Expectation Maximization

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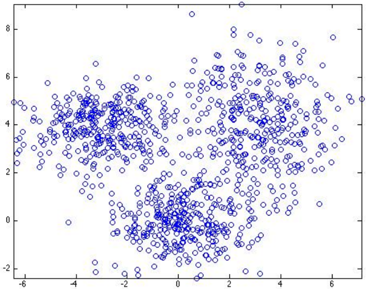
November 20, 2014

Motivation - Mixture Densitiy models

When you have data that looks like:



Can you fit them using a single-mode Gaussian distribution, i.e.,:

$$
\begin{aligned}
p(X) &= \mathcal{N}(X|\mu, \Sigma) \\
&= (2\pi)^{-k/2}|\Sigma|^{-\frac{1}{2}} \exp^{-\frac{1}{2}(x-\mu)^T\Sigma^{-1}(x-\mu)}
\end{aligned}
$$

Clearly NOT! This is typically modelling using Mixture Densities, in the case of Gaussian Mixture Model (k-mixture) (GMM):

$$
p(X) = \sum_{l=1}^{k} \alpha_l \mathcal{N}(X|\mu_l, \Sigma_l) \qquad \sum_{l=1}^{k} \alpha_l = 1
$$

Gaussian Mixture model result

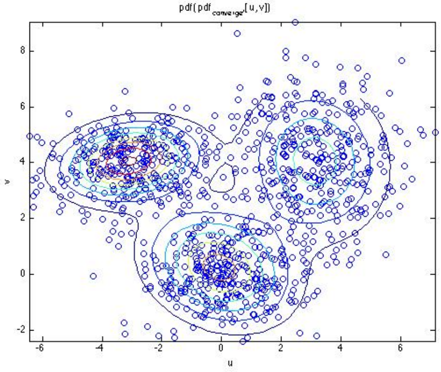


Figure: gmm fitting result

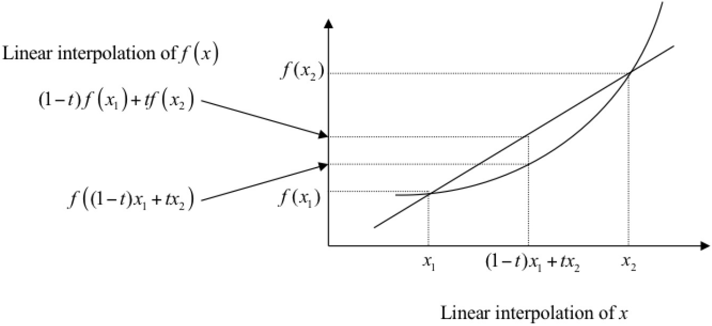
Let $\Theta = \{\alpha_1, \dots \alpha_k, \mu_1, \dots \mu_k, \Sigma_1, \dots \Sigma_k\}$

$$\Theta_{\text{MLE}} = \arg\max_{\Theta} \mathcal{L}(\Theta|X)$$

$$= \arg\max_{\Theta} \left(\sum_{i=1}^{n} \log \sum_{l=1}^{k} \alpha_l \mathcal{N}(X|\mu_l, \Sigma_l) \right)$$

- Unlike single mode Gaussian, we can't just take derivatives and let it equal zero easily.
- We need to use Expectation-Maximization to help us solving this

Convex function



$$f((1-t)x_1 + tx_2) \leq (1-t)f(x_1) + tf(x_2) \qquad t \in (0 \ldots 1)$$

Jensens inequality

Using notation Φ instead of f:

$$\Phi\left((1-t)x_1 + tx_2\right) \leq (1-t)\Phi(x_1) + t\Phi(x_2) \qquad t \in (0 \ldots 1)$$

Can be generalised further, let $\sum_{i=1}^{n} p_i = 1$:

$$\Phi\left(p_1 x_1 + p_2 x_2 + \ldots p_n x_n\right) \leq p_1\Phi(x_1) + p_2\Phi(x_2) \ldots p_n\Phi(x_n) \qquad \sum_{i=1}^{n} p_i = 1$$

$$\implies \Phi\left(\sum_{i=1}^{n} p_i x_i\right) \leq \sum_{i=1}^{n} p_i \Phi(x_i)$$

$$\implies \Phi\left(\sum_{i=1}^{n} p_i f(x_i)\right) \leq \sum_{i=1}^{n} p_i \Phi(f(x_i)) \qquad \text{by replacing } x_i \text{ with } f(x_i)$$

Can also generalised to the continous case, by letting $\int_{x \in \mathbb{S}} p(x) = 1$:

$$\Phi\left(\int_{x \in \mathbb{S}} f(x)p(x)\right) \leq \int_{x \in \mathbb{S}} \Phi(f(x_i))p(x) \implies \Phi\mathbb{E}[f(x)] \leq \mathbb{E}[\Phi(f(x_i))]$$

$\Phi(x) = -\log(x)$ is a convex function:

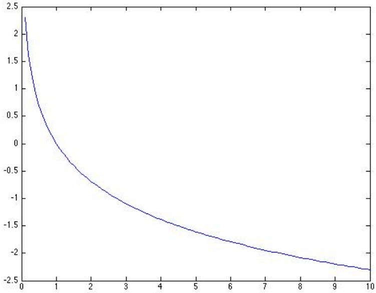


Figure: plot of $\Phi(x) = -\log(x)$

when $\Phi(.)$ is convex

$$\begin{aligned} & \Phi\mathbb{E}[f(x)] \leq \mathbb{E}[\Phi(f(x_i))] \\ \Longrightarrow \quad & -\log \mathbb{E}[f(x)] \leq \mathbb{E}[-\log(f(x_i))] \end{aligned}$$

when $\Phi(.)$ is concave

$$\begin{aligned} & \Phi\mathbb{E}[f(x)] \geq \mathbb{E}[\Phi(f(x_i))] \\ \Longrightarrow \quad & -\log \mathbb{E}[f(x)] \geq \mathbb{E}[-\log(f(x_i))] \end{aligned}$$

Instead of perform:

$$\theta^{\text{MLE}} = \arg\max_{\theta}(\mathcal{L}(\theta)) = \arg\max_{\theta}\left(\log[p(X|\theta)]\right)$$

- **The trick** is to assume some "latent" variable Z to the model.
- such that we generate a series of $\Theta = \{\theta^{(1)}, \theta^{(2)}, \ldots \theta^{(t)}\}$

For each iteration of the E-M algorithm, we perform:

$$\Theta^{(g+1)} = \arg\max_{\theta}\left(\int_z \log\left(p(X, Z|\theta)\right)p(Z|X, \Theta^{(g)})\right) dz$$

However, we must ensure convergence:

$$\log[p(X|\Theta^{(g+1)})] = \mathcal{L}(\Theta^{(g+1)}) \geq \mathcal{L}(\Theta^{(g)}) \qquad \forall i$$

First proof of convergence: using M-M

$$
\begin{aligned}
\mathcal{L}(\theta|X) &= \ln\left(p(X|\theta)\right) \\
&= \ln\left(\frac{p(X,Z|\theta)}{p(Z|X,\theta)}\right) = \ln\left(\frac{\frac{p(X,Z|\theta)}{Q(Z)}}{\frac{p(Z|X,\theta)}{Q(Z)}}\right) \\
&= \ln\left(\frac{p(X,Z|\theta)}{Q(Z)} \times \frac{Q(Z)}{p(Z|X,\theta)}\right) \\
&= \ln\left(\frac{p(X,Z|\theta)}{Q(Z)}\right) + \ln\left(\frac{Q(Z)}{p(Z|X,\theta)}\right) \\
\implies \ln\left(p(X|\theta)\right) &= \int_Z \ln\left(\frac{p(X,Z|\theta)}{Q(Z)}\right) Q(Z) + \int_Z \ln\left(\frac{Q(Z)}{p(Z|X,\theta)}\right) Q(Z) \\
&= \int_Z \ln\left(\frac{p(X,Z|\theta)}{Q(Z)}\right) Q(Z) + \underbrace{\mathrm{KL}(Q(Z)\|p(Z|X,\theta))}_{\geq 0} \\
&= F(\theta, Q) + \int_Z \ln\left(\frac{Q(Z)}{p(Z|X,\theta)}\right) Q(Z)
\end{aligned}
$$

Proof of convergence: using M-M (2)

Another way of knowing:

$$\mathcal{L}(\theta|X) = \ln\left(p(X|\theta)\right) \geq \int_Z \ln\left(\frac{p(X,Z|\theta)}{Q(Z)}\right) Q(Z)$$

is to use Jensen's inequality:

$$\begin{aligned}
\mathcal{L}(\theta|X) = \ln p(X|\theta) &= \ln \int_Z p(X,Z|\theta) \\
&= \underbrace{\ln\left(\int_Z \frac{p(X,Z|\theta)}{Q(Z)} Q(Z)\right)}_{\ln \mathbb{E}_{Q(z)}[f(Z)]} \\
&\geq \underbrace{\int_Z \ln\left(\frac{p(X,Z|\theta)}{Q(Z)}\right) Q(Z)}_{\mathbb{E}_{Q(z)} \ln[f(Z)]}
\end{aligned}$$

Proof of convergence: using M-M (3)

E-M becomes a M-M algorithm

$$\begin{aligned}\mathcal{L}(\Theta|X) &= \int_Z \ln\left(\frac{p(X,Z|\Theta)}{Q(Z)}\right) Q(Z) + \int_Z \ln\left(\frac{Q(Z)}{p(Z|X,\Theta)}\right) Q(Z) \\ &= F(\Theta, Q) + \mathrm{KL}(Q(Z)\|p(Z|X,\Theta))\end{aligned}$$

STEP 1 Fix $\Theta = \Theta^{(g)}$, maximize $Q(Z)$

- $\mathcal{L}(\Theta|X)$ is fixed, i.e., indepedant of $Q(Z)$. Therefore, $\mathcal{L}(\Theta|X)$ is the upper bound of $F(\Theta, Q)$.
- To make $\mathcal{L}(\Theta|X) = F(\Theta, Q)$, i.e, $\mathrm{KL}(.) = 0$, we choose $Q(Z) = p(Z|X, \Theta^{(g)})$. Therefore:

$$\mathcal{L}(\Theta|X) = \int_Z \ln\left(\frac{p(X,Z|\Theta)}{p(Z|X,\Theta^{(g)})}\right) p(Z|X,\Theta^{(g)})$$

STEP 2 Fix $Q(Z)$, maximize Θ

$$\Theta^{(g+1)} = \arg\max_{\Theta} \left(\int_z \log\left(p(X,Z|\Theta)\right) p(Z|X,\Theta^{(g)}) \right) dz$$

Proof of convergence: "Tagare" approach (1)

$$\mathcal{L}(\theta|X) = \ln[p(X|\theta)] = \ln[p(Z,X,\theta)] - \ln[p(Z|X,\theta)]$$

$$\Longrightarrow \int_{z\in\mathbb{S}} \ln[p(X|\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z$$

$$= \int_{z\in\mathbb{S}} \ln[p(Z,X,\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z - \int_{z\in\mathbb{S}} \ln[p(Z|X,\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z$$

$$\Longrightarrow \ln[p(X|\theta)] = \underbrace{\int_{z\in\mathbb{S}} \ln[p(Z,X,\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z}_{Q(\theta,\theta^{i})} - \underbrace{\int_{z\in\mathbb{S}} \ln[p(Z|X,\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z}_{H(\theta,\Theta^{(g)})}$$

In E-M, we only maximise, i.e., $\Theta^{(g+1)} = \arg\max_{\theta} Q(\theta,\Theta^{(g)})$. Why? **a trick** If we can prove:

$$\arg\max_{\theta}\left[\int_{z\in\mathbb{S}} \ln[p(Z|X,\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z\right] = \Theta^{(g)} \implies H(\Theta^{(g+1)},\Theta^{(g)}) \leq H(\Theta^{(g)},\Theta^{(g)})$$

Then

$$\mathcal{L}(\Theta^{(g+1)} = \underbrace{Q(\Theta^{(g+1)},\Theta^{(g)})}_{\geq Q(\Theta^{(g)},\Theta^{(g)})} - \underbrace{H(\Theta^{(g+1)},\Theta^{(g)})}_{\leq H(\Theta^{(g)},\Theta^{(g)})} \geq Q(\Theta^{(g)},\Theta^{(g)}) - H(\Theta^{(g)},\Theta^{(g)}) = \mathcal{L}(\Theta^{(g)}$$

The “Tagare” approach (2)

$$\text{To prove} \quad \arg\max_{\theta}[H(\theta, \Theta^{(g)})] = \arg\max_{\theta}\left[\int_{z\in\mathbb{S}} \ln[p(Z|X,\theta)]p(z|X,\Theta^{(g)})\mathrm{d}z\right] = \Theta^{(g)}$$

$$\Longrightarrow \text{To prove} \quad H(\Theta^{(g)}, \Theta^{(g)}) - H(\theta, \Theta^{(g)}) \geq 0 \quad \forall\theta$$

$$H(\Theta^{(g)}, \Theta^{(g)}) - H(\theta, \Theta^{(g)}) = \int_{z\in\mathbb{S}} \ln[p(Z|X,\Theta^{(g)})]p(z|X,\Theta^{(g)})\mathrm{d}z - \int_{z\in\mathbb{S}} \ln[p(Z|X,\theta)]p(z|X,\Theta$$

$$= \int_{z\in\mathbb{S}} \ln\left[\frac{p(Z|X,\Theta^{(g)})}{p(Z|X,\theta)}\right] p(z|X,\Theta^{(g)})\mathrm{d}z = \int_{z\in\mathbb{S}} -\ln\left[\frac{p(Z|X,\theta)}{p(Z|X,\Theta^{(g)})}\right] p(z|X,\Theta^{(g)})\mathrm{d}z$$

$$\geq -\ln\left[\int_{z\in\mathbb{S}} \frac{p(Z|X,\theta)}{p(Z|X,\Theta^{(g)})} p(z|X,\Theta^{(g)})\mathrm{d}z\right] = 0$$

Since $\Phi(.) = -\ln$ is a convex unction:

The E-M Examples

- Gaussian Mixture Model
- Probabilistic Latent Semantic Analysis (PLSA)

E-M Example: Gaussian Mixture Model

Gaussian Mixture Model (k-mixture) (GMM):

$$p(X|\Theta) = \sum_{l=1}^{k} \alpha_l \mathcal{N}(X|\mu_l, \Sigma_l) \qquad \sum_{l=1}^{k} \alpha_l = 1$$

$$\text{and } \theta = \{\alpha_1, \dots \alpha_k, \mu_1, \dots \mu_k, \Sigma_1, \dots \Sigma_k\}$$

For data $X = \{x_1, \dots x_n\}$ we introduce "latent" variable $Z = \{z_1, \dots z_n\}$, each z_i indicates which mixture component x_i belong to.
Looking at the E-M algorithm:

$$\Theta^{(g+1)} = \arg\max_{\Theta} \left[Q(\Theta, \Theta^{(g)}) \right] = \arg\max_{\Theta} \left(\int_z \log\left(p(X, Z|\Theta)\right) p(Z|X, \Theta^{(g)}) dz \right)$$

We need to define both $p(X, Z|\Theta)$ and $p(Z|X, \Theta)$

$$p(X|\Theta) = \sum_{l=1}^{k} \alpha_l \mathcal{N}(X|\mu_l, \Sigma_l) = \prod_{i=1}^{n} \sum_{l=1}^{k} \alpha_l \mathcal{N}(X|\mu_l, \Sigma_l)$$

How to define $p(X, Z|\Theta)$

$$p(X, Z|\Theta) = \prod_{i=1}^{n} p(x_i, z_i|\Theta) = \prod_{i=1}^{n} \underbrace{p(x_i|z_i, \Theta)}_{\mathcal{N}(\mu_{z_i}, \Sigma_{z_i})} \underbrace{p(z_i|\Theta)}_{\alpha_{z_i}} = \prod_{i=1}^{n} \alpha_{z_i} \mathcal{N}(\mu_{z_i}, \Sigma_{z_i})$$

Notice that $p(X, Z|\Theta)$ is actually simple than $p(X|\Theta)$.

How to define $p(Z|X, \Theta)$

$$p(Z|X, \Theta) = \prod_{i=1}^{n} p(z_i|x_i, \Theta) = \prod_{i=1}^{n} \frac{\alpha_{z_i} \mathcal{N}(\mu_{z_i}, \Sigma_{z_i})}{\sum_{l=1}^{k} \alpha_l \mathcal{N}(\mu_l, \Sigma_l)}$$

The E-Step: (1)

$$
\begin{aligned}
Q(\Theta, \Theta^{(g)}) &= \int_{z} \ln\left(p(X, Z|\Theta)\right) p(Z|X, \Theta^{(g)}) \mathrm{d}z \\
&= \int_{z_1} \dots \int_{z_n} \left(\sum_{i=1}^{n} \ln p(z_i, x_i|\Theta) \prod_{i=1}^{n} p(z_i|x_i, \Theta^{(g)}) \right) \mathrm{d}z_1, \dots \mathrm{d}z_n
\end{aligned}
$$

- Let $P(Y)$ be the joint pdf: $P(y_1, ...y_n)$
- also let $F(Y)$ be a linear function, where each term involves only one variable y_i, i.e., $F(Y) = f_1(x_1) + \dots f_n(x_n) = \sum_{i=1}^{n} f_i(y_i)$

Theorem:

$$\int_{y_1} \cdots \int_{y_n} \left(\sum_{i=1}^{n} f_i(y_i) \right) P(Y) \mathrm{d}Y = \sum_{i}^{N} \left(\int_{y_i} f_i(y_i) P_i(y_i) \mathrm{d}y_i \right)$$

Proof

$$\int_Y (F(Y))P(Y)dY = \int_{y_1}\int_{y_2}\dots\int_{y_N}\left(\sum_{i=1}^{N}(f_i(y_i))\right)P(Y)\mathrm{d}y_1,\dots\mathrm{d}y_n$$

Expand it out, this equation has N sum terms. The first term is:

$$= \int_{y_1}\int_{y_2}\dots\int_{y_N} f_1(y_1)P(y_1,\dots,y_N)\prod_{i=1}^{N}(\mathrm{d}y_i) = \int_{y_1} f_1(y_1)\left(\int_{y_2}\dots\int_{y_N} P(y_1,\dots,y_N)\prod_{i=2}^{N}(\mathrm{d}y_i)\right)\mathrm{d}y_1$$

What's inside the big bracket becomes the marginal probability density of $P(y_1)$, therefore, the first term becomes:

$$= \int_{y_1} f_1(y_1)p(y_1)dy_1$$

Apply this to each of the N terms, therefore:

$$\int_Y (F(Y))P(Y)\mathrm{d}Y = \int_{y_1} f_1(y_1)P_1(y_1)\mathrm{d}y_1 + \dots + \int_{y_n} f_n(y_n)P_n(y_n)\mathrm{d}y_n$$

The E-Step: (2)

Knowing,

$$\int_{y_1} \cdots \int_{y_n} \left(\sum_{i=1}^{n} f_i(y_i) \right) P(Y) \mathrm{d} Y = \sum_{i}^{N} \left(\int_{y_i} f_i(y_i) P_i(y_i) \mathrm{d} y_i \right)$$

$$\begin{aligned}
Q(\Theta, \Theta^{(g)}) &= \int_{z_1} \cdots \int_{z_n} \left(\sum_{i=1}^{n} \ln p(z_i, x_i | \Theta) \prod_{i=1}^{n} p(z_i | x_i, \Theta^{(g)}) \right) \mathrm{d} z_1, \dots \mathrm{d} z_n \\
&= \sum_{i=1}^{n} \left(\int_{z_i} \ln p(z_i, x_i | \Theta) p(z_i | x_i, \Theta^{(g)}) \mathrm{d} z_i \right) \qquad z_i \in \{1, \dots, k\} \\
&= \sum_{z_i=1}^{k} \sum_{i=1}^{n} \ln p(z_i, x_i | \Theta) p(z_i | x_i, \Theta^{(g)}) \qquad \text{swap the summation terms} \\
&= \sum_{l=1}^{k} \sum_{i=1}^{n} \ln [\alpha_l \mathcal{N}(x_i | \mu_l, \Sigma_l)] p(l | x_i, \Theta^{(g)}) \qquad \text{substitute Gaussan and replace } z_i \rightarrow l
\end{aligned}$$

The M-Step objective function

$$
\begin{aligned}
Q(\Theta, \Theta^{(g)}) &= \sum_{l=1}^{k} \sum_{i=1}^{n} \ln[\alpha_l \mathcal{N}(x_i|\mu_l, \Sigma_l)] p(l|x_i, \Theta^{(g)}) \\
&= \sum_{l=1}^{k} \sum_{i=1}^{n} \ln(\alpha_l) p(l|x_i, \Theta^{(g)}) + \sum_{l=1}^{k} \sum_{i=1}^{n} \ln[\mathcal{N}(x_i|\mu_l, \Sigma_l)] p(l|x_i, \Theta^{(g)})
\end{aligned}
$$

The first term contains only α and the second term contains only μ, Σ. So we can maximize both terms independantly.

The M-Step: maximizing α

Maximizing α means that:

$$\frac{\partial \sum_{l=1}^{k} \sum_{i=1}^{n} \ln(\alpha_l) p(l|x_i, \Theta^{(g)})}{\partial \alpha_1, \dots, \partial \alpha_k} = [0 \dots 0] \qquad \text{subject to } \sum_{l=1}^{k} \alpha_l = 1$$

This is to be solved using Lagrange Multiplier

$$\mathbb{LM}(\alpha_1, \dots \alpha_k, \lambda) = \sum_{l=1}^{k} \ln(\alpha_l) \underbrace{\left(\sum_{i=1}^{n} p(l|x_i, \Theta^{(g)}) \right)}_{\text{contains no } \alpha} - \lambda \left(\sum_{l=1}^{k} -1 \right)$$

$$\implies \frac{\partial \mathbb{LM}}{\partial \alpha_l} = \frac{1}{\alpha_l} \left(\sum_{i=1}^{n} p(l|x_i, \Theta^{(g)}) \right) - \lambda = 0$$

$$\implies \alpha_l = \frac{1}{N} \sum_{i=1}^{n} p(l|x_i, \Theta^{(g)})$$

The M-Step: maximizing μ, Σ

Maximizing μ, Σ means that:

$$\frac{\partial \sum_{l=1}^{k} \sum_{i=1}^{n} \ln(\alpha_l) p(l|x_i, \Theta^{(g)})}{\partial \mu_1, \ldots, \partial \mu_k, \partial \Sigma_1, \ldots, \partial \Sigma_k} = [0 \ldots 0]$$

- You will need some linear algebra identities to solve this. It's quite involved. For details, please refer:
- J. Bilmes. "A Gentle Tutorial on the EM Algorithm and its Application to Parameter Estimation for Gaussian Mixture and Hidden Markov Models"

Some formulas to remember

Fact 1:

$$\sum_i x_i^T A x_i = \text{tr}\left(A \sum_i x_i x_i^T\right)$$

Fact 2:

$$\frac{\partial \ln |X|}{\partial X} = 2X^{-1} - \text{diag}(X^{-1})$$

When matrix X is symmetric:

$$\frac{\partial \text{tr}(XB)}{\partial X} = B + B^T - \text{diag}(B)$$

However, in general:

$$\frac{\partial \text{tr}(XB)}{\partial X} = B^T$$

Maximization μ_l

$$\text{second part of } Q(\Theta, \Theta^{(g)}) = \mathcal{S}(\mu_l, \Sigma_l^{-1}) = \sum_{l=1}^{k} \sum_{i=1}^{n} \ln[\mathcal{N}(x_i|\mu_l, \Sigma_l)] p(l|x_i, \Theta^{(g)})$$

$$\mathcal{S}(\mu_l, \Sigma_l^{-1}) = \sum_{i=1}^{n} \underbrace{-\frac{1}{2}\ln(|\Sigma_l|)}_{\text{Constant}} - \frac{1}{2}(x_i - \mu_l)^T \Sigma^{-1}(x - \mu_l) p(l|x_i, \Theta^{(g)})$$

$$\implies \mathcal{S}(\mu_l, \Sigma_l^{-1}) = -\text{Tr}\left(\frac{\Sigma_l^{-1}}{2} \sum_{i=1}^{n} (x_i - \mu_l)(x - \mu_l)^T p(l|x_i, \Theta^{(g)})\right) + \text{ Constant}$$

$$\implies \frac{\partial \mathcal{S}(\mu_l, \Sigma_l^{-1})}{\partial \mu_l} = \frac{2\Sigma^{-1} - \text{diag}(\Sigma^{-1})}{2} \sum_{i=1}^{n} 2(x_i - \mu_l) p(l|x_i, \Theta^{(g)}) = 0$$

$$\implies \sum_{i=1}^{n} x_i p(l|x_i, \Theta^{(g)}) = \mu_l \sum_{i=1}^{n} p(l|x_i, \Theta^{(g)})$$

$$\implies \mu_l = \frac{\sum_{i=1}^{n} p(l|x_i, \Theta^{(g)})}{\sum_{i=1}^{n} x_i p(l|x_i, \Theta^{(g)})}$$

Maximization Σ_l

$$\mathcal{S}(\mu_l, \Sigma_l^{-1}) = \sum_{i=1}^{n} \left(-\frac{1}{2}\ln(|\Sigma_l|) - \frac{1}{2}(x_i - \mu_l)^T \Sigma^{-1}(x - \mu_l) \right) p(l|x_i, \Theta^{(g)})$$

Change Σ to Σ^{-1}, this is so that after taking derivative of $\ln(X)$, the result is in terms of X^{-1}

$$= \left(\sum_{i=1}^{n} \ln(|\Sigma_l^{-1}|) p(l|x_i, \Theta^{(g)}) - \frac{1}{2}\mathrm{tr}\left(\Sigma^{-1} \underbrace{\sum_{i=1}^{n}(x_i - \mu_l)(x - \mu_l)^T p(l|x_i, \Theta^{(g)})}_{M_l} \right) \right)$$

$$\implies \frac{\partial \mathcal{S}(\mu_l, \Sigma_l^{-1})}{\partial \Sigma_l^{-1}} = \frac{2\sum_{i=1}^{n} \Sigma_l p(l|x_i, \Theta^{(g)}) - \sum_{i=1}^{n} \mathrm{diag}(\Sigma) p(l|x_i, \Theta^{(g)})}{2} - \frac{2M_l - \mathrm{diag}(M_l)}{2} = 0$$

$$\implies 2(\sum_{i=1}^{n} \Sigma p(l|x_i, \Theta^{(g)}) - M_l) - \sum_{i=1}^{n} \mathrm{diag}(\Sigma p(l|x_i, \Theta^{(g)}) - M_l) = 0$$

$$\implies \sum_{i=1}^{n} \Sigma p(l|x_i, \Theta^{(g)}) - M_l = 0$$

$$\implies \Sigma = \frac{\sum_{i=1}^{n} M_l}{\sum_{i=1}^{n} p(l|x_i, \Theta^{(g)})} = \frac{\sum_{i=1}^{n}(x_i - \mu_l)(x - \mu_l)^T p(l|x_i, \Theta^{(g)})}{\sum_{i=1}^{n} p(l|x_i, \Theta^{(g)})}$$

Summary of Gaussian Mixture Model

Maximizing μ, Σ means that to update $\Theta^{(g)} \rightarrow \Theta^{(g+1)}$:

$$\alpha_l^{(g+1)} = \frac{1}{N} \sum_{i=1}^{N} p(l|x_i, \Theta^{(g)})$$

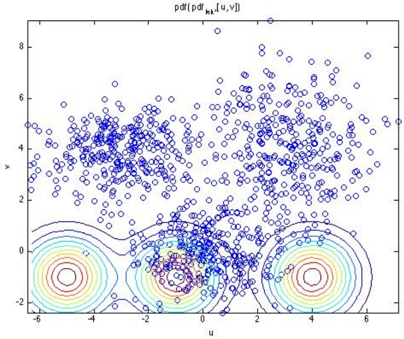
$$\mu_l^{(g+1)} = \frac{\sum_{i=1}^{N} x_i p(l|x_i, \Theta^{(g)})}{\sum_{i=1}^{N} p(l|x_i, \Theta^{(g)})}$$

$$\Sigma_l^{(g+1)} = \frac{\sum_{i=1}^{N} [x_i - \mu_l^{(i+1)}][x_i - \mu_l^{(i+1)}]^T p(l|x_i, \Theta^{(g)})}{\sum_{i=1}^{N} p(l|x_i, \Theta^{(g)})}$$

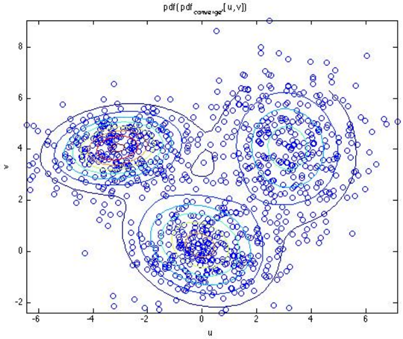
To program it to MATLAB, note that we need to compute the responsibility probability $p(l|x_i, \Theta^{(g)}) = \frac{\mathcal{N}(x_i|\mu_l, \Sigma_l)}{\sum_{s=1}^{k} \mathcal{N}(x_i|\mu_s, \Sigma_s)}$

To show the diagram again

This shows $\Theta^{(1)}$:

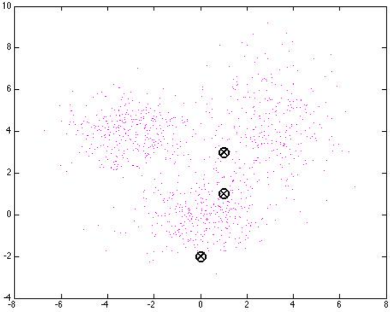


This shows $\Theta^{(\text{Converge})}$:



Other clustering methods: K-means

This shows the data and the initial "means":

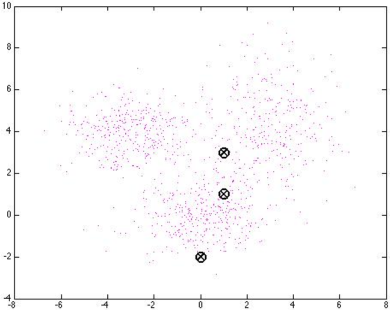


- Imagine we know that there are K types of data, and we have N data.
- How do we cluster these N data into K types automatically?
- Like GMM, this is unsupervised, clustering algorithm

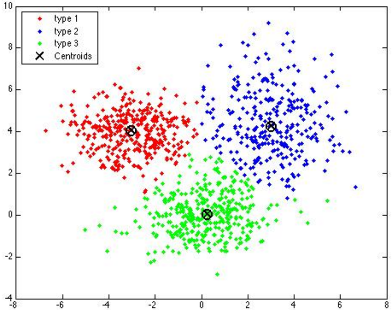
- **STEP 1:** Place K points into the space represented by the objects that are being clustered. These points represent initial group centroids.
- **STEP 2:** Assign each object to the group that has the closest centroid.
- **STEP 3:** When all objects have been assigned, recalculate the positions of the K centroids. Repeat Steps 2 and 3 until the centroids no longer move.

K-means

The data and the initial K "means":



The final K "means":



See the MATLAB Demos