SENSING_SG8A-ORIN-GMSL2_adapter_board use_FAQ

1. Driver package download?

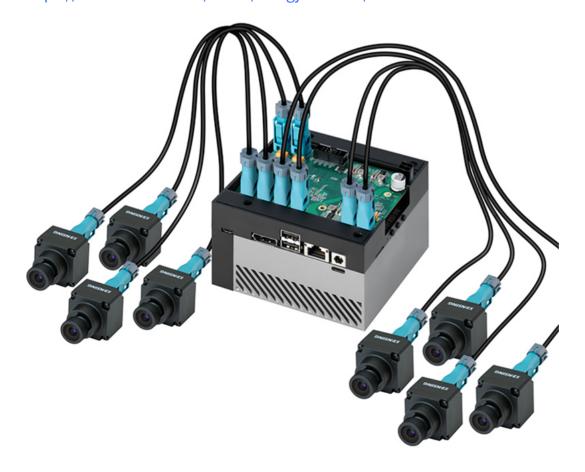
| | Camera | JP version for custom er NVIDIA devices | Driver package download link | Driver package download method: copy the previous "Driver Package Download Link" into the web box below, and click to download | Remarks |
|-----------------------|--|---|---|--|------------------|
| Driver packag e | Camera connected to GMSL (YUV format) (Example: SG2- | JP5.1.2 (Recom mended use) | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack5.1.2/SG8A_ORI N_GMSL2- F_V2_AGX_Orin_YUV_GMS L1_JP5.1.2_L4TR35.4.1 | https://minhaskamal.git hub.io/DownGit/#/home | |
| | AR0231C- 0202- GMSL - Hxxx) | JP6.0 | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack6.0/SG8A_ORIN_ GMSL2- F_V2_AGX_Orin_YUV_GMS L1_JP6.0_L4TR36.3.0 | | |
| | Camera connected | JP5.1.2 | https://github.com/SENSI NG-Technology/nvidia- | | General package: |

| | to GMSL2 (G2A) (YUV format) (Example: SG3S- ISX031C- GMSL2 - Hxxx) | (Recom mended use) | jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack5.1.2/SG8A_ORI N_GMSL2- F_V2_AGX_Orin_YUV_JP5. 1.2_L4TR35.4.1 | 1. | Only YUV format cameras can be lit, RAW format cameras are not |
|----------------------------------|---|--------------------------|--|----|--|
| | | JP6.0 | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack6.0/SG8A_ORIN_ GMSL2- F_V2_AGX_Orin_YUV_JP6. 0_L4TR36.3.0 | 2. | support ed. Can light up 8 channel s of GMSL2F. |
| | , | (Recom mended | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack5.1.2/SG8A_ORI N_GMSL2- F_V2_AGX_Orin_RAW_JP5 .1.2_L4T35.4.1 | | |
| | | JP6.0 | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack6.0/SG8A_ORIN_ GMSL2- F_V2_AGX_Orin_RAW_JP6 .0_L4TR36.3.0 | | |
| Other dedicat ed camera | SG5- OX05BC- 4000- GMSL2- | JP5.1.2 | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson | | |

| driver packag es | Hxxx (AA Frame Mode) | | %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack5.1.2/SG8A_ORI N_GMSL2- F_V2_AGX_Orin_YUV_OX0 5B-AA_JP5.1.2_L4TR35.4.1 |
|------------------------|--|---------|--|
| | SG5- OX05BC- 4000- GMSL2- Hxxx (AB Frame Mode) | JP5.1.2 | https://github.com/SENSI NG-Technology/nvidia- jetson-camera- drivers/tree/main/Jetson %20AGX%20Orin%20Devk it/SG8A-ORIN-GMSL2- F/JetPack5.1.2/SG8A_ORI N_GMSL2- F_V2_AGX_Orin_YUV_OX0 5B- AB_JP5.1.2_L4TR35.4.1 |

2. How to install SG8A-ORIN-GMSL2 main board?

https://www.bilibili.com/video/BV1gj5TzdEAo/



Simplified method 1: You can directly plug and press the adapter board intermediate connector with the connector in the middle of the NVIDIA AGX Orin kit. At the same time, the adapter board needs to be connected to the shipping matching "power connection cable" and "12V power supply" for separate power supply.

3. Confirm the Jetson Orin system version

3.1 JP version

If the above driver package does not correspond to the JP version, you need to flash the machine first and update it to the JP version corresponding to the driver package. The corresponding JP versions are as follows:

SG8A_ORIN_GMSL2 - F_V2_AGX_Orin_YUV_JP5. 2_L4TR35.4.1.zip corresponds to: Jetpack5.1.2-L4TR35.4.1

SG8A_ORIN_GMSL2 - F_V2_AGX_Orin_YUV_JP6. 0_L4TR36.3.zip corresponds to: Jetpack6.0-L4TR36.3.

3.2 Flashing method

You can refer to the documentation in the driver package and follow the instructions on the NVIDIA official website for flashing updates.

4. Product manual

SG8A-ORIN-GMSL2 User Manual for Adapter BoardV1.0-en.pdf

5. Adaptation list

■ SG8A-ORIN-GMSL2 Compatible Camera List-20241031

| | Model number | Pixel | Number | Remarks |
|---|-----------------------------|-------|------------------------------|---------|
| 1 | SG8S-AR0820C-5300-G2A-Hxxx | 8M | Cannot be 8 at the same time | |
| 2 | SG5-IMX490C-5300-GMSL2-Hxxx | 5M | Cannot be 8 at the same time | |

| 3 | SG3S-ISX031C-GMSL2F-Hxxx | 3M | Eight | Verified | |
|---|--------------------------|----|-------------|----------|--|
| | | | simultaneou | | |
| | | | sly | | |

6. Use of external triggers

■ SENSING SG8A_ORIN_GMSL2-F External Trigger synchronization Settings

7. After running seven cameras together for dozens of seconds, how many cameras will freeze? What is the reason?

Answer: Lighting up and displaying images requires GPU resources, just like the logic of playing games. If you want to display all of them, it will definitely lag, and in actual use, it is not for lighting up, just for data processing.

8. Is there an application example of v4l-ctl?

Answer: The following OpenCV demos can be referred to:

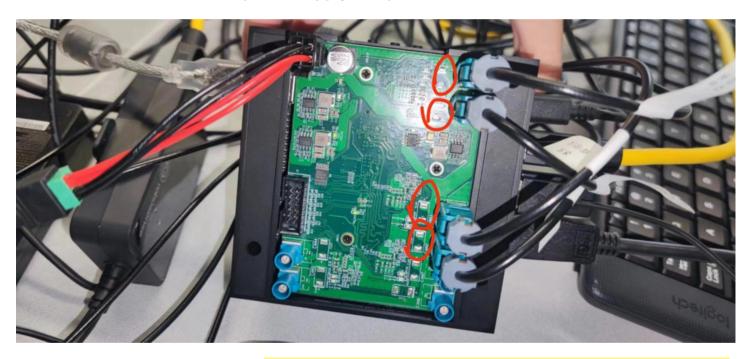
https://gitee.com/fangzhutech/jetson_cam_app

9. The main board cannot display the image after loading the driver?

The phenomenon is as follows:

```
2:SSC-OND-CC-SIDD-CHSIP
3:SSC-SIDN-SIC-CHSIP
4:SSC-INKADC-SIDD-CHSIP
4:SSC-SIDN-CHSIP
5:SSC-NORBEC-SIDD-CHSI2
6-FORS SELECT YOUR CAMERA
6-FORS SELECT YOUR CAMERA
7-FORS SELEC
```

1. Confirm that the main board power supply is normal, and the normal is about 10V. Below 9V is not normal. Main board power supply test points:



2. If the power supply is normal, you need to check the trig_mode settings of the script; change the tiger_mode to 0 or delete it.

```
gst-launch-1.0 v412src device=/dev/video${port} ! xvimagesink -ev
elif [ ${cam_mode} -eq 2 ]; then #For yuv_gms12 mode
   if [ ${yuv cam type} == 0 ];then
       v412-ctl -d /dev/video${port} -c sensor_mode=0,trig_pin=0xffff0007
   elif [ ${yuv_cam_type} == 1 ];then
       v412-ctl -d /dev/videos -c sensor_mode=0,trig_pin=0xffff0007
   elif [ ${yuv cam type} == 2 ]; then
       v412-ctl -d /dev/videos[port] -c sensor_mode=0,trig_pin=0xffff0007
   elif [ ${yuv_cam_type} == 3 ];then
       v412-ctl -d /dev/videos[port] -c sensor_mode=1,trig_pin=0xffff0007
   elif [ ${yuv_cam_type} == 4 ];then
       v412-ctl -d /dev/videos(port) -c sensor mode=2,trig pin=0xffff0008,trig mode=1
   elif [ ${yuv_cam_type} == 5 ];then
      v412-ctl -d /dev/video${port} -c sensor_mode=3,trig_pin=0xffff0008,trig_mode=3
    elif [ ${yuv_cam_type} == 6 ];then
       v412-ctl -d /dev/video [port] -c sensor_mode=3,trig_pin=0xffff0000 ,trig_mode=3
    elif [ ${yuv cam type} == 7 ];then
       v412-ctl -d /dev/video${port} -c sensor_mode=1,trig_pin=0xffff0007
   gst-launch-1.0 v412src device=/dev/video (port) ! xvimagesink -ev
else #for raw camera
   nvgstcapture-1.0 --sensor-id=${port}
```

10. How to obtain timestamps with multiple cameras:

Reference link: 国 Jetson Orin 相机v4l2_buffer时间戳和系统Unix时间戳对齐方法

The premise is that the corresponding trigger signal needs to be given by the orin platform.

V4l_buf Read to camera timestamp: v4l2-ctl --stream-mmap --stream-count = 0 -d /dev/video0 --verbose

After timestamp alignment, the camera time is still 2 seconds different from the system time: change to use CLOCK MONOTONIC RAW to calculate off

11. Loading the driver displays the following error "ctrl Gain range update failed":

```
sgx-yuv-gmsl2 30-001b: tegracam sensor driver:sgx-yuv-gmsl2-0_v2.0.6
sgx-yuv-gmsl2 30-001b: ctrl Gain range update failed
sgx-yuv-gmsl2 30-001b: Error -34 updating mode specific control ranges
sgx-yuv-gmsl2 30-001b: Failed to init ctrls sgx-yuv-gmsl2-0
sgx-yuv-gmsl2 30-001b: tegra camera subdev registration failed
sgx-yuv-gmsl2: probe of 30-001b failed with error -34
sgx-yuv-gmsl2 30-001c: tegracam sensor driver:sgx-yuv-gmsl2-1_v2.0.6
max9296 30-0048: max9296_sdev_register: serdes csi link is in use
sgx-yuv-gmsl2 30-001c: gmsl deserializer register failed
sgx-yuv-gmsl2: probe of 30-001c failed with error -22
```

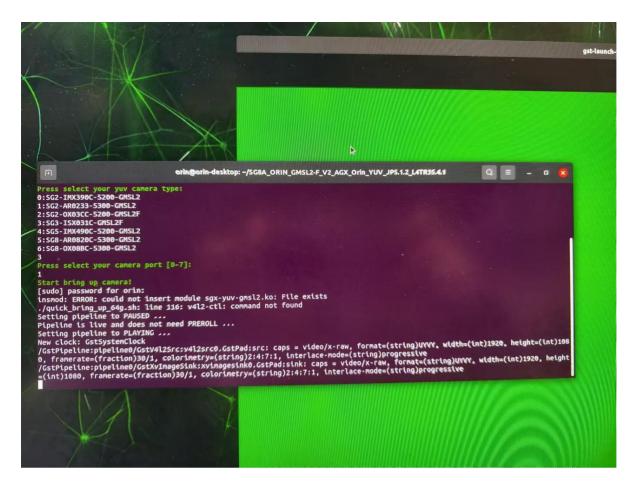
Exposure gain error in the device tree, check the device tree of the sensor.

12. How is the i2c device address of the device mapped?

| max9296 bus | max9296 adder | max9295 adder | EEPROM adder | Video Port mapping |
|----------------|------------------|------------------|-----------------|--------------------|
| 30 | 0x48 | A:0x60 B:0x62 | 0x51 | Cam0 and Cam1 |
| 31 | 0x48 | A:0x60 B:0x62 | 0x51 | Cam2 and Cam3 |
| 32 | 0x48 | A:0x60 B:0x62 | 0x51 | Cam4 and Cam5 |
| 33 | 0x48 | A:0x60 B:0x62 | 0x51 | Cam7 and Cam8 |

Update: The above is for 35.x.x. After 36.x.x, the i2C bus becomes 9~12.

13. How to deal with the following error?



A: You need to install the v4l-utils tool and execute the following command

```
1 sudo apt-get install v4l-utils
```

14. What is the specification of the power adapter connector corresponding to the power connection cable of the adapter board?

Answer: DC5-2.5, that is, the DC head is 5.5mm * 2.5mm.

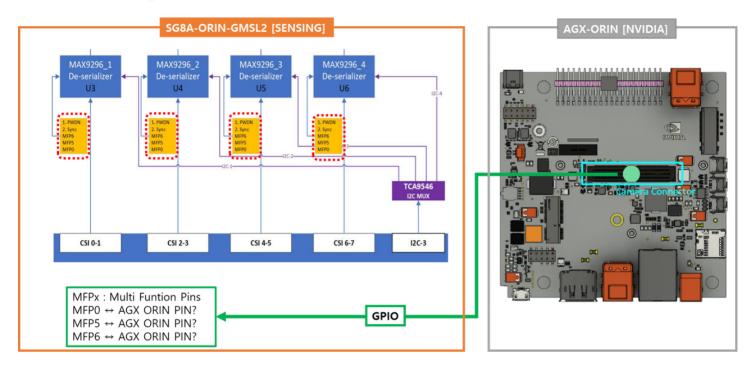
15. How to save the camera's stream as an mp4 format video and save it locally?

Command:

```
gst-launch-1.0 v4l2src device=/dev/video0 ! video/x-raw,format=UYVY,width=1920,height=1080,framerate=30/1 ! nvvidconv ! nvv4l2h264enc ! h264parse ! qtmux ! filesink location=video0.mp4 -ev
```

Pay attention to changing the resolution of the camera and the name of the video saved locally.

16. Which (GPIO) pins of the AGX ORIN camera connector are the following three PINs connected to respectively?



- MFP6/MAX_ALL_CAM_SYNC ==PIN:117 CAM_INT1
- MFP5/MAX1_CSI1_SYNC== PIN85: CAM_FRSYNC1
- MFP0/MAX1 CSI0 SYNC== PIN97:CAM FRSYNC3

•

17. In JP6.2 version YUV driver package, how can GMSL2F camera and GMSL2 camera be compatible and both be lit up?

The quick_bring_up.sh script can only support one mode of operation after the first execution. For the second mode, the commands in the following figure need to be manually executed to turn on the camera.

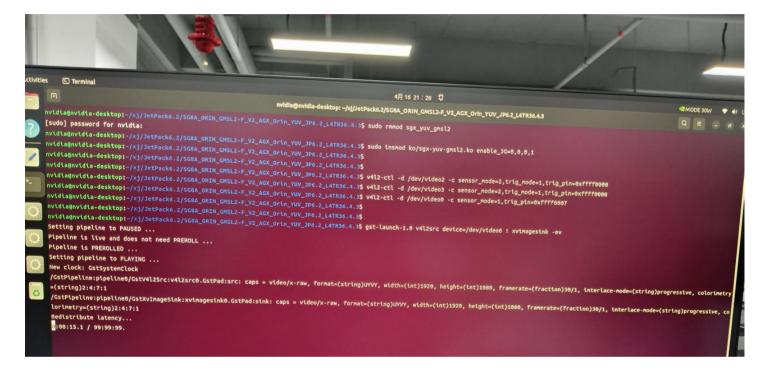
For example: The SG5-IMX490-5300-GMSL2 camera was lit up for the first time. For the second time, manual commands need to be executed to operate and light up the SG3S-ISX031C-GMSL2F camera of the video6 node:

代码块

- 1 sudo rmnod sgx_yuv_gmsl2
- 2 sudo insmod ko/sgx-yuv-gnsl2.ko enable_3G-0,0,0,1
- 3 v4l2-ctl -d /dev/video6 -c sensor_mode=1,trig_pin=0xffff0007

enable_3G-0,0,0,1 Explanation: enable_3G-0,0,0,1: Here, 0,0,0,1 represents setting the working modes of four max9296. 0 means not enabling the 3G mode, and 1 means enabling the chip to be in the 3G mode.

"0,0,0,1" from left to right represents: video0/video1, video2/video3, video4/video5, video6/video7.



V4L2-CTL setting table:

| sensor_mod e | Resolution | Camera Part Number | trig_mode | trig_pin(lo w_16bits) | trig_pin(hi gh_16bits) |
|-----------------|------------|--------------------------------------|----------------|--------------------------|---------------------------|
| 0 | 1920*1080 | 1920*1080 SG2-IMX390C-5200- GMSL2 | | 7:mfp7 | 1 |
| | | SG2-AR0233-5300-GMSL2 | 0:Rise edge | 7:mfp7 | / |
| 1 | 1920*1536 | SG3-ISX031C-GMSL2F | 0:Rise edge | 7:mfp7 | / |
| 2 | 2880*1860 | SG2-IMX490C-5200- GMSL2 | 1:Fall edge | 8:mfp8 | / |
| 3 | 3840*2160 | SG8-AR0820C-5300- GMSL2 | 3:Auto Trigger | 8:mfp8 | / |
| 3 | 3840*2160 | | 3:Auto Trigger | 8:mfp8 | 1 |

| | | SG8-OX08BC-5300- GMSL2 | | | |
|---|-----------|---------------------------|-----------------------|--------|--------|
| 3 | 3840*2160 | SG8-OX08BC-5300- GMSL2 | 2:external Trigger | 8:mfp8 | 6:mfp6 |

- The lower 16 bits of parameter trig_pin are the trigger pins of the serializer, and the upper 16 bits are the trigger pins of the deserializer.
- The parameter trig_mode corresponds to four trigger modes.
- The parameter sensor_mode corresponds to different resolutions.