# Operating System Labs

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### Announcement

- Project 1 due
  - 21:00 Oct. 9

# Operating System Labs

- The abstraction of process
- Process API
  - fork(), exec(), wait()
  - Project 1a
- CPU virtualization
  - Low level & high level mechanisms
  - Project 1b

- Process
  - Running programs
- What does a running program require?
  - CPU
    - Program Counter (PC)
    - Stack Pointer / Frame Pointer
  - Memory
    - Address space
  - Disk
    - Set of file descriptors

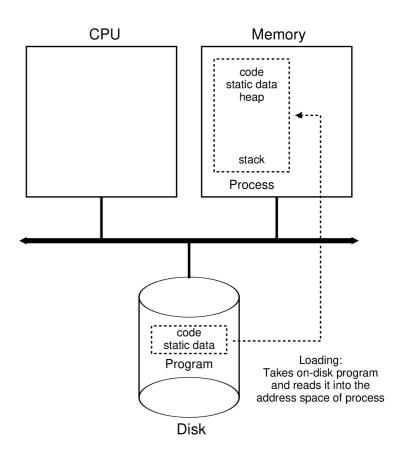
#### proc file system

- The Linux kernel has two primary functions:
  - control access to physical devices on the computer
  - schedule when and how processes interact with these devices.
- /proc/ directory contains a hierarchy of special files
- the current state of the kernel allowing applications and users to peer into the kernel's view of the system.

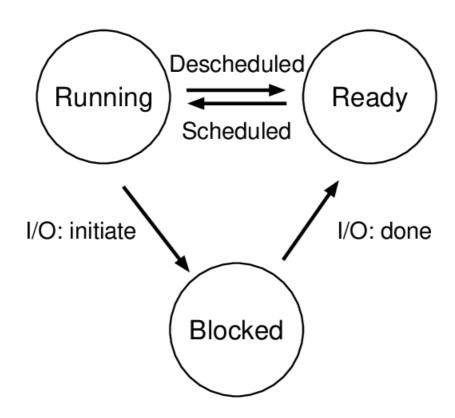
- proc file system
  - processes as files ("Everything is file")
  - Example
    - cat /proc/<PID>/status
    - cat /proc/<PID>/maps
    - cat /proc/<PID>/fd
    - cat /proc/<PID>/io
  - /proc/interrupts, /proc/meminfo, /proc/mounts, /proc/partitions
  - Provide a method of communication between kernel space and user space
    - ps command

- Process operations
  - Create
  - Destroy
  - Wait
  - Miscellaneous Control
  - Get status

- Example: process creation
  - Load code and static data
  - Establish stack
    - local variables, function calls
  - Init heap
    - malloc, free
  - Allocate file descriptors
    - STDIN\_FILENO
    - STDOUT\_FILENO
    - STDERR\_FILENO



Process States



#### • Process States

Time	$\mathbf{Process}_0$	$\mathbf{Process}_1$	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	
4	Running	Ready	Process <sub>0</sub> now done
5	_	Running	
6	_	Running	
7	_	Running	
8	_	Running	Process <sub>1</sub> now done

Time	$\mathbf{Process}_0$	$\mathbf{Process}_1$	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	Process <sub>0</sub> initiates I/O
4	Blocked	Running	Process <sub>0</sub> is blocked,
5	Blocked	Running	so $Process_1$ runs
6	Blocked	Running	
7	Ready	Running	I/O done
8	Ready	Running	Process <sub>1</sub> now done
9	Running	_	
10	Running	_	Process <sub>0</sub> now done

• Data structures

```
// the registers xv6 will save and restore
// to stop and subsequently restart a process
struct context {
  int eip;
 int esp;
 int ebx;
 int ecx;
 int edx;
 int esi;
 int edi;
 int ebp;
};
// the different states a process can be in
enum proc_state { UNUSED, EMBRYO, SLEEPING,
                  RUNNABLE, RUNNING, ZOMBIE };
// the information xv6 tracks about each process
// including its register context and state
struct proc {
 char *mem;
                              // Start of process memory
                              // Size of process memory
 uint sz;
                              // Bottom of kernel stack
 char *kstack;
                              // for this process
                             // Process state
 enum proc_state state;
 int pid;
                             // Process ID
  struct proc *parent;
                              // Parent process
 void *chan;
                              // If non-zero, sleeping on chan
 int killed;
                              // If non-zero, have been killed
  struct file *ofile[NOFILE]; // Open files
 struct inode *cwd;
                             // Current directory
  struct context context;
                             // Switch here to run process
                             // Trap frame for the
  struct trapframe *tf;
                              // current interrupt
```

- fork(), exec(), wait(), exit()
- Create, execute, wait and terminate a process
- May be the strangest API you've ever met

- fork()
  - Create a new process
  - Exactly copy the calling process
- The return code of fork() is different
  - In parent: fork() return the pid of the child
  - In child: fork() return 0
- Who will run first is not determined

- wait()
  - Wait for a child to finish his job
  - The parent will not proceed until wait() return.
- waitpid()

- exec()
  - Execute a different program in child process
- A group of system calls:
  - execl, execv, execle, execve, execlp, execvp, fexecv

- Some Coding
  - fork
  - fork, wait
  - fork, wait, execvp

- What's happening behind fork()?
  - The child get a "copy" of parent's data space, stack, heap
    - the system call: clone()
  - "Copy-on-write"
    - Not really copy the data, but share the data with "read only" flag
    - If parent or child writes on a shared address, the kernel make a copy of that piece of memory only (usually a page)

- What's happening behind fork()?
  - File sharing
    - fd
    - File offsets

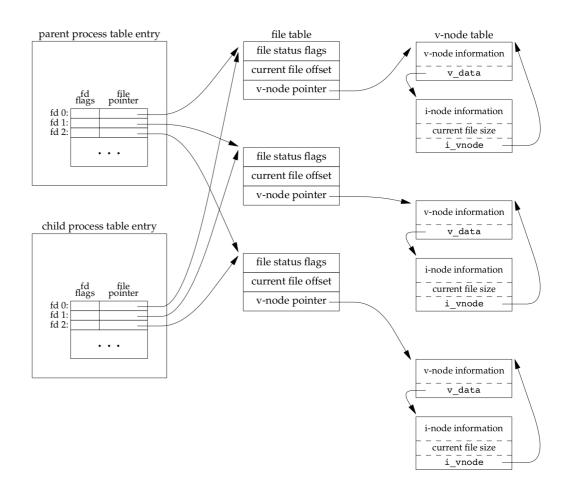


Figure 8.2 Sharing of open files between parent and child after fork

- What's happening behind fork()?
  - Other shared data:
    - User ID, group ID...
    - Current working directory
    - Environment
    - Memory mapping
    - Resources limits

• ...

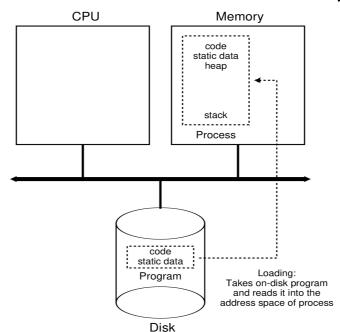
- What's happening behind exit()?
  - Close all fds, release all memory, ...
  - Inform the exit status to the parent process,
     which can be captured by wait()

- What's happening behind wait()?
  - The parent terminates first?
    - The init process (PID=0)
  - The child terminates first?
    - The kernel keeps a small amount of information for every terminating process
    - Available when the parent calls wait()
      - PID, termination status the amount of CPU time
    - zombies



- What's happen behind wait()/waitpid()
  - wait(): block the caller until a child process terminates
  - waitpid(): wait which child, and some other options

- What's happening behind exec()?
  - Replace the current process with a new program from disk
    - Text, data, heap, stack
  - Start from the main() of that program



- Process API summary
  - fork(): create a new process
  - wait(): wait for a child
  - exit(): destroy a process
  - exec(): execute a program in child

# Project1a

- Implement your own shell
  - Use fork, wait, execvp
  - Also open, close, dup2

- Basic shell
  - Run your shell by: ./mysh
  - It will print a prompt:

mysh>

You can type some commands

mysh> ls

Hit ENTER, the command will be executed

#### Build-in Commands

- When "mysh" execute a command, it will check weather it is a **build-in** or not.
- For build-in commands, you should involve your implementation.
- They are:
  - exit
  - wait
  - cd
  - pwd

#### • Redirection

– Your shell should support redirection:

mysh> ls -l > output

- The file "output" contain the result of "ls -l"

- Background Jobs
  - Your shell should be able to run jobs in the background

mysh> ls &

- Your shell will continue to work rather than wait.

- Batch mode
  - Your shell should be able to run in batch mode

```
./mysh batch_file
```

- Your shell will run the commands in batch\_file
- E.g, "batch\_file" contains

```
ls -1
```

echo hello

- Bonus: Pipe
  - The pipe connect the input/output of different commands

mysh> grep "hello" FILE | wc -l

How many lines have "hello"

### **CPU Virtualization**

- What
  - Provide the illusion of many CPUs
- Why
  - Multi-task
- How
  - Time sharing

### **CPU Virtualization**

- Mechanisms
  - Low level mechanisms
    - Context switch
  - High level intelligence
    - Scheduling policy

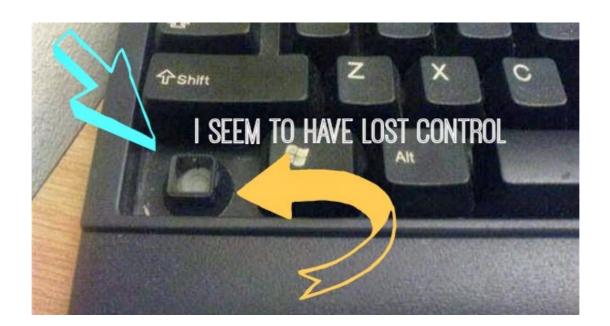
## **CPU Virtualization**

- Low level mechanisms
  - Direct Execution
    - Just run a program on CPU directly

OS	Program
Create entry for process list	
Allocate memory for program	
Load program into memory	
Set up stack with argc/argv	
Clear registers	
Execute call main()	
	Run main()
	Execute <b>return</b> from main
Free memory of process	
Remove from process list	

### Direct Execution

- Problems of direct execution
  - Visit any memory address
  - Open any file
  - Directly play with hardwares (e.g. I/O)



Lost control

- Limited Direct Execution
  - Kernel model and user model
  - "restricted operations"
    - By OS
  - When a thread needs "restricted operations"
    - System call

- User mode
  - The behavior of the code is restricted
- Kernel mode
  - The code can do whatever it wants to do
    - Issue I/O, executing all types of instructions,...
- How to switch?
  - System call

## System Call

- Hardware supports on system call
  - A bit in CPU identifies kernel/user mode
  - "trap" instruction
  - "return-from-trap" instruction
  - Save the registers before do the restricted operation (kernel stack)

OS @ run (kernel mode) Hardware

Program (user mode)

Run main()

... Call system call **trap** into OS

OS @ run	
(kernel mode	(؛

#### Hardware

Program (user mode)

Run main()

...

Call system call **trap** into OS

save regs to kernel stack move to kernel mode jump to trap handler

OS @ run	
(kernel mode)	)

#### Hardware

Program (user mode)

Run main()

...

Call system call **trap** into OS

save regs to kernel stack move to kernel mode jump to trap handler

Handle trap
Do work of syscall
return-from-trap

OS @ run	
(kernel mod	e)

#### Hardware

#### Program (user mode)

Run main()

...

Call system call **trap** into OS

save regs to kernel stack move to kernel mode jump to trap handler

Handle trap
Do work of syscall
return-from-trap

restore regs from kernel stack move to user mode jump to PC after trap

OS @ run (kernel mode)	Hardware	Program (user mode)
Create entry for process list		
Allocate memory for program		
Load program into memory Setup user stack with argy		
Fill kernel stack with reg/PC		
return-from-trap		
	restore regs from kernel stack	
	move to user mode	
	jump to main	D
		Run main()
		 Call system call
		trap into OS
	save regs to kernel stack	_
	move to kernel mode	
	jump to trap handler	
Handle trap		
Do work of syscall		
return-from-trap		
	restore regs from kernel stack	
	move to user mode jump to PC after trap	

OS @ run (kernel mode)	Hardware	Program (user mode)
Create entry for process list Allocate memory for program		
Load program into memory		
Setup user stack with argy		
Fill kernel stack with reg/PC return-from-trap		
•	restore regs from kernel stack move to user mode	
	jump to main	
		Run main()
		 Call system call <b>trap</b> into OS
	save regs to kernel stack move to kernel mode	•
Handle trap	jump to trap handler	
Do work of syscall return-from-trap		
•	restore regs from kernel stack move to user mode	
	jump to PC after trap	
		return from main
Free memory of process		trap (via exit ())
Remove from process list		

OS @ boot (kernel mode)	Hardware	
initialize trap table	remember address of syscall handler	
OS @ run (kernel mode)	Hardware	Program (user mode)
Create entry for process list Allocate memory for program Load program into memory Setup user stack with argv Fill kernel stack with reg/PC		
return-from-trap	restore regs from kernel stack move to user mode jump to main	
		Run main()
		 Call system call <b>trap</b> into OS
	save regs to kernel stack move to kernel mode jump to trap handler	
Handle trap Do work of syscall return-from-trap		
	restore regs from kernel stack move to user mode jump to PC after trap	
		<pre> return from main trap (via exit ())</pre>
Free memory of process Remove from process list		

- Switching between processes
  - Cooperative approach
    - OS trusts the process to yield CPU properly
  - Non-cooperative approach
    - OS revokes the control of CPU periodically
    - Time interrupt
    - Scheduler

OS @ boot (kernel mode)	Hardware	
initialize trap table start interrupt timer	remember addresses of syscall handler timer handler start timer interrupt CPU in X ms	
OS @ run (kernel mode)	Hardware	Program (user mode)
Handle the trap  Call switch() routine save regs(A) to proc-struct(A) restore regs(B) from proc-struct(B) switch to k-stack(B)	timer interrupt save regs(A) to k-stack(A) move to kernel mode jump to trap handler	Process A
return-from-trap (into B)	restore regs(B) from k-stack(B) move to user mode jump to B's PC	Process B

• • •

- Low-level mechanisms: summary
  - Direct execution
  - Limited direct execution
  - Switch between processes

# Scheduling Policy

- High level intelligence
  - Scheduling policy
    - First In, First Out
    - Shortest job first
    - Shortest time to complete first
    - Round Roubin

## •CPU virtualization

- Summary of CPU virtualization
  - Low level mechanisms
    - A little hardware support goes a long way
  - High level mechanisms

## Project1b Details

- Adding a system call for xv6
  - Understanding the low-level mechanism
  - Kernel mode, user mode
  - Trap
  - Interrupt handler

## Project1b Details

- The system call
  - int getreadcount()
  - Return how many times the read() system call has been called

## Project1b Details

- Get familiar with xv6
  - QEMU emulator
    - Installed with make
  - Compile and run xv6
    - Compile: make
    - Run: make qemu-nox
    - Debug: make qemu-nox-gdb