



Queen Mary
University of London

Science and Engineering

School of Electronic Engineering and Computer Science
QMUL-BUPT Joint Programme

EBU6475 Microprocessor System Design

EBU5476 Microprocessors for Embedded Computing

Introduction to Embedded Systems Design

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University Program Education Kits

Introduction

- What is an Embedded System?
 - Application-specific computer system
 - Built into a larger system
- Why add a computer to the larger system?
 - Better performance
 - More functions and features
 - Lower cost
 - More dependability
- Economics
 - Microcontrollers (used for embedded computers) are high-volume, so recurring cost is low
 - Nonrecurring cost dominated by software development
- Networks
 - Often embedded system will use multiple processors communicating across a network to lower parts and assembly costs and improve reliability

Options for Building Embedded Systems

	Implementation	Design Cost	Unit Cost	Upgrades & Bug Fixes	Size	Weight	Power	System Speed
Dedicated Hardware	Discrete Logic	low	mid	hard	large	high	?	very fast
	ASIC	high (\$500K/ mask set)	very low	hard	tiny - 1 die	very low	low	extremely fast
	Programmable logic – FPGA, PLD	low	mid	easy	small	low	medium to high	very fast
Software Running on Generic Hardware	Microprocessor + memory + peripherals	low to mid	mid	easy	small to med.	low to moderate	medium	moderate
	Microcontroller (int. memory & peripherals)	low	mid to low	easy	small	low	medium	slow to moderate
	Embedded PC	low	high	easy	medium	moderate to high	medium to high	fast

Example:

Embedded System: Bike Computer

- Functions
 - Speed and distance measurement
- Constraints
 - Size
 - Cost
 - Power and Energy
 - Weight
- Inputs
 - Wheel rotation indicator
 - Mode key
- Output
 - Liquid Crystal Display
- Low performance MCU
 - 8-bit, 10 MIPS



Example: Motor Control Unit

- Functions
 - Motor control
 - System communications
 - Current monitoring
 - Rotation speed detection
- Constraints
 - Reliability in harsh environment
 - Cost
 - Weight
- Many Inputs and Outputs
 - Discrete sensors & actuators
 - Network interface to rest of car
- High Performance MCU
 - 32-bit, 256 KB flash memory, 80 MHz

Benefits of Embedded Computer Systems

- Greater performance and efficiency
 - Software makes it possible to provide sophisticated control
- Lower costs
 - Less expensive components can be used
 - Manufacturing costs reduced
 - Operating costs reduced
 - Maintenance costs reduced
- More features
 - Many not possible or practical with other approaches
- Better dependability
 - Adaptive system which can compensate for failures
 - Better diagnostics to improve repair time

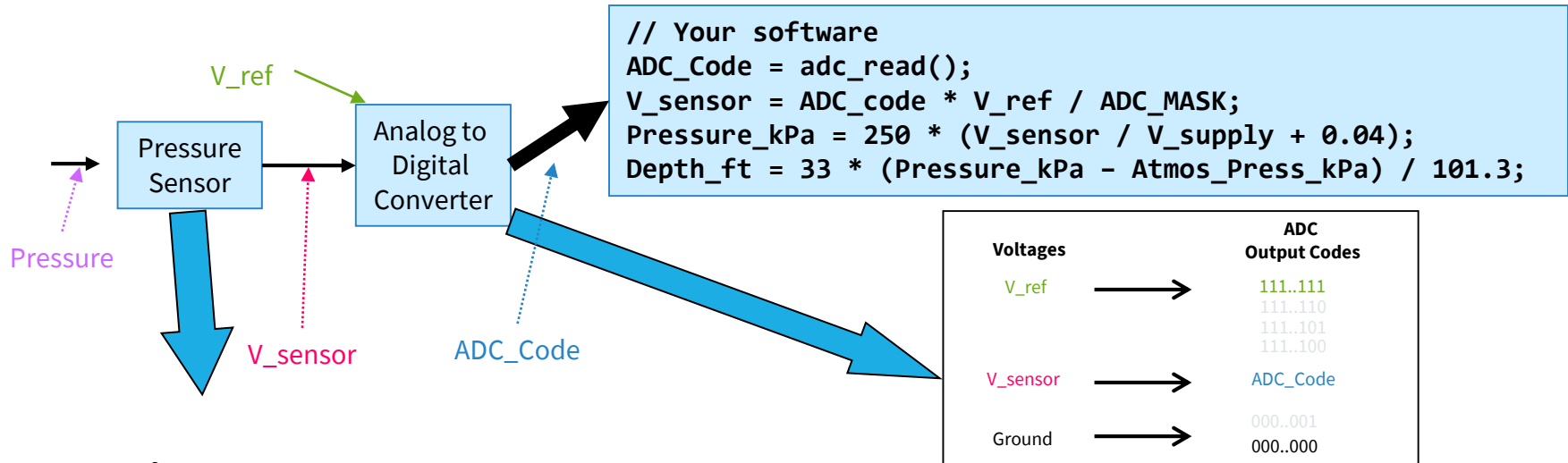
Embedded System Functions

- Closed-loop control system
 - Monitor a process, adjust an output to maintain desired set point (temperature, speed, direction, etc.)
- Sequencing
 - Step through different stages based on environment and system
- Signal processing
 - Remove noise, select desired signal features
- Communications and networking
 - Exchange information reliably and quickly

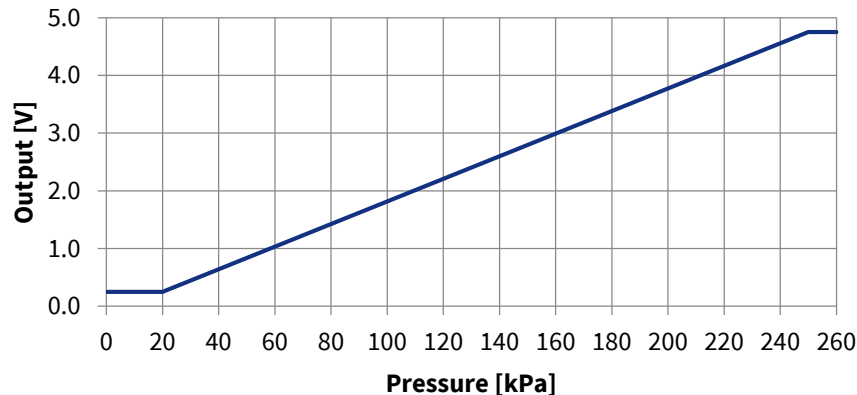
Attributes of Embedded Systems

- Interfacing with larger system and environment
 - Analog signals for reading sensors
 - Typically use a voltage to represent a physical value
 - Power electronics for driving motors, solenoids
 - Digital interfaces for communicating with other digital devices
 - Simple - switches
 - Complex - displays

Example: Analog Sensor - Depth Gauge



Typical Absolute Pressure vs. Output



- Sensor detects pressure and generates a proportional output voltage V_{sensor}
- ADC generates a proportional digital integer (code) based on V_{sensor} and V_{ref}
- Code can convert that integer to a something more useful
 - first a float representing the voltage,
 - then another float representing pressure,
 - finally another float representing depth

Microcontroller vs. Microprocessor

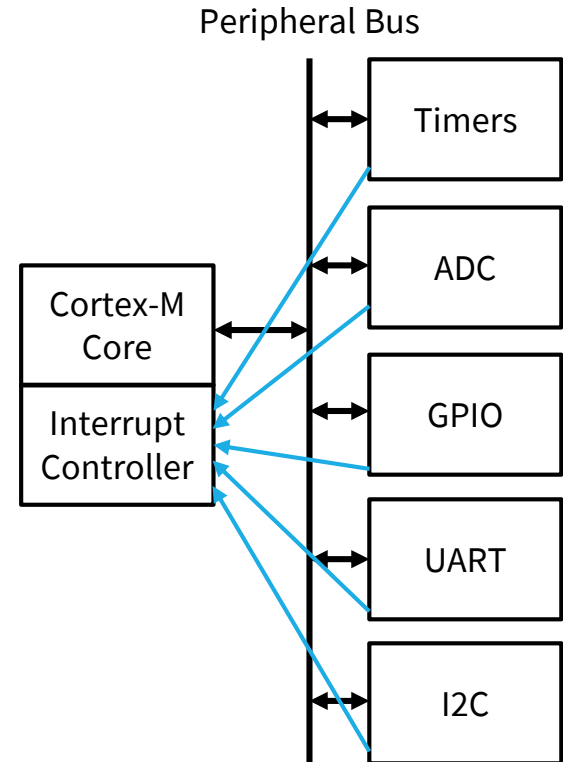
- Both have a CPU core to execute instructions
- Microcontroller has on-chip peripherals for concurrent embedded interfacing and control
 - Analog
 - Non-logic level signals
 - Timing
 - Clock generators
 - Communications
 - Reliability and safety

Attributes of Embedded Systems

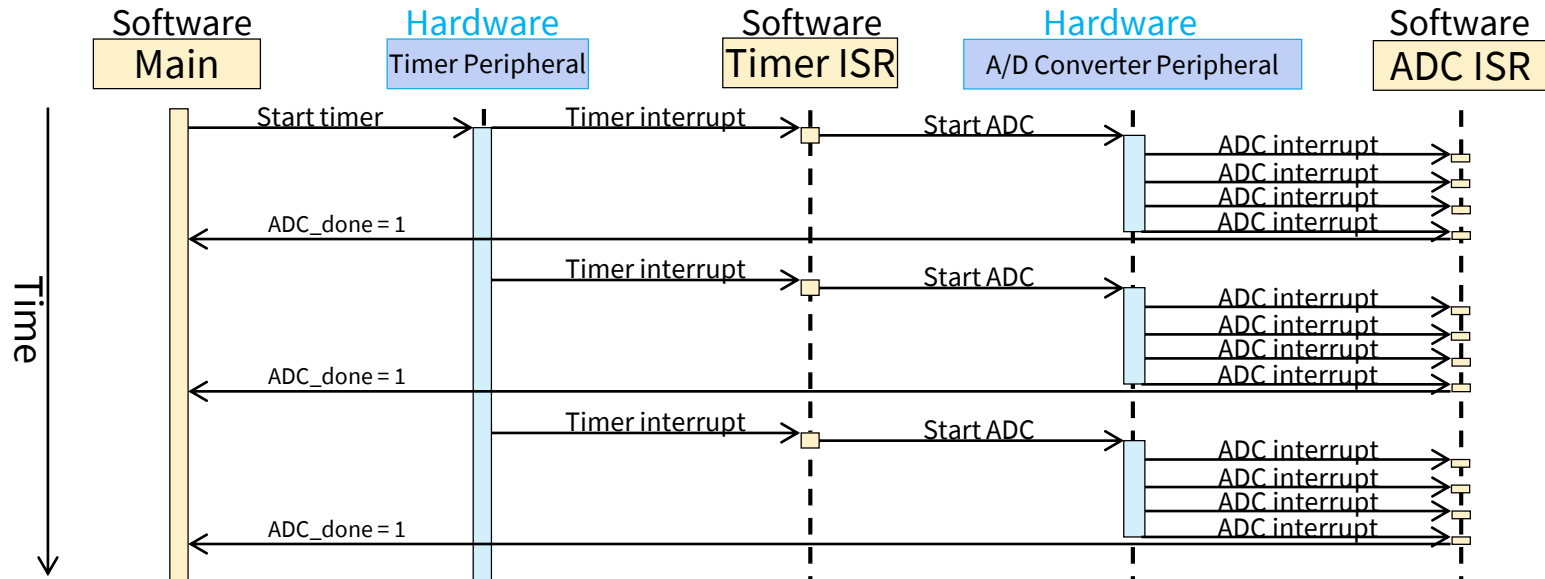
- Concurrent, reactive behaviors
 - Continuously react to inputs from the environment by generating corresponding outputs
 - Must respond to sequences and combinations of events
 - Real-time systems have deadlines on responses
 - Typically must perform multiple separate activities concurrently
 - Typical applications include vehicle control, consumer electronics, remote sensing, smart household appliances etc.

MCU Hardware & Software for Concurrency

- CPU executes instructions from one or more thread of execution
- Specialized hardware peripherals add dedicated concurrent processing
 - Watchdog timer
 - Analog interfacing
 - Timers
 - Communications with other devices
 - Detecting external signal events
 - LCD driver
- Peripherals use interrupts to notify CPU of events



Concurrent Hardware & Software Operation



- Embedded systems rely on both MCU hardware peripherals and software to get everything done on time

Attributes of Embedded Systems

- Fault handling
 - Many systems must operate independently for long periods of time, requiring system to handle likely faults without crashing
 - Often fault-handling code is larger and more complex than the normal-case code
- Diagnostics
 - Help service personnel determine problem quickly

Constraints

- Cost
 - Competitive markets penalize products which don't deliver adequate value for the cost
- Size and weight limits
 - Mobile (aviation, automotive) and portable (e.g. handheld) systems
- Power and energy limits
 - Battery capacity
- Environment
 - Temperatures may range from -40°C to 125°C, or even more
 - Cooling limits

Impact of Constraints

- Microcontrollers used (rather than microprocessors)
 - Include peripherals to interface with other devices, respond efficiently
 - On-chip RAM, ROM reduce circuit board complexity and cost
- Programming language
 - Programmed in C rather than Java (smaller and faster code, so less expensive MCU)
 - Some performance-critical code may be in assembly language
- Operating system
 - Typically no OS, but instead simple scheduler (or even just interrupts + main code (foreground/background system))
 - If OS is used, likely to be a lean RTOS

Overview of this module

- Introductory Course:
- Building an Embedded System with an MCU
 - Microcontroller concepts
 - Processor core architecture and interrupt system
 - C as implemented in assembly language
 - Peripherals and interfacing

Why Are We...?

- Using C instead of Java (or Python, or your other favourite language)?
 - C is the de facto standard for embedded systems because of:
 - Precise control over what the processor is doing.
 - Modest requirements for ROM, RAM, and MIPS, so much cheaper system
 - Predictable behavior, no OS needed
- Learning assembly language?
 - The compiler translates C into assembly language. To understand whether the compiler is doing a reasonable job, you need to understand what it has produced.
 - Sometimes we may need to improve performance by writing assembly versions of functions.

Short Quiz (1)

- Which of the following includes on-chip peripherals?
 - (a) Microcontroller (MCU)
 - (b) Microprocessor (MPU)
- When building a system, which hardware is the most suitable if targeting a specific application for optimization in size, footprint, and power consumption?
 - (a) ASIC
 - (b) Embedded PC
 - (c) Programmable logic (FPGA, PLD)
 - (d) Microcontroller (internal memory and peripherals)
- Which programming language is most commonly used for programming microcontrollers?
 - (a) Java/Swift 3
 - (b) Assembly language
 - (c) C and assembly language
 - (d) All of the above

Short Quiz (2)

- How does an embedded system usually represent logic values physically?
 - (a) Different current levels
 - (b) Different voltage levels
 - (c) None of these
 - (d) Both (a) and (b) are correct
- In which of the following applications can the MCU not be used as the main processor?
 - (a) Automotive (brakes, speed control, etc)
 - (b) Smart Watch
 - (c) Electronic home devices (washing machines, microwaves, etc)
 - (d) None of the above
- How can a peripheral notify a CPU of events?
 - (a) Using exceptions
 - (b) Using interrupts
 - (c) Using polling
 - (d) None of the above