

Introduction to RaspberryPi GPIO

Notebook: irasoberrvpi

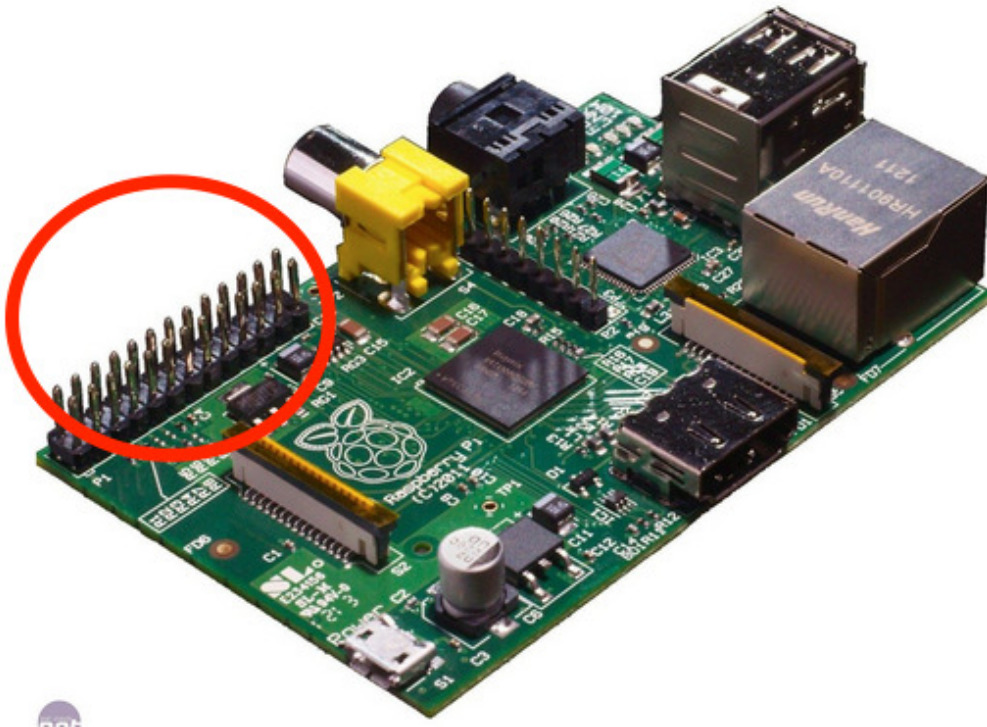
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Location: Bangalore Urban, Karnataka, I...

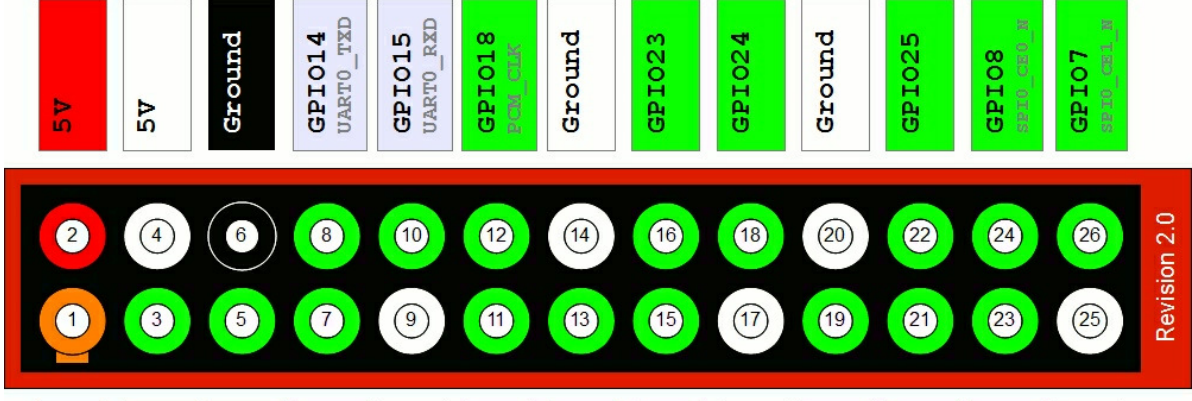
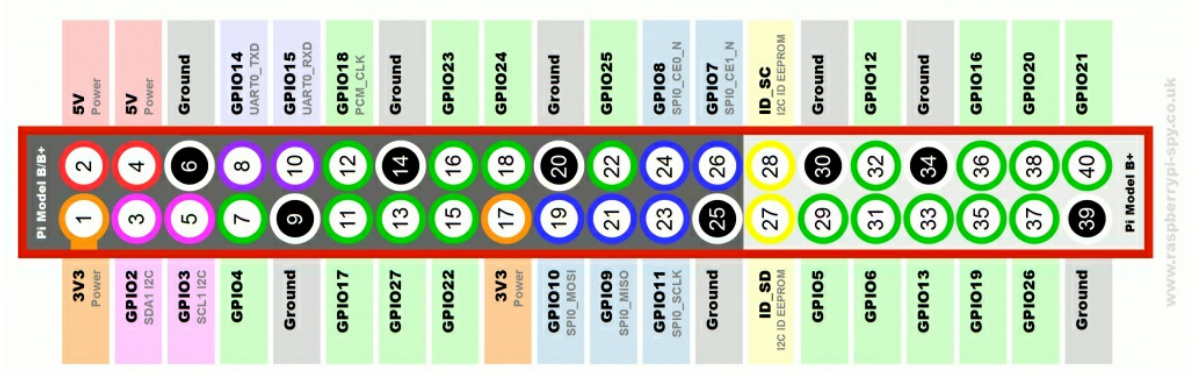
GPIO = General-purpose input/output (GPIO)



Two different Mode for GPIO.

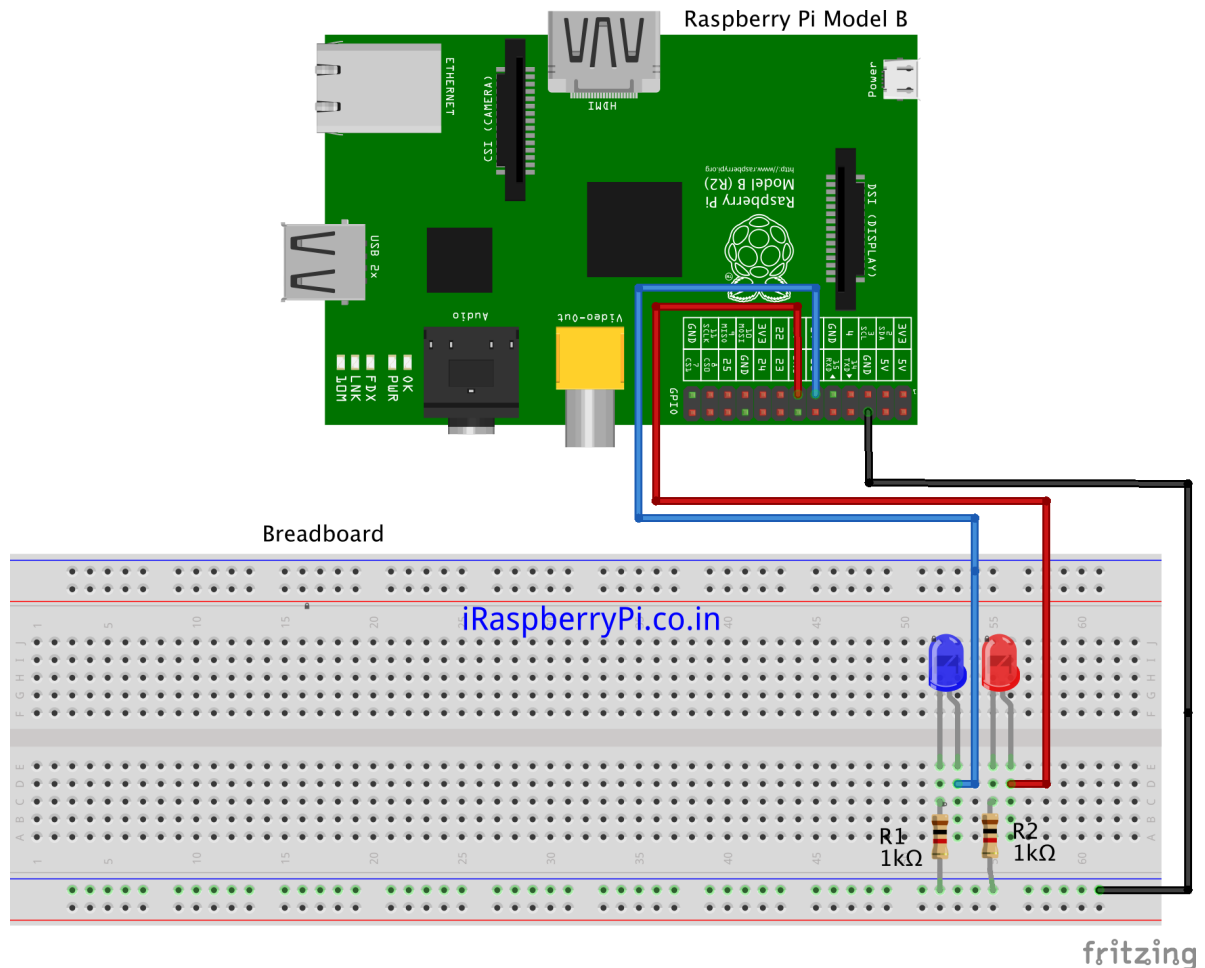
The **GPIO.BOARD** option specifies that you are referring to the pins by the number of the pin the the plug - i.e the numbers printed on the board (e.g. P1) and in the middle of the diagrams below.

The **GPIO.BCM** option means that you are referring to the pins by the "Broadcom SOC channel" number, these are the numbers after "GPIO" in the green rectangles around the outside of the below diagrams:



GPIO & LEDs

circuit diagram...



we can use GPIO 3 ways..

1) GPIO control from shell

Export the required GPIO

```
echo "17" > /sys/class/gpio/export
```

Set the direction

```
echo "out" > /sys/class/gpio/gpio17/direction
```

Set the value

```
echo "1" > /sys/class/gpio/gpio17/value
```

Configure GPIO27 as input and read its value

1. Export the required GPIO

```
echo "27" > /sys/class/gpio/export
```

2. Set the direction

```
echo "in" > /sys/class/gpio/gpio27/direction
```

3. Set the value

```
cat /sys/class/gpio/gpio27/value
```

2) through python api

```
#!/usr/bin/python
import RPi.GPIO as GPIO
GPIO.setmode(GPIO.BCM)
GPIO.cleanup()
GPIO.setwarnings(False)
GPIO.setup(17,GPIO.OUT)
GPIO.setup(27,GPIO.OUT)
print "Lights on"
GPIO.output(17,GPIO.HIGH)
GPIO.output(27,GPIO.HIGH)
```

```
#!/usr/bin/python
import RPi.GPIO as GPIO
GPIO.setmode(GPIO.BCM)
GPIO.cleanup()
GPIO.setwarnings(False)
GPIO.setup(17,GPIO.OUT)
GPIO.setup(27,GPIO.OUT)
print "Lights off"
GPIO.output(17,GPIO.LOW)
GPIO.output(27,GPIO.LOW)
```

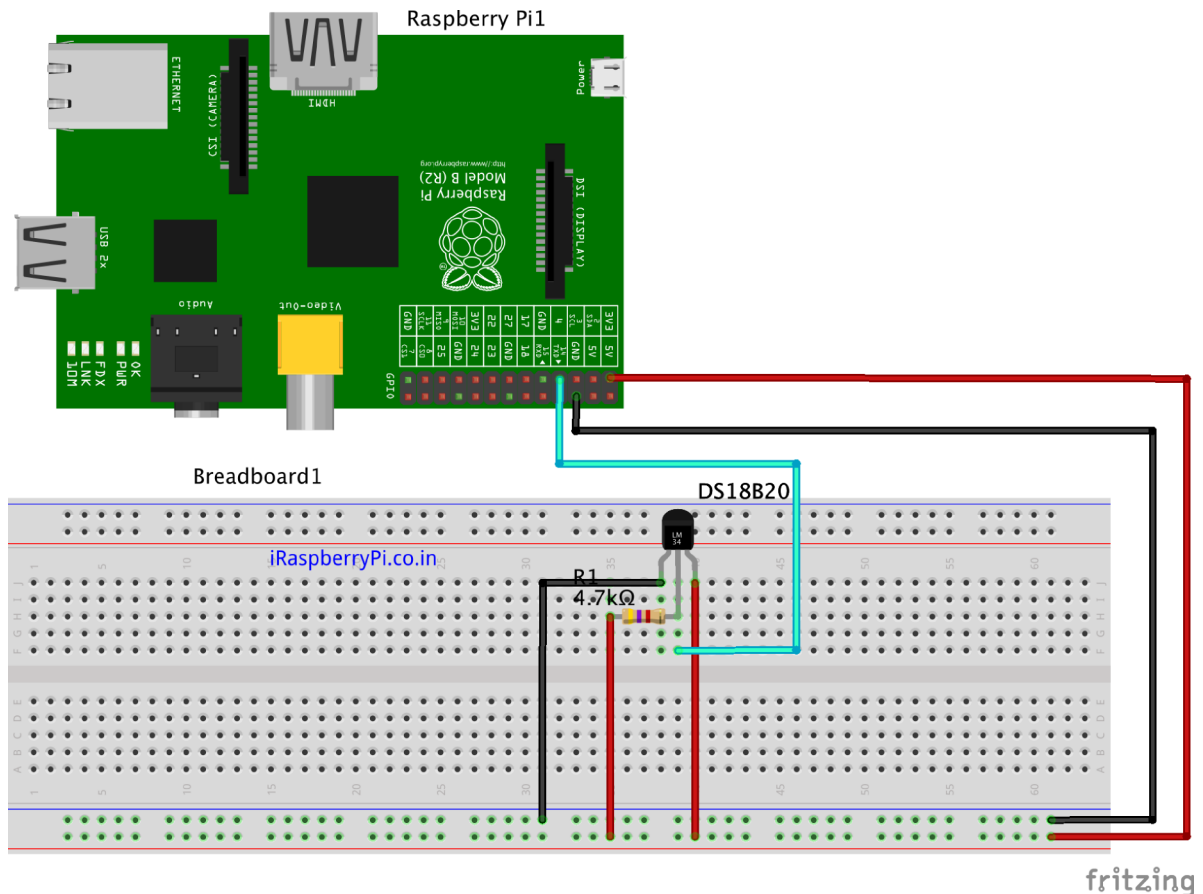
3) through web

access python script through web OR WEBIOPI

```
/var/www
visudo /etc/sudoers
```

GPIO & temperature sensor

circuit diagram...



enable 1-wire protocol

```
sudo modprobe w1-gpio  
sudo modprobe w1-therm
```

go to `/sys/bus/w1/devices`

Python Code

```
import os  
import glob  
import time  
#initialize the device  
os.system('modprobe w1-gpio')  
os.system('modprobe w1-therm')  
  
base_dir = '/sys/bus/w1/devices/'  
device_folder = glob.glob(base_dir + '28*')[0]  
device_file = device_folder + '/w1_slave'
```

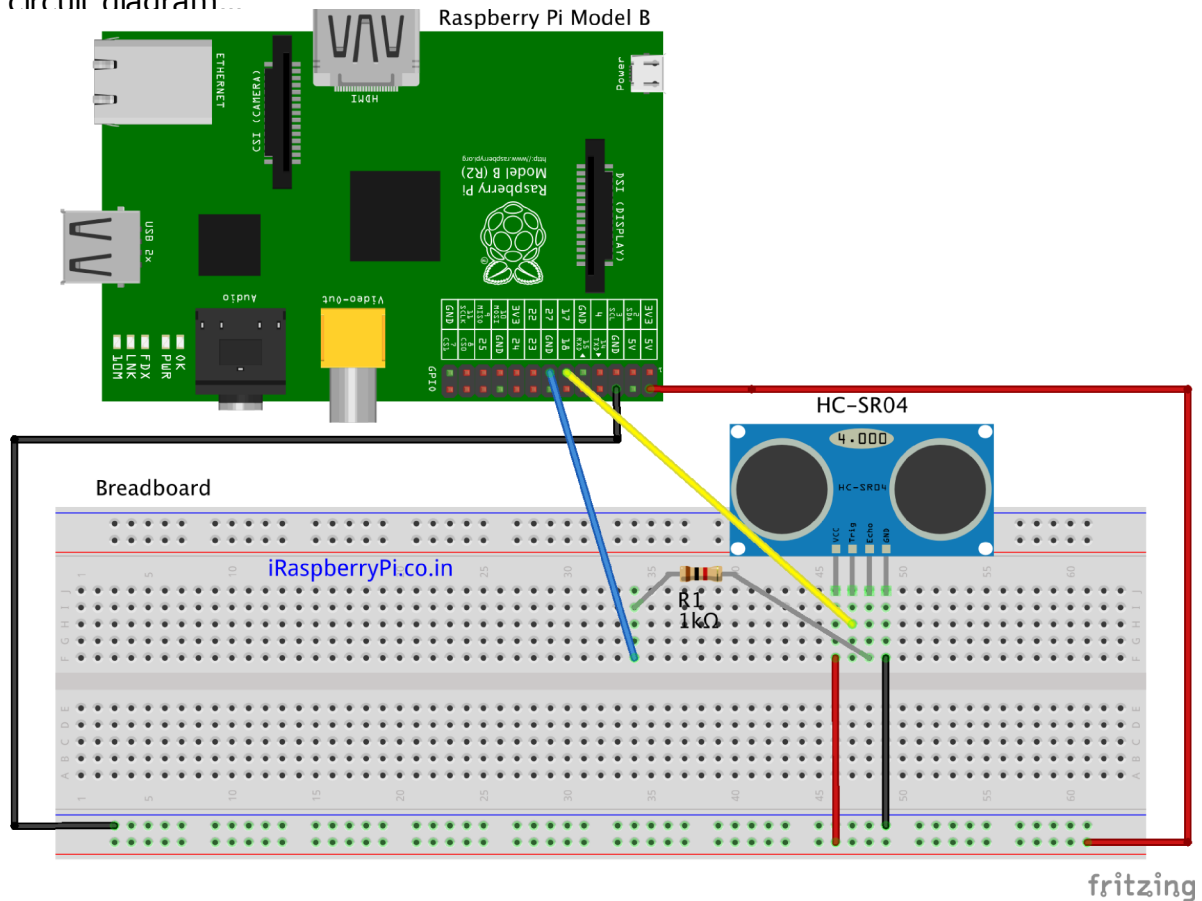
```
def read_temp_raw():
    f = open(device_file, 'r')
    lines = f.readlines()
    f.close()
    return lines

def read_temp():
    lines = read_temp_raw()
    while lines[0].strip()[-3:] != 'YES':
        time.sleep(0.2)
        lines = read_temp_raw()
    equals_pos = lines[1].find('t=')
    if equals_pos != -1:
        temp_string = lines[1][equals_pos+2:]
        temp_c = float(temp_string) / 1000.0
        temp_f = temp_c * 9.0 / 5.0 + 32.0
        return temp_c, temp_f

while True:
    print(read_temp())
    time.sleep(1)
```

GPIO & HC-SR04 Ultrasonic Distance Measuring Sensor

circuit diagram...



Now, we will use GPIO to measure distance with HC-SR04 sensor...



What is an Ultrasonic Module HC-SR04 Distance Sensor?

It's a cheap sensor that can be used to measure the distance between itself and an object in front of it by sending an ultrasonic pulse and listening for its echo. The HC-SR04 can be connected to many things including the Raspberry Pi.

Why do I need a resistor and where can I get it?

You need a resistor because the HC-SR04 sensor sends a 5v signal to a GPIO pin on the Raspberry Pi that is only rated for 3.3v. The GPIO pins on the Raspberry Pi are unprotected, which means if you were to connect the sensor without the resistor you are likely to permanently damage the GPIO pins.

How do I connect everything?

There are four pins on the HC-SR04 sensor. The pin labelled VCC requires connecting to a 5V pin, the pin labelled "Gnd" requires connecting to a ground pin, and the pins "Trig" and "Echo" need to be each wired to a unique GPIO pin on the Raspberry Pi.

You need to connect your 1K resistor between the echo pin and the GPIO pin (to protect the Raspberry Pi from receiving a 5V signal to a 3.3V pin).

source code:- <http://nayaneye.co.in/rpi/usonicl.py>