

# Scheduling Pipelined Circuits

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**Abstract**—This seminar work is about scheduling pipelined circuits where a circuit is allowed to perform multiple tasks at the same time with maximum overall timing proficiency. In this paper, it is explained what a pipelined circuit is, several possible ways to schedule it, why to use it, the mathematical proof of its efficiency, several examples with mathematical computations, area of use, etc. Different scheduling techniques and comparisons will help us to use the maximum of our hardware components.

## I. INTRODUCTION

With the development of science and technology, more and more complicated tasks are easily handled using modern method and technique. Hardware components are costly and hard to built. So, it is always better to make the maximum use of a hardware component. Circuits is main part of a hardware component regarding the functionalities. Pipelining circuit has added a milestone on getting maximum output from a circuit with fastest time. The main idea behind pipelining is dividing an operation in many stages so that a design can accept new operation even if the previous operation has not been finished completely yet. Pipelining is not using a circuit concurrently, but, It uses the part of circuit which is unused for another process without interrupting the ongoing execution. Sharing resources like this way has boosted the efficiency of a circuit(e.g CPU) like an unimaginable way. There are are different type of pipelined circuits like asynchronous, synchronous pipeline circuits which is discussed in this paper with proper explanation and examples. Off course, what is pipelining and how it works also has been elaborated. And processes in a pipelined circuits can be scheduled in many ways. This is also discussed in this paper.

## II. PIPELINING

To get the better understanding of Pipelining, Let's go through an well known example before we move to pipelined circuits.

While washing clothes in washing machine in a dormitory or anywhere else, there is washing machine as well as dryer. Lets consider Figure 1, a washing Machine takes 90 min. for a wash, and a dryer takes 90 min. for drying.

Suppose, there is 10 cloth load,  
So, If someone want to wash and dry these all, by normal calculation,  
the amount of time necessary=

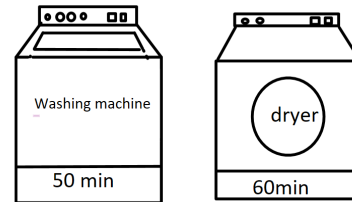


Figure 1. washing machine and dryer

$$N * (\text{washing time} + \text{drying time}) = N * (50 + 60) = N * 110$$

This is without pipelining.

But this is not the smartest way. one can easily put 2nd bundle of cloths to waschine machine after first wash while 1st load is drying. Figure 2 explains it very well where this task is done step by step with a pipelined technique:

So the amount of time necessary inn this case would be  $= N * 60$  minutes.

It is more like to be  $(N * 60 + 50)$ .

But we consider mostly the Steady State situation in pipelining which is our interest.

The technique described here is nothing but Pipelining !!

### A. Some Definition

**Latency:** The delay between the establishment of a an input untill the output associated with this input is valid.

for the above mentioned example, for 11 hours (660 minutes), if there is no pipelining,  
total load that is finished washing and drying =  $660 / 110 = 6$  load  
while with pipelining, that is =  $660 / 60 = 11$  load. it is easily noticable that with pipelining, with the same time, 11 load of cloths are washed and dried!!

**throughput:**  
throughput is the rate of which input and output are processed. For this scenario, without pipelining =  $1 / 110 = 0.009$  min/sec  
with pipelining =  $1 / 60 = 0.016$  min/sec

### B. pipelined circuits

Let's consider combinational circuit shown in Figure 3. there are several block A, B, C and D, the input of the circuit

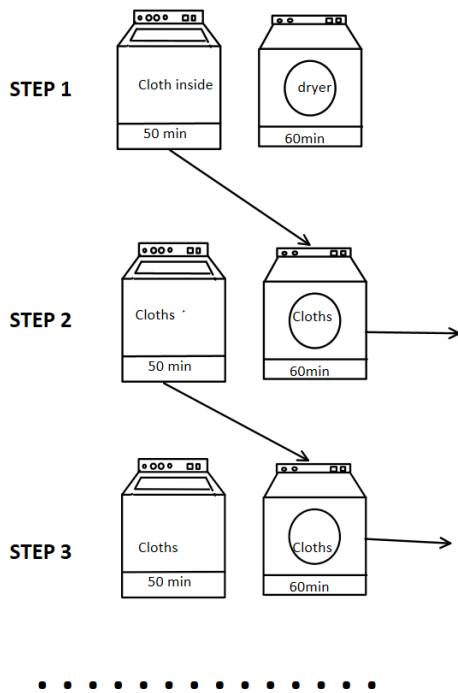


Figure 2. pipelining for using washing machine and dryer multiple time

is  $X$  and the output of the circuit is  $O$ .

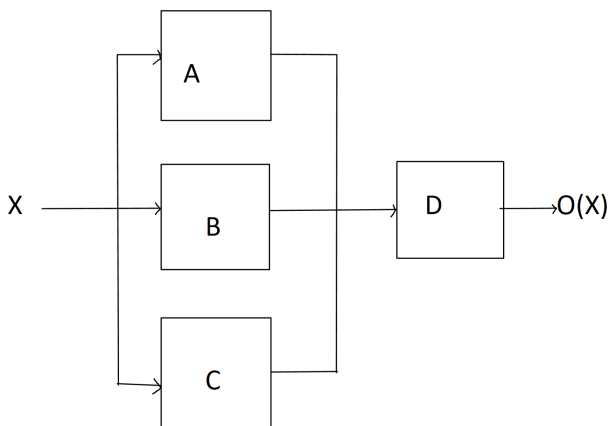


Figure 3. A combinational circuit

Suppose, Latency =  $L$   
 so throughput =  $1/L$  .  
 assume that , the processing time of  $A$  ,  $B$  and  $C$  is not equal.  
 Now how this circuit performs a execution ?  
 in Figure 4, The executional behaviour with time is given.

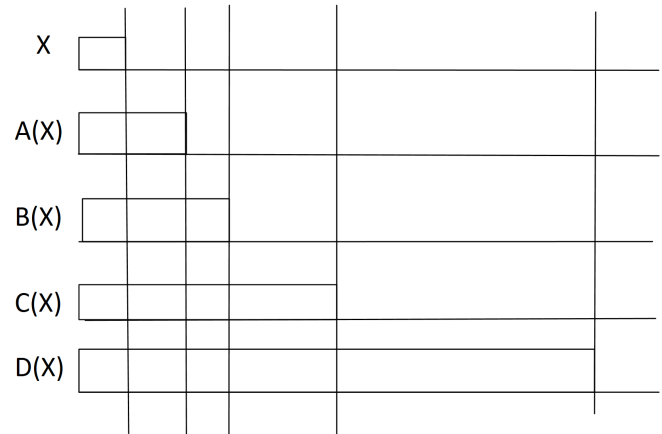


Figure 4. execution of a process in a the combinationa circuit shown in Figure 3

It is clearly noticed that, while  $D$  performs its execution,  $A, B$  and  $C$  are idle just keeping the output stable.

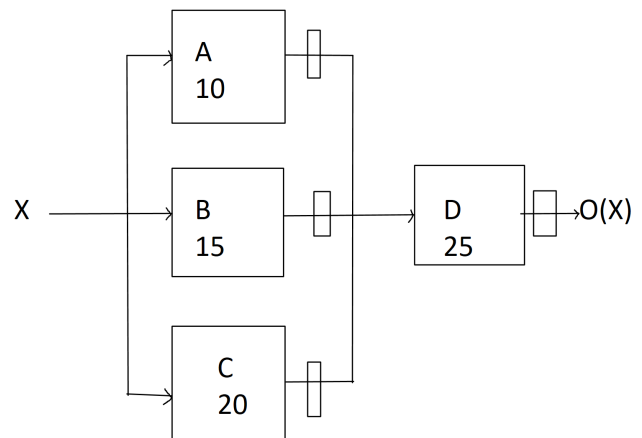


Figure 5. Pipelined circuit

Let's use registers to hold the input values for  $D$  stable.  
 and we put some execution time for each elements. COnsider  
 Figure 5 where a register is used after each of the blocks  
 shown in Figure 3.

Now, we can consider this combinational circuit as 2 stage pipeline.

A, B and C are working on input

$$X_{i+1}$$

A valid input X during clock cycle j,  
O(X) is valid till j+2.

Now, Suppose,  
Propagation delays of A, B, C and D in Figure 5 is 10,15,20 and 25 ns.

An we used ideal zero delay registers.

So, for unpipelined:

$$\text{Latency} = 20 + 25 = 45$$

$$\text{Throughput} = 1/45$$

For two stage pipeline:

$$\text{Latency} = 50$$

$$\text{Throughput} = 1/25$$

we see that, though latency is worse in pipelined circuits than the unpipelined circuit, the processing rate which is called throughput is better in pipelined version.

in Figure 6, overall timing behaviour of the circuit shown in

Clock cycle		→			
	i	i+1	i+2	i+3	
input	$X_i$	$X_{i+1}$	$X_{i+2}$	$X_{i+3}$	
Pipeline stages	A reg	$A(X_i)$	$A(X_{i+1})$	$A(X_{i+2})$	
	B reg	$B(X_i)$	$B(X_{i+1})$	$B(X_{i+2})$	
	C reg	$C(X_i)$	$C(X_{i+1})$	$C(X_{i+2})$	
	D reg		$D(X_i)$	$D(X_{i+1})$	$D(X_{i+2})$

Figure 6. Pipeline diagram of the circuit shown in Figure 5

Figure 5 is explained .

for a particular set of inpts data, the result move diagonally through the diagram proccessing one pipeline stage for each clock cycle.

### C. K-stage pipeline

A K-stage pipeline is an acyclic circuit having exactly K number of register through the path from input to output. for every pipeline stages, there is an register on it's output.

Latency = K times the period of the clock common to all registers

Throughput= the frequency of the clock

## III. SYNCHRONOUS PIPELINING

In a synchronous pipelined circuit, all the pipelining stages are controlled by the same clock signal, a global clock. consider Figure 7, Where pipelining is is controlled by global clock, for each stage, input data is processed by combinational logic and output is latched to the input of another stage. The clock duration is large enough which result in filtering hazards or glitch.

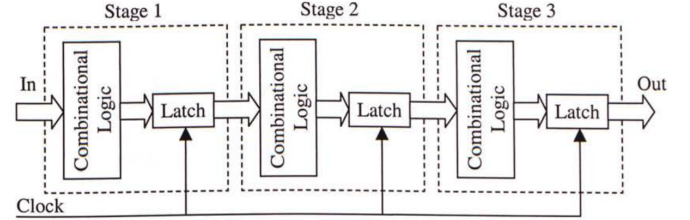


Figure 7. architecture of a pipelined synchronous circuit (from reference 5)

### Asynchronous pipelining

In a asynchronous pipelined circuit, all the pipelining stages are controlled by localizes signal instead of global clock signal in synchronous pipelining. consider Figure 8 shows a classical asynchronous pipelined architecture that makes use of Differential Cascode Voltage-Switch-Logic (DCVSL) as logic cell. here, handshake control signal is used insted of global clock to

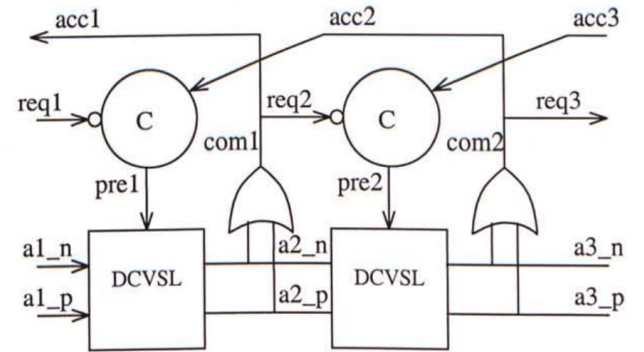


Figure 8. architecture of a pipelined asynchronous circuit (from reference 5)

manage the data flow as well as operation between two pipelined stages. completion of each stages is determined by the data output.

## IV. SCHEDULING PIPELINE CIRCUITS

generally, a pipelined circuits consists of a sequential graph model and corresponding data rate.

we consider nonpipelined sequencing graphs whose operations can be bound to pipelined resources. (i.e., pipelined submodels).

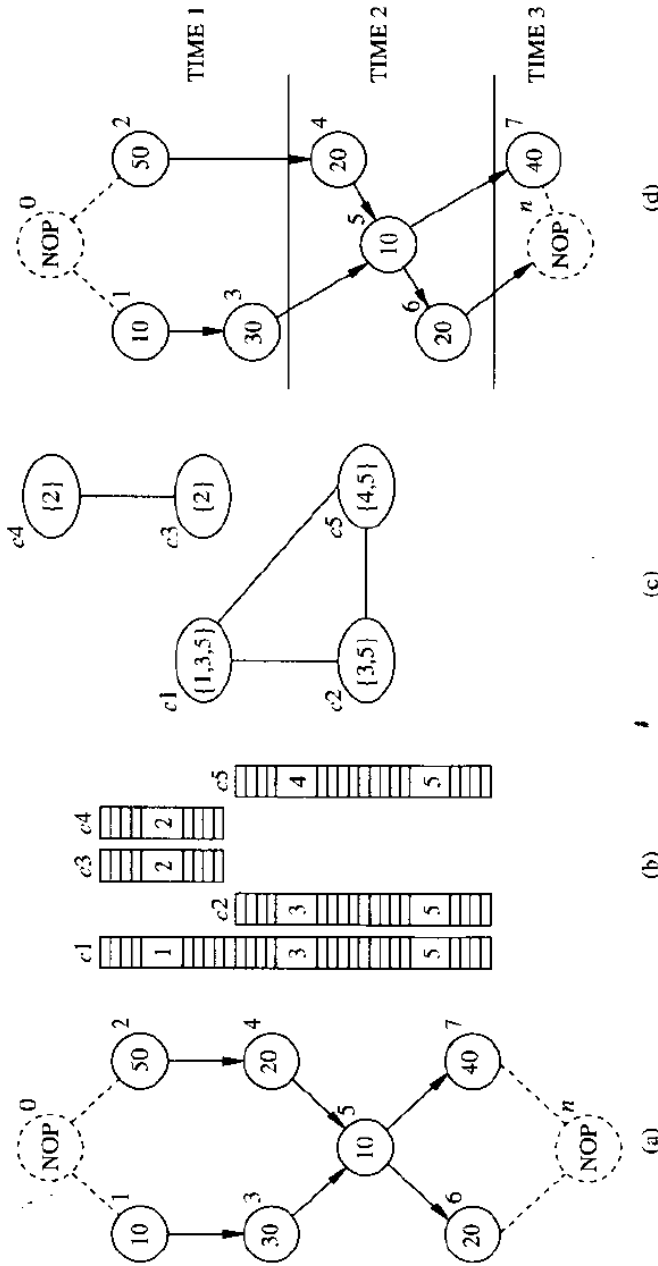


Figure 9. (a) sequential graphs (b) cuts (c) cut intersection graph (d) scheduled sequencing graph (from reference 3)

In Figure 9, a scheduling example of pipelined circuit or resources is shown,

#### A. Scheduling with pipelined resources

pipelined resources or hardware components or pipelined circuits consumes and produces data at time interval less than the execution delay. the time interval which is call data introduction interval are assumed to be constant.

It is possible for pipelined resources to be shared even operations overlap. The fact is, there should be no data

dependency, and the operations do not begin at the same time step .

In this case, The list scheduling algorithm can be used to schedule this operation with different time steps and with no data dependency. considering the time introduction interval is 1, the list scheduling algorithm for constraint resources is usable.

Interested reader can find details of List scheduling on page 207 to 210 of the book on reference 3. In Figure 10, a

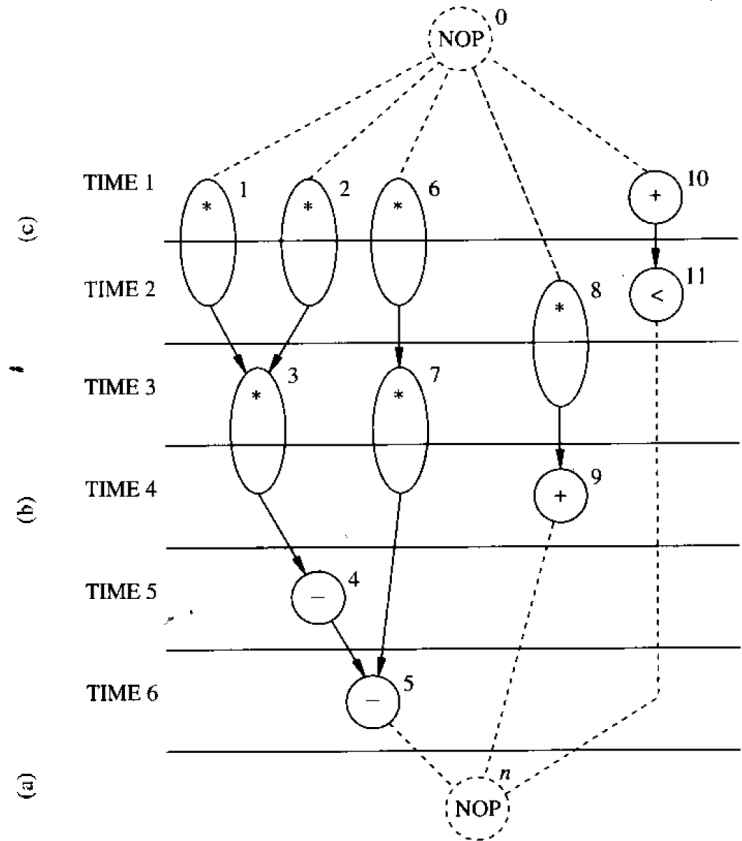


Figure 10. scheduled sequential graphs with pipeline resources(image taken from reference 3)

scheduled sequential graph with pipeline resources is show. one can find that , it is divided into time slices which is data introduction interval.

#### B. Loop folding

Loop folding is an technique which can reduce the execution delay of a loop. we consider the use of pipelining to speed up the execution of loops. This technique is called loop winding and loop folding.

Let's consider a loop,

number of loop iteration =  $n_l$

So, the execution delay of the loop =  $n_l \cdot \lambda_l$

where, Latency of the loop =  $\lambda_l$

pipelining the loop body with local data introduction interval  $\delta_l < \lambda_l$ , results in:

overall loop execution delay =

$$[n_l + \lambda_l / \delta_l - 1] * \delta_l$$

So, Loop folding in reducing a scheduled sequency graph that has loop, possibly nested loop. loop folding can be viewed as pipelining the graph entity of the loop body with the goal of reducing the execution delay

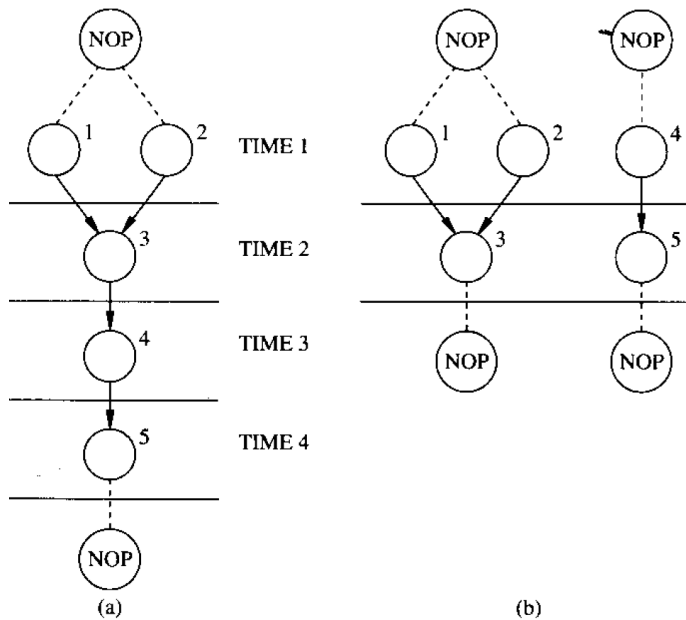


Figure 11. (a) sequential graph of a loop body (b)sequential graph after loop folding (image from reference 3)

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