Video Object Detection using Faster R-CNN

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start from Image Object Detection

Faster R-CNN: Towards Real-Time Object Detection with Region Proposal Networks

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Abstract—State-of-the-art object detection networks depend on region proposal algorithms to hypothesize object locations. Advances like SPPnet [1] and Fast R-CNN [2] have reduced the running time of these detection networks, exposing region proposal computation as a bottleneck. In this work, we introduce a *Region Proposal Network* (RPN) that shares full-image convolutional features with the detection network, thus enabling nearly cost-free region proposals. An RPN is a fully convolutional network that simultaneously predicts object bounds and objectness scores at each position. The RPN is trained end-to-end to generate high-quality region proposals, which are used by Fast R-CNN for detection. We further merge RPN and Fast R-CNN into a single network by sharing their convolutional features—using the recently popular terminology of neural networks with "attention" mechanisms, the RPN component tells the unified network where to look. For the very deep VGG-16 model [3], our detection system has a frame rate of 5fps (*including all steps*) on a GPU, while achieving state-of-the-art object detection accuracy on PASCAL VOC 2007, 2012, and MS COCO datasets with only 300 proposals per image. In ILSVRC and COCO 2015 competitions, Faster R-CNN and RPN are the foundations of the 1st-place winning entries in several tracks. Code has been made publicly available.

Index Terms—Object Detection, Region Proposal, Convolutional Neural Network.

Faster R-CNN

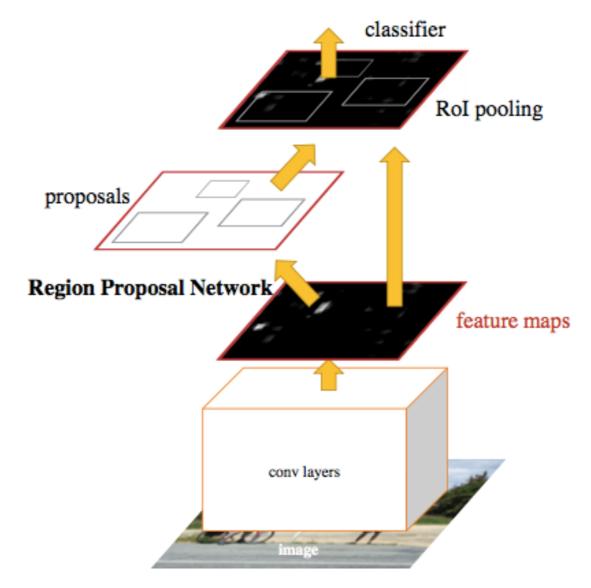


Figure 2: Faster R-CNN is a single, unified network for object detection. The RPN module serves as the 'attention' of this unified network.

Region Proposal Network (RPN)

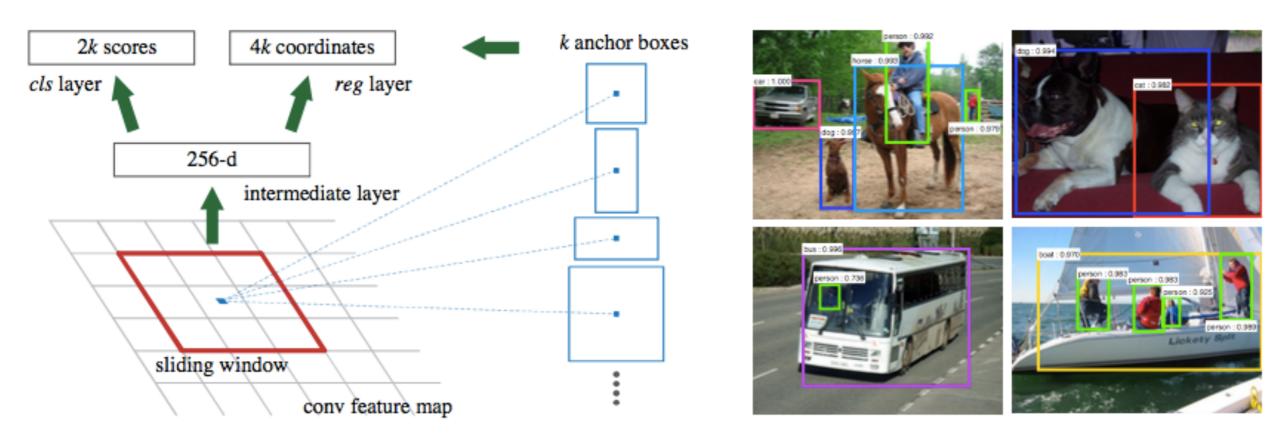
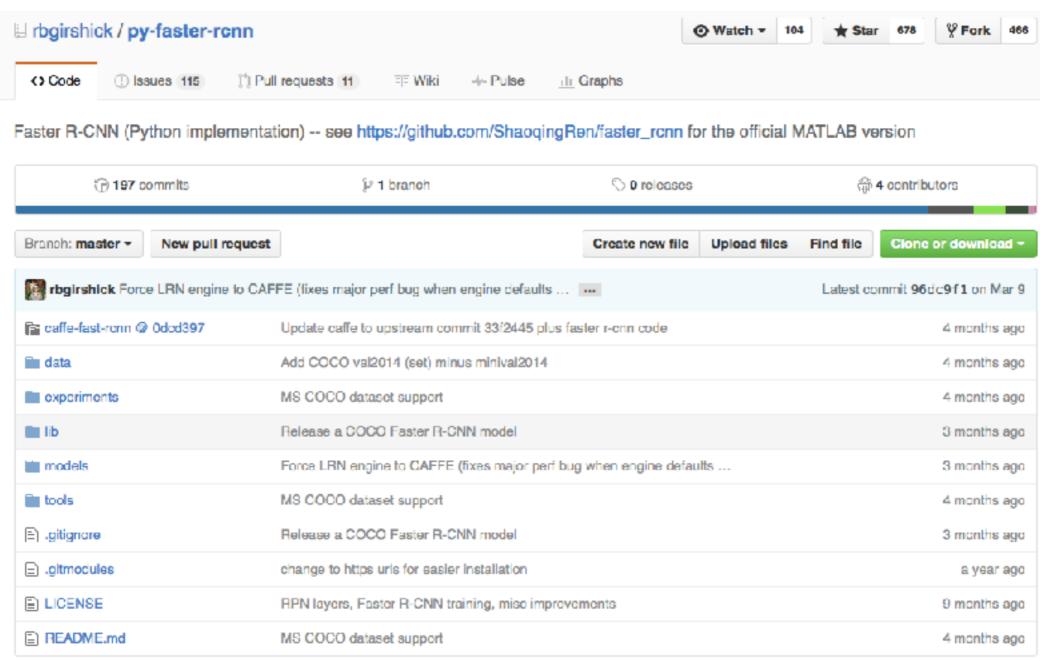


Figure 3: Left: Region Proposal Network (RPN). Right: Example detections using RPN proposals on PASCAL VOC 2007 test. Our method detects objects in a wide range of scales and aspect ratios.

Source Code on Github (framework : Caffe)



Extend PASCAL VOC to ImageNet



PASCAL VOC 2007 20 Categories





ImageNet 200 Categories

Training Details

Duration: 16 hours

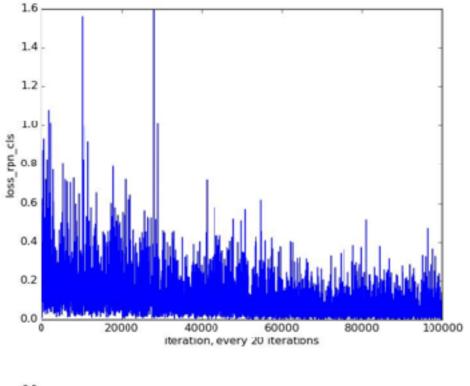
Tool: Geforce GTX Titan X

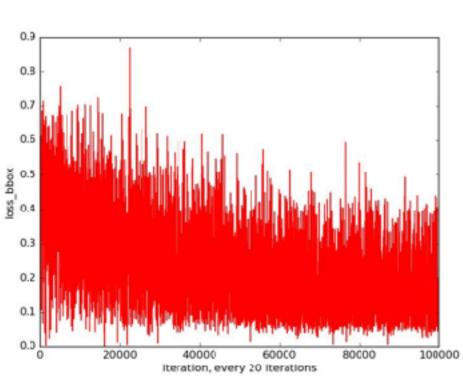
Train Data: ImageNet Validation Set 1

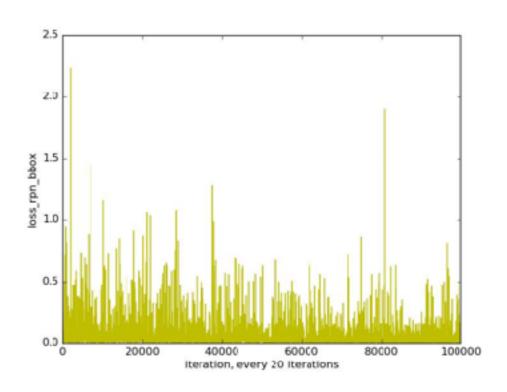
Final Model: 100000 iterations

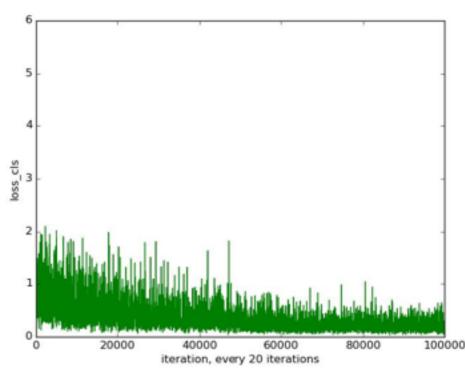
Training Details

Loss:









Training Details

Accuracy:

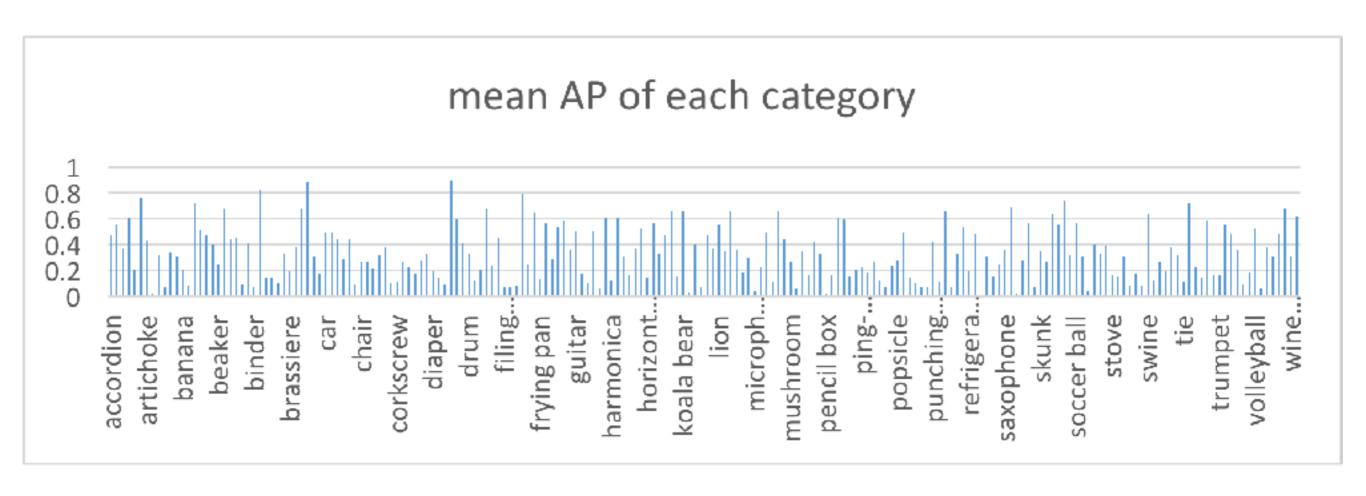


Image Detection Output

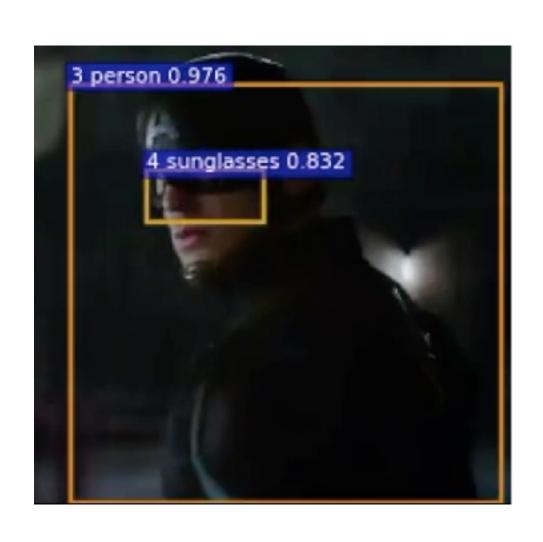




Image v.s Video

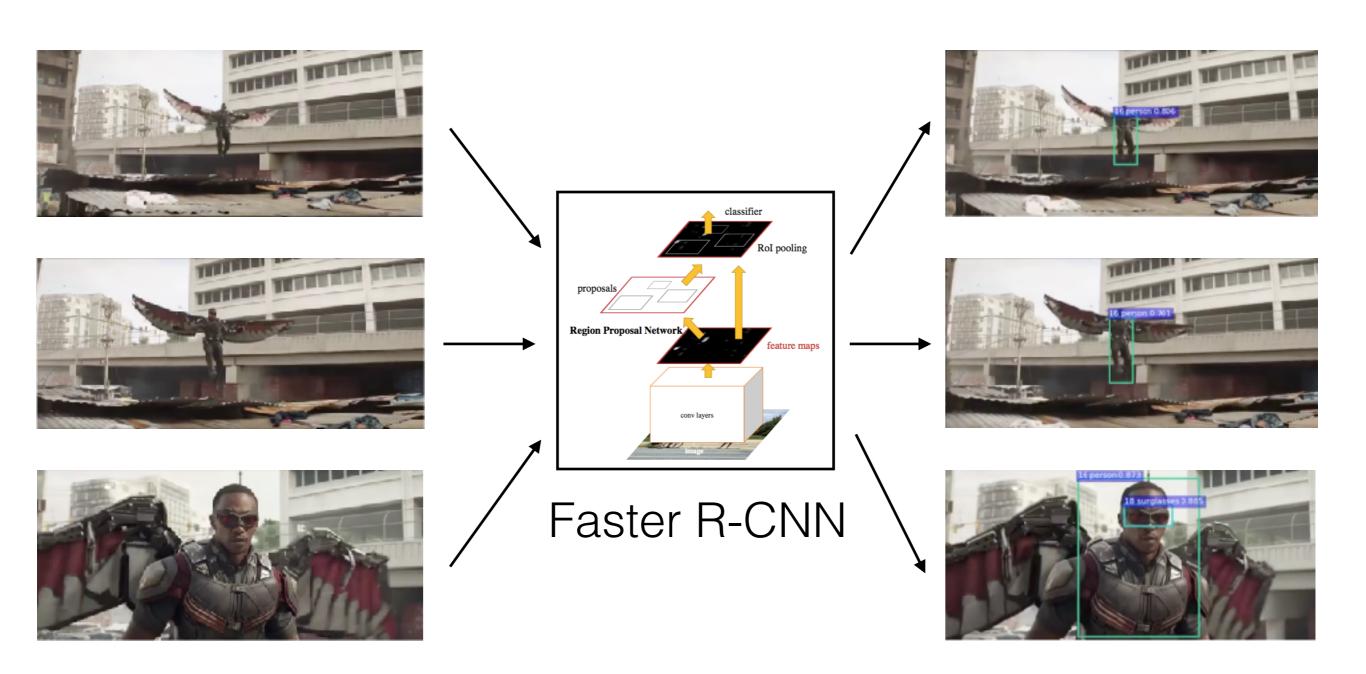
Image: Single Frame



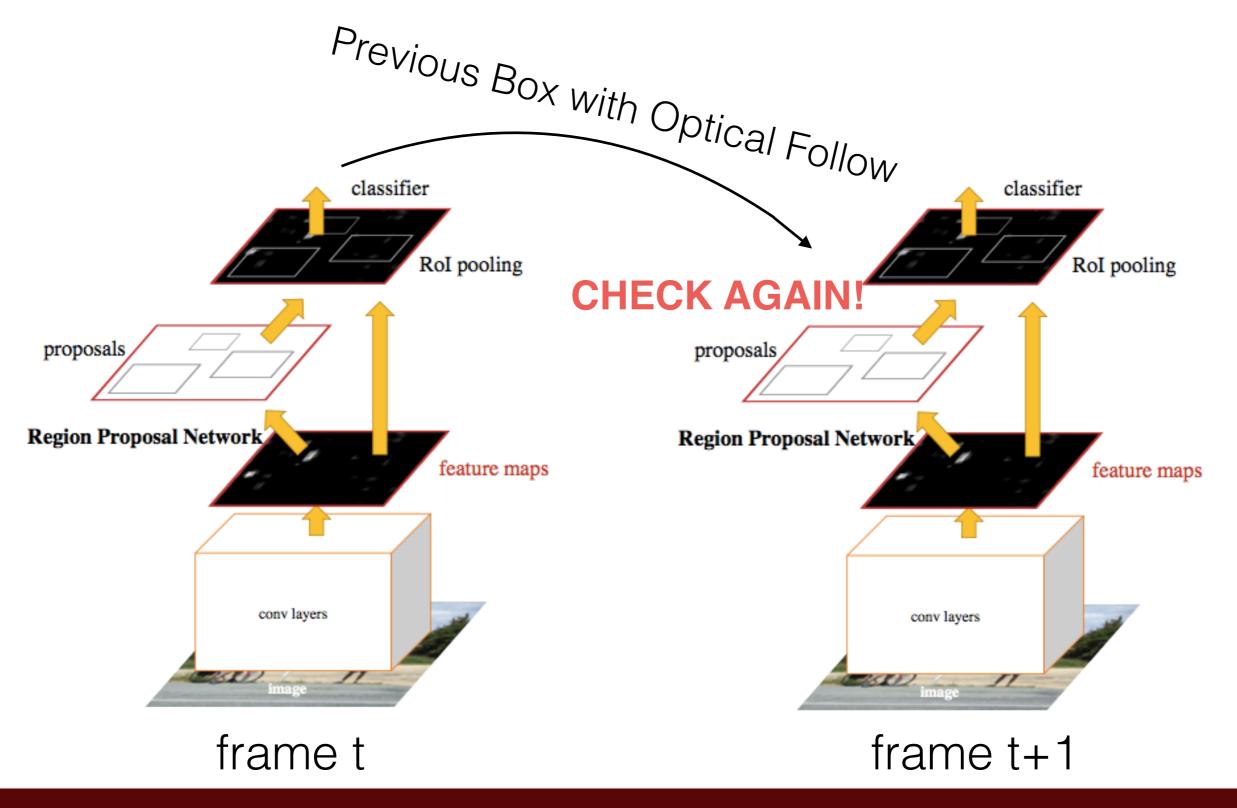
Video: Multiple Frame



Extend Image to Video



Tracker



Contribution

- 1.Set up the environment
- 2. Modify Faster R-CNN to adapt IMAGENET
- 3. Extend Image Object Detection to Video
- 4. Construct **Tracker** to make the bounding box stable
- 5. Result Visualisation

Demo: Captain America

https://www.youtube.com/watch?v=zebSqDt6oMM

Q&A