# Computational Finance



## **Binomial Trees**

## **Setup and Notation**

- Consider a market containing three assets: a risk-free bond with price  $B_t=e^{rt}$ , a stock  $S_t$ , and a (European style) derivative  $C_t$  with maturity T and payoff  $C_T(S_T)$  that we wish to price.
- ullet Split the time interval [0,T] into N parts of length  $\delta t=T/N$  and let  $t_i=i\delta t, i=0,\ldots,N$ , so  $t_0=0$  and  $t_N=T$ .
- Write  $\{B_i,S_i,C_i,i=0,\ldots,N\}$  for asset prices at time  $t_i=i\delta t$ . E.g.,  $C_1\equiv C_{\delta t},C_N\equiv C_T$ , and  $B_i=e^{r\,i\delta t}$ .
- The stock price  $S_i$  either moves up to  $S_{i+1}(u)$  or down to  $S_{i+1}(d)$ . Usually  $S_{i+1}(u)=S_iu$  and  $S_{i+1}(d)=S_id$  for fixed u and d, often u=1/d.

#### The One-Period Case: N=1.

ullet To find  $C_0$  , construct a replicating portfolio  $V_t = \phi S_t + \psi B_t$  in such a way that

$$egin{aligned} V_T(u) &= \phi S_0 u + \psi B_0 e^{rT} = C(S_0 u) =: c_u, \ V_T(d) &= \phi S_0 d + \psi B_0 e^{rT} = C(S_0 d) =: c_d. \end{aligned}$$

• Solving for  $\phi$  and  $\psi B_0$  yields

$$\phi = rac{c_u - c_d}{S_0 u - S_0 d}, \quad \psi B_0 = e^{-rT} \left( c_u - rac{c_u - c_d}{S_0 u - S_0 d} S_0 u 
ight).$$

ullet  $\phi$  is known as the *hedge ratio*, or *delta* of the derivative.

• Therefore,

$$egin{align} V_0 &= \phi S_0 + \psi B_0 \ &= rac{c_u - c_d}{u - d} + e^{-rT} \left( c_u - rac{c_u - c_d}{u - d} u 
ight) \ &= e^{-rT} \left( c_u rac{e^{rT} - d}{u - d} + c_d rac{u - e^{rT}}{u - d} 
ight) \ &= e^{-rT} \left( c_u p + c_d [1 - p] 
ight). \end{split}$$

ullet In the absence of arbitrage, we must have  $C_0=V_0$  , and hence  $C_0=e^{-rT}\left(c_up+c_d[1-p]
ight)$  .

- Interpretation:  $p \in [0,1]$ , so p is a probability and  $C_0$  is an expectation.
- p and 1-p are known as risk-neutral probabilities. We collect these in the risk-neutral probability measure  $\mathbb{Q}$ , so that  $\mathbb{Q}[u]=1-\mathbb{Q}[d]=p$ .
- We write

$$C_0 = e^{-rT} \mathbb{E}^\mathbb{Q}[C_T] = e^{-rT} \left( c_u p + c_d [1-p] 
ight).$$

• The probabilities are called risk-neutral because if these were the true probabilities, all assets would earn the risk-free rate. E.g.,

$$\mathbb{E}^{\mathbb{Q}}[S_T] = S_0 e^{rT},$$

which you should verify.

ullet Note that we do *not* assume that  $p=\mathbb{P}[u]$ . The actual probability  $\mathbb{P}[u]$  is *irrelevant* for the value  $C_0$  of the derivative (as long as it is not zero or one).

# The N-Period Case

ullet Next, consider a two-period model (N=2):

- This stock price tree is *recombinant*: an up move followed by a down move leads to the same value as a down move followed by an up move. This is a consequence of u and d being fixed and independent of the price.
- ullet Advantage: the number of nodes remains managable (N+1 at the Nth step, rather than  $2^N$ ).
- ullet This leads to a derivative price tree that is also recombinant. Given a recombinant stock price tree, this follows from the fact that  $C_N$  only depends on  $S_N$ .
- ullet Path-dependent derivatives where  $C_N=C(S_i,i\leq N)$  may lead to non-recombinant trees.

$$C_N(uu)$$
  $\nearrow$   $C_1(u)$   $\nearrow$   $C_1(u)$   $\nearrow$   $C_N(ud) = C_N(du)$   $\nearrow$   $C_1(d)$   $\nearrow$   $C_N(dd)$ 

- Only the payoffs  $C_N(uu)$ ,  $C_N(ud)$  and  $C_N(dd)$  are known, and we wish to obtain  $C_0$ ,  $C_1(u)$  and  $C_1(d)$ .
- ullet At time  $t=\delta t$  (after one step), we know whether the stock has gone up or down.
- If it has gone up, then only the branch from  $C_1(u)$  to  $C_N(uu)$  or C(ud) is relevant.
- Since this is just a binary model, we can price  $C_1(u)$  (and  $C_1(d)$ ) by noarbitrage:

$$C_1(u) = e^{-r\,\delta t}\left[C_N(uu)p + C_N(ud)(1-p)
ight] = e^{-r\,\delta t}\mathbb{E}^{\mathbb{Q}}\left[C_N|S_1 = S_0u
ight], \ C_1(d) = e^{-r\,\delta t}\left[C_N(du)p + C_N(dd)(1-p)
ight] = e^{-r\,\delta t}\mathbb{E}^{\mathbb{Q}}\left[C_N|S_1 = S_0d
ight].$$

• Recall that  $p=\dfrac{e^{r\,\delta t}-d}{u-d}$ ; in general the risk-neutral probability might depend on  $S_1$ , but in this case it doesn't, because r,u and d are the same at each step.

- The values  $C_1(u)$  and  $C_1(d)$  are the market prices (under the no-arbitrage condition), so the derivative can be sold at this price at time  $t=\delta t$ , depending on whether the stock goes up or down.
- ullet Therefore, at time t=0 we know that the two possible payoffs in the next period are  $C_1(u)$  and  $C_1(d)$ , and so

$$egin{aligned} C_0 &= e^{-r\,\delta t} \left[ C_1(u) p + C_1(d) (1-p) 
ight] \ &= e^{-rT} \left[ C_N(uu) p^2 + C_N(ud) [p(1-p) + (1-p)p] 
ight. \ &+ C_N(dd) (1-p)^2 
ight] \ &= e^{-rT} \mathbb{E}^{\mathbb{Q}} \left[ C_N 
ight]. \end{aligned}$$

• In the N-period case, denote by  $\mathcal{F}_t$  the information at time t, i.e., whether the stock went up or down at each  $s \leq t$ . Then, at each step in the tree,

$$C_t = e^{-r\delta t} \mathbb{E}^{\mathbb{Q}}[C_{t+\delta t}|\mathcal{F}_t].$$

- ullet Starting at  $C_T$ , this can be solved backwards until one arrives at the price at t=0.
- At every step in the tree, we have that

$$C_t = e^{-r(T-t)} \mathbb{E}^{\mathbb{Q}}[C_T | \mathcal{F}_t],$$

and in particular

$$C_0 = e^{-rT} \mathbb{E}^{\mathbb{Q}}[C_T].$$

• This is known as the *risk neutral pricing formula*: the price of an attainable European claim equals the expected discounted payoff, but where expectations are under a set of risk-neutral probabilities  $\mathbb{Q}$ .

- It is worth noting that the hedging strategy is dynamic: let  $\phi_{i+1}$  and  $\psi_{i+1}$  denote the number of shares and cash bonds held from  $t_i$  till  $t_{i+1}$ .
- The single-period binary model implies

$$\phi_{i+1} = rac{C_{i+1}(u) - C_{i+1}(d)}{S_{i+1}(u) - S_{i+1}(d)}.$$

- Between  $t_i$  and  $t_{i+1}$ , the value changes from  $V_i$  to  $\phi_{i+1}S_{i+1}+\psi_{i+1}B_{i+1}$ , after which rebalancing occurs.
- ullet The strategy is *replicating*: after N steps, the value is  $V_N = \phi_N S_N + \psi_N B_N = C_N$ .
- It can also be verified to be *self-financing*:

$$V_i = \phi_i S_i + \psi_i B_i = \phi_{i+1} S_i + \psi_{i+1} B_i,$$

which may be rewritten as

$$V_{i+1} - V_i = \phi_{i+1}(S_{i+1} - S_i) + \psi_{i+1}(B_{i+1} - B_i).$$

ullet Thus, a dynamic strategy allows us to hedge against more than two states at time T with only two assets.

## Martingales and the FTAP

- A sequence of random variables such as  $\{S_i\}_{i\geq 0}$  is called a *stochastic* process.
- Observe that under Q,

$$\mathbb{E}^{\mathbb{Q}}\left[S_{i+1}|\mathcal{F}_i
ight] = S_iig(up+d(1-p)ig) = S_ie^{r\delta t}.$$

ullet Define the discounted stock price process  ${ ilde S}_i=S_ie^{-ir\delta t}.$  Then

$$\mathbb{E}^{\mathbb{Q}}\left[ ilde{S}_{i+1}|\mathcal{F}_i
ight] = S_i e^{r\delta t} e^{-(i+1)r\delta t} = S_i e^{-ir\delta t} = ilde{S}_i.$$

This is the defining property of a martingale. Hence, the risk-neutral measure is also called a martingale measure.

- ullet  $\mathbb{Q}$  and  $\mathbb{P}$  are equivalent if  $\mathbb{Q}[A]=0 \Longleftrightarrow \mathbb{P}[A]=0.$
- Fundamental Theorem of Asset Pricing: if (and only if) the market is arbitrage free, then there exists an equivalent martingale measure  $\mathbb Q$  under which discounted stock prices are martingales, and the risk neutral pricing formula holds.  $\mathbb Q$  is unique if the market is complete.

#### **Tree Calibration**

- ullet We are given  $S_0, T$  (measured in years), and the function  $C_T=C(S_T)$ ; for a European call,  $C(S_T)=\max{\{(S_T-K),0\}}.$
- ullet We have to choose the number N of steps, and hence  $\delta t=T/N$ . This involves a trade-off between computational burden and accuracy.
- $r = \log(1+R)$ , where R is the current value (per annum) of a suitable risk-free interest rate (e.g. LIBOR) over the holding period of the option.
- ullet u and d are chosen to match the stock price volatility: under  $\mathbb{Q}$ ,

$$R_{i+1} \equiv \log(S_{i+1}/S_i) = egin{cases} \log u & ext{with probability $p$,} \ \log d = -\log u & ext{with probability $1-p$.} \end{cases}$$

• Thus,

$$\mathbb{E}^\mathbb{Q}[R_{i+1}] = 2p-1 \quad ext{and} \ \sigma^2 \delta t := ext{var}^\mathbb{Q}(R_{i+1}) = (\log u)^2 \left[1-(2p-1)^2
ight] pprox (\log u)^2.$$

Hence we choose

$$u=e^{\sigma\sqrt{\delta t}}, \qquad d=1/u=e^{-\sigma\sqrt{\delta t}}.$$

- Possible estimates for  $\sigma$ :
  - Annualized historical volatility (see last week):

$$\sigma = \sqrt{252}\sigma_{t,HIST}$$

• Implied volatility: the value of  $\sigma$  that equates model price and market price (see later).

# **Binomial Trees in Python**

- We will look at several Python implementations and compare their speed.
- The first implementation is a "loopy" version that could be written in a similar way in most imperative programming languages.

```
In [1]:
        import numpy as np
         def calltree(S0, K, T, r, sigma, N):
             European call price based on an N-step binomial tree.
             deltaT = T/float(N)
             u=np.exp(sigma * np.sqrt(deltaT))
             d=1/u
             p=(np.exp(r*deltaT) - d)/(u-d)
             C=np.zeros([N+1,N+1])
             S=np.zeros([N+1,N+1])
             piu=np.exp(-r*deltaT)*p
             pid=np.exp(-r*deltaT)*(1-p)
             for i in xrange(N+1):
                 for j in xrange(i, N+1):
                     S[i,j]=S0*u**j*d**(2*i)
             for i in xrange(N+1):
                 C[i,N]=\max(0, S[i,N]-K)
             for j in xrange(N-1,-1,-1):
                 for i in xrange(j+1):
                     C[i,j] = piu * C[i,j+1] + pid * C[i+1,j+1]
             return C[0,0]
```

• Let's see if it works:

```
In [2]: S0=50.;K=50.;T=5.0/12;r=.1;sigma=.4;N=500;
calltree(S0, K, T, r, sigma, N)
```

Out[2]: 6.1139619792052535

Great. Now let's look at the speed:

```
In [3]: %timeit calltree(S0, K, T, r, sigma, N) #ipython magic for timing things
```

1 loop, best of 3: 178 ms per loop

- Loops tend to be slow in Python. It is often preferable to write code in a vectorized style.
- This means calling NumPy ufuncs on entire vectors of data, so that the looping happens inside NumPy, i.e., in compiled C code (which means it's fast).

```
In [4]:
        def calltree numpy(S0, K, T, r, sigma, N):
             European call price based on an N-step binomial tree.
             11 11 11
             deltaT = T/float(N)
             u=np.exp(sigma * np.sqrt(deltaT))
             d=1/u
             p=(np.exp(r*deltaT) - d)/(u-d)
             piu=np.exp(-r*deltaT)*p
             pid=np.exp(-r*deltaT)*(1-p)
             C=np.zeros([N+1,N+1])
             S=S0*u**np.arange(N+1)*d**(2*np.arange(N+1)[:, np.newaxis])
             S=np.triu(S) #keep only upper triangular part
             C[:,N]=np.maximum(0, S[:,N]-K) #note maximum in place of max
             for j in xrange(N-1,-1,-1):
                 C[:j+1,j] = piu * C[:j+1,j+1] + pid * C[1:j+2,j+1]
             return C[0,0]
```

- Let's verify that both implementations give the same answer.
- We'll use NumPy's allclose function, which tests if all elements of an array are close to zero.

```
In [5]: np.allclose(calltree(S0, K, T, r, sigma, N), calltree_numpy(S0, K, T, r, sigma, N))
Out[5]: True
```

• Now let's time it:

- A third option is to use Numba (<u>user guide (http://numba.pydata.org/numba-doc/latest/index.html)</u>).
- Numba implements a just in time compiler. It can compile certain (array-heavy) code to native machine code.
- If Numba is able to compile your code, then the speed is often comparable to C.
- All we need to do is import the package, and then add a *decorator* to our function.
- Other than that, the code is exactly the same as our first attempt.

```
In [7]:
        from numba import jit
        @jit
        def calltree numba(S0, K, T, r, sigma, N):
             European call price based on an N-step binomial tree.
             deltaT = T/float(N)
             u=np.exp(sigma * np.sqrt(deltaT))
             d=1/u
             p=(np.exp(r*deltaT) - d)/(u-d)
             C=np.zeros([N+1,N+1])
             S=np.zeros([N+1,N+1])
             piu=np.exp(-r*deltaT)*p
             pid=np.exp(-r*deltaT)*(1-p)
             for i in xrange(N+1):
                 for j in xrange(i, N+1):
                     S[i,i]=S0*u**i*d**(2*i)
             for i in xrange(N+1):
                 C[i,N]=\max(0, S[i,N]-K)
             for j in xrange(N-1,-1,-1):
                 for i in xrange(j+1):
                     C[i,j] = piu * C[i,j+1] + pid * C[i+1,j+1]
             return C[0,0]
```

• Check that it gives the right answer:

In [8]: np.allclose(calltree(S0, K, T, r, sigma, N), calltree\_numba(S0, K, T, r, sigma, N))

Out[8]: True

• The moment of truth:

In [9]: %timeit calltree\_numba(S0, K, T, r, sigma, N)

100 loops, best of 3: 4.23 ms per loop

- Not bad at all. We essentially match our NumPy implementation.
- There's one more thing we might try: what if we JIT-compile the vectorized version?
- Instead of writing out the whole function again, we'll use an alternative way to invoke the JIT compiler:

```
In [10]: calltree_numpy_numba=jit(calltree_numpy)
    np.allclose(calltree(S0, K, T, r, sigma, N), calltree_numpy_numba(S0, K, T, r, sigma, N))
Out[10]: True
In [11]: %timeit calltree_numpy_numba(S0, K, T, r, sigma, N)
    1000 loops, best of 3: 1.1 ms per loop
```

- Wow. On my office machine, it's three times as fast as the pure NumPy version, and 150 times as fast as our naive implementation.
- Looking at the absolute timings, the improvements may seem small, but keep in mind that you may need to call these functions many many times.
- Other tools for compiling Python to native code include <u>Cython</u>
   (<a href="http://cython.org/">http://cython.org/</a>) and <u>Pythran (<a href="https://pythonhosted.org/pythran/">Pythran (<a href="https://pythonhosted.org/pythran/">https://pythonhosted.org/pythran/</a>).
  </u>

## A Closed Form for European Options

• The price of a European option

$$C_0 = e^{-rT}\mathbb{E}^{\mathbb{Q}}\left[\max(S_T - K), 0
ight]$$

depends only on  $S_T$ , so there is no need to use a tree explicitly to evaluate it.

ullet Let k denote the number of up moves of the stock , so that N-k is the number of down moves. Then

$$S_T = S_0 u^k d^{N-k} = S_0 u^{2k-N},$$

where under  $\mathbb{Q}$  ,  $k \sim \mathrm{Bin}(N,p)$  , with pmf

$$f(k;N,p)=inom{N}{k}p^k(1-p)^{N-k}$$
 . Thus

$$C_0 = e^{-rT} \sum_{k=0}^N f(k;N,p) \max(S_0 u^k d^{N-k} - K,0).$$

ullet Let a denote the minimum number of up moves so that  $S_T>K$ , i.e., the smallest integer greater than  $N/2+\log(K/S_0)/(2\log u)$  . Then

$$C_0 = e^{-rT} \sum_{k=a}^N f(k;N,p) \left[ S_0 u^k d^{N-k} - K 
ight].$$

- The second term is  $[1-F(a-1;N,p)]e^{-rT}K=\bar{F}(a-1;N,p)e^{-rT}K, \text{ where } F \text{ is the binomial cdf and } \bar{F} \text{ is the survivor function.}$
- ullet Let  $p_*=e^{-r\delta t}pu.$  The first term is

$$e^{-rT}S_0\sum_{k=a}^Ninom{N}{k}p^k(1-p)^{N-k}u^kd^{N-k}=S_0$$

$$\sum_{k=a}^N inom{N}{k} p_*^k (1-p_*)^{N-k}.$$

• Putting things together,

$$egin{aligned} C_0 &= S_0 ar{F}(a-1;N,p_*) - ar{F}(a-1;N,p) e^{-rT} K \ &= S_0 \mathbb{Q}^* (S_T > K) - \mathbb{Q} (S_T > K) e^{-rT} K \end{aligned}$$

• You will be implementing this in a homework exercise.

#### The Black-Scholes Formula as Continuous Time Limit

- ullet Let's consider what happens if we let  $N o\infty$ .
- ullet First, a first-order Taylor expansion, together with l'Hopital's rule, can be used to show that, for small  $\delta t$ ,

$$ppproxrac{1}{2}\Biggl(1+\sqrt{\delta t}rac{r-rac{1}{2}\sigma^2}{\sigma}\Biggr)\,.$$

• Similarly,

$$p^* pprox rac{1}{2} \Biggl( 1 + \sqrt{\delta t} rac{r + rac{1}{2} \sigma^2}{\sigma} \Biggr) \, .$$

ullet Next, Let  $X_T \equiv \log S_T$  . Then

$$X_T = \log S_0 + \sum_{i=1}^N R_i = \log S_0 + \sigma \sqrt{\delta t} (2k-N),$$

because  $R_i$  is either  $\log u$  or  $\log d = -\log u$ .

- As  $k \sim \mathrm{Bin}(N,p)$ , we have  $\mathbb{E}^\mathbb{Q}[k] = Np$ ,  $\mathrm{Var}^\mathbb{Q}[k] = Np(1-p)$ , and  $\mathbb{E}^\mathbb{Q}[X_T] = \log S_0 + \sigma \sqrt{\delta t} \, N(2p-1) o \log S_0 + (r-\frac{1}{2}\sigma^2)T$   $\mathrm{Var}^\mathbb{Q}[X_T] = \sigma^2 \delta t 4Np(1-p) o \sigma^2 T.$
- ullet Finally, as  $N o \infty$ , the distribution of  $X_T$  tends to a normal. This follows from the *central limit theorem* and the fact that  $X_T$  is the sum of N i.i.d. terms.

ullet Thus, as  $N o\infty$ ,

$$egin{aligned} \mathbb{Q}(S_T > K) &= \mathbb{Q}(X_T > \log K) = \mathbb{Q}\left(rac{X_T - \mathbb{E}^\mathbb{Q}[X_T]}{\sqrt{\mathrm{Var}^\mathbb{Q}[X_T]}} > rac{\log K - \mathbb{E}^\mathbb{Q}[X_T]}{\sqrt{\mathrm{Var}^\mathbb{Q}[X_T]}}
ight) \ &= 1 - \Phi\left(rac{\log K - \mathbb{E}^\mathbb{Q}[X_T]}{\sqrt{\mathrm{Var}^\mathbb{Q}[X_T]}}
ight) =: 1 - \Phi(-d_2) = \Phi(d_2), \end{aligned}$$

where  $\Phi$  is the standard normal cdf and

$$d_2 \equiv rac{\mathbb{E}^{\mathbb{Q}}[X_T] - \log K}{\sqrt{\mathrm{Var}^{\mathbb{Q}}[X_T]}} = rac{\log(S_0/K) + (r - rac{1}{2}\sigma^2)T}{\sigma\sqrt{T}}.$$

ullet The same argument can be used to show that as  $N o\infty$ ,  $\mathbb{Q}^*(S_T>K)=\Phi(d_1),$  where

$$d_1 \equiv d_2 + \sigma \sqrt{T} = rac{\log(S_0/K) + (r + rac{1}{2}\sigma^2)T}{\sigma \sqrt{T}}.$$

• In summary, we have derived the Black-Scholes formula

$$egin{aligned} C_0 &= S_0 \Phi(d_1) - e^{-rT} K \Phi(d_2) \ &=: BS(S_0, K, T, r, \sigma). \end{aligned}$$

• Implementation in Python:

• Note that as written, the function can operate on arrays of strikes:

```
In [14]: Ks=np.linspace(K/2., 2.*K, 5)
blackscholes(S0, Ks, T, r, sigma)
Out[14]: array([ 26.0260491 , 9.77944137, 2.00056039, 0.27962697, 0.0331146 ])
```

## **American Options**

- Unlike a European call, an American call with price  $C_t^{Am}$  can be exercised at any time before it matures. When exercised at  $t \leq T$ , it pays  $\max(S_t K, 0)$ . Hence the call will be exercised early if at time t,  $S_t K > C_t^{Am}$ .
- Recall put-call parity:  $C_t-P_t=S_t-e^{-r(T-t)}K$ , which implies (for r>0) \begin{align}  $C_t$ \\geq  $S_t-e^{-r(T-t)}K$ \\geq  $S_t-K$ \\ P\_t\&\\geq Ke^{-r(T-t)}-S\_t.\\end{align}
- As  $C_t^{Am} \geq C_t$ , an American call is therefore never exercised early (in the absence of dividends).
- There is no closed-form expression for the price of an American put option, so numerical methods are needed. Binomial trees are a popular choice.

- This works as follows:
  - lacksquare At step N, the price of the put is  $P_N^{Am} = \max(K-S_N,0)$ , just like for a European put.
  - At step N-1, the *continuation value* of the option is  $e^{-r\delta t}\mathbb{E}^\mathbb{Q}[P_N^{Am}]$ . Early exercise yields  $K-S_{N-1}$ , so  $P_{N-1}^{Am}=\max(e^{-r\delta t}\mathbb{E}^\mathbb{Q}[P_N^{Am}|\mathcal{F}_{N-1}],K-S_{N-1}).$
  - lacksquare This is iterated backwards until  $P_0^{Am}$ .
- The implementation is part of the homework exercise.

## Implied Volatility

• The implied volatility (IV,  $\sigma_I$ ) of an option is that value of  $\sigma$  which equates the BS model price to the observed market price  $C_0^{obs}$ , i.e., it solves

$$C_0^{obs} = BS(S_0, K, T, r, \sigma_I).$$

- If the BS assumptions were correct, then any option traded on the asset should have the same IV, which should in turn equal historical volatility.
- ullet In practice, options with different strikes K and hence moneyness  $K/S_0$  have different IVs: volatility smile or smirk/skew. Also, options with different times to maturity have different IVs: volatility term structure.
- These phenomena are evidence of a failure of the assumptions of the Black-Scholes model, most importantly that of a constant volatility  $\sigma$ .

- In practice, the BS formula is used as follows: the implied volatility is computed for options that are already traded in the market, for different strikes and maturities. This leads to the *IV surface*.
- When a new option is issued, the implied volatility corresponding to its strike and time to maturity is determined by interpolation on the surface. The BS formula then gives the corresponding price.
- Mathematically, the IV is the root (or zero) of the function

$$f(\sigma_I) = BS(S_0,K,T,r,\sigma_I) - C_0^{obs}.$$

• In Python, root finding can be done via SciPy's brentq function. In its simplest form, it takes 3 arguments: the unary function  $f(\cdot)$ , and a lower bound L and upper bound U such that [L,U] contains exactly one root of f.

• <u>Tehranchi (2016) (https://arxiv.org/abs/1512.06812)</u> shows that for European calls,

$$-\Phi^{-1}\left(rac{S_0-C_0^{obs}}{2\min(S_0,e^{-rT}K)}
ight) \leq rac{\sqrt{T}}{2}\sigma_I \leq -\Phi^{-1}\left(rac{S_0-C_0^{obs}}{S_0+e^{-rT}K}
ight).$$

• It remains to transform our objective function into a unary (single argument) function, through *partial function application* via, e.g., an anonymous function:

```
In [15]: from scipy.optimize import brentq
def impvol(S0, K, T, r, C_obs, Type='call'):
    """Implied Black-Scholes volatility."""
    if Type=='put': #convert to call price via parity
        C_obs=C_obs+S0-np.exp(-r*T)*K
    L=-2*norm.ppf((S0-C_obs)/(2.0*min(S0, np.exp(-r*T)*K)))/np.sqrt(T)
    U=-2*norm.ppf((S0-C_obs)/(S0+np.exp(-r*T)*K))/np.sqrt(T)
    f=lambda s: blackscholes(S0, K, T, r, s)-C_obs #partial application: f(s)=BS(S0, K, T, r, s)-C_obs
    return brentq(f, L, U)
```

```
In [16]: C_obs=6.0 #for illustration
    IV=impvol(S0, K, T, r, C_obs); (IV, blackscholes(S0, K, T, r, IV))
```

Out[16]: (0.39056035816043205, 6.0)

