

Problem Set 9
Spring 2017

Issued: (Issued Date Here)

Due: (Due Date Here)

1. Bayesian Estimation of Exponential Distribution

We have already learned about MLE (non-Bayesian perspective) and MAP (Bayesian perspective). In this problem, we will introduce the fully Bayesian approach to statistical estimation.

Suppose that X is an exponential random variable with unknown rate Λ (Λ is a random variable). As a Bayesian practitioner, you have a prior belief that Λ is equally likely to be λ_1 or λ_2 .

You collect one sample X_1 from X .

- (a) Find the posterior distribution $\Pr(\Lambda = \lambda_1 \mid X_1 = x_1)$.
- (b) If we were using the MLE or MAP rule, then we would choose a single value λ for Λ ; this is sometimes called a *point estimate*. This amounts to saying X has the exponential distribution with rate λ .

In the Bayesian approach, we will not use a point estimate. Instead, we will keep the full information of the posterior distribution of Λ , and we compute the distribution of X as

$$f_X(x) = \sum_{\lambda \in \{\lambda_1, \lambda_2\}} f_{X|\Lambda}(x \mid \lambda) \Pr(\Lambda = \lambda \mid X_1 = x_1).$$

Notice that in the Bayesian approach, we do not necessarily have an exponential distribution for X anymore. Compute $f_X(x)$ in closed-form.

- (c) You might guess from the previous part that the fully Bayesian approach is often computationally intractable. This is one of the main reasons why point estimates are common in practice.

Compute the MAP estimate for Λ and calculate $f_X(x)$ again using the MAP rule.

2. Flipping Coins and Hypothesizing

You flip a coin until you see heads. Let $X = 0$ be the hypothesis that the bias of the coin (the probability of heads) is p , and $X = 1$ be the hypothesis that the bias of the coin is q , for $q > p$. Solve the hypothesis testing problem: maximize $\Pr[\hat{X} = 1 \mid X = 1]$ subject to $\Pr[\hat{X} = 1 \mid X = 0] \leq \beta$ for $\beta \in [0, 1]$.

3. Hypothesis Test for Uniform Distribution

If $X = 0$, $Y \sim U[-1, 1]$ and if $X = 1$, $Y \sim U[0, 2]$. Solve a hypothesis testing problem so that the probability of false alarm is less than or equal β .

4. Sufficient Statistics

Suppose X_1, \dots, X_n are i.i.d. samples drawn from a probability distribution parameterized by θ (we are in the non-Bayesian setting, so θ is deterministic, but unknown). A statistic $T(X_1, \dots, X_n)$ is a *sufficient statistic* for θ if for all t , the conditional distribution of X_1, \dots, X_n given $T = t$ does not depend on θ . Intuitively, $T(X_1, \dots, X_n)$ “captures all that there is to know about θ from the sample X_1, \dots, X_n ”.

- (a) Let X_1, \dots, X_n be drawn from a Poisson distribution with mean μ . Show that $T = \sum_{i=1}^n X_i$ is a sufficient statistic for μ .
- (b) Let T be a sufficient statistic for θ . Let $\hat{\theta}$ be an estimator for θ with $E[\hat{\theta}^2] < \infty$. Prove that for all θ ,

$$E[(E[\hat{\theta} | T] - \theta)^2] \leq E[(\hat{\theta} - \theta)^2].$$

Remark: The above result states that $E[\hat{\theta} | T]$ is at least as good as $\hat{\theta}$ at estimating θ , in a mean-squared error sense. Since $E[\hat{\theta} | T]$ is a function of T , the result implies that we should be looking for estimators of θ that are functions of sufficient statistics.

5. Gaussian LLSE

The random variables X, Y, Z are i.i.d. $\mathcal{N}(0, 1)$.

- (a) Find $L[X^2 + Y^2 | X + Y]$.
- (b) Find $L[X + 2Y | X + 3Y + 4Z]$.
- (c) Find $L[(X + Y)^2 | X - Y]$.

6. Photodetector LLSE

Consider a photodetector in an optical communications system that counts the number of photons arriving during a certain interval. A user conveys information by switching a photon transmitter on or off. Assume that the probability of the transmitter being on is p . If the transmitter is on, the number of photons transmitted over the interval of interest is a Poisson random variable Θ with mean λ , and if it is off, the number of photons transmitted is 0. Unfortunately, regardless of whether or not the transmitter is on or off, photons may be detected due to “shot noise”. The number N of detected shot noise photons is a Poisson random variable N with mean μ . Given the number of detected photons, find the LLSE of the number of transmitted photons.