



Implicitly-Defined Neural Networks for Sequence Labeling

WeiYang

weiyang@godweiyang.com

www.godweiyang.com

East China Normal University
Department of Computer Science

2017.11.03





Outline

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Traditional RNN

INN

Experiments







Formula

input sequence

$$[\xi_1,\xi_2,\ldots,\xi_n]$$

states production

$$h_1 = f(\xi_1, h_s)$$

$$h_2 = f(\xi_2, h_1)$$

$$\cdots$$

$$h_n = f(\xi_n, h_{n-1})$$

LSTM & GRU



(2)







Structure

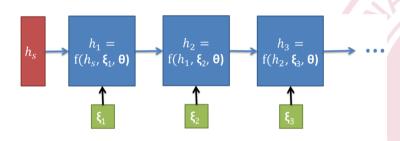


Figure 1: Traditional RNN structure.



Formula

• implicit hidden layer

where

$$h_1 = f(h_s, h_2, \xi_1)$$

 $H = [h_1, h_2, \dots, h_n]$

. .

$$h_i = f(h_{i-1}, h_{i+1}, \xi_i)$$

. . .

$$h_n = f(h_{n-1}, h_e, \xi_n)$$

INN

$$\xi = q(\theta, X)$$

$$H = F(\theta, \xi, H)$$

$$L = \ell(\theta, H, Y)$$

(3)

(4)

._.





Structure

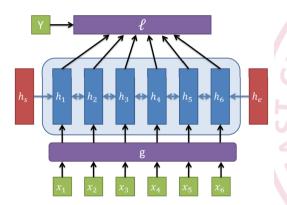


Figure 2: Proposed INN Architecture



Forward propagation

solve the equation

$$H = F(H)$$

approximate Newton solve

$$H_{n+1} = H_n - (I - \nabla_H F)^{-1} (H_n - F(H_n))$$

Krylov subspace methods(BiCG-STAB method)



(7





Backward propagation

gradient of the loss function

$$\nabla_{\theta} L = \nabla_{\theta} \ell + \nabla_{H} \ell \nabla_{\theta} H$$

where

$$\nabla_{\theta} H = (I - \nabla_{H} F)^{-1} (\nabla_{\theta} F + \nabla_{\varepsilon} F \nabla_{\theta} \xi)$$

so

$$\nabla_{\theta} L = \nabla_{\theta} \ell + \nabla_{H} \ell (I - \nabla_{H} F)^{-1} (\nabla_{\theta} F + \nabla_{\varepsilon} F \nabla_{\theta} \xi)$$

Krylov subspace methods(BiCG-STAB method)

(8)

(9)

(10)



Transition Functions

$$h_t = (1 - z_t)\hat{h}_t + z_t\tilde{h}_t$$

$$\tilde{h}_t = \tanh(Wx_t + U(r_t\hat{h}_t) + \tilde{b})$$

$$z_t = \sigma(W_zx_t + U_z\hat{h}_t + b_z)$$

$$r_t = \sigma(W_rx_t + U_r\hat{h}_t + b_r)$$

where

$$\hat{h}_{t} = sh_{t-1} + (1 - s)h_{t+1}$$

$$s = \frac{s_{p}}{s_{p} + s_{n}}$$

$$s_{p} = \sigma(W_{p}x_{t} + U_{p}h_{t-1} + b_{p})$$

$$s_{n} = \sigma(W_{n}x_{t} + U_{n}h_{t+1} + b_{n})$$



(12)





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Architecture	WSJ Accuracy
GRU	96.43
LSTM	96.47
Bidirectional GRU	97.28
b-LSTM	97.25
INN	97.37
Stanford POS Tagger	97.33

Table 2: Tagging performance relative to recurrent architectures and Stanford POS Tagger.