MX2

Born to drive machines

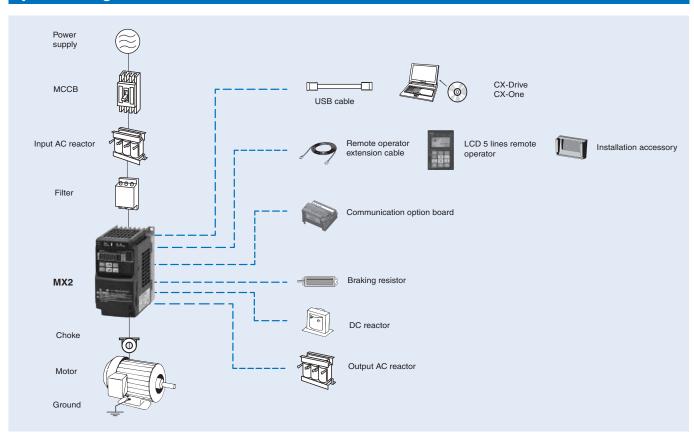
- · Current vector control
- High starting torque: 200% at 0.5 Hz
- Double rating VT 120%/1 min and CT 150%/1 min
- IM & PM motor control
- Torque control in open loop vector
- · Positioning functionality
- Built-in application functionality (i.e. Brake control)
- · Built-in logic programing
- Safety embedded compliant with ISO13849-1 (double input circuit and external device monitor EDM)
- · USB port for PC programming
- 24 VDC backup supply for control board
- Fieldbus communications: Modbus, DeviceNet, Profibus, CompoNet, EtherCAT, ML-II and EtherNet/IP
- PC configuration tool: CX-Drive
- · RoHS, CE, cULus

Ratings

- 200 V Class single-phase 0.1 to 2.2 kW
- 200 V Class three-phase 0.1 to 15.0 kW
- 400 V Class three-phase 0.4 to 15.0 kW

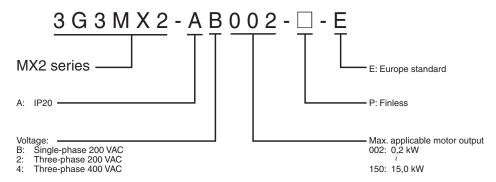


System configuration



Specifications

Type designation



200 V class

	Single-phase: 3G3l	VIX2-□	B001	B002	B004	B007 ¹	B015	B022	-	-	-	-	-		
	Three-phase: 3G3N	/IX2-□	2001	2002	2004	2007	2015	2022	2037	2055	2075	2110	2150		
Motor	For VT set	tting	0.2	0.4	0.55	1.1	2.2	3.0	5.5	7.5	11	15	18.5		
kW ²	For CT set	tting	0.1	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15		
		200 VT	0.4	0.6	1.2	2.0	3.3	4.1	6.7	10.3	13.8	19.3	23.9		
υ		200 CT	0.2	0.5	1.0	1.7	2.7	3.8	6.0	8.6	11.4	16.2	20.7		
t stic	Inverter capacity kVA	240 VT	0.4	0.7	1.4	2.4	3.9	4.9	8.1	12.4	16.6	23.2	28.6		
Output racteristics	•	240 CT	0.3 0.6 1.2 2.0				3.3	4.5	7.2	10.3	13.7	19.5	24.9		
On act	Rated output current (A) at VT	1.2	1.9	3.5	6.0	9.6	12.0	19.6	30.0	40.0	56.0	69.0		
	Rated output current (A) at CT	1.0	1.6	3.0	5.0	8.0 11.0 17.5 25.0 33.0 47.0								
0	Max. output voltage					Pro	oportional to input voltage: 0240 V								
	Max. output frequency	1					400 Hz								
	Rated input voltage and frequency					S	ingle-phas 3-phase 2	e 200240 200240 V		lz					
o di	Allowable voltage fluc	tuation					-	15%+10%	6						
ш б	Allowable frequency f	luctuation						5%							
	Braking torque	At short-time deceleration At capacitor feedback			<50Hz <60Hz		70%: <50Hz 50%: <60Hz	Appro	x 20%			-			
	Cooling metho	od		Self c	ooling			•	For	ced-air-coc	ling	•			

- 1. Three phase model use forced-air-cooling but single phase model is self cooling.
- 2. Based on a standard 3-Phase standard motor.

400 V class

	Three-phase: 3G3I	MX2-□	4004	4007	4015	4022	4030	4040	4055	4075	4110	4150		
Motor	For VT set	tting	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15	18.5		
kW ¹	For CT se	tting	0.4	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15		
		380 VT	1.3	2.6	3.5	4.5	5.7	7.3	11.5	15.1	20.4	25.0		
y,	Inverter capacity kVA	380 CT	1.1	2.2	3.1	3.6	4.7	6.0	9.7	11.8	15.7	20.4		
t stic	inverter capacity KVA	480 VT	1.7	3.4	4.4	5.7	7.3	9.2	14.5	19.1	25.7	31.5		
Output characteristics		480 CT	1.4	2.8	3.9	4.5	5.9	7.6	12.3	14.9	19.9	25.7		
On	Rated output current (A) at VT	2.1	4.1	5.4	6.9	8.8	11.1	17.5	23.0	5.1 20.4 2 1.8 15.7 2 0.1 25.7 3 1.9 19.9 2 3.0 31.0 3			
hai	Rated output current ((A) at CT	1.8	3.4	4.8	5.5	7.2	9.2	14.8	18.0	24.0	31.0		
0	Max. output voltage					Proport	Proportional to input voltage: 0480 V							
	Max. output frequency	/					400) Hz						
. >	Rated input voltage and frequency					3-p	3-phase 380480 V 50/60 Hz							
Power	Allowable voltage fluctuation						-15%.	.+10%						
	Allowable frequency fluctuation						5	%						
	Braking torque	At short-time deceleration At capacitor feedback			<50Hz <60Hz	·								
	Cooling metho	od	Self c	ooling				Forced-a	ir-cooling					

1. Based on a standard 3-Phase standard motor.

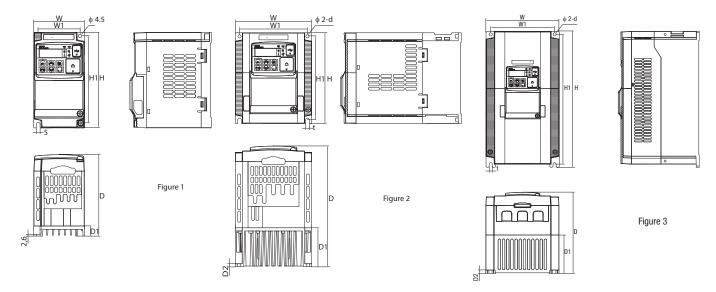
Specifications

Common specifications

	Model number 3G3MX2	Specifications
	Control methods	Phase-to-phase sinusoidal pulse with modulation PWM (Sensorless vector control, V/F)
	Output frequency range	0.10400.00 Hz
	F	Digital set value: ±0.01% of the max. frequency
ક	Frequency precision	Analogue set value: ±0.2% of the max. frequency (25 ±10°C)
Control functions	Resolution of frequency set value	Digital set value: 0.01 Hz
ıncı	nesolution of frequency set value	Analogue set value: 1/1000 of maximum frequency
1	Resolution of output frequency	0.01Hz
tro	Starting torque	200% / 0.5 Hz
Š		Dual rating:
	Overload capability	Heavy duty (CT): 150% for 1 minute Normal Duty (VT): 120% for 1 minute
	Frequency set value	0 to 10 VDC (10 KΩ), 4 to 20 mA (100 Ω), RS485 Modbus, Network options
		Constant/ reduced torque, free V/f
	V/f Characteristics	FW (forward run command), RV (reverse run command), CF1~CF4 (multi-stage speed setting), JG (jog command), DB (ex-
	Inputs signals	trinal braking), SET (set second motor), 2CH (2-stage accel./decel. command), FRS (free run stop command), EXT (external trip), USP (startup function), CS (commercial power switchover), SFT (soft lock), AT (analog input selection), RS (reset), PTC (thermistor thermal protection), STA (start), STP (stop), F/R (forward/reverse), PID (PID disable), PIDC (PID reset), UP (remote control up function), DWN (remote control down function), UDC (remote control data clear), OPE (operator control), SF1~SF7 (multi-stage speed setting; bit operation), OLR (overload restriction), TL (torque limit enable), TRQ1 (torque limit changeover1), TRQ2 (torque limit changeover2), BOK (Braking confirmation), LAC (LAD cancellation), PCLR (position deviation clear), ADD (add frequency enable), F-TM (force terminal mode), ATR (permission of torque command input), KHC (Cumulative power clear), MI1~MI7 (general purpose inputs for Drive Programming), AHD (analog command hold), CP1~CP3 (multistage-position switches), ORL (limit signal of zero-return), ORC (trigger signal of zero-return), SPD (speed/position changeover), GS1~GS2 (STO inputs, safety related signals), 485 (Starting communication signal), PRG (executing Drive Programming), HLD (retain output frequency), ROK (permission of run command), EB (rotation direction detection of B-phase), DISP (display limitation), OP (option control signal), NO (no function), PSET (preset position)
Functionality	Output signals	RUN (run signal), FA1~FA5 (frequency arrival signal), OL,OL2 (overload advance notice signal), OD (PID deviation error signal), AL (alarm signal), OTQ (over/under torque threshold), UV (under-voltage), TRQ (torque limit signal), RNT (run time expired), ONT (power ON time expired), THM (thermal warning), BRK (brake release), BER (brake error), ZS (OHz detection), DSE (speed deviation excessive), POK (positioning completion), ODc (analog voltage input disconnection), OIDc (analog current input disconnection), FBV (PID second stage output), NDc (network disconnect detection), LOG1~LOG3 (Logic output signals), WAC (capacitor life warning), WAF (cooling fan warning), FR (starting contact), OHF (heat sink overheat warning), LOC (Low load), MO1~MO3 (general outputs for Drive Programming), IRDY (inverter ready), FWR (forward operation), RVR (reverse operation), MJA (major failure), WCO (window comparator O), WCOI (window comparator OI), FREF (frequency command source), REF (run command source), SETM (second motor in operation), EDM (STO (safe torque off) performance monitor), OP (option control signal), NO (no function)
	Standard functions	Free-V/f, manual/automatic torque boost, output voltage gain adjustment, AVR function, reduced voltage start, motor data selection, auto-tuning, motor stabilization control, reverse running protection, simple position control, simple torque control, torque limiting, automatic carrier frequency reduction, energy saving operation, PID function, non-stop operation at instantaneous power failure, brake control, DC injection braking, dynamic braking (BRD), frequency upper and lower limiters, jump frequencies, curve accel and decel (S, U, inversed U,EL-S), 16-stage speed profile, fine adjustment of start frequency, accel and decel stop, process jogging, frequency calculation, frequency addition, 2-stage accel/decel, stop mode selection, start/end freq., analog input filter, window comparators, input terminal response time, output signal delay/hold function, rotation direction restriction, stop key selection, software lock, safe stop function, scaling function, display restriction, password function, user parameter, initialization, initial display selection, cooling fan control, warning, trip retry, frequency pull-in restart, frequency matching, overload restriction, over current restriction. DC bus voltage AVR
	Analogue inputs	2 analogue inputs 0 to 10 V (10 K Ω). 4 to 20 mA (100 Ω)
	Pulse train input terminal	0 to 24 V, up to 32 kHz
	Accel/Decel times	0.01 to 3600.0 s (line/curve selection), 2nd accel/decel setting available
		Status indicator LED's Run, Program, Alarm, Power, Hz, Amps
	Display	Digital operator: Available to monitor 32 items: frequency reference, output current, output frequency
	Motor overload protection	Electronic Thermal overload relay and PTC thermistor input
	Instantaneous overcurrent	200% of rated current
functions	Overload	Dual rating: Heavy duty (CT): 150% for 1 minute Normal Duty (VT): 120% for 1 minute
nu	Overvoltage	800 V for 400 V type and 400 V for 200 V type
	Undervoltage	345 V for 400 V type and 172.5 V for 200 V type
Protection	Momentary power loss	Following items are selectable: Alarm, decelerates to stop, decelerates to stop with DC bus controlled, restart
ote	Cooling fin overheat	Temperature monitor and error detection
4	Stall prevention level	Stall prevention during acceleration/deceleration and constant speed
	Ground fault	Detection at power-on
	Power charge indication	On when power is supplied to the control part
S	Degree of protection	IP20
conditions	Ambient humidity	90% RH or less (without condensation)
dit	Storage temperature	-20°C+65°C (short-term temperature during transportation)
S	Ambient temperature	-10°C to 50°C (Both the carrier frequency and output current need to be reduced over 40°C)
	Installation	Indoor (no corrosive gas, dust, etc.)
Ambient	Installation height	Max. 1000 m
Am	-	5.9 m/s ² (0.6G), 10 to 55 Hz
_	Vibration	0.0 H/s (0.00), 10 to 00 H/2

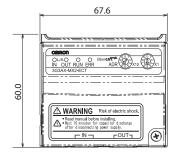
Dimensions

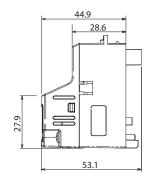
Standard models



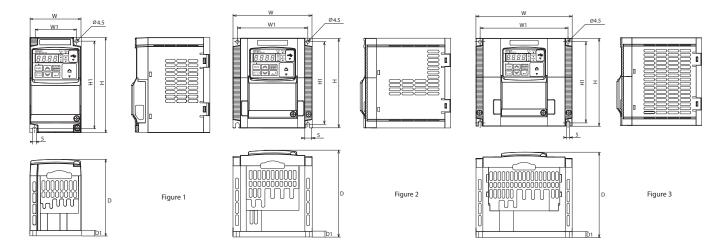
Vallana alaas	Inverter model	F:					Dimens	ions in mi	n			
Voltage class	3G3MX2-A□	Figure	W	W1	Н	H1	t	D	D1	D2	d	Weight (kg)
	B001-E							109	13.5			1.0
	B002-E	1	68	56	128	118		109	13.5	-	-	1.0
Single-phase	B004-E						_	122.5	27			1.1
200 V	B007-E						_					1.4
	B015-E	2	108	96	128	118		170.5	55	4.4	4.5	1.8
	B022-E											1.8
	2001-E							109	13.5			1.0
_	2002-E	1	68	56	128	118				_	_	1.0
_	2004-E		00	30	120	110	_	122.5	27			1.1
_	2007-E							145.5	50			1.2
Three-phase	2015-E	2	108	96	128	118		170.5	55	4.4		1.6
Three-phase 200 V	2022-E	_			_						4.5	1.8
	2037-E	3	140	128	128	118	5	170.5	55	4.4		2.0
_	2055-E		140	122	260	248	6	155	73.3	6	6	3.0
_	2075-E						ŭ	.00		ŭ	ŭ	3.4
_	2110-E		180	160	296	284	7	175	97	5	7	5.1
	2150-E		220	192	350	336			84	ŭ		7.4
_	4004-E							143.5	28			1.5
_	4007-E											1.6
_	4015-E	2	108	96	128	118	-	170.5	55	-	-	1.8
_	4022-E											1.9
Three-phase	4030-E											1.9
400 V	4040-E			128	128	118	5	170.5	55	4.4	4.5	2.1
	4055-E	3	140	122	260	248	6	155	73.3	6	6	3.5
]	4075-E						ŭ		. 0.0	ŭ	Ĭ	3.5
	4110-E		180	160	296	284	7	175	97	5	7	4.7
	4150-E								· ·	Ĭ		5.2

Option board





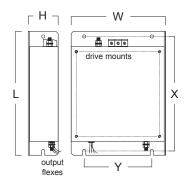
Finless models



	Inverter model				Di	mensions	in mm		
Voltage class	3G3MX2-A□	Figure	W	W1	Н	H1	D	D1	Weight (kg)
	B001-P-E								
	B002-P-E	1	68	56	128	118	103	7.5	1.1
Single-phase	B004-P-E								
200 V	B007-P-E								
	B015-P-E	2	108	96	128	118	123	7.5	1.8
	B022-P-E								
	2001-P-E								
	2002-P-E	1	68	56	128	118	103	7.5	1.1
Three phase	2004-P-E	'	00	50	128	110	103	7.5	1.1
Three-phase 200 V	2007-P-E								
200 V	2015-P-E	2	108	96	128	118	123	7.5	1.8
	2022-P-E	2	100	90	120	110	123	7.5	1.0
	2037-P-E	3	140	128	128	118	123	7.5	2.1
	4004-P-E								
	4007-P-E								
Three-phase	4015-P-E	2	108	96	128	118	123	7.5	1.8
400 V	4022-P-E								
	4030-P-E								
	4040-P-E	3	140	128	128	118	123	7.5	2.1

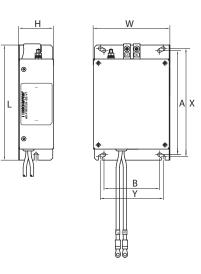
Rasmi footprint filters

D	anni madal			Dimer	nsions		
n:	asmi modei	W	Н	L	Х	Υ	M
	AX-FIM1024-RE AX-FIM2010-RE AX-FIM2020-RE AX-FIM2030-RE AX-FIM2080-RE AX-FIM2080-RE AX-FIM2080-RE AX-FIM2010-RE AX-FIM3005-RE AX-FIM3010-RE	71	45	169	156	51	M4
1x200 V	AX-FIM1014-RE□	111	50	169	156	91	M4
	AX-FIM1024-RE□	111	50	169	156	91	M4
	AX-FIM2010-RE□	82	50	194	181	62	M4
	AX-FIM2020-RE□	111	50	169	156	91	M4
3x200 V	AX-FIM2030-RE□	144	50	174	161	120	M4
3x200 V	AX-FIM2060-RE□	150	52	320	290	122	M5
	AX-FIM2080-RE□	188	62	362	330	160	M5
	AX-FIM2100-RE□	220	62	415	380	192	M6
	AX-FIM3005-RE□	114	46	169	156	91	M4
	AX-FIM3010-RE□	114	46	169	156	91	M4
3x400 V	AX-FIM3014-RE□	144	50	174	161	120	M4
	AX-FIM3030-RE□	150	52	306	290	122	M5
	AX-FIM3050-RE□	182	62	357	330	160	M5



Schaffner footprint filters

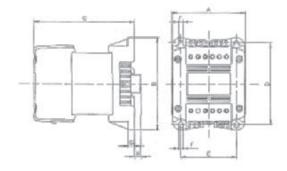
Sch	affner model				Dimer	nsions			
0011	anner moder	W	Н	L	Х	Υ	Α	В	M
	AX-FIM1010-SE□	70	40	166	156	51	150	50	M5
1x200 V	AX-FIM1014-SE□	110	45	166	156	91	150	80	M5
	AX-FIM1024-SE□	110	50	166	156	91	150	80	M5
	AX-FIM2010-SE□	80	40	191	181	62	150	50	M5
	AX-FIM2020-SE□	110	50	166	156	91	150	80	M5
2×200 V	AX-FIM2030-SE□	142	50	171	161	120	150	112	M5
3x200 V	AX-FIM2060-SE□	140	55	304	290	122	286	112	M5
	AX-FIM2080-SE□	180	55	344	330	160	323	140	M5
	AX-FIM2100-SE□	220	65	394	380	192	376	180	M5
	AX-FIM3005-SE□	110	50	166	156	91	150	80	M5
	AX-FIM3010-SE□	110	50	166	156	91	150	80	M5
3x400 V	AX-FIM3014-SE□	142	50	171	161	120	150	112	M5
	AX-FIM3030-SE□	140	55	304	290	122	286	112	M5
	AX-FIM3050-SE□	180	55	344	330	160	323	140	M5



Input AC Reactor

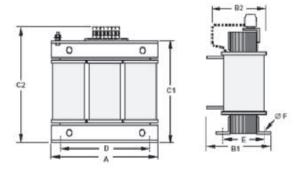
Single-phase

Ī	Voltage	Reference			Weight						
	voitage	neierence	Α	В	С	D	Е	F	G	Н	kg
ĺ		AX-RAI02000070-DE	84	113	96	101	66	5	7.5	2	1.22
	200.17	AX-RAI01700140-DE	84	113	116	101	66	5	7.5	2	1.95
	200 V	AX-RAI01200200-DE	84	113	131	101	66	5	7.5	2	2.55
		AX-RAI00630240-DE	84	113	116	101	66	5	7.5	2	1.95



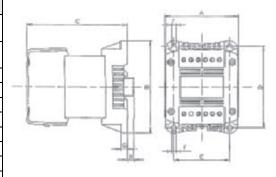
Three-phase

Voltage	Reference			Dimer	nsions			Weight
voltage	neierence	Α	B2	C2	D	Е	F	kg
	AX-RAI02800080-DE	120	70	120	80	52	5.5	1.78
200 V	AX-RAI00880200-DE	120	80	120	80	62	5.5	2.35
200 V	AX-RAI00350335-DE	180	85	190	140	55	6	5.5
	AX-RAI00180670-DE	180	85	190	140	55	6	5.5
	AX-RAI07700050-DE	120	70	120	80	52	5.5	1.78
400 V	AX-RAI03500100-DE	120	80	120	80	62	5.5	2.35
400 V	AX-RAI01300170-DE	120	80	120	80	62	5.5	2.50
	AX-RAI00740335-DE	180	85	190	140	55	6	5.5



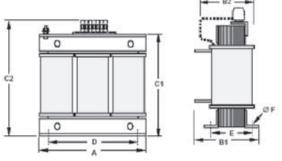
DC Reactor

Voltage	Reference				Dimer	sions				Weight
voilage	neierence	Α	В	С	D	Е	F	G	Н	kg
	AX-RC21400016-DE			96						1.22
	AX-RC10700032-DE			30						1.22
	AX-RC06750061-DE	84	113	105	101	66	5	7.5	2	1.60
	AX-RC03510093-DE			103						1.00
	AX-RC02510138-DE			116						1.95
200 V	AX-RC01600223-DE	108	135	124	120	82	6.5		9.5	3.20
	AX-RC01110309-DE	120	152	136	135	94		9.5		5.20
	AX-RC00840437-DE	120	152	146	133	94	7		· ·	6.00
	AX-RC00590614-DE	150	177	160	160	115	/	2	- '	11.4
	AX-RC00440859-DE	150	177	182.6	100	115		_	· ·	14.3
	AX-RC43000020-DE			96						1.22
	AX-RC27000030-DE	84	113	105	101	66	5	7.5	2	1.60
	AX-RC14000047-DE	04	113	103	101	00	3	7.5	_	1.00
	AX-RC10100069-DE			116						1.95
400 V	AX-RC06400116-DE	108	135	133	120	82	6.5		9.5	3.70
	AX-RC04410167-DE	120	152	136	135	94	7	9.5		5.20
	AX-RC03350219-DE	120	152	146	133	94	/		·	6.00
	AX-RC02330307-DE	150	477	160	100	445	7		- '	11.4
	AX-RC01750430-DE	150	177	183	160	115	7	2		14.3



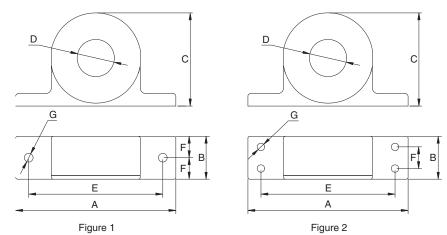
Output AC Reactor

Voltage	Reference			Dimer	nsions			Weight
Voltage	Reference	Α	B2	C2	D	Е	F	kg
	AX-RAO11500026-DE	120	70	120	80	52	5.5	1.78
	AX-RAO07600042-DE	120	70	120	80	52	5.5	1.78
	AX-RAO04100075-DE	120	80	120	80	62	5.5	2.35
	AX-RAO03000105-DE	120	80	120	80	62	5.5	2.35
200 V	AX-RAO01830180-DE	180	85	195	140	55	6	5.5
	AX-RAO01150220-DE	180	85	195	140	55	6	5.5
	AX-RAO00950320-DE	180	85	210	140	55	6	6.5
	AX-RAO00630430-DE	180	95	210	140	65	6	9.1
	AX-RAO00490640-DE	180	105	210	140	75	6	11.7
	AX-RAO16300038-DE	120	80	120	80	62	5.5	2.35
	AX-RAO11800053-DE	120	80	120	80	62	5.5	2.35
	AX-RAO07300080-DE	180	95	195	140	55	6	5.5
400 V	AX-RAO04600110-DE	180	85	195	140	55	6	5.5
	AX-RAO03600160-DE	180	85	210	140	55	6	6.5
	AX-RAO02500220-DE	180	95	210	140	65	6	9.1
	AX-RAO02000320-DE	240	110	275	200	75	6	16.0



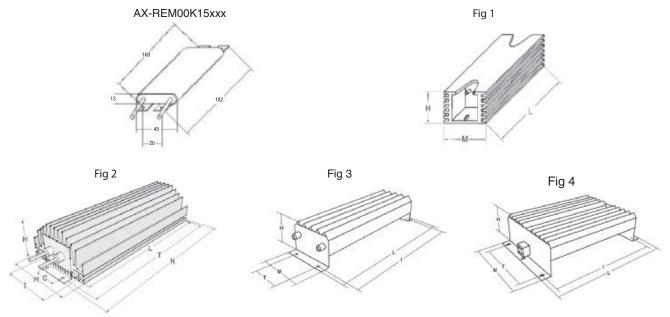
OMRON

Chokes



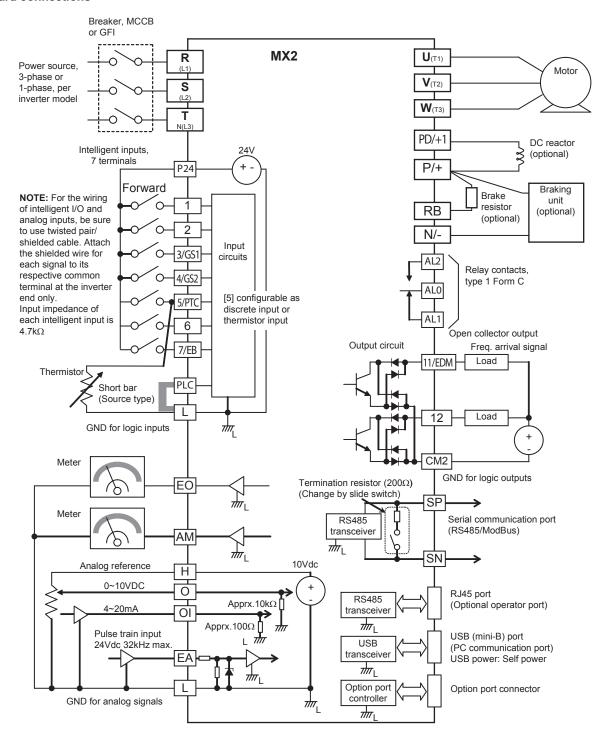
	Dimensions (mm)										
Reference	Fig	(diameter)	Motor (kW)	Α	В	С	D	Е	F	G (diameter)	Weight (kg)
AX-FER2102-PE	1	21	< 2.2	86	24	50	21	70	12	4	0.09
AX-FER2815-PE		28	< 15	106	25	65	28	90	12.5		0.22
AX-FER5045-PE	2	50	< 45	150	51	112	50	125	30	5	0.53

Resistor dimensions



Type	Fig.				Dimensions	;			Weight
Туре	r ig.	L	Н	M	I	T	G	N	kg
AX-REM00K1400-IE									
AX-REM00K2070-IE		105	27	36	94			_	0.2
AX-REM00K2120-IE		105	21	30	94	-	-	-	0.2
AX-REM00K2200-IE									
AX-REM00K4075-IE	4								
AX-REM00K4035-IE	1	200	27	36	189	-	-	-	0.425
AX-REM00K4030-IE									
AX-REM00K5120-IE		260	27	36	249		-	-	0.58
AX-REM00K6100-IE		320	27	36	309		_	_	0.73
AX-REM00K6035-IE		320	21	30	309	1	-	-	0.73
AX-REM00K9070-IE									
AX-REM00K9020-IE	2	200	61	100	74.5	216	40	230	1.41
AX-REM00K9017-IE									
AX-REM01K9070-IE	3	365	73	105	350	70		_	4
AX-REM01K9017-IE	3	303	73	105	330	70	-	-	4
AX-REM02K1070-IE		310	100	240	295	210	_	_	7
AX-REM02K1017-IE	4	310	100	240	295	210	-	-	/
AX-REM03K5035-IE	4	365	100	240	350	210	_		8
AX-REM03K5010-IE		303	100	240	330	210	-	-	0

Standard connections



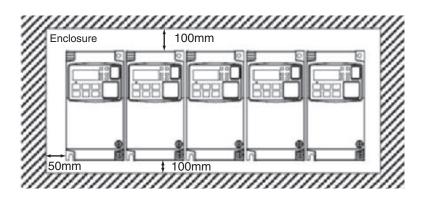
Terminal Block Specifications

Terminal	Name	Function (signal level)
R/L1, S/L2, T/L3	Main circuit power supply input	Used to connect line power to the drive. Drives with single-phase 200 V input power use only terminals R/L1 and N (T/L3), terminal S/L2 is not available for these units
U/T1, V/T2, W/T3	Inverter output	Used to connect the motor
PD/+1, P/+	External DC reactor terminal	Normally connected by the short-circuit bar. Remove the short-circuit bar between +1 and P/+2 when a DC reactor is connected.
P/+, N/-	Regenerative braking unit terminal	Connect optional regenerative braking units (If a braking torque is required)
P/+, RB	Braking resistor terminals	Connect option braking resistor (if a braking torque is required)
⊕	Grounding	For grounding (grounding should conform to the local grounding code.)

Control Circuit

Туре	No.	Signal name	Function	Signal level
	PLC	Intelligent input common	Source type: connecting [P24] to [1]-[7] turns inputs ON Sink type: connecting [L] to [1]-[7] turns inputs ON	-
	P24	Internal 24 VDC	24 VDC, 30mA	24 VDC, 100 mA
	1	Multi-function Input selection 1	Factory setting: Forward/ Stop	
Digital input signals	2	Multi-function Input selection 2	Factory setting: Reverse/ Stop	
ut si	3/GS1	Multi-function Input selection 3 / safe stop input 1	Factory setting: External trip	
di in	4/GS2	Multi-function Input selection 4 / safe stop input 2	Factory setting: Reset	27 VDC max
Digita	5/PTC	Multi-function Input selection 5 / PTC thermistor input	Factory setting: Multi-step speed reference 1	
	6	Multi-function input selection 6	Factory setting: Multi-step speed reference 2	
	7/EB	Multi-function input selection 7 / Pulse train input B	Factory setting: Jog	
	L	Multi-function Input selection common (in upper row)		
se	EA	Pulse train input A	Factory setting: Speed reference	32 kHz max 5 to 24 VDC
Pulse train	EO	Pulse train output	LAD frequency	10 VDC 2 mA 32 kHz max
Ħ	Н	Frequency reference power supply	10 VDC 10 mA max	•
jinpi mal	0	Voltage frequency reference signal	0 to 10 VDC (10 kΩ)	
Analog input signal	OI	Current frequency reference signal	4 to 20 mA (250 Ω)	
Ā	L	Frequency reference common (bottom row)		
	11/EDM	Discrete logic output 1 / EDM output	Factory setting: During Run	27 VDC, 50 mA max
Ħ	12	Discrete logic output 2	Factory setting: Frequency arrival type 1	EDM based on ISO13849-1
Digital output signals	CM2	GND logic output		15013649-1
gital (sign	AL0	Relay common contact	Factory setting: Alarm signal	R load 250 VAC 2.5 A
Ď	AL1	Relay contact, normally open	Under normal operation AL1 - AL0 Closed	30 VDC 3.0 A I load
	AL2	Relay contact, normally closed	AL2 - AL0 Open	250 VAC 0.2 A 30 VDC 0.7 A
Monitor Signal	AM Analog voltage output		Factory setting: LAD frequency	0 to 10 VDC 1 mA
Comms	SP	Serial communication terminal	RS485 Modbus communication	•
Con	SN	Sonal Communication terminal	TO 100 MODELO COMMUNICATION	

Side by side mounting



Inverter heat loss

Single-phase 200 V class

	Model 3G3MX2	AB001	AB002	AB004	AB007	AB015	AB022
I	200V VT	0.4	0.6	1.2	2.0	3.3	4.1
Inverter capacity	200V CT	0.2	0.5	1.0	1.7	2.7	3.8
kVA	240V VT	0.4	0.7	1.4	2.4	3.9	4.9
NVA	240V CT	0.3	0.6	1.2	2.0	3.3	4.5
	Rated current (A) VT	1.2	1.9	3.4	6.0	9.6	12.0
	Rated current (A) CT	1.0	1.6	3.0	5.0	8.0	11.0
	Total heat loss	12	22	30	48	79	104
	Efficiency at rated load	89.5	90	94	95	95.5	
	Cooling Method		Self c	ooling		Forced-a	ir-cooling

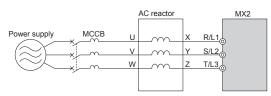
Three-phase 200 V class

	Model 3G3MX2	A2001	A2002	A2004	A2007	A2015	A2022	A2037	A2055	A2075	A2110	A2150
	200 VT	0.4	0.6	1.2	2.0	3.3	4.1	6.7	10.3	13.8	19.3	23.9
Inverter	200 CT	0.2	0.5	1.0	1.7	2.7	3.8	6.0	8.6	11.4	16.2	20.7
kVA	240 VT	0.4	0.7	1.4	2.4	3.9	4.9	8.1	12.4	16.6	23.2	28.6
NVA	240 CT	0.3	0.6	1.2	2.0	3.3	4.5	7.2	10.3	13.7	19.5	24.9
	Rated current (A) VT	1.2	1.9	3.4	6.0	9.6	12.0	19.6	30.0	40.0	56.0	69.0
	Rated current (A) CT	1.0	1.6	3.0	5.0	8.0	11.0	17.5	25.0	33.0	47.0	60.0
	Total heat loss	12	22	30	48	79	104	154	229	313	458	625
	Efficiency at rated load	89.5	90	93	94	95	95.5	96	96	96	96	96
	Cooling Method		Self cooling	olf cooling Forced-air-cooling								

Three-phase 400 V class

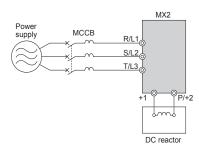
	Model 3G3MX2	A4004	A4007	A4015	A4022	A4030	A4040	A4055	A4075	A4110	A4150
	380V VT	1.3	2.6	3.5	4.5	5.7	7.3	11.5	15.1	20.4	25.0
Inverter	380V CT	1.1	2.2	3.1	3.6	4.7	6.0	9.7	11.8	15.7	20.4
capacity kVA	480V VT	1.7	3.4	4.4	5.7	7.3	9.2	14.5	19.1	25.7	31.5
	480V CT	1.4	2.8	3.9	4.5	5.9	7.6	12.3	14.9	19.9	25.7
	Rated current (A) VT	2.1	4.1	5.4	6.9	8.8	11.1	17.5	23.0	31.0	38.0
	Rated current (A) CT	1.8	3.4	4.8	5.5	7.2	9.2	14.8	18.0	24.0	31.0
	Total heat loss	35	56	96	116	125	167	229	296	411	528
	Efficiency at rated load	92	93	94	95	96	96	96	96.2	96.4	96.6
	Cooling Method Self cooling Forced-air-cooling										

Input AC Reactor



	1 phase 200 V cla	ISS			3 phase 200 V cla	ISS		400 V class					
Max. ap- plicable motor output kW	Reference	Current value A	tance	Max. ap- plicable motor output kW	Reference	Current value A	Induc- tance mH	Max. ap- plicable motor out- put kW	Reference	Current value A	Induc- tance mH		
0.4	AX-RAI02000070-DE	7.0	2.0	1.5	AX-RAI02800080-DE	8.0	2.8	1.5	AX-RAI07700050-DE	5.0	7.7		
0.75	AX-RAI01700140-DE	14.0	1.7	3.7	AX-RAI00880200-DE	20.0	0.88	4.0	AX-RAI03500100-DE	10.0	3.5		
1.5	AX-RAI01200200-DE	20.0	1.2	7.5	AX-RAI00350335-DE	33.5	0.35	7.5	AX-RAI01300170-DE	17.0	1.3		
2.2	AX-RAI00630240-DE	24.0	0.63	15	AX-RAI00180670-DE	67.0	0.18	15	AX-RAI00740335-DE	33.5	0.74		

DC Reactor

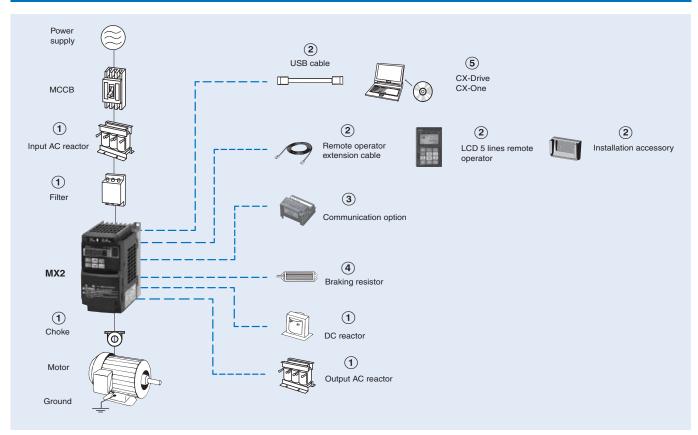


	200 V cla	ass		400 V class						
Max. applicable motor output kW	Reference	Current value A	Inductance mH	Max. applicable motor output kW	Reference	Current value A	Inductance mH			
0.2	AX-RC21400016-DE	1.6	21.4	0.4	AX-RC43000020-DE	2.0	43.0			
0.4	AX-RC10700032-DE	3.2	10.7	0.7	AX-RC27000030-DE	3.0	27.0			
0.7	AX-RC06750061-DE	6.1	6.75	1.5	AX-RC14000047-DE	4.7	14.0			
1.5	AX-RC03510093-DE	9.3	3.51	2.2	AX-RC10100069-DE	6.9	10.1			
2.2	AX-RC02510138-DE	13.8	2.51	3.0 to 4.0	AX-RC06400116-DE	11.6	6.40			
3.7	AX-RC01600223-DE	22.3	1.60	5.5	AX-RC04410167-DE	16.7	4.41			
5.5	AX-RC01110309-DE	30.9	1.11	7.5	AX-RC03350219-DE	21.9	3.35			
7.5	AX-RC00840437-DE	43.7	0.84	11.0	AX-RC02330307-DE	30.7	2.33			
11.0	AX-RC00590614-DE	61.4	0.59	15.0	AX-RC01750430-DE	43.0	1.75			
15.0	AX-RC00440859-DE	85.9	0.44		-					

Output AC Reactor

	200 V cla	SS		400 V class					
Max. applicable motor output kW	Reference	Current value A	Inductance mH	Max. applicable motor output kW	Reference	Current value A	Inductance mH		
0.4	AX-RAO11500026-DE	2.6	11.50						
0.75	AX-RAO07600042-DE	4.2	7.60	1.5	AX-RAO16300038-DE	3.8	16.30		
1.5	AX-RAO04100075-DE	7.5	4.10						
2.2	AX-RAO03000105-DE	10.5	3.00	2.2	AX-RAO11800053-DE	5.3	11.80		
3.7	AX-RAO01830160-DE	16.0	1.83	4.0	AX-RAO07300080-DE	8.0	7.30		
5.5	AX-RAO01150220-DE	22.0	1.15	5.5	AX-RAO04600110-DE	11.0	4.60		
7.5	AX-RAO00950320-DE	32.0	0.95	7.5	AX-RAO03600160-DE	16.0	3.60		
11	AX-RAO00630430-DE	43.0	0.63	11	AX-RAO02500220-DE	22.0	2.50		
15	AX-RAO00490640-DE	64.0	0.49	15	AX-RAO02000320-DE	32.0	2.00		

Ordering information



3G3MX2

		Specifications	Mo	odel			
V. II	Constar	nt torque	Variable	e torque	Observation of	Et al	
Voltage class	Max motor kW	Rated current A	Max motor kW	Rated current A	Standard	Finless	
	0.1	1.0	0.2	1.2	3G3MX2-AB001-E	3G3MX2-AB001-P-E	
	0.2	1.6	0.4	1.9	3G3MX2-AB002-E	3G3MX2-AB002-P-E	
Single-phase	0.4	3.0	0.55	3.5	3G3MX2-AB004-E	3G3MX2-AB004-P-E	
200 V	0.75	5.0	1.1	6.0	3G3MX2-AB007-E	3G3MX2-AB007-P-E	
	1.5	8.0	2.2	9.6	3G3MX2-AB015-E	3G3MX2-AB015-P-E	
	2.2	11.0	3.0	12.0	3G3MX2-AB022-E	3G3MX2-AB022-P-E	
	0.1	1.0	0.2	1.2	3G3MX2-A2001-E	3G3MX2-A2001-P-E	
	0.2	1.6	0.4	1.9	3G3MX2-A2002-E	3G3MX2-A2002-P-E	
	0.4	3.0	0.55	3.5	3G3MX2-A2004-E	3G3MX2-A2004-P-E	
	0.75	5.0	1.1	6.0	3G3MX2-A2007-E	3G3MX2-A2007-P-E	
	1.5	8.0	2.2	9.6	3G3MX2-A2015-E	3G3MX2-A2015-P-E	
Three-phase	2.2	11.0	3.0	12.0	3G3MX2-A2022-E	3G3MX2-A2022-P-E	
200 V	3.7	17.5	5.5	19.6	3G3MX2-A2037-E	3G3MX2-A2037-P-E	
	5.5	25.0	7.5	30.0	3G3MX2-A2055-E	-	
	7.5	33.0	11	40.0	3G3MX2-A2075-E	-	
	11	47.0	15	56.0	3G3MX2-A2110-E	-	
	15	60.0	18.5	69.0	3G3MX2-A2150-E	-	
	0.4	1.8	0.75	2.1	3G3MX2-A4004-E	3G3MX2-A4004-P-E	
	0.75	3.4	1.5	4.1	3G3MX2-A4007-E	3G3MX2-A4007-P-E	
	1.5	4.8	2.2	5.4	3G3MX2-A4015-E	3G3MX2-A4015-P-E	
	2.2	5.5	3.0	6.9	3G3MX2-A4022-E	3G3MX2-A4022-P-E	
Three-phase	3.0	7.2	4.0	8.8	3G3MX2-A4030-E	3G3MX2-A4030-P-E	
400 V	4.0	9.2	5.5	11.1	3G3MX2-A4040-E	3G3MX2-A4040-P-E	
	5.5	14.8	7.5	17.5	3G3MX2-A4055-E	-	
-	7.5	18.0	11	23.0	3G3MX2-A4075-E	-	
	11	24.0	15	31.0	3G3MX2-A4110-E	-	
	15	31.0	18.5	38.0	3G3MX2-A4150-E	-	

1 Line filters

	Investor		Standard	line filter		Low leakage line filter					
	Inverter	Rasm	i	Schaffr	ner	Rasm	i	Schaffi	ner		
Voltage	Model 3G3MX2-□	Reference AX-FIM	Current (A)	Reference AX-FIM	Current (A)	Reference AX-FIM	Current (A)	Reference AX-FIM	Current (A)		
1Phase	AB001 / AB002 / AB004	1010-RE	10	1010-SE-V1	8	1010-RE-LL	10	1010-SE-LL	10		
200 VAC	AB007	1014-RE	14	1014-SE-V1	14	1014-RE-LL	14	1014-SE-LL	14		
	AB015 / AB022	1024-RE	24	1024-SE-V1	27	1024-RE-LL	24	1024-SE-LL	24		
	A2001 / A2002 / A2004 / A2007	2010-RE	10	2010-SE-V1	7.8	2010-RE-LL	10	-	-		
	A2015 / A2022	2020-RE	20	2020-SE-V1	16	2020-RE-LL	20	2020-SE-LL	20		
3Phase 200 VAC	A2037	2030-RE	30	2030-SE-V1	25	2030-RE-LL	30	2030-SE-LL	30		
200 VAC	A2055 / A2075	2060-RE	60	2060-SE-V1	50	2060-RE-LL	60	2060-SE-LL	50		
	A2110	2080-RE	80	2080-SE-V1	70	2080-RE-LL	80	-	-		
	A2150	2100-RE	100	2100-SE-V1	75	2100-RE-LL	100	-	-		
	A4004 / A4007	3005-RE	5	3005-SE-V1	6	3005-RE-LL	5	3005-SE-LL	5		
3Phase	A4015 / A4022 / A4030	3010-RE	10	3010-SE-V1	12	3010-RE-LL	10	3010-SE-LL	10		
400 VAC	A4040	3014-RE	14	3014-SE-V1	15	3014-RE-LL	14	3014-SE-LL	15		
	A4055 / A4075	3030-RE	30	3030-SE-V1	29	3030-RE-LL	30	3030-SE-LL	30		
	A4110 / A4150	3050-RE	50	3050-SE-V1	48	3050-RE-LL	50	3050-SE-LL	50		

1 Input AC reactors

	Inverter	AC Reactor
Voltage	Model 3G3MX2-□	Reference
	AB002 / AB004	AX-RAI02000070-DE
-Phase 200 VAC	AB007	AX-RAI01700140-DE
1-Filase 200 VAC	AB015	AX-RAI01200200-DE
	AB022	AX-RAI00630240-DE
	A2002 / A2004 / A2007	AX-RAI02800080-DE
3-Phase 200 VAC	A2015 / A2022 / A2037	AX-RAI00880200-DE
3-Filase 200 VAC	A2055 / A2075	AX-RAI00350335-DE
	A2110 / A2150	AX-RAI00180670-DE
	A4004 / A4007 / A4015	AX-RAI07700050-DE
3-Phase 400 VAC	A4022 / A4030 / A4040	AX-RAI03500100-DE
3-Filase 400 VAC	A4055 / A4075	AX-RAI01300170-DE
	A4110 / A4150	AX-RAI00740335-DE

① DC reactors

200V	1-phase	200V	3-phase	400V 3-phase		
Inverter	DC Reactor	Inverter DC Reactor		Inverter	DC Reactor	
3G3MX2-AB001	AX-RC10700032-DE	3G3MX2-A2001	AX-RC21400016-DE	3G3MX2-A4004 AX-RC4300002		
3G3MX2-AB002	AX-NC10700032-DE	3G3MX2-A2002	AX-NO21400010-DE	3G3MX2-A4007	AX-RC27000030-DE	
3G3MX2-AB004	AX-RC06750061-DE	3G3MX2-A2004	AX-RC10700032-DE	3G3MX2-A4015	AX-RC14000047-DE	
3G3MX2-AB007	AX-RC03510093-DE	3G3MX2-A2007	AX-RC06750061-DE	3G3MX2-A4022	AX-RC10100069-DE	
3G3MX2-AB015	AX-RC02510138-DE	3G3MX2-A2015	AX-RC03510093-DE	3G3MX2-A4030 / A4040	AX-RC06400116-DE	
3G3MX2-AB022	AX-RC01600223-DE	3G3MX2-A2022	AX-RC02510138-DE	3G3MX2-A4055	AX-RC04410167-DE	
		3G3MX2-A2037	AX-RC01600223-DE	3G3MX2-A4075	AX-RC03350219-DE	
		3G3MX2-A2055	AX-RC01110309-DE	3G3MX2-A4110	AX-RC02330307-DE	
-		3G3MX2-A2075	AX-RC00840437-DE	3G3MX2-A4150 AX-RC017504		
		3G3MX2-A2110	AX-RC00590614-DE	E		
		3G3MX2-A2150	AX-RC00440859-DE			

1 Chokes

ı	Model Diameter		Description
	AX-FER2102-PE	21	For 2.2 KW motors or below
	AX-FER2815-PE	28	For 15 KW motors or below
	AX-FER5045-PE	50	For 45 KW motors or below

1 Output AC reactor

	AC Reactor		
Voltage Model 3G3MX2-□		Reference	
	AB001 / AB002 / AB004 A2001 / A2002 / A2004	AX-RAO11500026-DE	
	AB007 / A2007	AX-RAO07600042-DE	
	AB015 / A2015	AX-RAO04100075-DE	
2221/12	AB022 / A2022	AX-RAO03000105-DE	
200 VAC	A2037	AX-RAO01830160-DE	
	A2055	AX-RAO01150220-DE	
	A2075	AX-RAO00950320-DE	
	A2110	AX-RAO00630430-DE	
	A2150	AX-RAO00490640-DE	
	A4004 / A4007 / A4015	AX-RAO16300038-DE	
	A4022	AX-RAO11800053-DE	
	A4030 / A4040	AX-RAO07300080-DE	
400 VAC	A4055	AX-RAO04600110-DE	
	A4075	AX-RAO03600160-DE	
	A4110	AX-RAO02500220-DE	
	A4150	AX-RAO02000320-DE	

2 Accessories

Types	Model	Description	Functions		
	AX-OP05-E	LCD remote operator	5 Line LCD remote operator with copy function, cable length max. 3m.		
a to	3G3AX-CAJOP300-EE	Remote operator cable	3 meters cable for connecting remote operator		
Digital operator	3G3AX-OP01	LED remote operator	LED remote operator, cable length max. 3m		
οğ	4X-KITMINI	Mounting kit for LED operator	Mounting kit for LED operator on panel		
	3G3AX-OP05-H-E	Operator holder	Holder to put the AX-OP05-E inside of the cabinet		
Accessories	AX-CUSBM002-E	PC configuration cable	Mini USB to USB connector cable		

③ Communication option boards

Types	Model	Description	Functions			
	3G3AX-MX2-PRT	Profibus option card				
options	3G3AX-MX2-DRT DeviceNet option card					
	3G3AX-MX2-ECT	EtherCAT option card	Used for running or stopping the inverter, setting or referencing parameters, and monitorin output frequency, output current, or similar items through communications with the host co			
munica	3G3AX-MX2-ECT EtherCAT option 3G3AX-MX2-CRT CompoNet option 3G3AX-MX2-MRT MECHATROLINK-II of		troller.			
Comr	3G3AX-MX2-MRT	MECHATROLINK-II option card				
	3G3AX-MX2-EIP	EtherNet/IP option card				
I/O option	3G3AX-MX2-EIO15-E	Extra input/output option board	1 analog voltage input, 1 analog current input, 1 analog voltage output, 8 discrete logic inputs, 4 discrete logic outputs			

OMRON

4 Braking unit, braking resistor unit

		Inverte	r		Braking resistor unit					
Voltage	Max. motor kW	Inverter 3G3MX2□		Connectable min.	Inverter mounted type (3 %ED, 10 sec max)		Braking	Inverter mounted type (10%ED, 10 sec max)		Braking
· ·		1-phase	3-phase	resistance Ω	Type AX-	Resist Ω	torque %	Type AX-	Resist Ω	torque %
	0.12	B001	2001	100	REM00K1400-IE	400	200 BE	REM00K1400-IE	400	200
	0.25	B002	2002			400	180	TILINIOOIT 1400-IL		180
	0.55	B004	2004		REM00K1200-IE	200	180	REM00K1200-IE	200	180
	1.1	B007	2007	50	HEIWOOK 1200-IE	200	100	REM00K2070-IE	70	200
200 V	1.5	B015	2015	50	REM00K2070-IE	REM00K2070-IE 70	140	REM00K4075-IE	75	130
(Single-/ Three-	2.2	B022	2022	35	HEIVIOURZU/U-IE	70	90	REM00K4035-IE	35	180
phase)	4.0	-	2040		REM00K4075-IE	75	50	REM00K6035-IE	35	100
	5.5	-	2055	20	REM00K4035-IE 35	75	REM00K9020-IE	20	150	
	7.5	-	2075	17		33	55	REM01K9017-IE	17	110
	11	-	2110		REM00K6035-IE	35	40	REM02K1017-IE	17	75
	15	-	2150	10	REM00K9017-IE	17	55	REM03K5010-IE	10	95
	0.55	-	4004		REM00K1400-IE 400	200	REM00K1400-IE	400	200	
	1.1	-	4007	180	HEMOOK 1400-IE	400	200	HEIWOOK 1400-IE	400	200
	1.5	-	4015		REM00K1200-IE	200	190	REM00K2200-IE	200	190
	2.2	-	4022		REM00K2200-IE	200	130	REM00K5120-IE	120	200
400 V (Three-	3.0	-	4030	100	REM00K2120-IE 120	160	HEIWIOOKS 120-1E	120	160	
phase)	4.0	-	4040			120	120	REM00K6100-IE	100	140
	5.5	-	4055	70	REM00K4075-IE	75	140	REM00K9070-IE	70	150
	7.5	-	4075				100	REM01K9070-IE	70	110
	11	-	4110		REM00K6100-IE	100	50	REM02K1070-IE	70	75
	15	-	4150	35	REM00K9070-IE	70	55	REM03K5035-IE	35	110

5 Computer software

Types	Model	Description	Installation
Φ	CX-Drive	Computer software	Configuration and monitoring software tool
Software	CX-One	Computer software	Configuration and monitoring software tool
S	€Saver	Computer software	Software tool for Energy Saving calculation

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Cat. No. I113E-EN-06B

In the interest of product improvement, specifications are subject to change without notice.