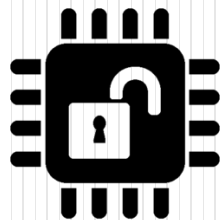
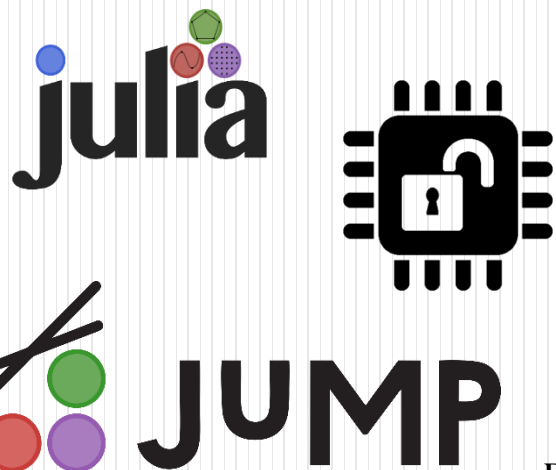


# Tópico

## JULIA LANGUAGE FOR MATHEMATICAL PROGRAMMING

Mar 2019

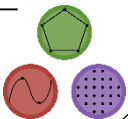


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- *Open-source* & lenguaje de programación libre (MIT license).
  - Desarrollado a partir del **2012** (por: MIT researchers)
  - Creciente popularidad a nivel mundial, en investigación, data science, finanzas, etc.
  - Multi-platform: Windows, Mac OS X, GNU/Linux...
- Diseño para la *performance*:
  - Interpretador & compilador, *muy eficiente*
  - Fácil de *run codes* en paralelo (multi-core & cluster)
- Diseño para ser *simple de aprender y usar*:
  - Easy syntax, dynamic typing (como MATLAB & Python)





Link: [Home · The Julia Language](#)



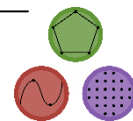
Link: [Introduction · JuMP](#)



Link: [GLPK - GNU Project - Free Software Foundation \(FSF\)](#)

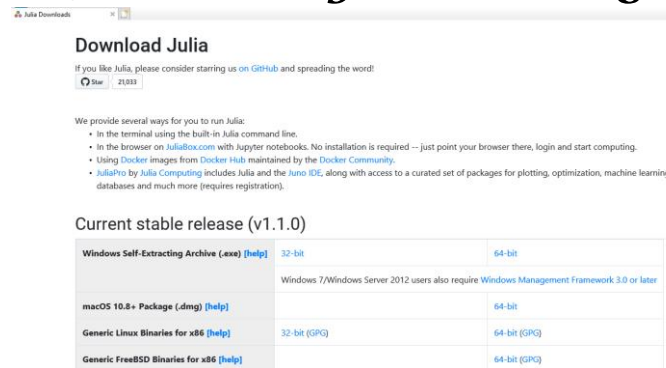


Link: [Introduction to IPOPT: A tutorial for downloading, installing, and using IPOPT](#)

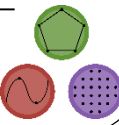
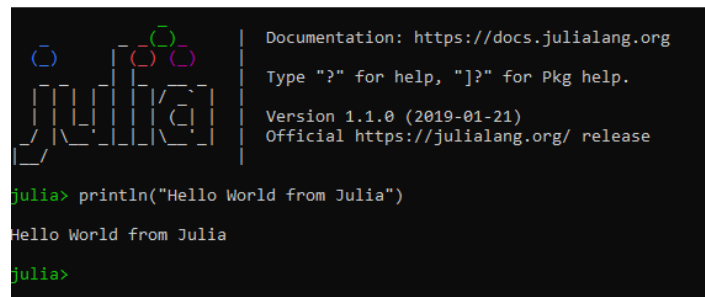


	Julia 😊	MATLAB ☹️
<b>Cost</b>	Free	Hundreds of €/ \$ per year
<b>License</b>	Open-source	1 year user license
<b>Comes from</b>	A non-profit foundation, and the community	Mathworks Company
<b>Editor/IDE</b>	<i>Jupyter</i> and <i>Atom / Juno</i> are recommend	Good IDE already included
<b>Parallel computations</b>	Very esasy, low overhead cost	Possible, high overhead
<b>Usage</b>	Generic, worldwide	Research in academy and industry
<b>Fame</b>	Young but starts to be known	Old and known

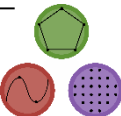
- Para Linux, Mac OS o Windows.
  - Se puede descargar el instalador JuliaLang en: [Julia Downloads](https://julialang.org/downloads/)
  - Atom se puede descargar de: [Atom](https://atom.io/)
- 1. Descarga e instalar Julia con *default settings*.



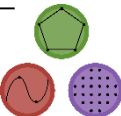
## 2. Abrir Julia



1. En Julia: Crtl + tecla “}” para establecer el (v1.1) pkg>
2. En: (v1.1) pkg> add JuMP
3. En: (v1.1) pkg> add GLPK
4. En: (v1.1) pkg> build GLPK
5. Apretar tecla “*backspace*”: julia>
6. En: julia> using JuMP
7. En: julia> using GLPK
8. En: julia> using GLPK
9. En: (v1.1) pkg> add Ipopt
10. En: (v1.1) pkg> build Ipopt
11. En: julia> using Ipopt
12. En: (v1.1) pkg> status



1. Descarga e instalar Julia con *default settings*.
2. In Atom, ir a **Settings** (Ctrl+,, or Cmd+, on macOS) e ir al "Install" panel.
3. Escribir **uber-juno** en la sección de búsqueda y apretar tecla **Enter**. Dar *click* en el boton *install* de la librería.
4. **Atom** instalará y configurará **Juno** por ti.

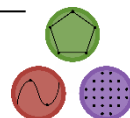




# Descripción general de los famosos “Packages” de Julia



- *Plotting:*
  - [Winston.jl](#) para plotear como MATLAB
  - [PyPlot.jl](#) , interfaz al Matplotlib (Python)
- [JuliaDiffEq.jl](#) , para ecuaciones diferenciales
- [JuliaStats.jl](#) , para estadística
- [JuliaDSP](#) , para procesamiento de señales
- [BackpropNeuralNet](#), para redes neuronales
- [JuliaOpt/JuMP](#) para optimización
- Más “Packages” en: [Julia Package Listing](#)





	Julia	MATLAB
<b>File ext.</b>	.jl	.m
<b>Comment</b>	# blabla...	% blabla...
<b>Indexing</b>	a[1] to a[end]	a(1) to a(end)
<b>Slicing</b>	a[1:100]	a(1:100)
<b>Operations</b>	Linear Algebra <i>special library</i>	Linear Algebra <i>by default</i>
<b>Block</b>	Use <b>end</b> to close all blocks	Use <b>endif</b> , <b>endfor</b> etc
<b>And</b>	a & b	a && b
<b>Or</b>	a   b	a    b
<b>Array</b>	[1 2; 3 4]	[1 2; 3 4]

- JuMP package: lenguaje de modelamiento para optimización
- Interfaces de JuMP con solver de optimización:

Solver	Julia Package	License	Supports
Artelys Knitro	KNITRO.jl	Comm.	LP, MILP, SOCP, MISOCP, NLP, MINLP
Cbc	Cbc.jl	EPL	MILP
Clp	Clp.jl	EPL	LP
CPLEX	CPLEX.jl	Comm.	LP, MILP, SOCP, MISOCP
CSDP	CSDP.jl	EPL	LP, SDP
ECOS	ECOS.jl	GPL	LP, SOCP
FICO Xpress	Xpress.jl	Comm.	LP, MILP, SOCP, MISOCP
GLPK	GLPK.jl	GPL	LP, MILP
Gurobi	Gurobi.jl	Comm.	LP, MILP, SOCP, MISOCP
Ipopt	Ipopt.jl	EPL	LP, QP, NLP
MOSEK	MosekTools.jl	Comm.	LP, MILP, SOCP, MISOCP, SDP
OSQP	OSQP.jl	Apache	LP, QP
SCS	SCS.jl	MIT	LP, SOCP, SDP
SDPA	SDPA.jl	GPL	LP, SDP
SeDuMi	SeDuMi.jl	GPL	LP, SOCP, SDP

- Donde:
  - LP: Linear Programming
  - QP: Quadratic Programming
  - SOCP = Second-order conic programming (including problems with convex quadratic constraints and/or objective)
  - MILP = Mixed-integer linear programming
  - NLP = Nonlinear programming
  - MINLP = Mixed-integer nonlinear programming
  - SDP = Semidefinite programming
  - MISDP = Mixed-integer semidefinite programming
- Otros lenguajes de modelamiento:
  - AMPL
  - GAMS
  - MATLAB: YALMIP, CVX
  - Python: Pyomo, PuLP, CVXPY



$$\min_x \sum_{(i,j) \in E} c_{i,j} x_{i,j}$$

s.t.



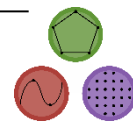
$$\sum_{(i,j) \in E} x_{i,j} = \sum_{(j,k) \in E} x_{j,k}, j = 2, \dots, n-1,$$



$$\sum_{(i,n) \in E} x_{i,n} = 1,$$



$$0 \leq x_{i,j} \leq c_{i,j}, \forall (i,j) \in E$$





## JuMP

immutable Edge

from; to; cost; capacity

end

```
edges = [Edge(1,2,1,0.5), Edge(1,3,2,0.4), Edge(1,4,3,0.6),
          Edge(2,5,2,0.3), Edge(3,5,2,0.6), Edge(4,5,2,0.5)]
```

Mcf = Model()



@variable(mcf, 0 <= flow[e in edges] <= e.capacity



@constraint(mcf, sum {flow[e], e in edges, e.to==5} == 1)



@constraint(mcf, flowcon[n=2:4], sum {flow[e], e in edges; e.to==node}  
== sum {flow[e], e in edges; e.from==node})



@objective(mcf, Min, sum {e.cost \* flow[e], e in edges})

## AMPL

set edges := {(1,2),(1,3),(1,4),(2,5),(3,5),(4,5)};

param cost {edges}; param capacity {edges};

data ...; # Data es almacenada separadamente en AMPL;



var flow {(i,j) in edges} >= 0.0, <= capacity[i,j];



subject to unitflow: sum {(i,5) in edges} flow[i,5] == 1;



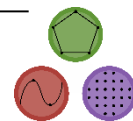
subject to flowconserve {n in 2..4}:



sum {(i,n) in edges} flow[i,n] == sum {(n,j) in edges} flow[n,j];



minimize flowcost: sum {(i,j) in edges} cost[i,j] \* flow[i,j];





# JuMP: Comparaciones “syntax” (2/2)

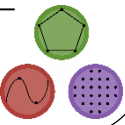







## Pyomo

```
edges = [(1,2), (1,3), (1,4), (2,5), (3,5), (4,5)]
cost = {(1,2):1, (1,3):2, (1,4):3, (2,5):2, (3,5):2, (4,5):2}
capacity = {(1,2):0.5, (1,3):0.4, (1,4):0.6, (2,5):0.3, (3,5):0.6, (4,5):0.5}
mcf = ConcreteModel()
mcf.flow = Var(edges, bounds=lambda m,i,j: (0,capacity[(i,j)]))
mcf.uf = Constraint(expr=sum(mcf.flow[e] for e in edges if e[1]==5) == 1)
def con_rule(mcf,n): return sum(mcf.flow[e] for e in edges if e[1]==n) ==
                        sum(mcf.flow[e] for e in edges if e[0]==n)
mcf.flowcon = Constraint([2,3,4],rule=con_rule)
mcf.flowcost = Objective(expr=sum(cost[e]*mcf.flow[e] for e in edges))
```

## GAMS

```
SET nodes /n1*n5/; SET midnodes(nodes) /n2*n4/; SET lastnode(nodes) /n5/;
ALIAS(nodes,nodefrom,nodeto,n);
SET edges(nodes,nodes) / n1.n2 n1.n3 n1.n4 n2.n5 n3.n5 n4.n5 /;
PARAMETER cost(nodes,nodes) / ... /; * Data omitted
PARAMETER capacity(nodes,nodes) / ... /; * for space reasons
POSITIVE VARIABLE flow(nodefrom,nodeto); flow.UP(edges) = capacity(edges);
EQUATION unitflow;
unitflow.. sum{edges(nodefrom,lastnode), flow(nodefrom,lastnode)} =e= 1;
EQUATION flowcon(nodes);
flowcon(midnodes(n)).. sum{edges(nodefrom,n), flow(nodefrom,n)} =e=
                        sum{edges(n,nodeto), flow(n,nodeto)};
FREE VARIABLE obj;
EQUATION flowcost; flowcost.. obj =e= sum{edges, cost(edges)*flow(edges)};
MODEL mincostflow /all/; SOLVE mincostflow USING lp MINIMIZING obj;
```



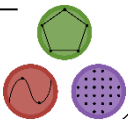
	 GAMS	 AMPL	 AIMMS		 PYOMO	JuMP
Data Input	hard	hard	✓	✓	✓	✓
Data Manipulation	✗	✗	✓	✓	✓	✓
Modeling	✓	✓	✓	hard	✓	✓
Advanced Algorithms	hard	hard	✓	✓	✓	✓
Solvers Availability	✓	✓	limited	✗	limited	limited
Visualization	✗	✗	✓	hard	hard	hard
License	\$	\$	\$\$	free	free	free

## Pros

- Nuevo lenguaje de modelamiento
- Muy rápido
- Open-source
- Facil y simple de codificar
- Acceso a C/C++
- Respaldado por una amplia comunidad científica
- Amplia variedad de librerías

## Cons

- Nuevo lenguaje de modelamiento
- Muchas librerías y plataformas aun en desarrollo
- Poco conocido



# ✿ JuMP: Quiénes aplican en mercados eléctricos?



Ministerio de  
Energía y Minas



**Joaquim Dias Garcia**

