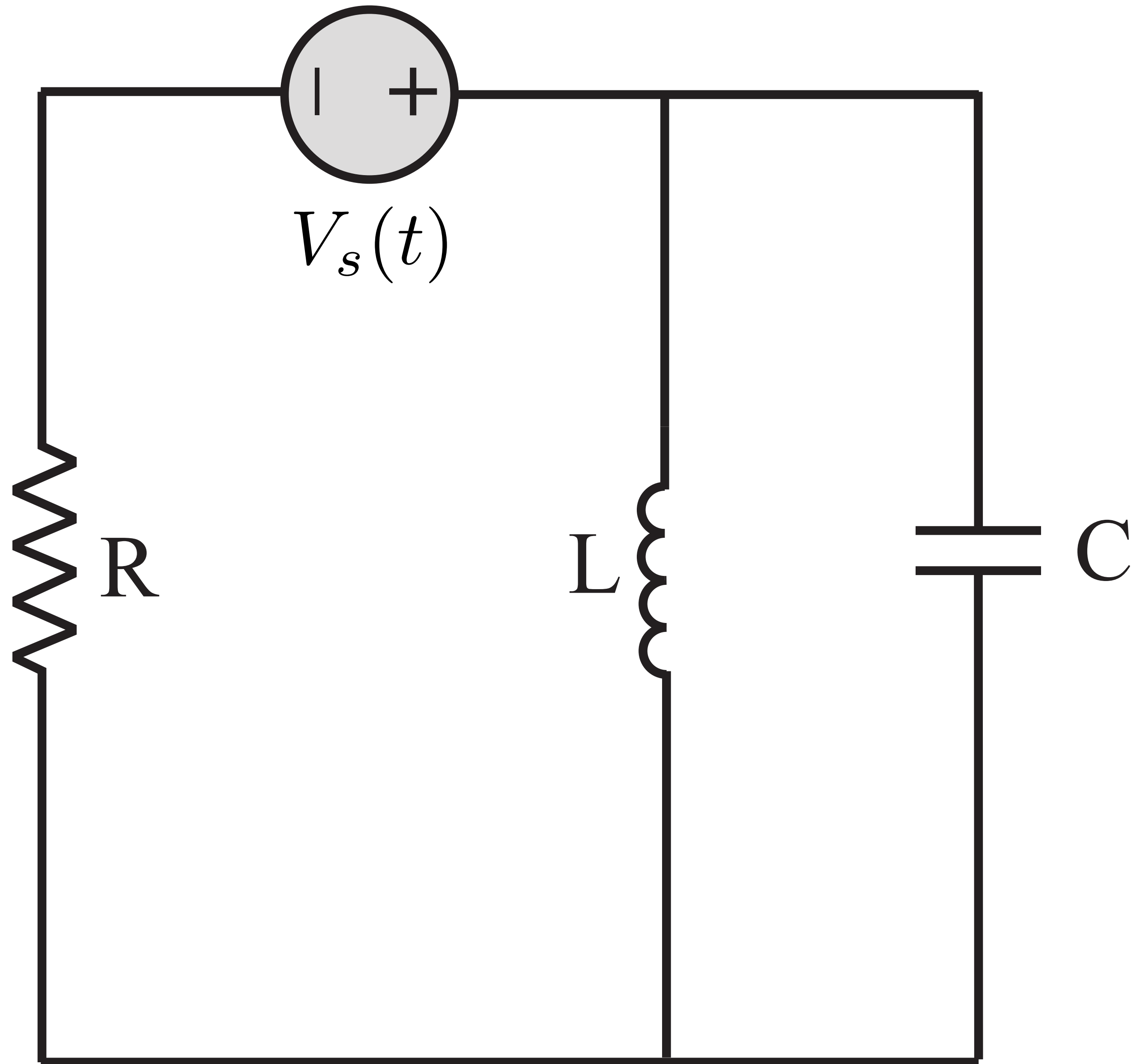


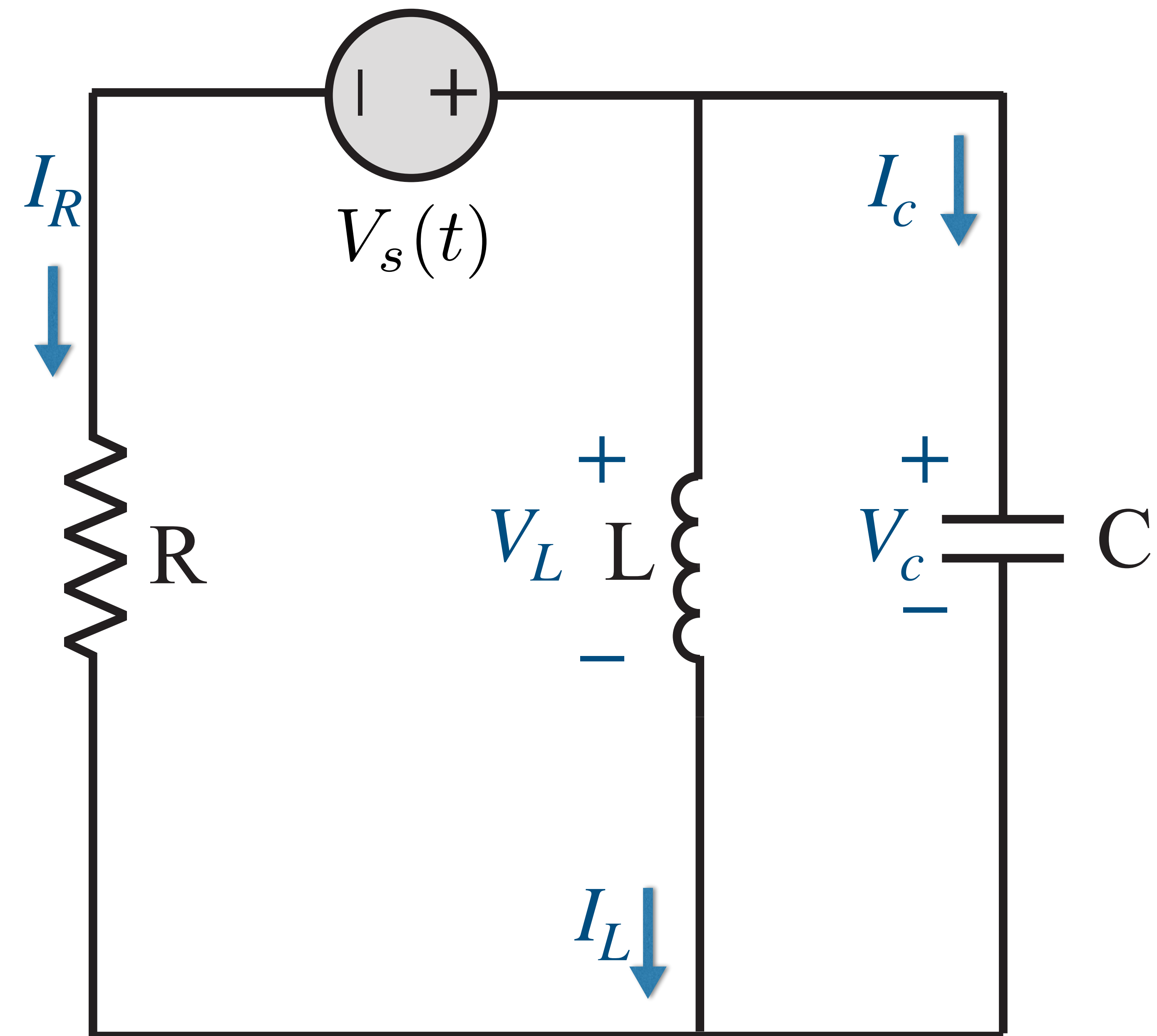
# EE281 - Second Order Circuits

## Step Response

Asst. Prof. M. Mert ANKARALI

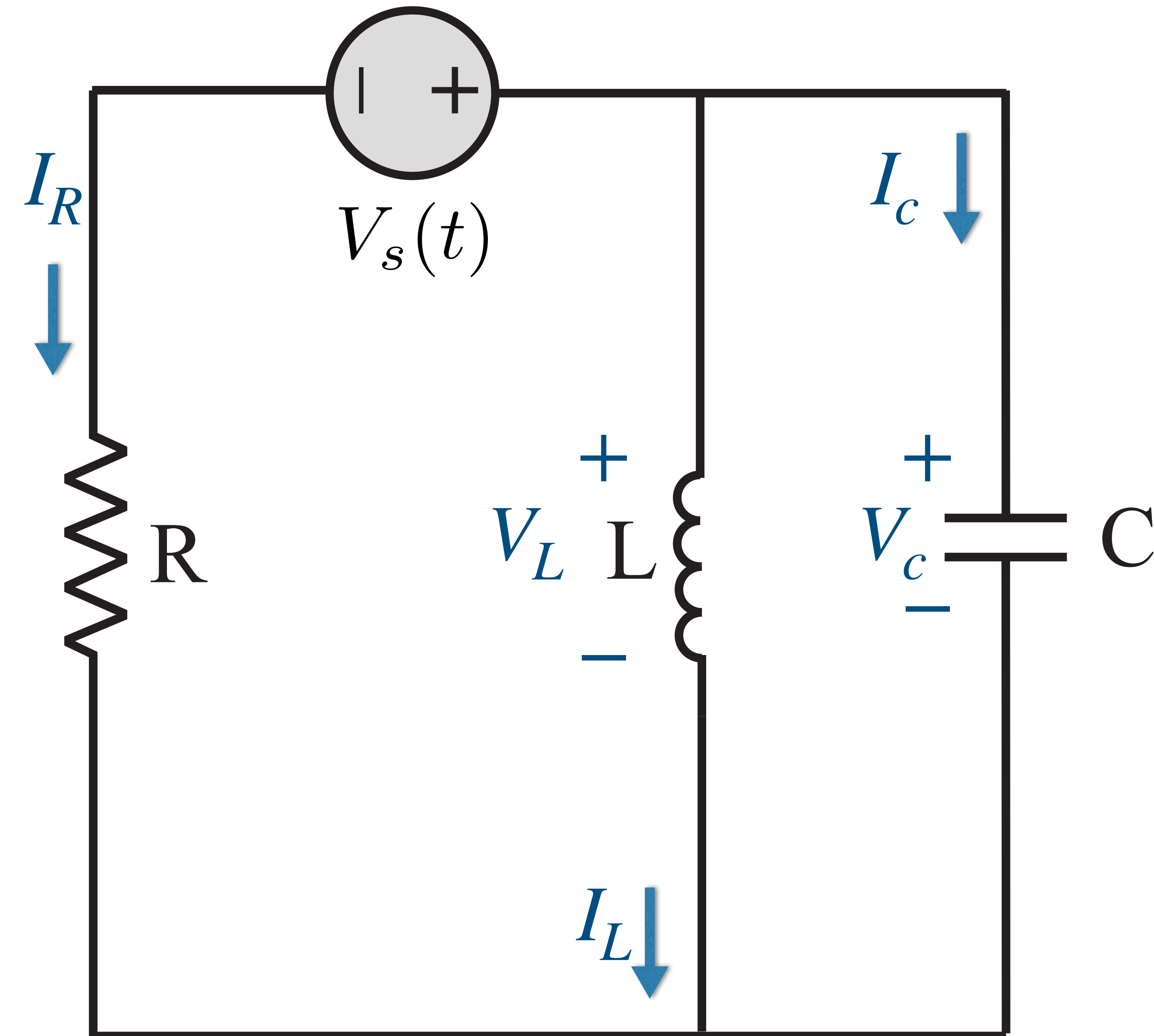
# RLC - Forced





Let  $I_L = I$      $V_L = V_c = V$

$$I_R + I_L + I_c = 0$$



$$\frac{V - V_s}{R} + I + C \frac{dV}{dt} = 0$$

$$V = L \frac{dI}{dt}$$

$$I + \frac{L}{R} \frac{dI}{dt} + LC \frac{d^2 I}{dt^2} = \frac{V_s}{R}$$

$$\ddot{I} + \frac{1}{RC} \dot{I} + \frac{1}{LC} I = \frac{V_s}{RLC}$$

$$I + \frac{L}{R} \frac{dI}{dt} + LC \frac{d^2 I}{dt^2} = \frac{V_s}{R}$$

$$\ddot{I} + \frac{1}{RC} \dot{I} + \frac{1}{LC} I = \frac{V_s}{RLC} \quad \longrightarrow \quad \ddot{y} + 2\alpha \dot{y} + \omega_0^2 y = \frac{F(t)}{\omega_o^2}$$

$$I \rightarrow y$$

$$\omega_0 = \sqrt{\frac{1}{LC}} \qquad F(t) = \frac{V_s}{R}$$

$$\alpha = \frac{1}{2RC}$$

$$\ddot{I} + \frac{1}{RC}\dot{I} + \frac{1}{LC}I = \frac{V_s}{RLC} \quad \longrightarrow \quad \ddot{y} + 2\alpha\dot{y} + \omega_0^2 y = \frac{F(t)}{\omega_o^2}$$

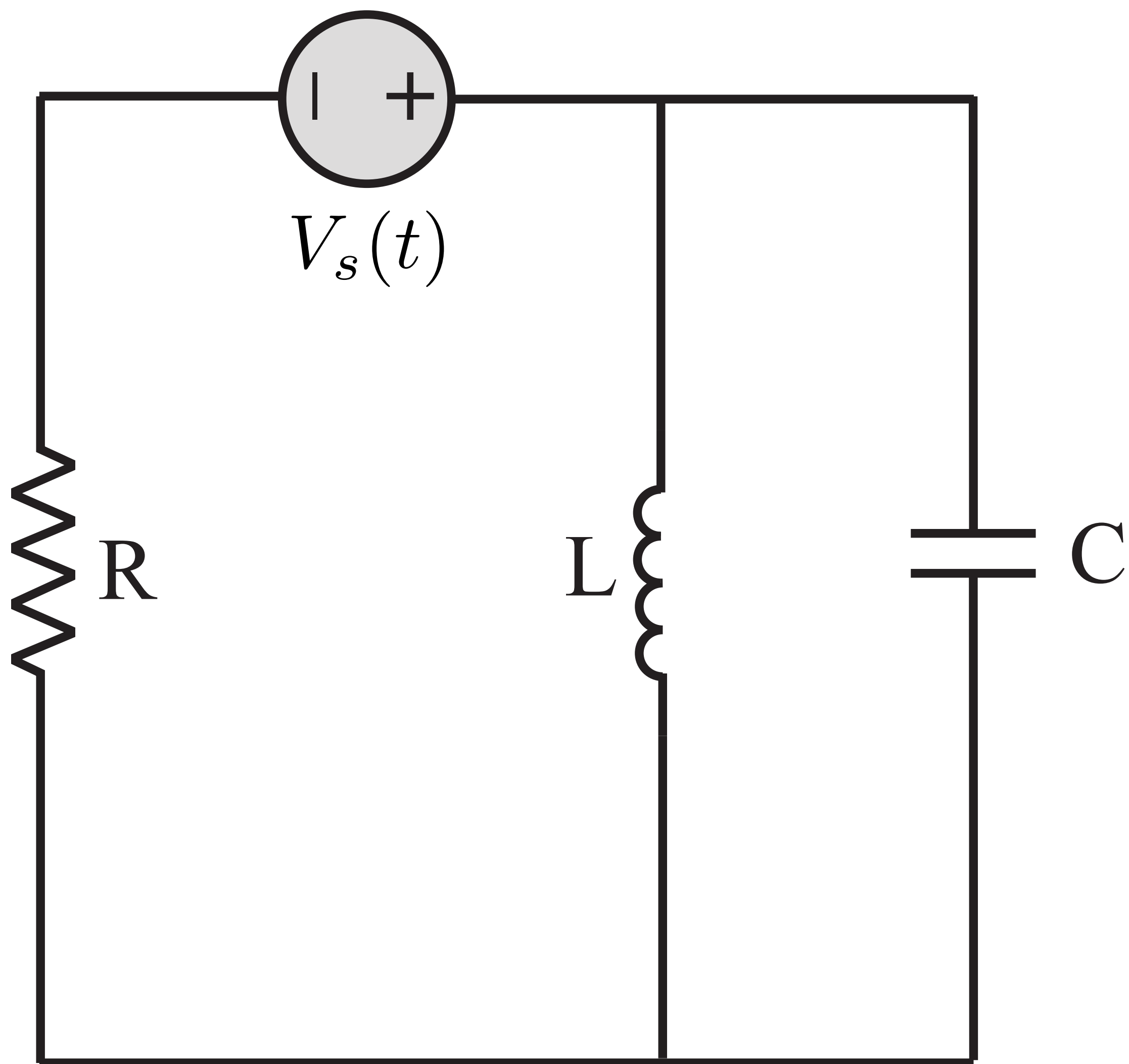
$$\ddot{I} + \frac{1}{RC}\dot{I} + \frac{1}{LC}I = \frac{V_s}{RLC} \quad \longrightarrow \quad \ddot{y} + 2\alpha\dot{y} + \omega_0^2 y = \frac{F(t)}{\omega_o^2}$$

$$y(t) = y_h(t) + y_p(t)$$

$$\textit{Let } F(t) = A \text{ for } t \geq 0 \quad \Rightarrow \quad y_p(t) = A = y_\infty = y_{ss}$$

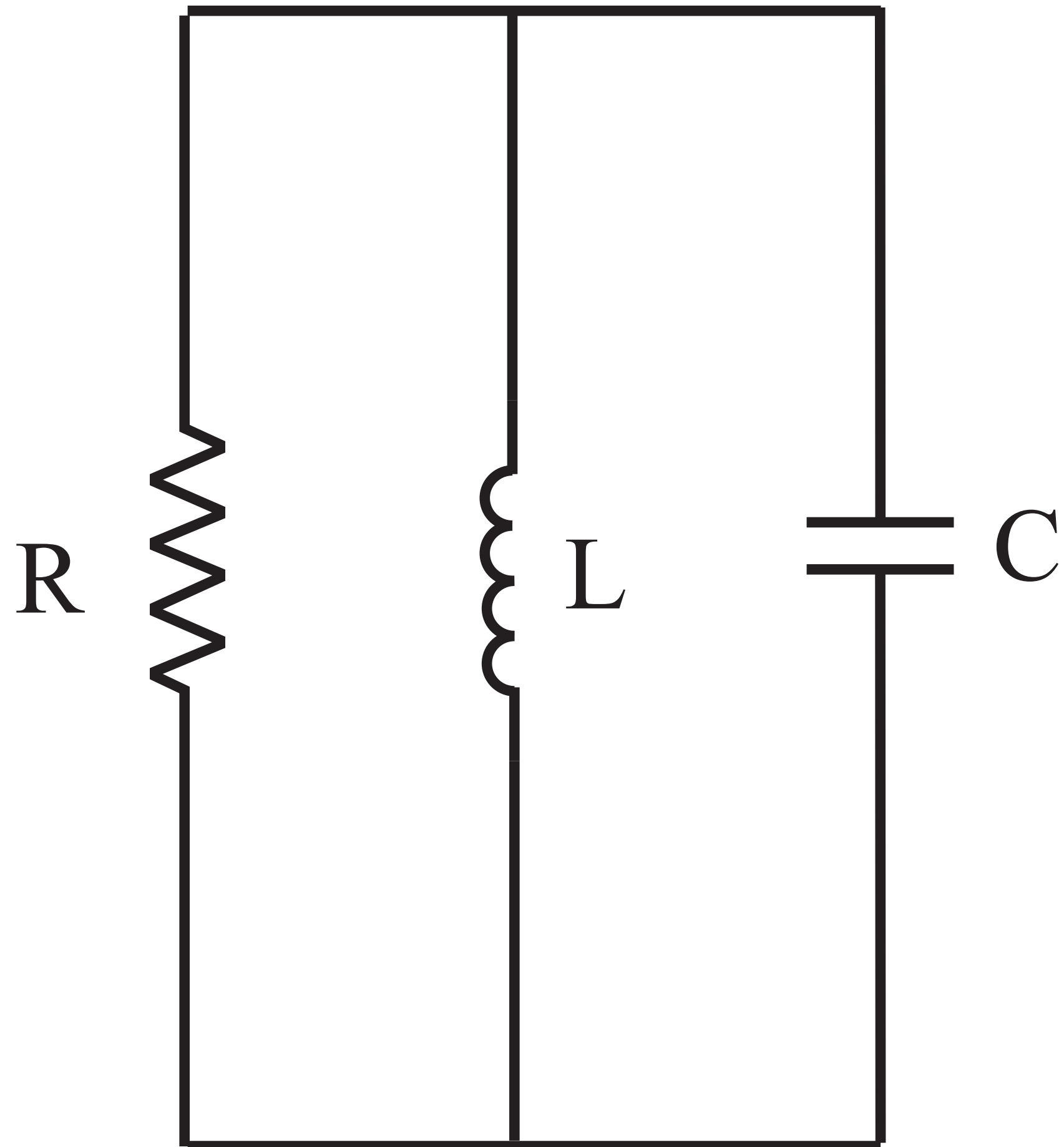
$$L = 0.4H, C = 0.1F, R = 1\Omega$$

$$V_s = 4u(t)V, V_C(0) = 0V, I_L(0) = 0A$$





$$L = 0.4H, C = 0.1F, R = 1\Omega$$



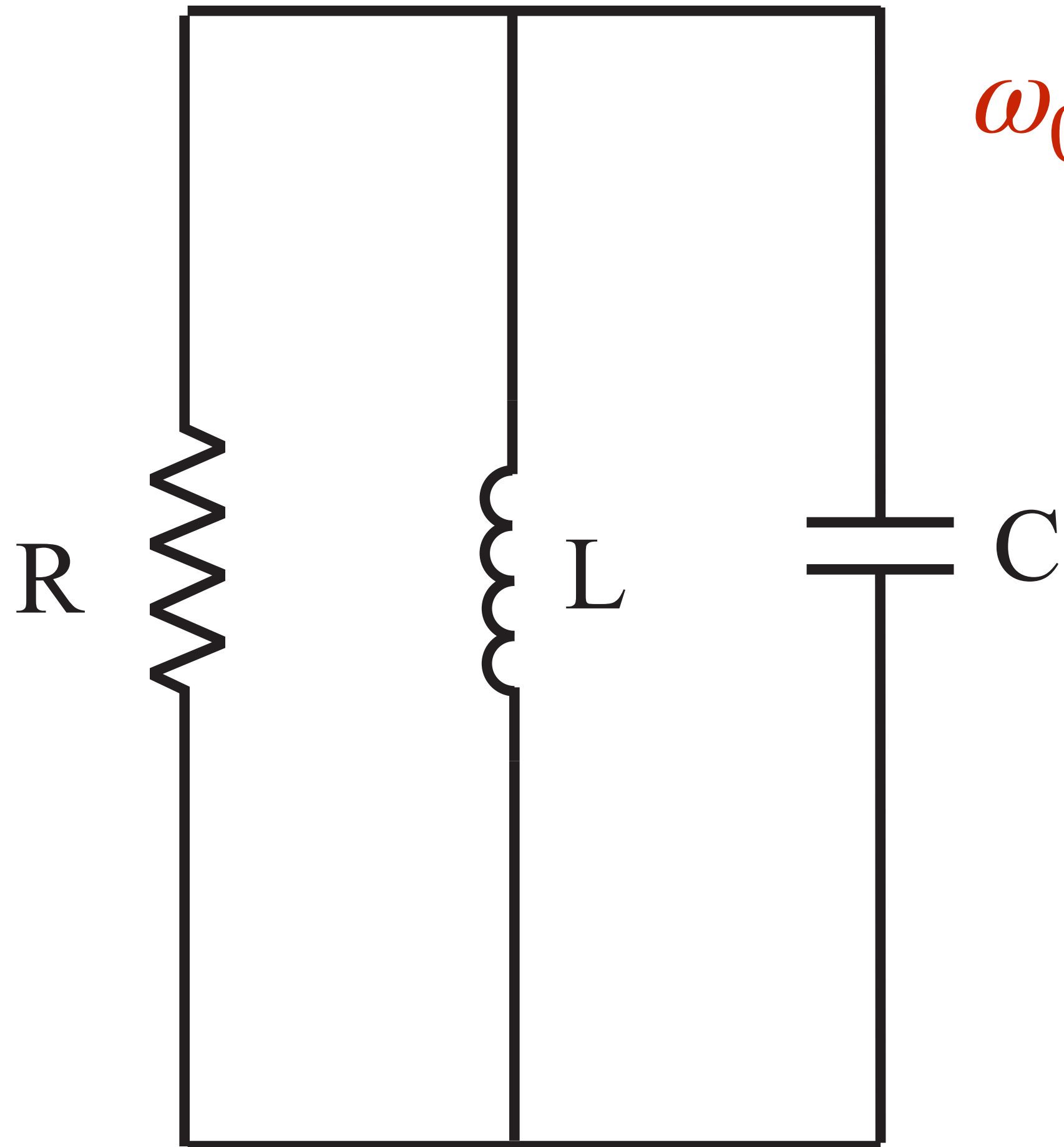
$$L = 0.4H, C = 0.1F, R = 1\Omega$$

$$\ddot{I} + \frac{1}{RC}\dot{I} + \frac{1}{LC}I = 0 \longrightarrow \ddot{y} + 2\alpha\dot{y} + \omega_0^2 y = 0$$

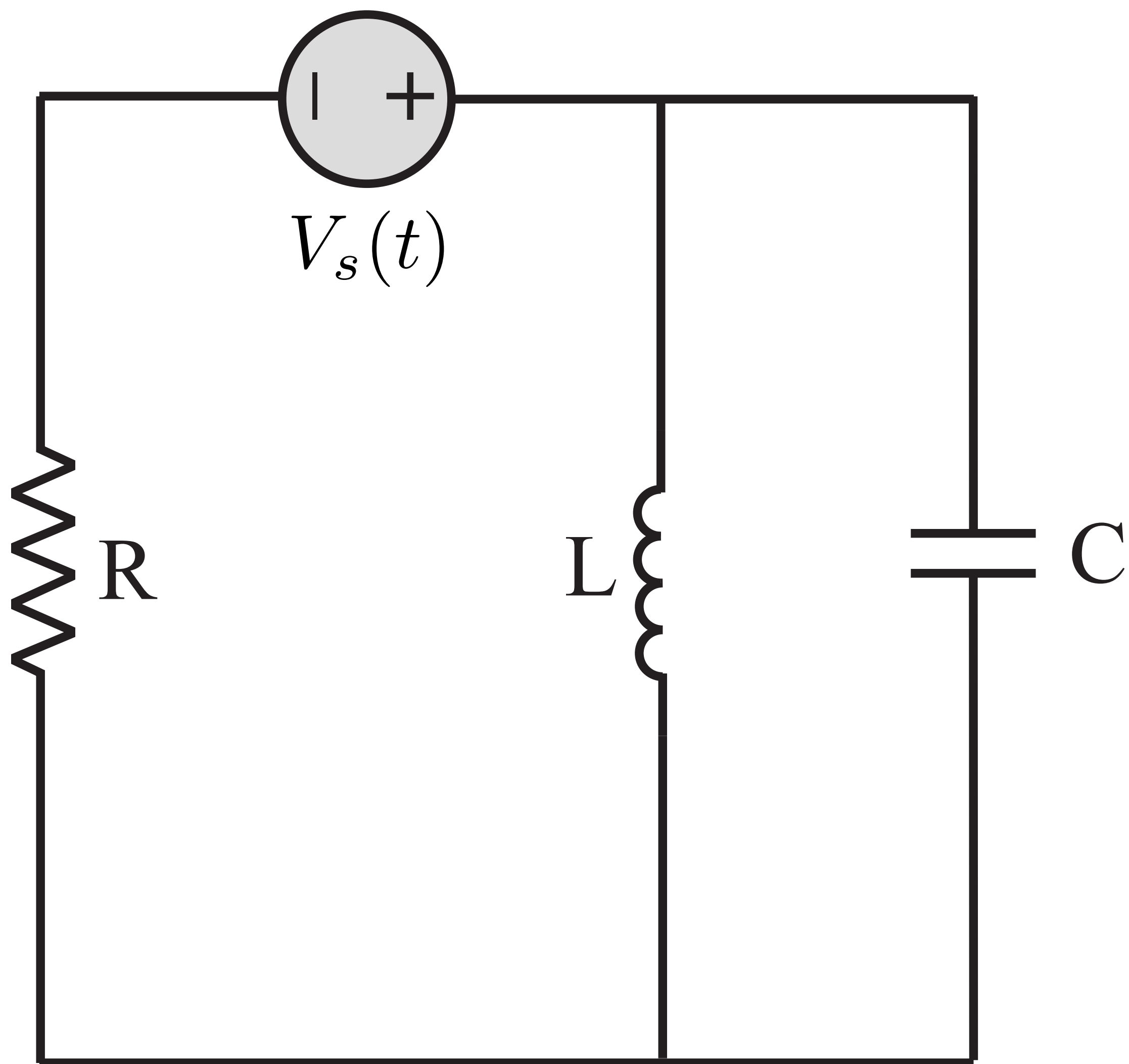
$$\omega_0 = \sqrt{\frac{1}{LC}} = 5 \text{ rad/s} \quad \alpha = \frac{1}{2RC} = 5 \text{ rad/s}$$

$$\alpha = \omega_0 \rightarrow \textbf{Critically-damped}$$

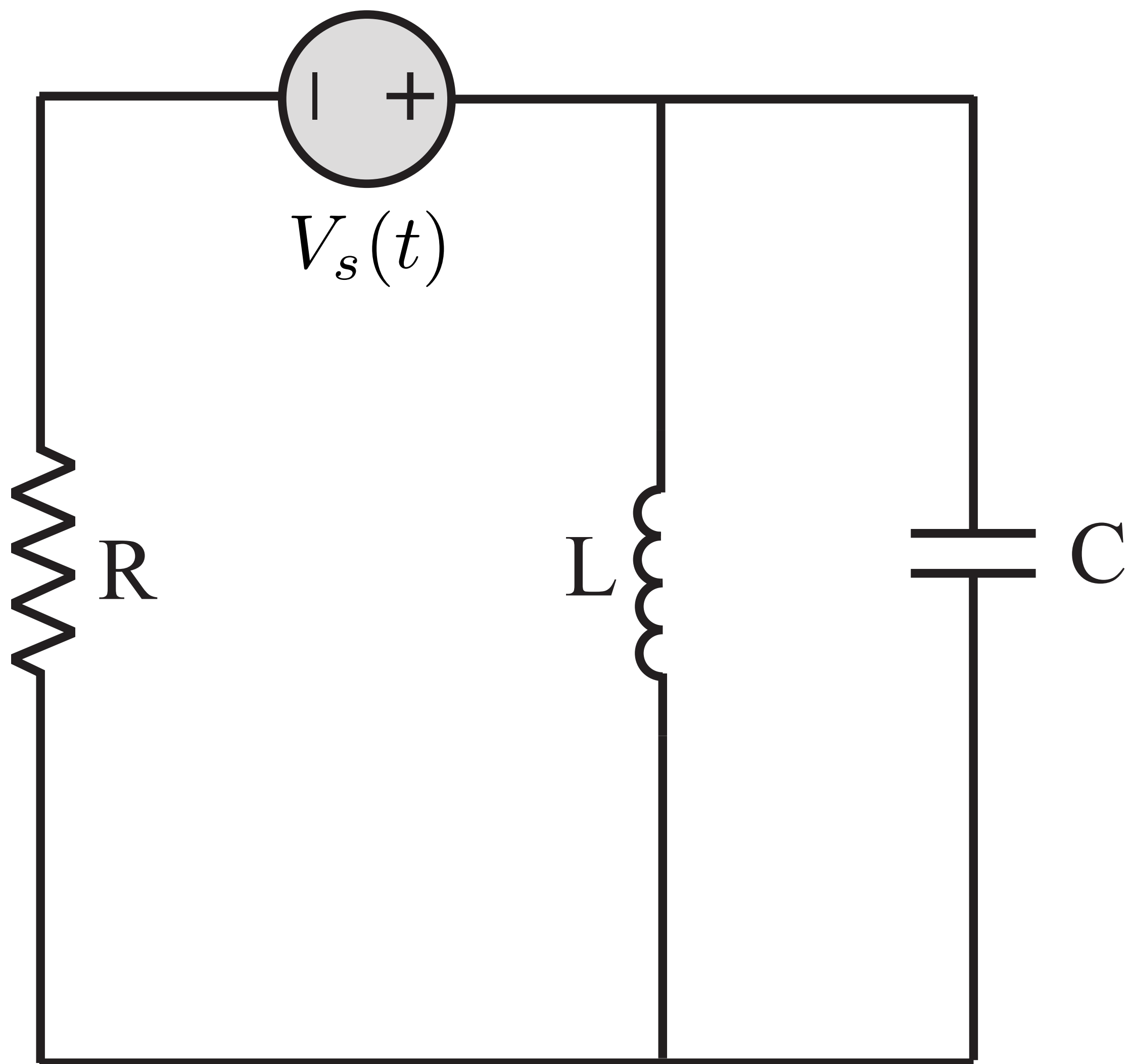
$$I_h(t) = C_1 e^{-5t} + C_2 t e^{-5t}$$



$$V_s = 4u(t)V$$

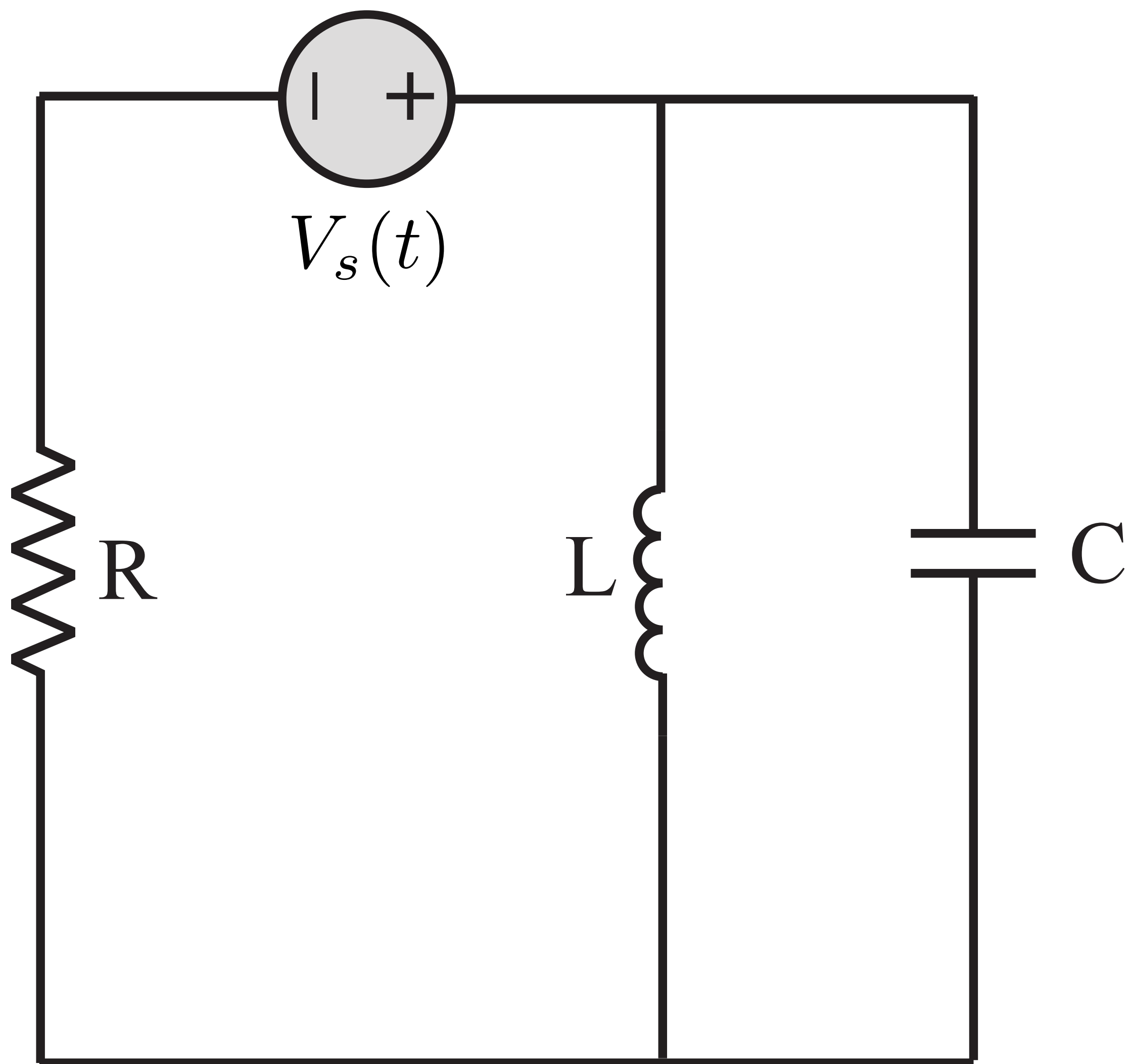


$$V_s = 4u(t)V$$



$$I_p(t) = I_\infty = 4A$$

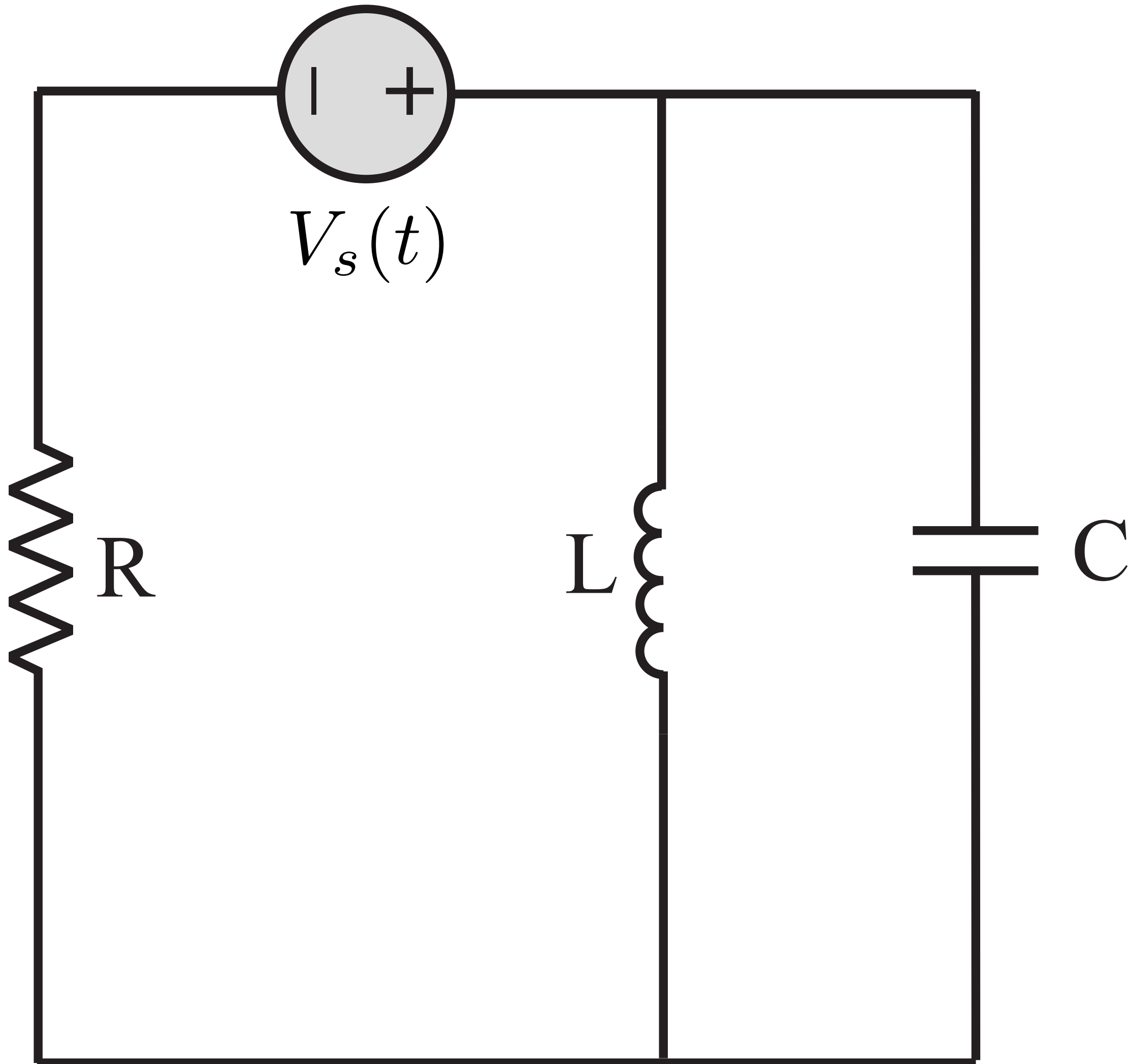
$$V_s = 4u(t)V, \quad V_C(0) = 0V, \quad I_L(0) = 0A$$



$$V_s = 4u(t)V, \quad V_C(0) = 0V, \quad I_L(0) = 0A$$

$$I(0) = I_L(0) = 0A$$

$$L\dot{I} = V_C \rightarrow \dot{I}(0) = 0A$$



$$I(0) = 0A$$

$$\dot{I}(0) = 0A$$

$$I(t) = C_1 e^{-5t} + C_2 t e^{-5t} + 4 A$$

$$I(0) = 0A$$

$$\dot{I}(0) = 0A$$

$$I(t) = C_1 e^{-5t} + C_2 t e^{-5t} + 4 A$$

$$I(0) = C_1 + 4 A = 0 \rightarrow C_1 = -4$$

$$\dot{I}(0) = -5C_1 + C_2 = 0 \rightarrow C_2 = -20$$

$$I(t) = \left( 4 - 4 e^{-5t} - 20 t e^{-5t} \right) A$$