ML/DL for Everyone with PYTERCH

Lecture 11: RNN



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Other slides: http://bit.ly/PyTorchZeroAll



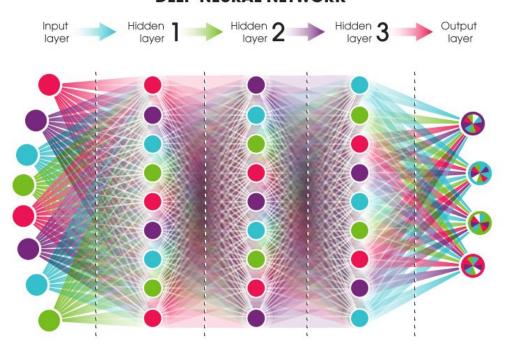
ML/DL for Everyone with PYTERCH

Lecture 11: RNN



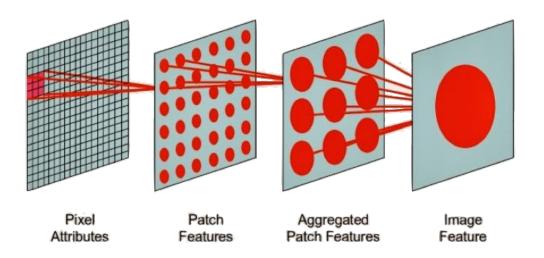
DNN, CNN, RNN

DEEP NEURAL NETWORK

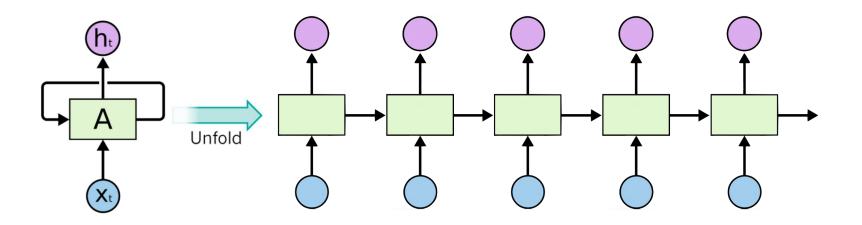


neuralnetworksanddeeplearning.com - Michael Nielsen, Yoshua Bengio, Ian Goodfellow, and Aaron Courville, 2016.

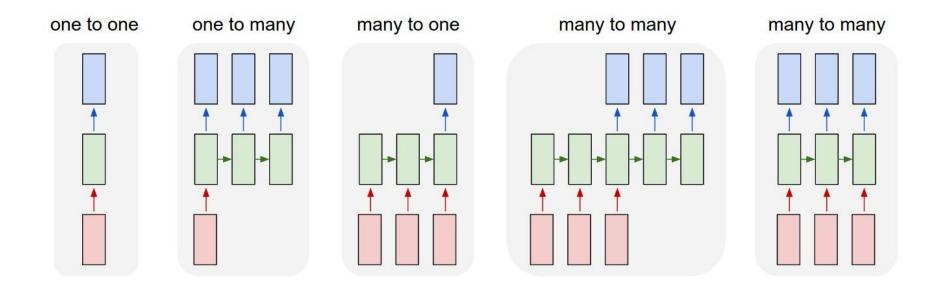
DNN, CNN, RNN



DNN, CNN, RNN



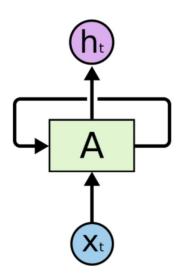
RNN Applications



RNN in PyTorch

```
cell = nn.LSTM(input_size=4, hidden_size=2, batch_first=True)
inputs = ... # (batch, seq_len, input_size) with batch_first=True
hidden = (..., ...) # (num_layers * num_directions, batch, hidden_size)
out, hidden = cell(inputs, hidden)
```

One node: 4 (input-dim) in 2 (hidden_size)

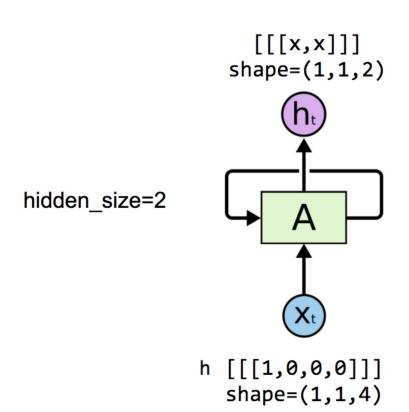


h [[[1,0,0,0]]]

shape=(1,1,4)

```
# One hot encoding
h = [1, 0, 0, 0]
e = [0, 1, 0, 0]
l = [0, 0, 1, 0]
o = [0, 0, 0, 1]
```

One node: 4 (input-dim) in 2 (hidden_size)



```
# One hot encoding
h = [1, 0, 0, 0]
e = [0, 1, 0, 0]
l = [0, 0, 1, 0]
o = [0, 0, 0, 1]
```

One node: 4 (input_dim) in 2 (hidden_size)

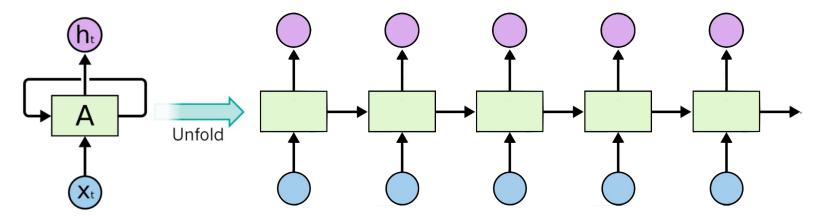
```
# One cell RNN input dim (4) -> output dim (2)
cell = nn.LSTM(input size=4, hidden size=2, batch first=True)
# One letter input
inputs = autograd. Variable(torch.Tensor([[h]])) # rank = (1, 1, 4)
# initialize the hidden state.
# (num layers * num directions, batch, hidden size)
hidden = (autograd.Variable(torch.randn(1, 1, 2)),
         autograd.Variable(torch.randn((1, 1, 2))))
# Feed to one element at a time.
# after each step, hidden contains the hidden state.
out, hidden = cell(inputs, hidden)
print("out", out.data)
-0.1243 0.0738
 [torch.FloatTensor of size 1x1x2]
```

[[[x,x]]] shape=(1,1,2)hidden size=2 [[[1,0,0,0]]] shape=(1,1,4)

Unfolding to n sequences

```
hidden_size=2
seq len=5
```

```
shape=(1,5,2): [[[x,x], [x,x], [x,x], [x,x], [x,x]]]
```



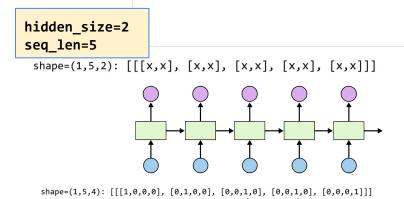
Unfolding to n sequences

```
# One hot encoding
h = [1, 0, 0, 0]
e = [0, 1, 0, 0]
l = [0, 0, 1, 0]
o = [0, 0, 0, 1]
```

```
input size torch.Size([1, 5, 4])

(0,.,.) =
-0.1825  0.0737
-0.1981  0.1164
-0.3367  0.2095
-0.3625  0.2503
-0.2038  0.3626

[torch.FloatTensor of size 1x5x2]
```



```
Hidden_size=2
sequence_length=5
batch_size=3
```

Batching input

```
shape=(3,5,2): [[[x,x], [x,x], [x,x], [x,x], [x,x]],
               [[x,x], [x,x], [x,x], [x,x], [x,x]],
               [[x,x], [x,x], [x,x], [x,x], [x,x]]]
```

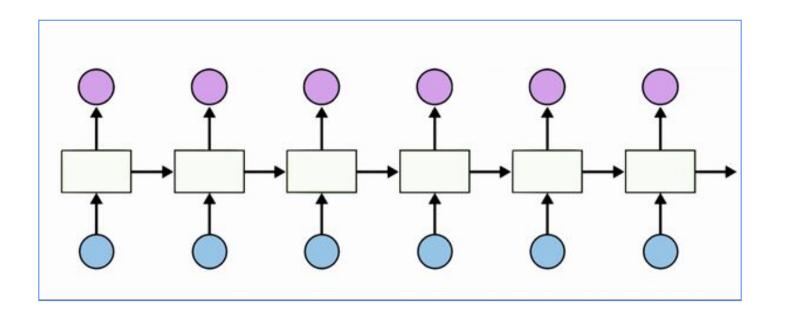
shape=(3,5,4): [[[1,0,0,0], [0,1,0,0], [0,0,1,0], [0,0,1,0], [0,0,0,1]], # hello [[0,1,0,0], [0,0,0,1], [0,0,1,0], [0,0,1,0], [0,0,1,0]] # eolll [[0,0,1,0], [0,0,1,0], [0,1,0,0], [0,0,1,0]]] # lleel

Batching input

```
# One cell RNN input dim (4) -> output dim (2). sequence: 5, batch 3
   # 3 batches 'hello', 'eolll', 'lleel'
   \# rank = (3, 5, 4)
   inputs = autograd.Variable(torch.Tensor([[h, e, 1, 1, o],
                                              [e, o, 1, 1, 1],
                                              [1, 1, e, e, 1]]))
   print("input size", inputs.size()) # input size torch.Size([3, 5, 4])
   # (num layers * num directions, batch, hidden size)
   hidden = (autograd.Variable(torch.randn(1, 3, 2)), autograd.Variable(
      torch.randn((1, 3, 2))))
   out, hidden = cell(inputs, hidden)
   print("out size", out.size()) # out size torch.Size([3, 5, 2])
shape=(3,5,2): [[[x,x], [x,x], [x,x], [x,x], [x,x]],
          [[x,x], [x,x], [x,x], [x,x], [x,x]],
          [[x,x], [x,x], [x,x], [x,x], [x,x]]]
                                          Hidden_size=2
                                          sequence length=5
                                          batch size=3
```

shape=(3,5,4): [[[1,0,0,0], [0,1,0,0], [0,0,1,0], [0,0,1,0], [0,0,0,1]], # hello [[0,1,0,0], [0,0,0], [0,0,1,0], [0,0,1,0]] # eolll [[0,0,1,0], [0,0,1,0], [0,1,0,0], [0,0,1,0]]] # lleel

```
[1, 0, 0, 0, 0],
                                                        # h 0
                                         [0, 1, 0, 0, 0], # i 1
Teach RNN 'hihell' to 'ihello' [0, 0, 1, 0, 0], # e 2
                                         [0, 0, 0, 0, 1],
                                                        # 0 4
```



```
Teach RNN 'hihell' to 'ihello' [0, 0, 1, 0, 0], # e 2 [0, 0, 0, 1, 0], # L 3 [0, 0, 0, 0, 1], # o 4
```

h 0

i 1

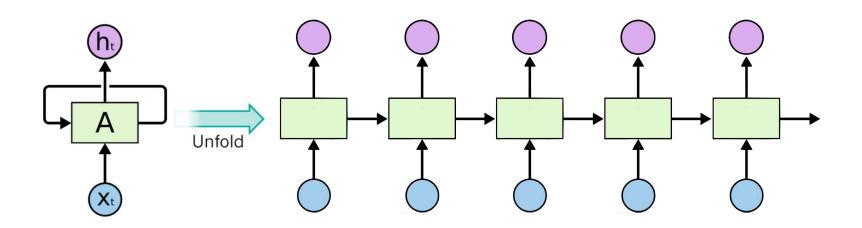
[1, 0, 0, 0, 0], [0, 1, 0, 0, 0],

```
[0, 1, 0, 0, 0] [1, 0, 0, 0, 0] [0, 1, 0, 0, 0] [0, 1, 0, 0, 0] [0, 1, 0, 0, 0] [0, 0, 0, 0, 1]
[1, 0, 0, 0, 0]
               [0, 1, 0, 0, 0]
                                [1, 0, 0, 0, 0] [0, 1, 0, 0, 0] [0, 1, 0, 0, 0]
                                                                                  [0, 1, 0, 0, 0]
```

Input_dim = 5

output_dim = 5

Unfolding one to n sequences



Teach RNN 'hihell' to 'ihello'

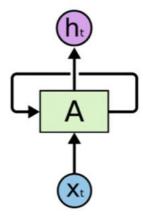
```
[1, 0, 0, 0, 0], # h 0

[0, 1, 0, 0, 0], # i 1

[0, 0, 1, 0, 0], # e 2

[0, 0, 0, 1, 0], # L 3

[0, 0, 0, 0, 1], # o 4
```



RNN inout and output

```
[0, 1, 0, 0, 0], # i 1

[0, 0, 1, 0, 0], # e 2

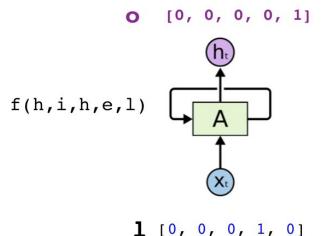
[0, 0, 0, 1, 0], # L 3

[0, 0, 0, 0, 1], # o 4
```

[1, 0, 0, 0, 0],

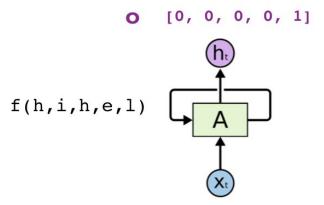
h 0

```
self.rnn = nn.RNN(input_size=5, hidden_size=5, batch_first=True)
```



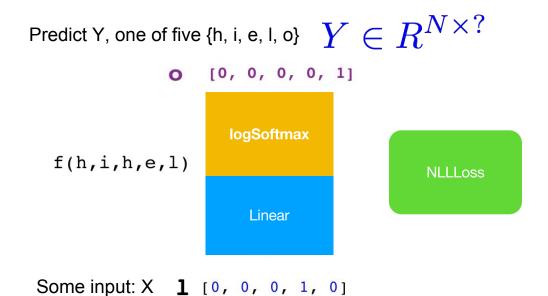
Designing Loss

Predict Y, one of five {h, i, e, l, o}



Some input: X 1 [0, 0, 0, 1, 0]

Designing Loss



Designing Loss

out = rnn_out.view(-1, 5) Predict Y, one of five {h, i, e, l, o} $Y \in R^{N imes 5}$ **o** [0, 0, 0, 0, 1] logSoftmax f(h,i,h,e,l) With **NLLLoss** Linear

Some input: X **1** [0, 0, 0, 1, 0]

(I) Data preperation



```
idx2char = ['h', 'i', 'e', 'l', 'o']
# Teach hihell -> ihello
x data = [[0, 1, 0, 2, 3, 3]] # hihell
x_{one}hot = [[[1, 0, 0, 0, 0], # h 0]]
            [0, 1, 0, 0, 0], #i1
            [1, 0, 0, 0, 0], #h0
            [0, 0, 1, 0, 0], \#e2
            [0, 0, 0, 1, 0], # 13
            [0, 0, 0, 1, 0]]] # L 3
y data = [1, 0, 2, 3, 3, 4] # ihello
# As we have one batch of samples, we will change them to variables only once
inputs = Variable(torch.Tensor(x one hot))
labels = Variable(torch.LongTensor(y data))
```

(2) Parameters



```
num_classes = 5
input_size = 5  # one-hot size
hidden_size = 5  # output from the LSTM. 5 to directly predict one-hot
batch_size = 1  # one sentence
sequence_length = 6  # |ihello| == 6
num_layers = 1  # one-layer rnn
```

```
self.num classes = num classes
   self.num_layers = num_layers
   self.input size = input size
   self.hidden size = hidden size
   self.sequence_length = sequence_length
   self.rnn = nn.RNN(input size=5, hidden size=5, batch first=True)
def forward(self, x):
   # Initialize hidden and cell states
   h 0 = Variable(torch.zeros(
       x.size(0), self.num layers, self.hidden size))
   # Reshape input
   x.view(x.size(0), self.sequence length, self.input size)
   # Propagate input through RNN
   # Input: (batch, seg len, input size)
   # h_0: (batch, num_layers * num_directions, hidden_size)
   out, \_ = self.rnn(x, h_0)
   print(out.size())
                                      Y \in \mathbb{R}^{N \times 5}
   return out.view(-1, num_classes)
```

def init (self, num classes, input size, hidden size, num layers):

super(RNN, self). init ()

(3) Our model

```
num_classes = 5
input_size = 5  # one-hot size
hidden_size = 5  # output from the LSTM.
batch_size = 1  # one sentence
sequence_length = 6  # |ihello| == 6
num_layers = 1  # one-layer rnn
```

```
# Instantiate RNN model
rnn = RNN(num classes, input size, hidden size, num layers)
print(rnn)
# Set loss and optimizer function
# CrossEntropyLoss = LogSoftmax + NLLLoss
criterion = torch.nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(rnn.parameters(), lr=0.1)
# Train the model
for epoch in range(100):
   outputs = rnn(inputs)
   optimizer.zero grad()
   loss = criterion(outputs, labels)
   loss.backward()
   optimizer.step()
   _, idx = outputs.max(1)
   idx = idx.data.numpy()
   result_str = [idx2char[c] for c in idx.squeeze()]
   print("epoch: %d, loss: %1.3f" % (epoch + 1, loss.data[0]))
   print("Predicted string: ", ''.join(result str))
print("Learning finished!")
```

(4) Loss & Training

```
num_classes = 5
input_size = 5  # one-hot size
hidden_size = 5  # output from the LSTM.
batch_size = 1  # one sentence
sequence_length = 6  # |ihello| == 6
num_layers = 1  # one-layer rnn
```

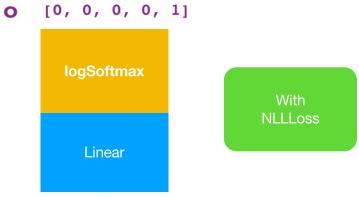
```
# Instantiate RNN model
rnn = RNN(num classes, input size, hidden size, num layers)
print(rnn)
# Set loss and optimizer function
# CrossEntropyLoss = LogSoftmax + NLLLoss
criterion = torch.nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(rnn.parameters(), lr=0.1)
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for epoch in range(100):
   outputs = rnn(inputs)
   optimizer.zero grad()
   loss = criterion(outputs, labels)
   loss.backward()
   optimizer.step()
   _, idx = outputs.max(1)
   idx = idx.data.numpy()
   result str = [idx2char[c] for c in idx.squeeze()]
   print("epoch: %d, loss: %1.3f" % (epoch + 1, loss.data[0]))
   print("Predicted string: ", ''.join(result str))
print("Learning finished!")
```



epoch: 1, loss: 1.673 Predicted string: ehehee epoch: 2, loss: 1.403 Predicted string: ehehel epoch: 3, loss: 1.240 Predicted string: ehelll epoch: 95, loss: 0.458 Predicted string: ihello epoch: 96, loss: 0.458 Predicted string: ihello epoch: 97, loss: 0.458 Predicted string: ihello epoch: 98, loss: 0.458 Predicted string: ihello epoch: 99, loss: 0.458 Predicted string: ihello epoch: 100, loss: 0.458 Predicted string: ihello

Exercise 11-1: Implement softmax classifier for 'hihell' to 'ihello'

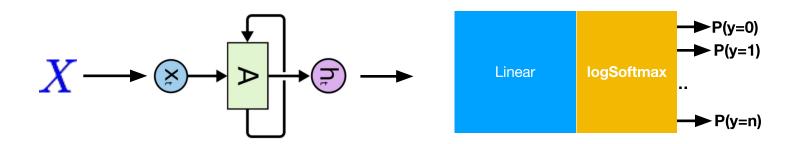
Predict Y, one of five {h, i, e, l, o} $Y \in R^{N imes 5}$



Some input: X 1 [0, 0, 0, 1, 0]

Why it does not work?

Exercise II-2: Combine RNN+Linear





Why it trains faster (more stable)?

Exercise 11-3: Teach RNN a long sequence



Lecture 12:
NSML,
Smartest ML Platform