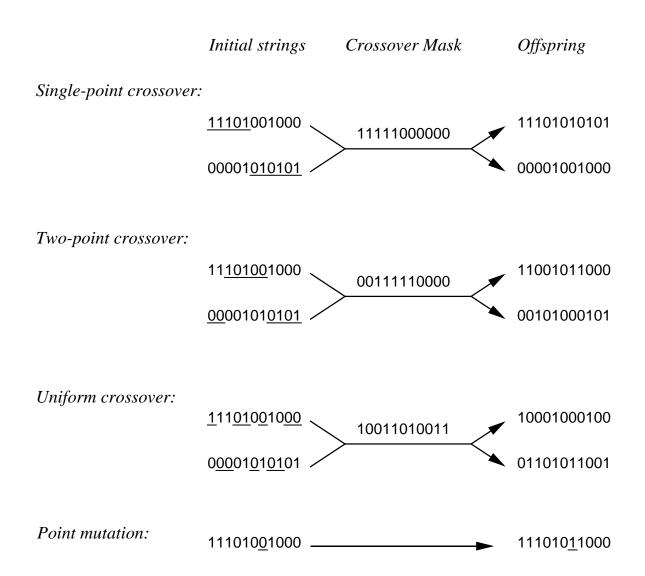
## Genetic Algorithms

[Read Chapter 9] [Exercises 9.1, 9.2, 9.3, 9.4]

- Evolutionary computation
- Prototypical GA
- An example: GABIL
- Genetic Programming
- Individual learning and population evolution

# Operators for Genetic Algorithms



## Representing Hypotheses

## Represent

$$(Outlook = Overcast \lor Rain) \land (Wind = Strong)$$
 by

$$Outlook Wind$$
  $011$   $10$ 

## Represent

IF 
$$Wind = Strong$$
 THEN  $PlayTennis = yes$  by

#### GA(Fitness, Fitness\_threshold, p, r, m)

Fitness:适应度评分函数,为给定假设赋予一个评估分数

Fitness\_threshold:指定终止判据的阈值

p:群体中包含的假设数量

r:每一步中通过交叉取代群体成员的比例

m:变异率

- ●初始化群体: P← 随机产生的 p 个假设
- ●评估:对于 P 中的每一个 h, 计算 Fitness(h)
- ●当[max Fitness(h)] < Fitness\_threshold, 做:

产生新的一代 Ps:

1. 选择:用概率方法选择 P 的(1-r)p 个成员加入 Ps。从 p 中选择 假设 hi 的概率 Pr(hi)用下面公式计算:

$$Pr(hi) = \frac{Fitness(hi)}{\sum_{j=1}^{p} Fitness(hj)}$$

- 2. 交叉: 根据上面给出的 Pr(hi), 从 p 中按概率选择 r.p/2 对假设。 对于每对假设<h1,h2>, 应用交叉算子产生两个后代。把所有的后代加入 Ps
- 3. 变异:使用均匀的概率从 Ps 中选择 m%的成员。对于选出的每个成员,在它的表示中随机选择一位取反
- 4. 更新: P←Ps
- 5. 评估:对于P中的每个h计算Fitness(h)
- ●从 P 中返回适应度最高的假设

| 个体 | 染色体        | 适应度 | 选择概率     | 累积概率     |
|----|------------|-----|----------|----------|
| 1  | 0001100000 | 8   | 0.086957 | 0.086957 |
| 2  | 0101111001 | 5   | 0.054348 | 0.141304 |
| 3  | 000000101  | 2   | 0.021739 | 0.163043 |
| 4  | 1001110100 | 10  | 0.108696 | 0.271739 |
| 5  | 1010101010 | 7   | 0.076087 | 0.347826 |
| 6  | 1110010110 | 12  | 0.130435 | 0.478261 |
| 7  | 1001011011 | 5   | 0.054348 | 0.532609 |
| 8  | 1100000001 | 19  | 0.206522 | 0.739130 |
| 9  | 1001110100 | 10  | 0.108696 | 0.847826 |
| 10 | 0001010011 | 14  | 0.152174 | 1.000000 |

随机数序列: 0.0702121, 0.545929, 0.784567, 0.44693, 0.507893 被选个体: 1, 8, 9, 6, 7

## Selecting Most Fit Hypotheses

Fitness proportionate selection:

$$Pr(h_i) = \frac{Fitness(h_i)}{\sum_{j=1}^{p} Fitness(h_j)}$$

... can lead to *crowding* 

Tournament selection:

- Pick  $h_1, h_2$  at random with uniform prob.
- With probability p, select the more fit.

#### Rank selection:

- Sort all hypotheses by fitness
- Prob of selection is proportional to rank

# GABIL [DeJong et al. 1993]

Learn disjunctive set of propositional rules, competitive with C4.5

#### Fitness:

$$Fitness(h) = (correct(h))^2$$

## Representation:

IF  $a_1 = T \wedge a_2 = F$  THEN c = T; IF  $a_2 = T$  THEN c = F represented by

## Genetic operators: ???

- want variable length rule sets
- want only well-formed bitstring hypotheses

# Crossover with Variable-Length Bitstrings

Start with

$$h_2: 01 \ 11 \ 0 \ 10 \ 01 \ 0$$

- 1. choose crossover points for  $h_1$ , e.g., after bits 1, 8
- 2. now restrict points in  $h_2$  to those that produce bitstrings with well-defined semantics, e.g.,  $\langle 1, 3 \rangle$ ,  $\langle 1, 8 \rangle$ ,  $\langle 6, 8 \rangle$ .

if we choose  $\langle 1, 3 \rangle$ , result is

### GABIL Extensions

Add new genetic operators, also applied probabilistically:

- 1. AddAlternative: generalize constraint on  $a_i$  by changing a 0 to 1
- 2. Drop Condition: generalize constraint on  $a_i$  by changing every 0 to 1

And, add new field to bitstring to determine whether to allow these

So now the learning strategy also evolves!

### GABIL Results

Performance of GABIL comparable to symbolic rule/tree learning methods C4.5, ID5R, AQ14

Average performance on a set of 12 synthetic problems:

- GABIL without AA and DC operators: 92.1% accuracy
- GABIL with AA and DC operators: 95.2% accuracy
- symbolic learning methods ranged from 91.2 to 96.6

#### Schemas

How to characterize evolution of population in GA? Schema = string containing 0, 1, \* ("don't care")

- Typical schema: 10\*\*0\*
- Instances of above schema: 101101, 100000, ...

Characterize population by number of instances representing each possible schema

• m(s,t) = number of instances of schema s in pop at time t

## Consider Just Selection

- $\bar{f}(t)$  = average fitness of pop. at time t
- m(s,t) = instances of schema s in pop at time t
- $\hat{u}(s,t)$  = ave. fitness of instances of s at time t

Probability of selecting h in one selection step

$$Pr(h) = \frac{f(h)}{\sum_{i=1}^{n} f(h_i)}$$
$$= \frac{f(h)}{n\bar{f}(t)}$$

Probabilty of selecting an instance of s in one step

$$\Pr(h \in s) = \sum_{h \in s \cap p_t} \frac{f(h)}{n \bar{f}(t)}$$
$$= \frac{\hat{u}(s, t)}{n \bar{f}(t)} m(s, t)$$

Expected number of instances of s after n selections

$$E[m(s,t+1)] = \frac{\hat{u}(s,t)}{\overline{f}(t)}m(s,t)$$

交叉操作对模式的影响:

$$A = 0 1 1 1 0 0 0$$

$$A = 0 1 1 | 1 0 0 0$$

S1 比 S2 更不易生存

模式 S 被破坏的概率为 d(S)/(L-1), 生存的概率为 1-d(S)/(L-1) 被挑选做交叉的概率 Pc

模式 S 生存的概率计算如下:

$$Ps \ge 1 - Pc \bullet \frac{d(S)}{L-1}$$

变异操作对模式的影响:

以概率 Pm 随机改变一个位上的值,单个位存活的概率为(1-Pm). 设模式 S 有 O(S)个确定位,模式 S 被保留下来的概率为:

$$(1-Pm)^{O(S)}$$

#### Schema Theorem

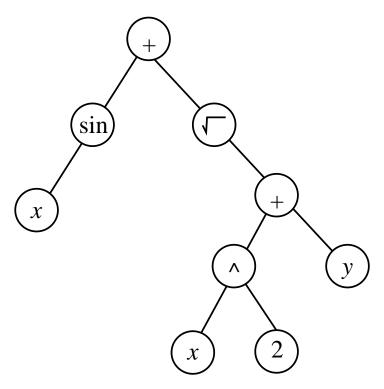
$$E[m(s,t+1)] \ge \frac{\hat{u}(s,t)}{\bar{f}(t)} m(s,t) \left(1 - p_c \frac{d(s)}{l-1}\right) (1 - p_m)^{o(s)}$$

- m(s,t) = instances of schema s in pop at time t
- $\bar{f}(t)$  = average fitness of pop. at time t
- $\hat{u}(s,t)$  = ave. fitness of instances of s at time t
- $p_c$  = probability of single point crossover operator
- $p_m = \text{probability of mutation operator}$
- l = length of single bit strings
- o(s) number of defined (non "\*") bits in s
- d(s) = distance between leftmost, rightmostdefined bits in s

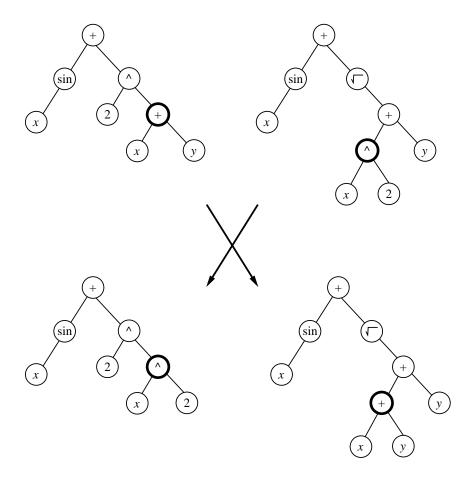
# Genetic Programming

Population of programs represented by trees

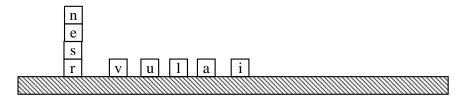
$$\sin(x) + \sqrt{x^2 + y}$$



# Crossover



### Block Problem



Goal: spell UNIVERSAL

#### Terminals:

- CS ("current stack") = name of the top block on stack, or F.
- TB ("top correct block") = name of topmost correct block on stack
- NN ("next necessary") = name of the next block needed above TB in the stack

#### Primitive functions:

- (MS x): ("move to stack"), if block x is on the table, moves x to the top of the stack and returns the value T. Otherwise, does nothing and returns the value F.
- (MT x): ("move to table"), if block x is somewhere in the stack, moves the block at the top of the stack to the table and returns the value T. Otherwise, returns F.
- (EQ x y): ("equal"), returns T if x equals y, and returns F otherwise.
- (NOT x): returns T if x = F, else returns F
- (DU x y): ("do until") executes the expression x repeatedly until expression y returns the value T

## Learned Program

Trained to fit 166 test problems

Using population of 300 programs, found this after 10 generations:

(EQ (DU (MT CS)(NOT CS)) (DU (MS NN)(NOT NN)) )

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## Genetic Programming

More interesting example: design electronic filter circuits

- Individuals are programs that transform begining circuit to final circuit, by adding/subtracting components and connections
- Use population of 640,000, run on 64 node parallel processor
- Discovers circuits competitive with best human designs

## GP for Classifying Images

[Teller and Veloso, 1997]

Fitness: based on coverage and accuracy

#### Representation:

- Primitives include Add, Sub, Mult, Div, Not, Max, Min, Read, Write, If-Then-Else, Either, Pixel, Least, Most, Ave, Variance, Difference, Mini, Library
- Mini refers to a local subroutine that is separately co-evolved
- Library refers to a global library subroutine (evolved by selecting the most useful minis)

## Genetic operators:

- Crossover, mutation
- Create "mating pools" and use rank proportionate reproduction

## Biological Evolution

Lamark (19th century)

- Believed individual genetic makeup was altered by lifetime experience
- But current evidence contradicts this view

What is the impact of individual learning on population evolution?

#### **Baldwin Effect**

#### Assume

- Individual learning has no direct influence on individual DNA
- But ability to learn reduces need to "hard wire" traits in DNA

#### Then

- Ability of individuals to learn will support more diverse gene pool
  - Because learning allows individuals with various "hard wired" traits to be successful
- More diverse gene pool will support faster evolution of gene pool
- $\rightarrow$  individual learning (indirectly) increases rate of evolution

### Baldwin Effect

### Plausible example:

- 1. New predator appears in environment
- 2. Individuals who can learn (to avoid it) will be selected
- 3. Increase in learning individuals will support more diverse gene pool
- 4. resulting in faster evolution
- 5. possibly resulting in new non-learned traits such as instintive fear of predator

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# Computer Experiments on Baldwin Effect

# [Hinton and Nowlan, 1987]

Evolve simple neural networks:

- Some network weights fixed during lifetime, others trainable
- Genetic makeup determines which are fixed, and their weight values

#### Results:

- With no individual learning, population failed to improve over time
- When individual learning allowed
  - Early generations: population contained many individuals with many trainable weights
  - Later generations: higher fitness, while number of trainable weights decreased

# Summary: Evolutionary Programming

- ullet Conduct randomized, parallel, hill-climbing search through H
- Approach learning as optimization problem (optimize fitness)
- Nice feature: evaluation of Fitness can be very indirect
  - consider learning rule set for multistep decision making
  - no issue of assigning credit/blame to indiv.steps

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