50

QA Results

Compact Bilinear d	Accuracy
1024	58.38
2048	58.80
4096	59.42
8192	59.69
16000	59.83
32000	59.71

Dimension of compact bilinear

No. of attention maps	Accuracy
1	64.67
2	65.08
4	64.24

Number of attention maps

Method	What	Where	When	Who	Why	How	Avg
Zhu et al.	51.5	57.0	75.0	59.5	55.5	49.8	54.3
Concat+Att.	47.8	56.9	74.1	62.3	52.7	51.2	52.8
MCB+Att.	60.3	70.4	79.5	69.2	58.2	51.1	62.2

Multiple-choice accuracy
on Visual7W

QA Results

	Test-dev					Test-standard				
	Open Ended				MC	Open Ended				MC
	Y/N	No.	Other	All	All	Y/N	No.	Other	All	All
MCB	81.7	36.9	49.0	61.1	-	-	-	-	-	-
MCB + Genome	81.7	36.6	51.5	62.3	66.4	-	-	-	-	-
MCB + Att.	82.2	37.7	54.8	64.2	-	-	-	-	-	-
MCB + Genome + Att.	81.7	38.2	57.0	65.1	-	-	-	-	-	-
MCB + Genome + Att. + GloVe	82.3	37.2	57.4	65.4	-	-	-	-	-	-
Ensemble of 7 Att. models	83.4	39.8	58.5	66.7	70.2	83.2	39.5	58.0	66.5	70.1
Naver Labs (2nd best on server)	83.5	39.8	54.8	64.9	69.4	83.3	38.7	54.6	64.8	69.3
HieCoAtt (Lu et al., 2016)	79.7	38.7	51.7	61.8	65.8	-	-	-	62.1	66.1
DMN+ (Xiong et al., 2016)	80.5	36.8	48.3	60.3	-	-	-	-	60.4	-
FDA (Ilievski et al., 2016)	81.1	36.2	45.8	59.2	-	-	-	-	59.5	-
D-NMN (Andreas et al., 2016a)	81.1	38.6	45.5	59.4	-	-	-	-	59.4	-
AMA (Wu et al., 2016)	81.0	38.4	45.2	59.2	-	81.1	37.1	45.8	59.4	-
SAN (Yang et al., 2015)	79.3	36.6	46.1	58.7	-	-	-	-	58.9	-
NMN (Andreas et al., 2016b)	81.2	38.0	44.0	58.6	-	81.2	37.7	44.0	58.7	-
AYN (Malinowski et al., 2016)	78.4	36.4	46.3	58.4	-	78.2	36.3	46.3	58.4	-
SMem (Xu and Saenko, 2015)	80.9	37.3	43.1	58.0	-	80.9	37.5	43.5	58.2	-
VQA team (Antol et al., 2015)	80.5	36.8	43.1	57.8	62.7	80.6	36.5	43.7	58.2	63.1
DPPnet (Noh et al., 2015)	80.7	37.2	41.7	57.2	-	80.3	36.9	42.2	57.4	-
iBOWIMG (Zhou et al., 2015)	76.5	35.0	42.6	55.7	-	76.8	35.0	42.6	55.9	62.0

QA Results

Q: What color is the boys shirt on the shoulder?, A: pink, P: pink
image att0 att1



Q: What vegetable is the dog chewing on?, A: carrot, P: carrot
image att0 att1



Q: What is on the boy's hand?, A: glove, P: glove
image att0 att1



Q: What kind of dog is this?, A: husky, P: husky
image att0 att1



Q: Is there grass?, A: yes, P: yes
image att0 att1

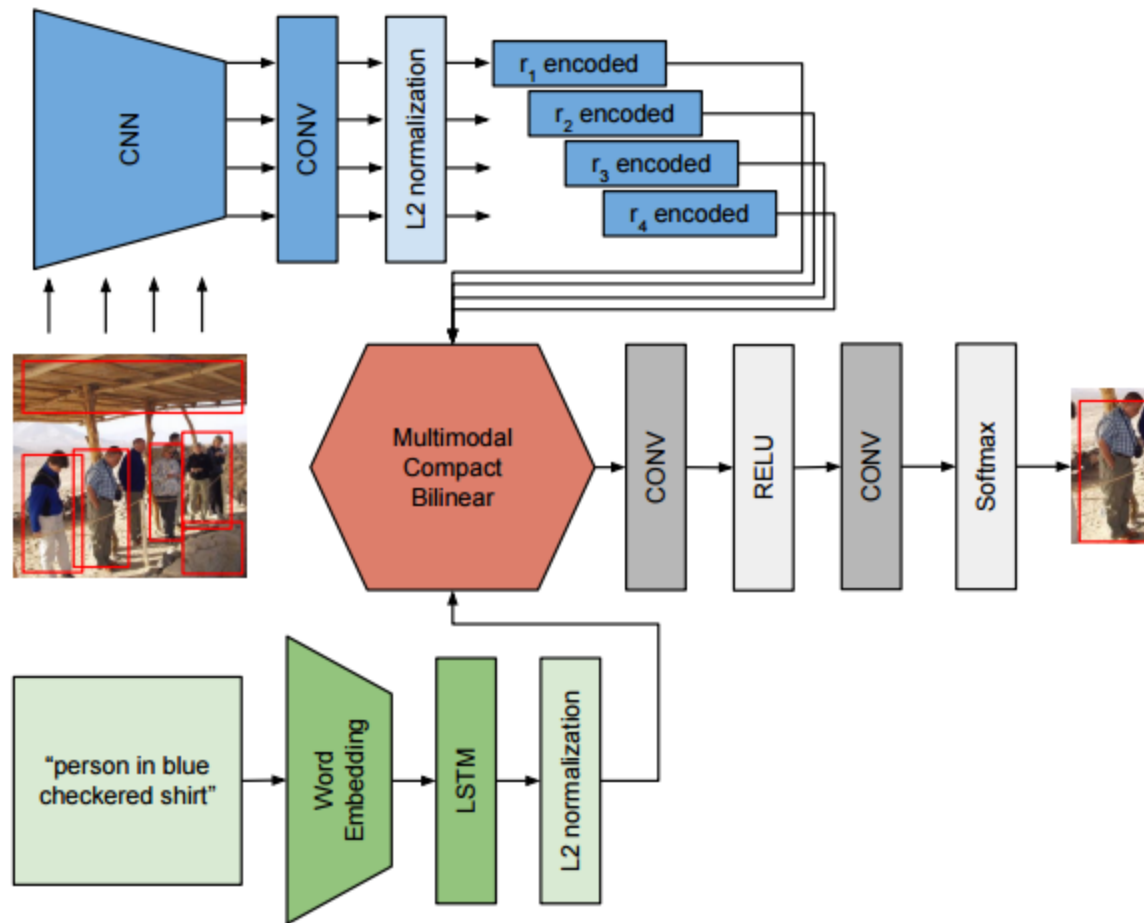


Q: What kind of flooring does the room have?, A: carpet, P: carpet
image att0 att1



Visual Grounding Models

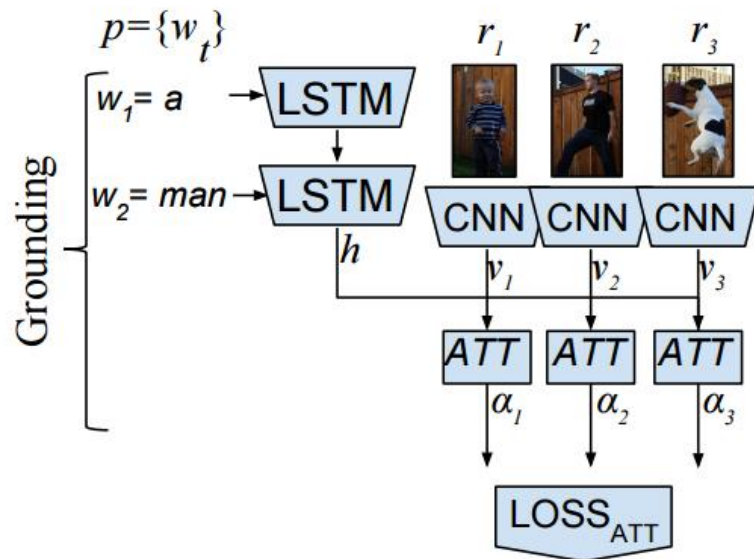
Visual Grounding



Visual Grounding Models

GrounderR

Fully-supervised version of GrounderR (for comparing)



Given I, p, r_i ,

$$h = f_{LSTM}(p)$$

$$v_i = f_{CNN}(I, r_i)$$

$$\alpha_i = f_{AT}(p, r_i) = W\Phi(W_h h + W_v v_i + b_1) + b_2$$

Visual Grounding Datasets

1) Flickr30k Entities

- 31K images from Flickr30k with 244K phrases localized with bounding boxes
- follow the experimental setup from **Rohrbach et al.** (Selective Search, Fast R-CNN, fine-tuned VGG16 features)

2) ReferItGame

- 20K images from IAPR TC-12 dataset, with segmented regions from SAIAPR-12 dataset, and 120K associated natural language referring expressions
- follow the experimental setup from **Hu et al.** (Edge Box object proposals and VGG16 combined with the spatial features)

Visual Grounding Results

Method	Accuracy, %
Plummer et al. (2015)	25.30
Hu et al. (2016b)	27.80
Plummer et al. (2016) ¹	43.84
Wang et al. (2016)	43.89
Rohrbach et al. (2016)	47.70
Concat	46.50
Eltwise Product	47.41
Eltwise Product + Conv	47.86
MCB	48.69

Table 6: Grounding accuracy on Flickr30k Entities dataset

Method	Accuracy, %
Hu et al. (2016b)	17.93
Rohrbach et al. (2016)	26.93
Concat	25.48
Eltwise Product	27.80
Eltwise Product + Conv	27.98
MCB	28.91

Table 7: Grounding accuracy on ReferItGame dataset.

Results (Visual QA + Visual Grounding)



What is the operating system on the laptop?

EP: apple

MCB: windows



How fast is this train?

EP: very

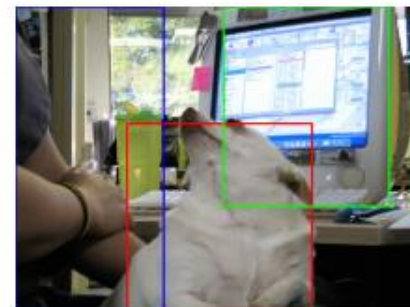
MCB: slow



What is parked next to the baskets?

EP: vegetables

MCB: motorcycle



A dog distracts his owner from working at her computer.



What moves people to the top of the hill?

EP: snow

MCB: ski lift



What kind of vehicle is this?

EP: motorcycle

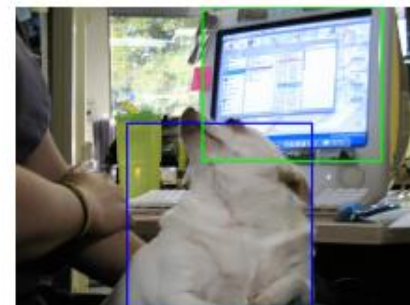
MCB: bicycle



What brand of tennis racket is that?

EP: adidas

MCB: wilson



A dog distracts his owner from working at her computer.

Conclusion

- Bilinear pooling is able to learn multiple interaction between all elements of two vectors.
- Compact bilinear pooling using tensor sketch solve the problem of dimension.
- Multimodal compact bilinear pooling model for Visual QA achieve state-of-art with relatively simple structure.
- Multimodal compact bilinear pooling would be able to be used in any multimodal tasks.

Thank you!

Reference

[Examples and Models]

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[Bilinear pooling]

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[Compact bilinear pooling]

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[Models]

L. A. Hendricks et al. Generating Visual Explanations. 2016.

A. Rohrbach et al. Grounding of Textual Phrases in Images by Reconstruction. 2016.

More for MCB for Visual QA

VQA model slides : http://visualqa.org/static/slides/vqa_final.pdf

Demo : demo.berkeleyvision.org

Code: <https://github.com/akirafukui/vqa-mcb/>

VQA challenge : <http://visualqa.org/challenge.html>

A special thanks to Yunseok Jang, Hyungjin Ko, and Sangeon Park