EBU4375 Signals and Systems Theory

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Basic Time Signals

Basic Continuous-Time Signals

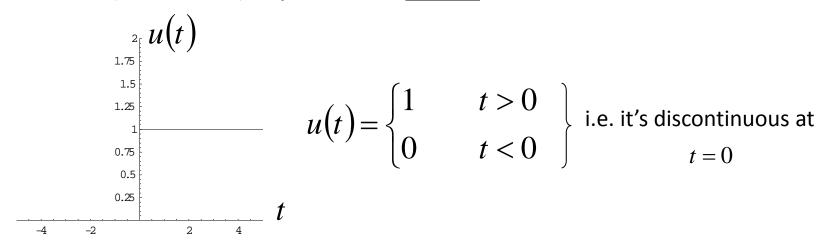
- The Unit-Step Function
- The Unit-Impulse Function
- Complex Exponential and Sinusoidal Signals

Basic Discrete-Time Signals

- The Unit-Step Sequence
- The Unit-Impulse Sequence
- Complex Exponential and sinusoidal Sequence

The Unit-Step Function (CT Signals)

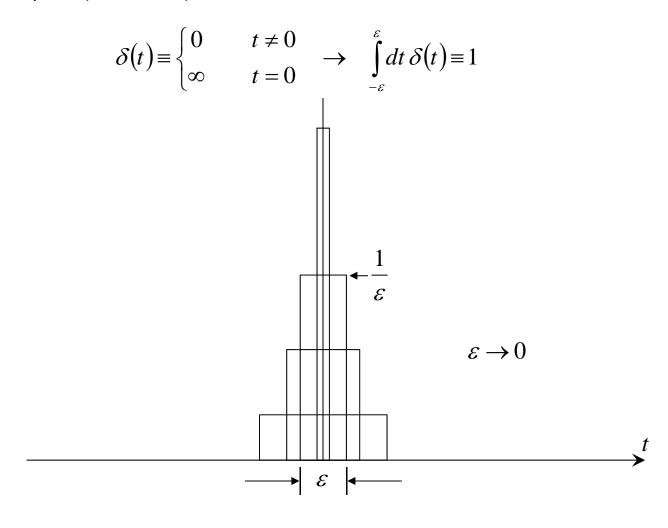
• the unit (or Heaviside) step function is <u>defined</u> as



• the shifted (retarded) step function is similarly defined as

The Unit-Impulse Function (CT Signals)

The unit-impulse (Dirac-delta) function is defined as

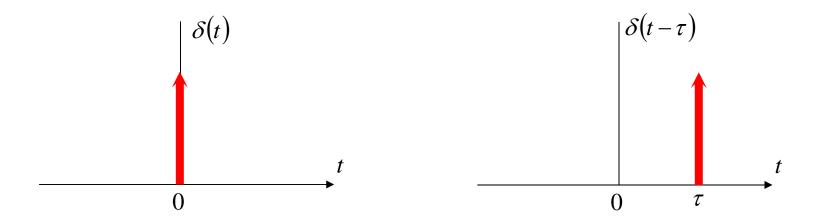


The Unit-Impulse Function (CT Signals)

• It is also defined by

$$\int_{a}^{b} dt \, \phi(t) \mathcal{S}(t) \equiv \begin{cases} \phi(0) & a < 0 < b \\ 0 & a < b < 0 \text{ or } 0 < a < b \\ undefined & a = 0 \text{ or } b = 0 \end{cases}$$

• A delayed (retarded) delta function $\delta(t-\tau)$ is <u>defined</u> by $\int_{-\infty}^{\infty} dt \, \phi(t) \delta(t-\tau) = \phi(\tau)$ (1)



The Unit-Impulse Function (CT Signals)

Properties of $\delta(t)$:

$$\delta(at) = \frac{1}{|a|} \delta(t)$$

$$\delta(-t) = \delta(t) \qquad (2)$$

$$x(t)\delta(t) = x(0)\delta(t) \qquad (\text{if } x(t) \text{ is continuous at } t = 0)$$

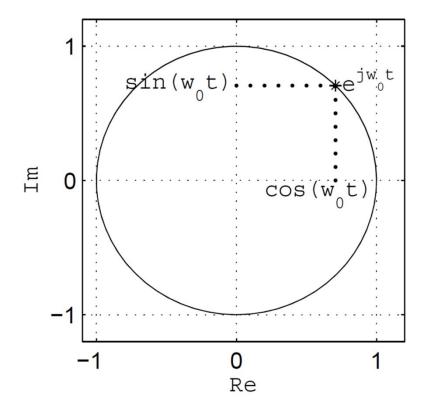
$$x(t)\delta(t-\tau) = x(\tau)\delta(t-\tau) \qquad (\text{if } x(t) \text{ is continuous at } t = \tau)$$

A continuous-time signal x(t) may be expressed as (we prove this in the following lecture)

$$x(t) = \int_{-\infty}^{\infty} d\tau \, x(\tau) \delta(t - \tau)$$

Euler's formula:
$$e^{jw_0t} = \underbrace{\cos(w_0t)}_{\text{Re}\{e^{jw_0t}\}} + j\underbrace{\sin(w_0t)}_{\text{Im}\{e^{jw_0t}\}}$$

where $j = \sqrt{-1}$, $w_0 \neq 0$ is real, and t is the time.



Since

$$e^{jw_0\left(t+\frac{2\pi}{|w_0|}\right)} = e^{jw_0t}e^{j2\pi\frac{w_0}{|w_0|}} = e^{jw_0t}\underbrace{e^{j2\pi\mathrm{sign}(w_0)}}_{=1} = e^{jw_0t}$$

we have

$$e^{jw_0t}$$
 is periodic with fundamental period $\frac{2\pi}{|w_0|}$

Note that

•
$$e^{j2\pi k} = 1$$
, for $k = 0, \pm 1, \pm 2, \dots$

- e^{jw_0t} and e^{-jw_0t} have the same fundamental period
- Energy in e^{jw_0t} : $\int_{-\infty}^{\infty} |e^{jw_0t}|^2 dt = \int_{-\infty}^{\infty} 1.dt = \infty$
- Average Power in e^{jw_0t} : $\lim_{T\to\infty} \frac{1}{2T} \int_{-T}^T |e^{jw_0t}|^2 dt$

$$= \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} 1.dt = 1$$

$$Ce^{at}$$

where C and a are complex numbers.

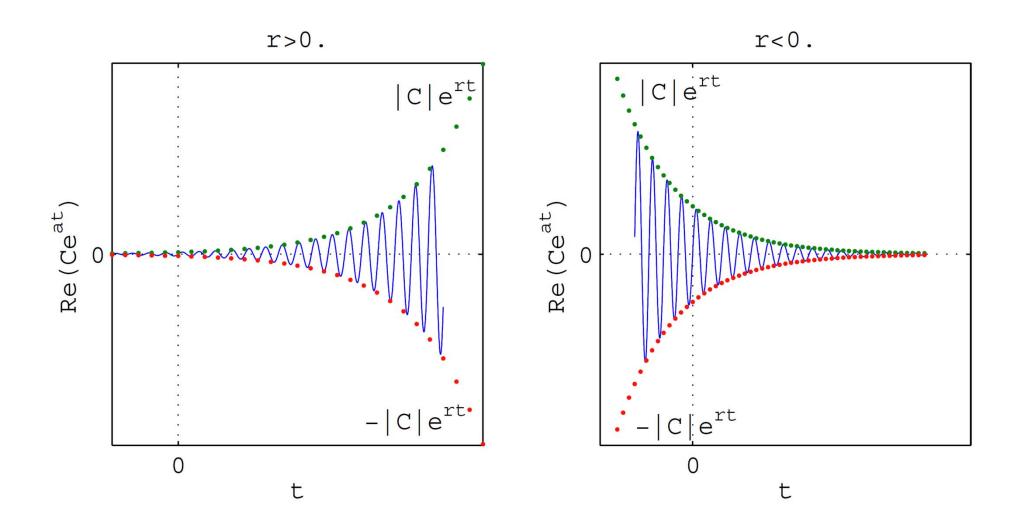
If

$$C = |C|e^{j\theta}$$
 and $a = r + jw_0$

then

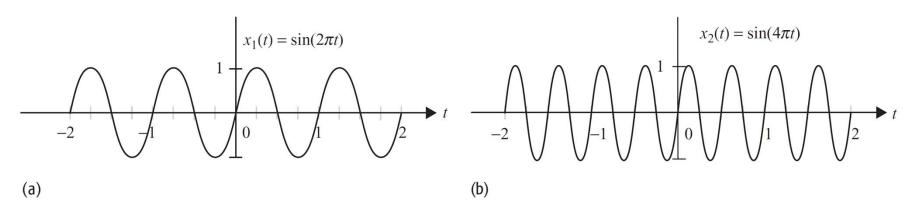
$$Ce^{at} = |C|e^{j\theta}e^{(r+jw_0)t} = |C|e^{rt}e^{j(w_0t+\theta)}$$

$$= \underbrace{|C|e^{rt}\cos(w_0t+\theta)}_{\text{Re}(Ce^{at})} + j\underbrace{|C|e^{rt}\sin(w_0t+\theta)}_{\text{Im}(Ce^{at})}$$



Periodicity and Fundamental Period (CT Signals)

Consider two sinusoidal functions $x(t) = \sin(\omega_0 t + \theta)$ and $x_m(t) = \sin(m\omega_0 t + \theta)$. The fundamental angular frequencies of these two CT signals are given by ω_0 and $m\omega_0$ radians/s, respectively. In other words, the angular frequency of the signal $x_m(t)$ is m times the angular frequency of the signal x(t). In such cases, the CT signal $x_m(t)$ is referred to as the mth harmonic of x(t).



Examples of harmonics. (a) Waveform for the sinusoidal signal $x(t) = \sin(2\pi t)$; (b) waveform for its second harmonic given by $x_2(t) = \sin(4\pi t)$.

Periodicity and Fundamental Period (CT Signals)

Proposition A signal g(t) that is a linear combination of two periodic signals, $x_1(t)$ with fundamental period T_1 and $x_2(t)$ with fundamental period T_2 as follows:

$$g(t) = ax_1(t) + bx_2(t)$$

is periodic iff

$$\frac{T_1}{T_2} = \frac{m}{n} = rational \ number.$$

The fundamental period of g(t) is given by $nT_1 = mT_2$ provided that the values of m and n are chosen such that the greatest common divisor (gcd) between m and n is 1.

Periodicity and Fundamental Period (CT Signals)

Example

Determine if the following signals are periodic. If yes, determine the fundamental period.

$$g_1(t) = 3\sin(4\pi t) + 7\cos(3\pi t);$$

Solution

$$\frac{T_1}{T_2} = \frac{1/2}{2/3} = \frac{3}{4}$$

fundamental period of $g_1(t)$ is given by $nT_1 = 4T_1 = 2$ s.

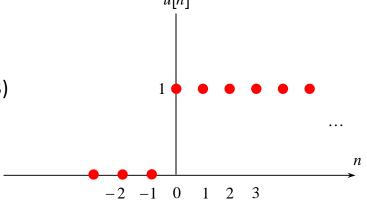
fundamental period of $g_1(t)$ can also be evaluated from $mT_2 = 3T_2 = 2$ s.

The Unit-Step Sequence (DT Signals)

ullet The unit-step sequence u[n] is defined by

$$u[n] \equiv \begin{cases} 1 & n \ge 0 \\ 0 & n < 0 \end{cases} \tag{3}$$

Unlike u(t), u[n] <u>is</u> defined at n = 0



• The shifted unit-step sequence u[n-k] is similarly defined by

$$u[n-k] \equiv \begin{cases} 1 & n \ge k \\ 0 & n < k \end{cases}$$

$$(4)$$

$$1$$

$$-2 -1 \quad 0 \quad 1 \qquad k$$

The Unit-Impulse Sequence (DT Signals)

ullet The unit-impulse (or unit-sample) sequence $\,\delta[n]$ is defined by

$$\mathcal{S}[n] = \begin{cases} 1 & n=0 \\ 0 & n \neq 0 \end{cases} \tag{5}$$

ullet The shifted unit-impulse (sample) sequence $\delta[n-k]$ is similarly defined by

$$\delta[n-k] = \begin{cases} 1 & n=k \\ 0 & n \neq k \end{cases}$$
 (6)

The Unit-Impulse Sequence (DT Signals)

• Unlike $\delta(t)$, $\delta[n]$ is readily defined. From (5) and (6) it is evident that

$$x[n]\delta[n] = x[0]\delta[n]$$
$$x[n]\delta[n-k] = x[k]\delta[n-k]$$

are the discrete-time counterparts of

$$x(t)\delta(t) = x(0)\delta(t)$$
$$x(t)\delta(t-\tau) = x(\tau)\delta(t-\tau)$$

ullet from (3) and (4), $\delta[n]$ and u[n] are related by

$$\delta[n] = u[n] - u[n-1]$$

$$u[n] = \sum_{k=0}^{\infty} \delta[n-k]$$

A discrete-time signal x[n] may be expressed as (we prove this in the following lecture)

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

$$x[n] = e^{jw_0 n}$$

 e^{jw_0n} is periodic $\Leftrightarrow e^{jw_0n} = e^{jw_0(n+M)}$ for some integer M > 0

 $\Leftrightarrow e^{jw_0M} = 1 \text{ for some integer } M > 0$

 $\Leftrightarrow w_0 M = 2\pi m \text{ for some integers } m, M > 0$

 $\Leftrightarrow \frac{w_0}{2\pi}$ is rational.

• If $\frac{w_0}{2\pi} = \frac{m}{M}$ for some integers m and M which have no common factors, then the fundamental period is

$$M = \frac{2m\pi}{w_0}$$

Periodicity and Fundamental Period (DT Signals)

Examples

1) Is $x[n] = e^{jn2\pi/3} + e^{jn3\pi/4}$ periodic? If it is periodic, what's its fundamental period?

For $e^{jn2\pi/3}$, $w_0/(2\pi) = 1/3$, so $e^{jn2\pi/3}$ is periodic with fundamental period 3.

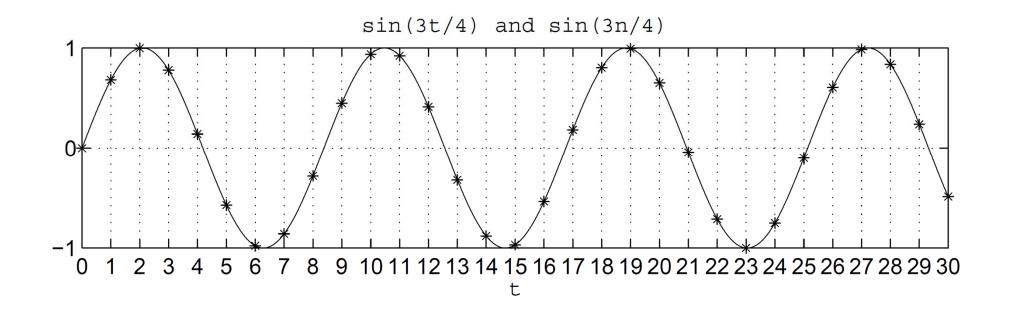
For $e^{jn3\pi/4}$, $w_0/(2\pi) = 3/8$, so $e^{jn3\pi/4}$ is periodic with fundamental period 8.

x[n] is periodic with fundamental period 24 = lcm(3, 8).

Periodicity and Fundamental Period (DT Signals)

Examples

2) Is $x[n] = \sin(3n/4)$ periodic? If it is periodic, what's its fundamental period? Since $\frac{w_0}{2\pi} = \frac{3}{8\pi}$ is irrational, x[n] is not periodic



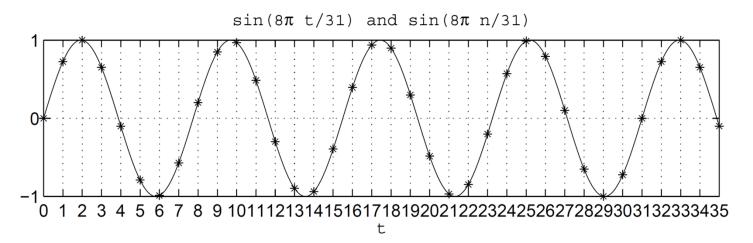
Periodicity and Fundamental Period (DT Signals)

Examples

3) Is $x[n] = \sin(8\pi n/31)$ periodic? If it is periodic, what's its fundamental period? Since $w_0/(2\pi) = 4/31$, x[n] is periodic with fundamental period 31

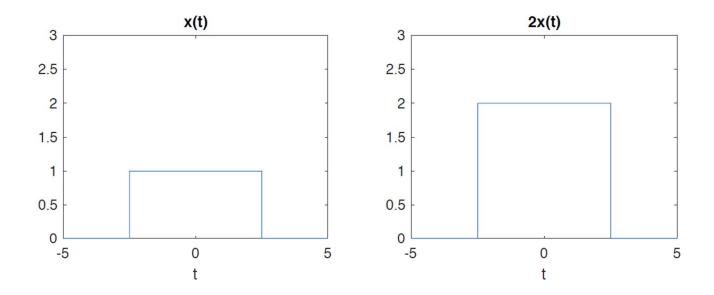
$$x[0] = x[31] = 0$$

Note that the continuous-time signal $\sin(8\pi t/31)$ has fundamental period 31/4 But x[n] has no 31/4—th sample and it misses 0 between x[7] and x[8]



Operations – Amplitude Scaling (CT Signals)

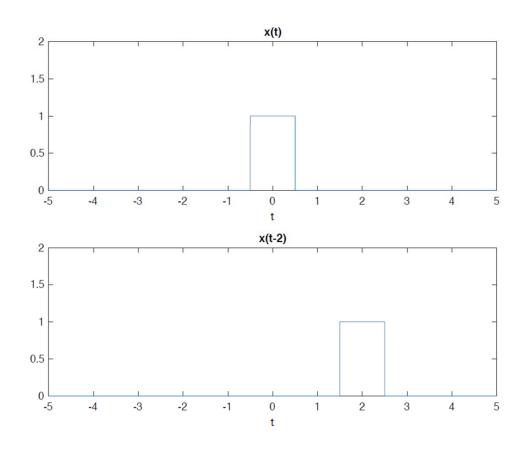
Given a CT signal x(t), scaling consist of multiplying it by a scalar value a, producing the new signal y(t) = ax(t).



Scaling is defined in an analogous way for DT signals.

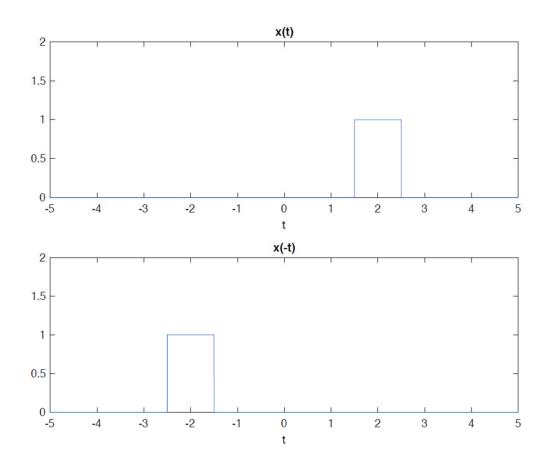
Operations – Time Shift (CT Signals)

Given a CT signal x(t), time shifting by t_0 units of time produces the new signal $y(t) = x(t - t_0)$ (DT shifting is defined in a similar way).



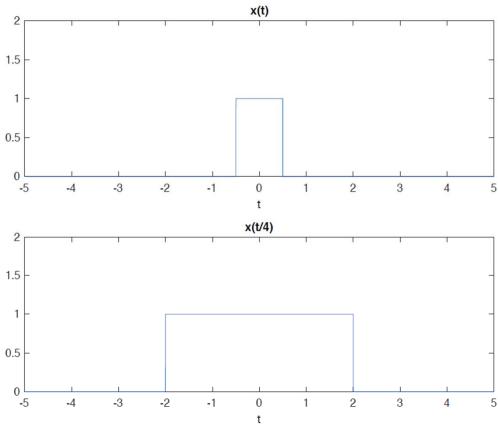
Operations – Time Inversion/Reversal (CT Signals)

Time reversal *flips* the time axis producing the signal y(t) = x(-t).



Operations – Time Scaling (CT Signals)

Time scaling **expands** or **compresses** the time axis. Signal y(t) = x(at) is a compressed version of x(t) if |a| > 1, and an expanded version if |a| < 1.



Operations – Combined Time Operations (CT Signals)

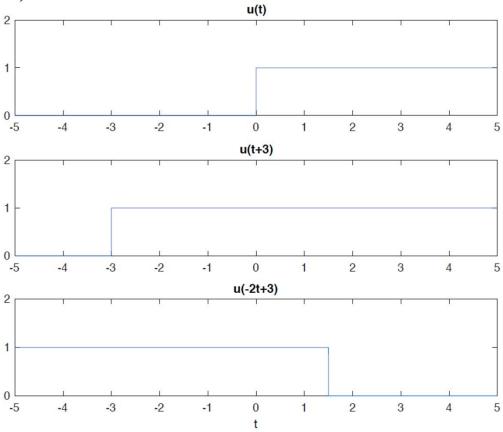
Consider the signal x(t) = u(-2t + 3). In order to obtain x(t) we will take the following steps:

- ▶ Define the time-shift y(t) = u(t+3).
- ▶ Define the time scaling and reverse z(t) = y(-2t).

As we can see, z(t) = y(-2t) = u(-2t + 3) and therefore x(t) = z(t).

Operations – Combined Time Operations (CT Signals)

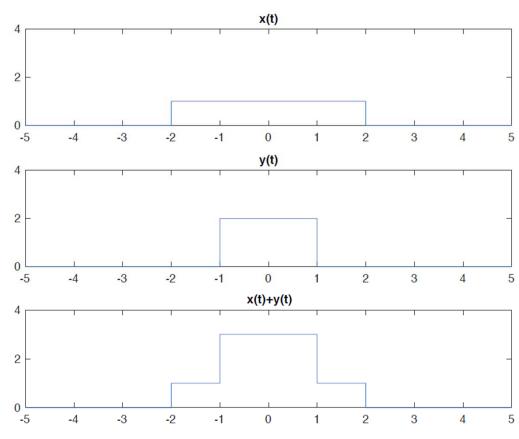
In general, we can obtain the signal $y(t) = x(-at + t_0)$ by shifting x(t) first and then by scaling and time reversing the result. Graphically, the signal u(-2t+3) can be obtained as follows:



You can see that u(-2(1.5) + 3) = u(0).

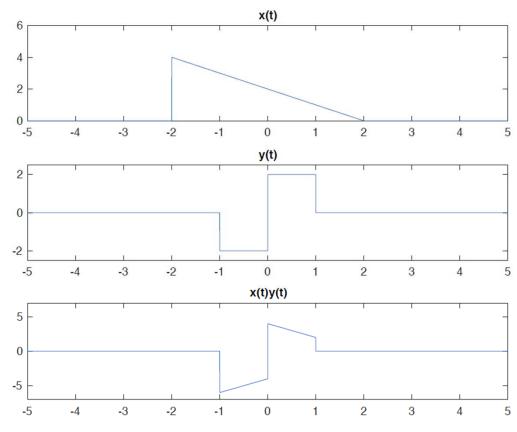
Operations – Sum (CT Signals)

Adding two signals x(t) and y(t) means adding their values each time instant.



Operations – Product (CT Signals)

Similarly, we multiply signals by multiplying their values each time instant.

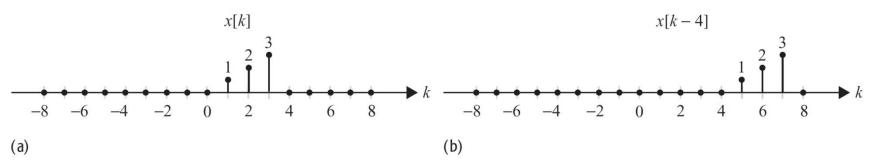


Operations – Time Shift (DT Signals)

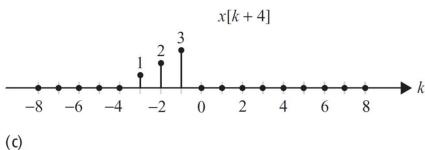
When a DT signal x[k] is shifted by m time units, the delayed signal $\phi[k]$ is expressed as

$$\phi[k] = x[k+m]$$

If m < 0, the signal is said to be delayed in time.



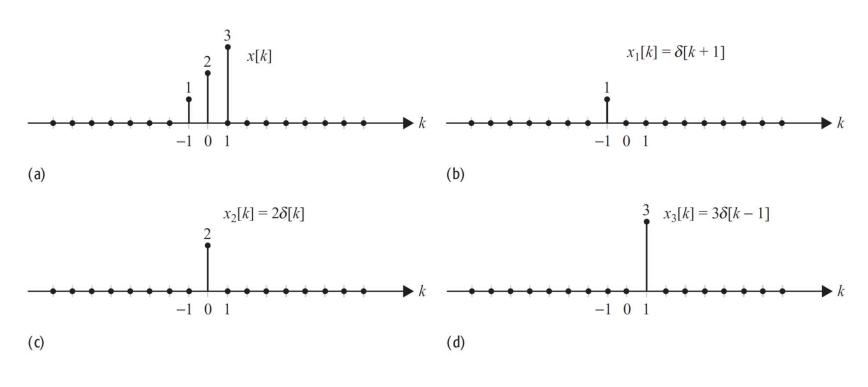
Time shifting of a DT signal. (a) Original DT signal x[k]. (b) Time-delayed version x[k-4] of the DT signal x[k]. (c) Time-advanced version x[k+4] of the DT signal x[k].



Operations – Time Shift (DT Signals)

Example

Represent the DT sequence shown in (a) as a function of time-shifted DT unit impulse functions.



$$x[k] = \delta[k+1] + 2\delta[k] + 3\delta[k-1]$$

Operations – Time Inversion/Reversal (DT Signals)

$$y(n) = x(-n)$$

positive time switches to negative time and vice versa

Example

Sketch the time-inverted version of the following DT sequence:

$$x[k] = \begin{cases} 1 & -4 \le k \le -1 \\ 0.25k & 0 \le k \le 4 \\ 0 & \text{elsewhere,} \end{cases}$$

Operations – Time Inversion/Reversal (DT Signals)

Solution

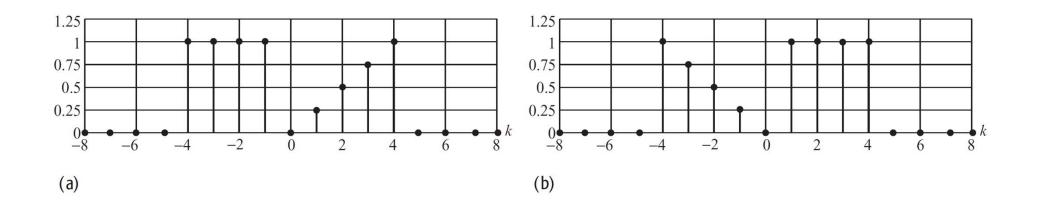
To derive the expression for the time-inverted signal x[-k], substitute k = -m

$$x[-m] = \begin{cases} 1 & -4 \le -m \le -1 \\ -0.25m & 0 \le -m \le 4 \\ 0 & \text{elsewhere.} \end{cases}$$

Simplifying the above expression and expressing it in terms of the independent variable k yields

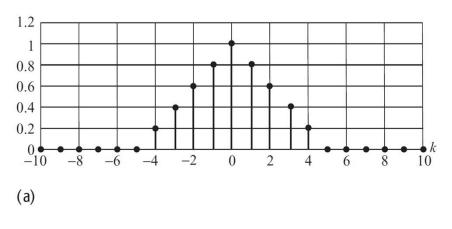
$$x[-m] = \begin{cases} 1 & 1 \le m \le 4 \\ -0.25m & -4 \le m \le 0 \\ 0 & \text{elsewhere.} \end{cases}$$

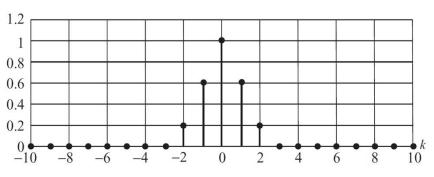
Operations – Time Inversion/Reversal (DT Signals)



- (a) Original CT sequence x[k]
- (b) Time-inverted version x[-k]

Operations – Time Scaling (DT Signals) also known as Decimation and Interpolation

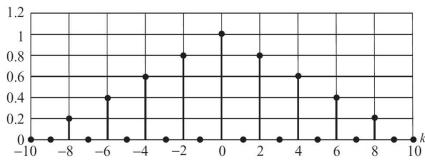




(a) Original DT sequence x[k].(b) Decimated version x[2k], of

x[k]. (c) Interpolated version

x[0.5k] of signal x[k].



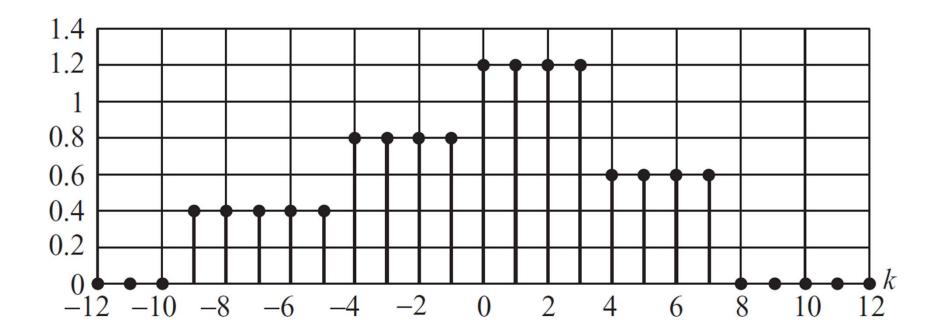
(c)

(b)

Operations – Combined Time Operations (DT Signals)

Example

Sketch the waveform for x[-15 - 3k] for the DT sequence x[k]



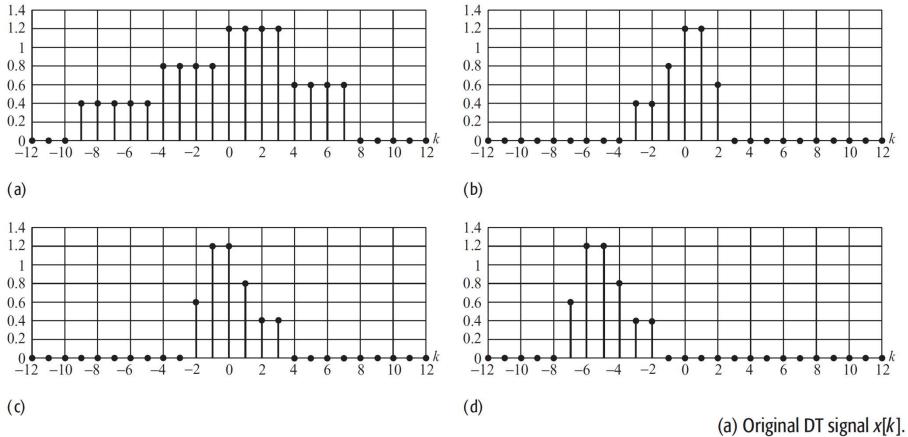
Operations – Combined Time Operations (DT Signals)

Solution

Express x[-15 - 3k] = x[-3(k+5)] and follow steps (i)–(iii) as outlined below.

- (i) Compress x[k] by a factor of 3 to obtain x[3k].
- (ii) Time-reverse x[3k] to obtain x[-3k].
- (iii) Shift x[-3k] towards the left-hand side by five time units to obtain x[-3(k+5)] = x[-15-3k].

Operations – Combined Time Operations (DT Signals)



- (b) Time-scaled version x[3k].
- (c) Time-inverted version x[-3k] of (b). (d) Time-shifted version x[-15 - 3k] of (c).