view_frames Result Recorded at time: 38112.819 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 0.000 (38112.819 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec _kinect2_link base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.250 Hz Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 38112.805 (0.014 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.000 sec _kinect2_ir_link shoulder_link base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.250 Hz Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 38112.805 (0.014 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.000 sec _kinect2_ir_optical_frame _kinect2_rgb_link upper_arm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.250 Hz Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 38112.805 (0.014 sec old) Buffer length: 0.000 sec Buffer length: 4.000 sec _kinect2_rgb_optical_frame forearm_link Broadcaster: /robot_state_publisher Average rate: 50.250 Hz Most recent transform: 38112.805 (0.014 sec old) Buffer length: 4.000 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 50.250 Hz Most recent transform: 38112.805 (0.014 sec old) Buffer length: 4.000 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 50.250 Hz Most recent transform: 38112.805 (0.014 sec old) Buffer length: 4.000 sec wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 0.000 (38112.819 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec ee_link gripper_base_link tool0 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.250 Hz Average rate: 50.250 Hz Average rate: 50.250 Hz Average rate: 50.250 Hz Most recent transform: 38112.805 (0.014 sec old) Most recent transform: 38112.805 (0.014 sec old) Most recent transform: 38112.805 (0.014 sec old) Most recent transform: 38112.805 (0.014 sec old) Buffer length: 4.000 sec Buffer length: 4.000 sec Buffer length: 4.000 sec Buffer length: 4.000 sec gripper_finger2_knuckle_link gripper_finger1_knuckle_link gripper_finger2_inner_knuckle_link gripper_finger1_inner_knuckle_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.250 Hz Average rate: 50.250 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 38112.805 (0.014 sec old) Most recent transform: 0.000 (38112.819 sec old) Most recent transform: 38112.805 (0.014 sec old) Most recent transform: 0.000 (38112.819 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.000 sec Buffer length: 4.000 sec gripper_finger2_finger_link gripper_finger2_finger_tip_link gripper_finger1_finger_tip_link gripper_finger1_finger_link