



```

x - □ pcl_viewer map.pcd
pcl_viewer map.pcd 88x26
% slambook/ch5
19:13 xiang@virtual /home/xiang/slambook/ch5
% ls
imageBasics  joinMap
19:13 xiang@virtual /home/xiang/slambook/ch5
% cd joinMap
19:13 xiang@virtual /home/xiang/slambook/ch5/joinMap
% ls
build          color  joinMap.cpp  map.pcd
CMakeLists.txt depth  joinMap.kdev4 pose.txt
19:13 xiang@virtual /home/xiang/slambook/ch5/joinMap
% build/joinMap
正在将图像转换为点云...
转换图像中: 1
转换图像中: 2
转换图像中: 3
转换图像中: 4
转换图像中: 5
点云共有1081843个点.
19:13 xiang@virtual /home/xiang/slambook/ch5/joinMap
% pcl_viewer map.pcd
The viewer window provides interactive commands; for help, press 'h' or 'H' from within
the window.
> Loading map.pcd [done, 536 ms : 1081843 points]
Available dimensions: x y z rgb

```

