# Lecture 1: Probability

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## Probability

### **Probability Space**

A sample space  $\Omega$  is a collection of all possible outcomes. It is a set of things.

An event A is a subset of  $\Omega$ . It is something of interest on the sample space.

A  $\sigma$ -field, denoted by  $\mathcal{F}$ , is a collection of  $(A_i \subseteq \Omega)_{i \in \mathbb{N}}$  events such that

- (i)  $\emptyset \in \mathcal{F}$ ;
- (ii) if an event  $A \in \mathcal{F}$ , then  $A^c \in \mathcal{F}$ ;
- (iii) if  $A_i \in \mathcal{F}$  for  $i \in \mathbb{N}$ , then  $\bigcup_{i \in \mathbb{N}} A_i \in \mathcal{F}$ .

It is easy to show that  $\Omega \in \mathcal{F}$  and  $\bigcap_{i \in \mathbb{N}} A_i \in \mathcal{F}$ . The  $\sigma$ -field can be viewed as a well-organized structure built on the ground of the sample space. The pair  $(\Omega, \mathcal{F})$  is called a *measure space*.

Let  $\mathcal{G} = \{B_1, B_2, \ldots\}$  be an arbitrary collection of sets, not necessarily a  $\sigma$ -field. We say  $\mathcal{F}$  is the smallest  $\sigma$ -field generated by  $\mathcal{G}$  if  $\mathcal{G} \subseteq \mathcal{F}$ , and  $\mathcal{F} \subseteq \tilde{\mathcal{F}}$  for any  $\tilde{\mathcal{F}}$  such that  $\mathcal{G} \subseteq \tilde{\mathcal{F}}$ . A Borel  $\sigma$ -field  $\mathcal{R}$  is the smallest  $\sigma$ -field generated by the open sets on the real line  $\mathbb{R}$ .

A function  $\mu:(\Omega,\mathcal{F})\mapsto [0,\infty]$  is called a *measure* if it satisfies

(i)  $\mu(A) \geq 0$  for all  $A \in \mathcal{F}$ ;

(ii) if  $A_i \in \mathcal{F}$ ,  $i \in \mathbb{N}$ , are mutually disjoint, then

$$\mu\left(\bigcup_{i\in\mathbb{N}}A_i\right)=\sum_{i\in\mathbb{N}}\mu\left(A_i\right).$$

Measure can be understand as weight or length in our daily life experience. In particular, we call  $\mu$  a probability measure if  $\mu(\Omega) = 1$ . A probability measure is often denoted as P. The triple  $(\Omega, \mathcal{F}, P)$  is called a probability space.

For a fixed measure space  $(\Omega, \mathcal{F})$ , we can have different probability measure P on it.

**Example** Let  $\Omega = \{a, b\}$ ,  $\mathcal{F} = \mathcal{P}(\Omega)$  where  $\mathcal{P}(\Omega)$  denote the power set of  $\Omega$ , i.e. the collection of all subsets of  $\Omega$ . Define  $P_1, P_2 : (\Omega, \mathcal{F}) \to [0, \infty)$  by

(i) 
$$P_1(\Omega) = 1$$
,  $P_1(\emptyset) = 0$ ,  $P_1(\{a\}) = \frac{1}{2}$ ,  $P_1(\{b\}) = \frac{1}{2}$ 

(ii) 
$$P_2(\Omega) = 1$$
,  $P_2(\emptyset) = 0$ ,  $P_2(\{a\}) = 1$ ,  $P_2(\{b\}) = 0$ 

Both  $P_1$  and  $P_2$  are probability measures on  $(\Omega, \mathcal{F})$ . If we simply take this abstract example as tossing a coin where a and b represent two possible symbols, say a number and a flower.  $P_1$  means we are tossing a fair coin with a number and a flower on each side respectively, and  $P_2$  means we are tossing a coin with a flower on both sides.

A sequence of events  $\{A_i\}_{i\in\mathbb{N}}$  is increasing (resp. decreasing) if  $A_1\subseteq A_2\subseteq\cdots$  (resp.  $A_1\supseteq A_2\supseteq\cdots$ ).

**Proposition** If  $\{A_i\}_{i\in\mathbb{N}}$  is increasing (resp. decreasing), then  $P(\bigcup_{i=1}^{\infty}) = \lim_{i\to\infty} P(A_i)$  (resp.  $P(\bigcap_{i=1}^{\infty}) = \lim_{i\to\infty} P(A_i)$ ).

**Example** Consider the probability space  $(\Omega, \mathcal{F}, P)$  where  $\Omega = (0, 1)$ ,  $\mathcal{F}$  is the  $\sigma$ -field generated by  $\mathcal{F}_0 = \{(a, b) : 0 < a < b < 1\}$ , and P is a probability measure on  $(\Omega, \mathcal{F})$  satisfying  $P_{|\mathcal{F}_0|}((a, b)) = b - a$ .

Note that  $\left\{\frac{1}{2}\right\} \in \mathcal{F}$  since  $\left\{\frac{1}{2}\right\} = \bigcap_{n=3}^{\infty} \left(\frac{1}{2} - \frac{1}{n}, \frac{1}{2} + \frac{1}{n}\right) \in \mathcal{F}$ . By the above proposition, we can

easily get

$$P\left(\left\{\frac{1}{2}\right\}\right) = P\left(\cap_{n=3}^{\infty} \left(\frac{1}{2} - \frac{1}{n}, \frac{1}{2} + \frac{1}{n}\right)\right) = \lim_{n \to \infty} P\left(\left(\frac{1}{2} - \frac{1}{n}, \frac{1}{2} + \frac{1}{n}\right)\right) = \lim_{n \to \infty} \frac{1}{2n} = 0$$

since  $\left\{\left(\frac{1}{2} - \frac{1}{n}, \frac{1}{2} + \frac{1}{n}\right)\right\}_{n=1}^{\infty}$  is decreasing. This example shows that some sets in the collection of events can be 0-measure.

#### Random Variable

The terminology  $random\ variable$  somewhat belies its formal definition of a deterministic mapping. It is a link between two measure spaces such that any event in the  $\sigma$ -field installed on the range can be tracked back to an event in the  $\sigma$ -field installed on the domain.

Formally, a function  $X: \Omega \mapsto \mathbb{R}$  is  $(\Omega, \mathcal{F}) \setminus (\mathbb{R}, \mathcal{R})$  measurable if

$$X^{-1}(B) = \{\omega \in \Omega : X(\omega) \in B\} \in \mathcal{F}$$

for any  $B \in \mathcal{R}$ . Random variable is an alternative common name for a measurable function. We say a measurable is a discrete random variable if the set  $\{X(\omega) : \omega \in \Omega\}$  is finite or countable. We say it is a continuous random variable if the set  $\{X(\omega) : \omega \in \Omega\}$  is uncountable.

A measurable function connects two measurable spaces. No probability is involved in its definition. However, if a probability measure P is installed on  $(\Omega, \mathcal{F})$ , the measurable function X will induce a probability measure on  $(\mathbb{R}, \mathcal{R})$ . It is easy to verify that  $P_X : (\mathbb{R}, \mathcal{R}) \mapsto [0, 1]$  is also a probability measure if defined as  $P_X(B) = P(X^{-1}(B))$  for any  $B \in \mathcal{R}$ . (If  $B_1, B_2 \in \mathcal{R}$  are disjoint, then  $X^{-1}(B_1), X^{-1}(B_2) \in \mathcal{F}$  are also disjoint.) This  $P_X$  is called the probability measure induced by the measurable function X. The induced probability measure  $P_X$  is an offspring of the parent probability measure P though the channel of X.

### **Distribution Function**

We go back to some terms that we have learned in the undergraduate probability course. A (cumulative) distribution function  $F : \mathbb{R} \mapsto [0,1]$  is defined as

$$F(x) = P(X \le x) = P(\{X \le x\}) = P(\{\omega \in \Omega : X(\omega) \le x\}).$$

It is often abbreviated as CDF, and it has the following properties.

- (i)  $\lim_{x\to-\infty} F(x) = 0$ ,
- (ii)  $\lim_{x\to\infty} F(x) = 1$ ,
- (iii) non-decreasing,
- (iv) right-continuous  $\lim_{y\to x^+} F(y) = F(x)$ .

For continuous distribution, if there exists a function f such that for all x,

$$F(x) = \int_{-\infty}^{x} f(y) \, dy,$$

then f is called the *probability density function* of X, often abbreviated as PDF. It is easy to show that  $f(x) \ge 0$  and  $\int_a^b f(x) dx = F(b) - F(a)$ .

**Example** We have learned many parametric distributions like the binary distribution, the Poisson distribution, the uniform distribution, the normal distribution,  $\chi^2$ , t, F and so on. They are parametric distributions, meaning that the CDF or PDF can be summarized in a few parameters.

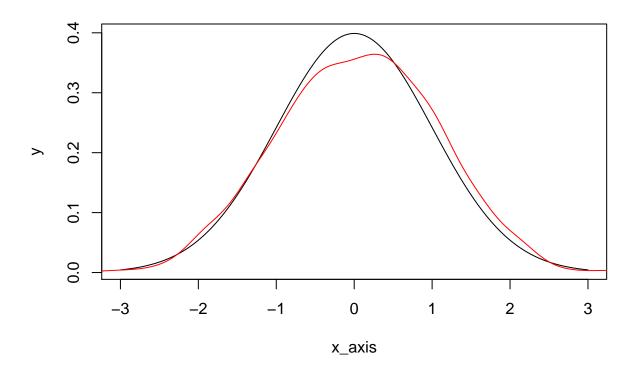
**Example** R has a rich collection of distributions implemented in a unified rule: **d** for density, **p** for probability, **q** for quantile, and **r** for random variable generation. For instance, **dnorm**, **pnorm**, **qnorm**, and **rnorm** are the corresponding functions of the normal distribution, and the parameters  $\mu$  and  $\sigma$  can be specified in the arguments of the functions.

Below is a piece of R code for demonstration.

1. Plot the density of standard normal distribution over an equally spaced grid system

 $x_axis = seq(-3, 3, by = 0.01)$  (black line).

- 2. Generate 1000 observations for N(0,1). Plot the kernel density, a nonparametric estimation of the density (red line).
- 3. Calculate the 95-th quantile and the empirical probability of observing a value greater than the 95-th quantile. In population, this value should be 5%. What is the number in this experiment?



## [1] 0.053