

19/3/21

Learn In ML Circle

Linear Regression Model

- Mathematical Understanding
- sklearn implementation

Terms

- 1) Dependent variable
- 2) Independent variable

Example:- Annual Sales of a company.

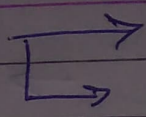
depends on:-
No. of employees } Independent variable
Profit
Product sale

And as annual sales depends on these factors, it is Dependent variable.

Factors affecting annual sales variable are your Independent variable.

* When we try to establish a relationship between dependent and independent variable, that is called Regression analysis.

Regression



Linear Regression
Logistic Regression.

Linear Regression

Why linear?

The effect that independent variable has on dependent variable is proportional.

Formal Definition.

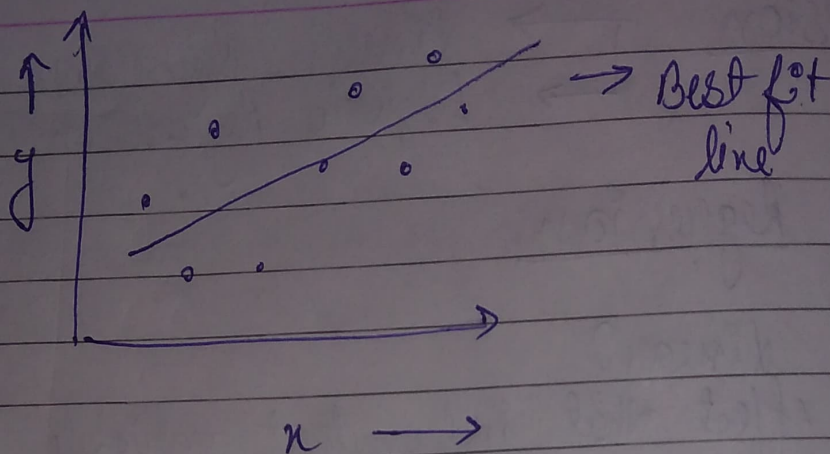
It is a technique which is used to model and analyse the relationship between variables and often times how they contribute and are related to a particular outcome.

Nature of independent :- Numeric and continuous

⚡ Difference b/w discrete and continuous

Countable/finite

When we have only one independent variable it is called simple linear regression and when we have more than one independent variable it is called multiple linear regression.



$$y = mx + c$$

↓ ↓
slope intercept.

What values of m and c will give us best fit line?

Approach

1. Gradient descent algo.
2. Direct formula (least sq. method)

Gradient Descent Algorithm

→ optimal m & b values
 ↳ slope ↳ intercept

m, b → machine learning → weights
 $b \rightarrow \theta_0$: intercept
 $m \rightarrow \theta_1$: slope

imp $\left\{ \begin{array}{l} y = b + mx. \\ y = \theta_0 + \theta_1 x \end{array} \right.$ → line equation
 ↳ linear regression
 ↳ Relationship is proportional in nature

In ML, hypothesis → dependent variable / Target value i.e. y in our case.

$$y = \theta_0 + \theta_1 x$$

↳ $h_0(x) = \theta_0 + \theta_1(x)$

~~h(x)~~ $h(x) / h_0(x) = y$

$h_0(x) \rightarrow y$ but this y is not the actual value in our dataset.
 It is the predicted y .

Example

x	y
10	5
12	6.6
13	1

$\theta_0 = 1$ intercept

$\theta_1 = 0.5$ slope

$$h_{\theta}(x) = \theta_0 + \theta_1(x)$$

for data point $x = 10$,

$$\text{predicted } \hat{y} = h_{\theta}(x) = 1 + (0.5) \times 10 = 6$$

$$\swarrow y = 5$$

Actual value from dataset

$$\text{Error} = (\text{predicted value} - \text{original value})^2$$

mean square error

$$= (6 - 5)^2 = 1$$

(white board: cost function)

$J(\theta_0, \theta_1)$
↳ cost function

$$\sum_{i=1}^m \frac{(\text{predicted} - \text{original})^2}{2m}$$

Our Goal is to minimize the cost function,
we want our error close to zero

Error

↳ Reduce it to zero.

↳ minimize my cost funct.

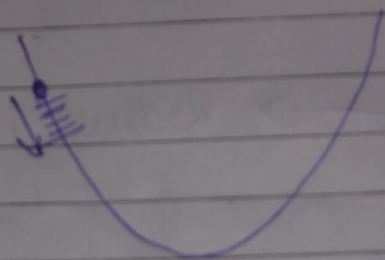
⇓
Best fit line

How Gradient descent will help in getting
those optimal m & b values?

Maths!

$\Rightarrow m \rightarrow$ current position of a person
 $D \rightarrow$ steepness slope.
 $L =$ Speed with which he should move.

$m' \rightarrow$ next position.
 $L \times D \rightarrow$ size of the step



$J(\theta) =$ cost function

$$= \frac{1}{2m} \sum_{i=1}^m [h_0(x) - y]^2$$

$$\frac{\partial J(\theta)}{\partial \theta} = \frac{\partial}{\partial \theta} \left[\frac{1}{2m} \sum_{i=1}^m [h_0(x) - y]^2 \right]$$

$$= \frac{1}{2m} \sum_{i=1}^m \frac{\partial}{\partial \theta} [h_0(x) - y]^2$$

$$\boxed{\frac{\partial}{\partial x} x^n = n x^{n-1}}$$

$$= \frac{1}{2m} \sum_{i=1}^m 2 [h_0(x) - y] \frac{\partial [h_0(x) - y]}{\partial \theta}$$

$$= \frac{1}{m} \sum_{i=1}^m [h_0(x) - y]$$

//
?

partial derivative wrt θ_1, θ_0

$$\frac{\partial}{\partial \theta_0} [h_0(x) - y] = \frac{\partial}{\partial \theta_0} [\theta_0 + \theta_1 x - y]$$

$$= [1 + 0 - 0]$$

$$= 1$$

$$\frac{\partial}{\partial \theta_1} [h_0(x) - y] = \frac{\partial}{\partial \theta_1} [\theta_0 + \theta_1 x - y] = x$$

Minimize cost function J

$$\frac{\partial}{\partial \theta_0} (J(\theta_0, \theta_1)) = \frac{1}{m} \left[\sum_{i=1}^m h_0(x) - y \right]$$

$$\frac{\partial}{\partial \theta_1} (J(\theta_0, \theta_1)) = \frac{1}{m} \left[\sum_{i=1}^m h_0(x) - y \right] \cdot x$$

New values of $m \rightarrow \theta_1$
 $b \rightarrow \theta_0$

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$$\begin{cases} \theta_0 = \theta_0 - \frac{\alpha}{m} \sum_{i=1}^m (h(\theta_0) - y) \\ \theta_1 = \theta_1 - \frac{\alpha}{m} \sum_{i=1}^m (h(\theta_1) - y) \cdot x \end{cases}$$

$\alpha =$ learning rate (length of step)

$\hookrightarrow 0.0001$

