



递推线性最小均方估计

基于矢量空间的
递推线性最小均方估计
算法推导

问题引入

基于矢量空间的推导

推导过程的几何演示

拓展：正交投影性质的补充

推导过程总结



1. 问题引入

考虑高斯白噪声中随机变量的估计问题,

$$z_i = A + w_i \quad i = 0, 1, \dots, N-1$$

其中 w_i 是均值为零、方差为 σ^2 的高斯白声, $A \sim N(0, \sigma_A^2)$,
且 w_i 与 A 统计独立。

根据 N 个观测得到的 A 的估计与均方误差为

$$\hat{A}[N-1] = \frac{\sigma_A^2}{\sigma_A^2 + \frac{\sigma^2}{N}} \bar{z} \quad Mse(\hat{A}[N-1]) = \frac{\sigma_A^2 \sigma^2}{N \sigma_A^2 + \sigma^2}$$



1. 问题引入

经过简单数学推导，可得

$$\hat{A}[N] = \hat{A}[N-1] + K[N](z_N - \hat{A}[N-1])$$

$$K[N] = \frac{Mse(\hat{A}[N-1])}{Mse(\hat{A}[N-1]) + \sigma^2}$$

$$Mse(\hat{A}[N]) = (1 - K[N])Mse(\hat{A}[N-1])$$

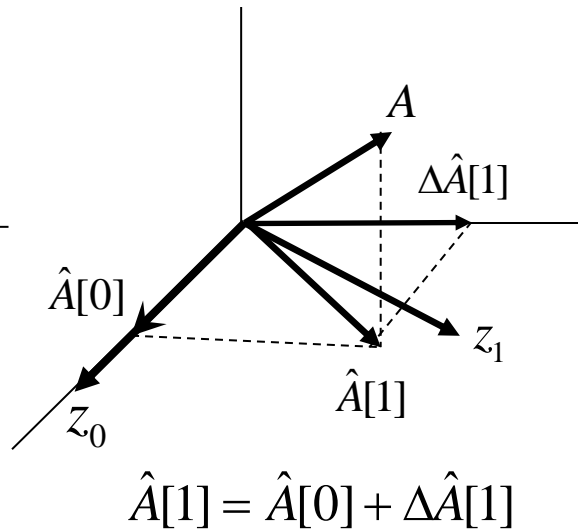
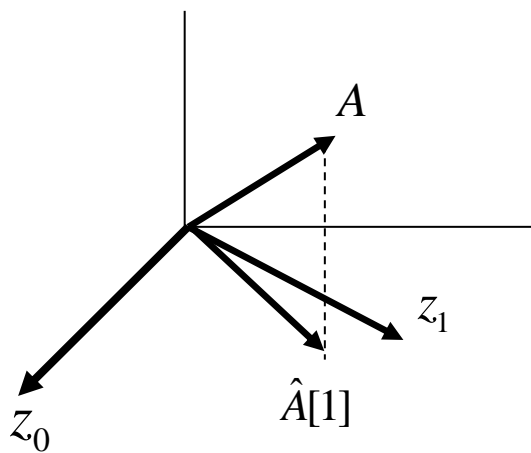
教材上有详细的推导



2. 随机矢量空间的方法推导递推算算法

假定 $\hat{A}[1]$ 是基于前两个观测数据 z_0, z_1 估计,

$\hat{A}[1]$ 可以看作是 $\hat{A}[0]$ 及一个与 $\hat{A}[0]$ 正交的矢量和。



$$\begin{aligned}\hat{A}[0] &= \hat{E}(A | z_0) \\ &= \left(A, \frac{z_0}{\|z_0\|} \right) \frac{z_0}{\|z_0\|} \\ &= \frac{E(Az_0)}{E(z_0^2)} z_0 \\ &= \frac{E[A(A + w_0)]}{E(A^2) + E(w_0^2)} z_0 \\ &= \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0\end{aligned}$$



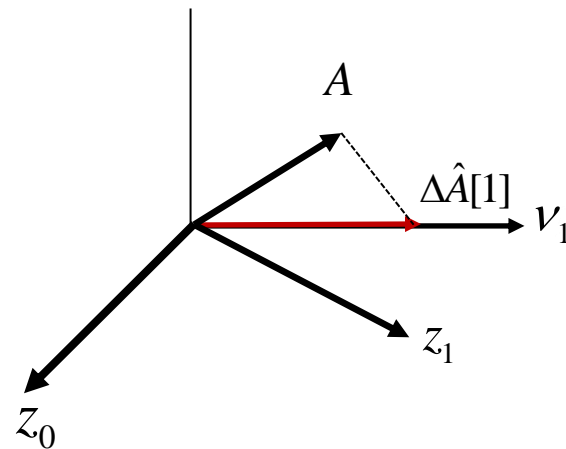
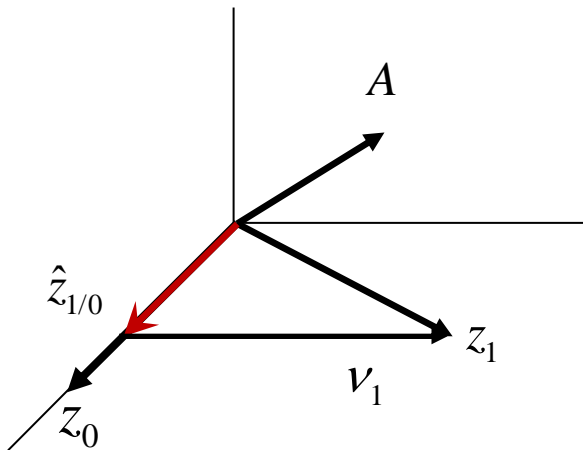
2. 随机矢量空间的方法推导递推算法

如何求得 $\Delta\hat{A}[1]$?

(1) 根据 z_0 求 z_1 的估计 $\hat{z}_{1/0}$ ，得到的误差矢量 $v_1 = z_1 - \hat{z}_{1/0}$ 与 z_0 正交。

$$\hat{z}_{1/0} = \hat{E}(z_1 | z_0)$$

(2) 将A投影到 $v_1 = z_1 - \hat{z}_{1/0}$ 上



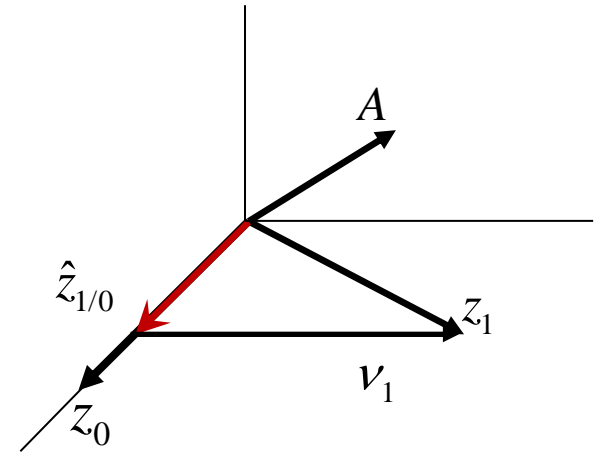


2. 随机矢量空间的方法推导递推算算法

$$\begin{aligned}\hat{z}_{1/0} &= \left(z_1, \frac{z_0}{\|z_0\|} \right) \frac{z_0}{\|z_0\|} \\ &= \frac{(z_1, z_0)}{\|z_0\|^2} z_0 = \frac{E(z_1 z_0)}{E(z_0^2)} z_0\end{aligned}$$

$$\begin{aligned}\hat{z}_{1/0} &= \frac{E[(A + w_1)(A + w_0)]}{E(A^2) + E(w_0^2)} z_0 \\ &= \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0\end{aligned}$$

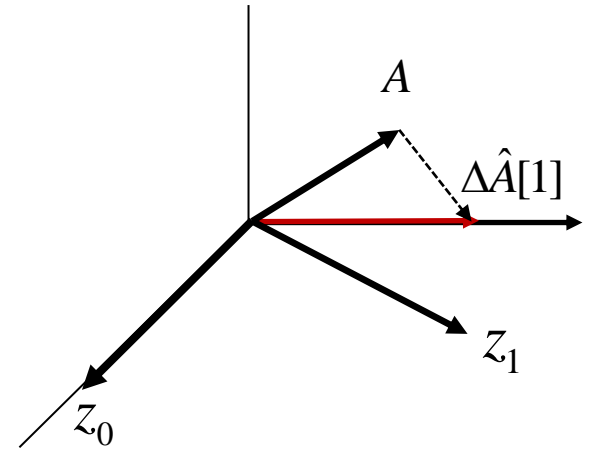
$$v_1 = z_1 - \hat{z}_{1/0} = z_1 - \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0$$





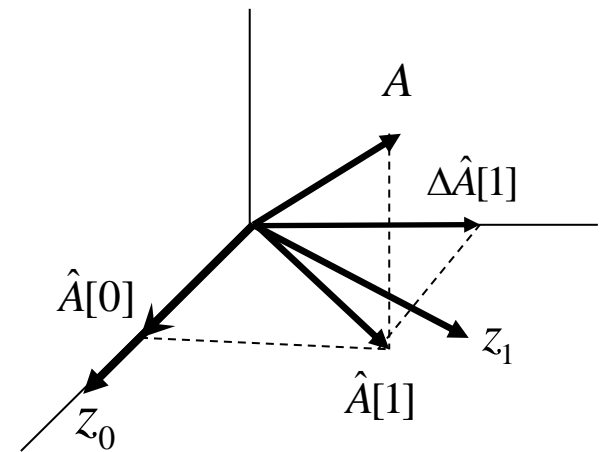
2. 随机矢量空间的方法推导递推算法

$$\begin{aligned}\Delta\hat{A}[1] &= \left(A, \frac{v_1}{\|v_1\|} \right) \frac{v_1}{\|v_1\|} \\ &= \frac{(A, v_1)}{\|v_1\|^2} v_1 = \frac{E(Av_1)}{E(v_1^2)} v_1\end{aligned}$$



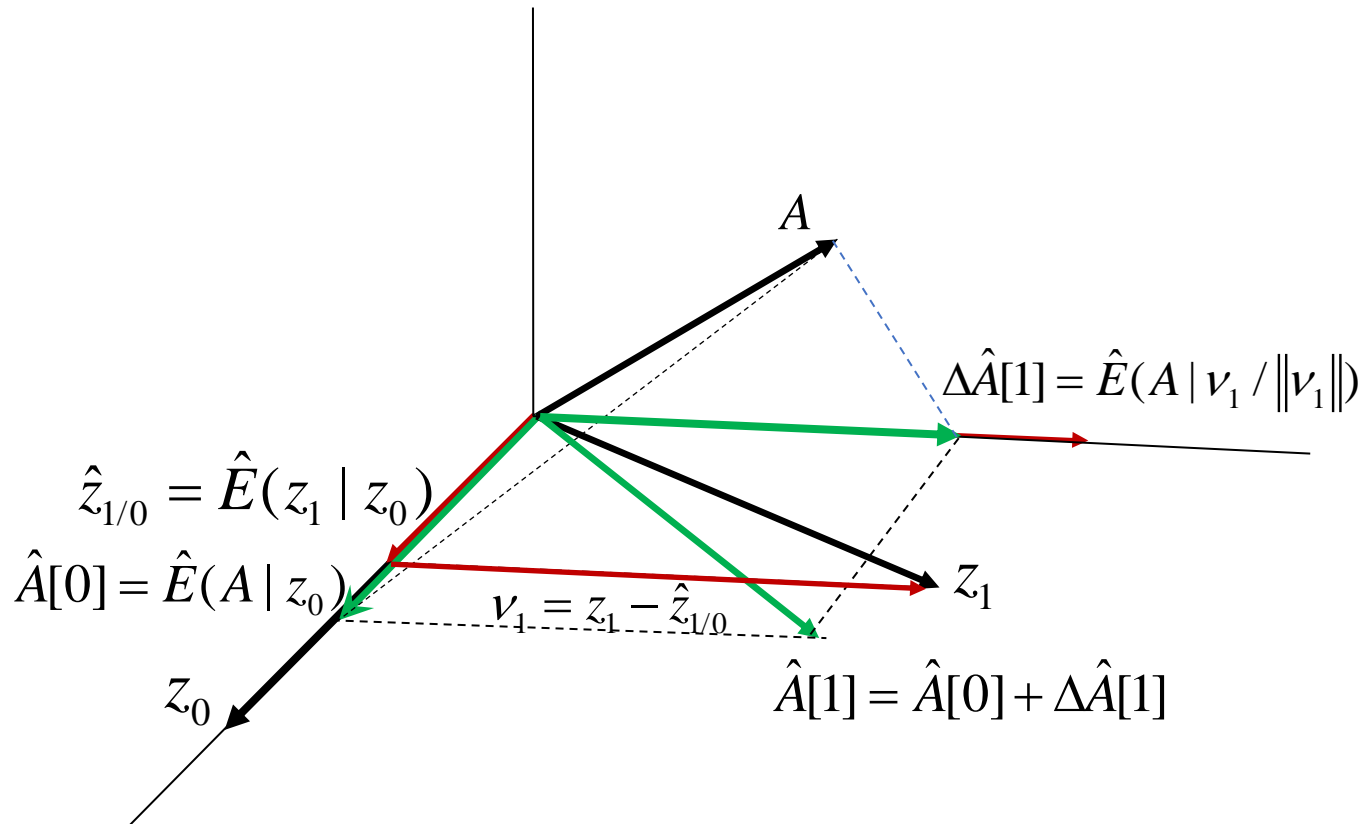
$$\hat{A}[1] = \hat{A}[0] + \frac{E(Av_1)}{E(v_1^2)} v_1 = \hat{A}[0] + K[1](z_1 - \hat{z}_{1/0})$$

$$K[1] = \frac{E(Av_1)}{E(v_1^2)} = \frac{E\left[A\left(z_1 - \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0\right)\right]}{E\left[\left(z_1 - \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0\right)^2\right]} = \frac{\sigma_A^2}{2\sigma_A^2 + \sigma^2}$$





3. 推导过程的几何解释

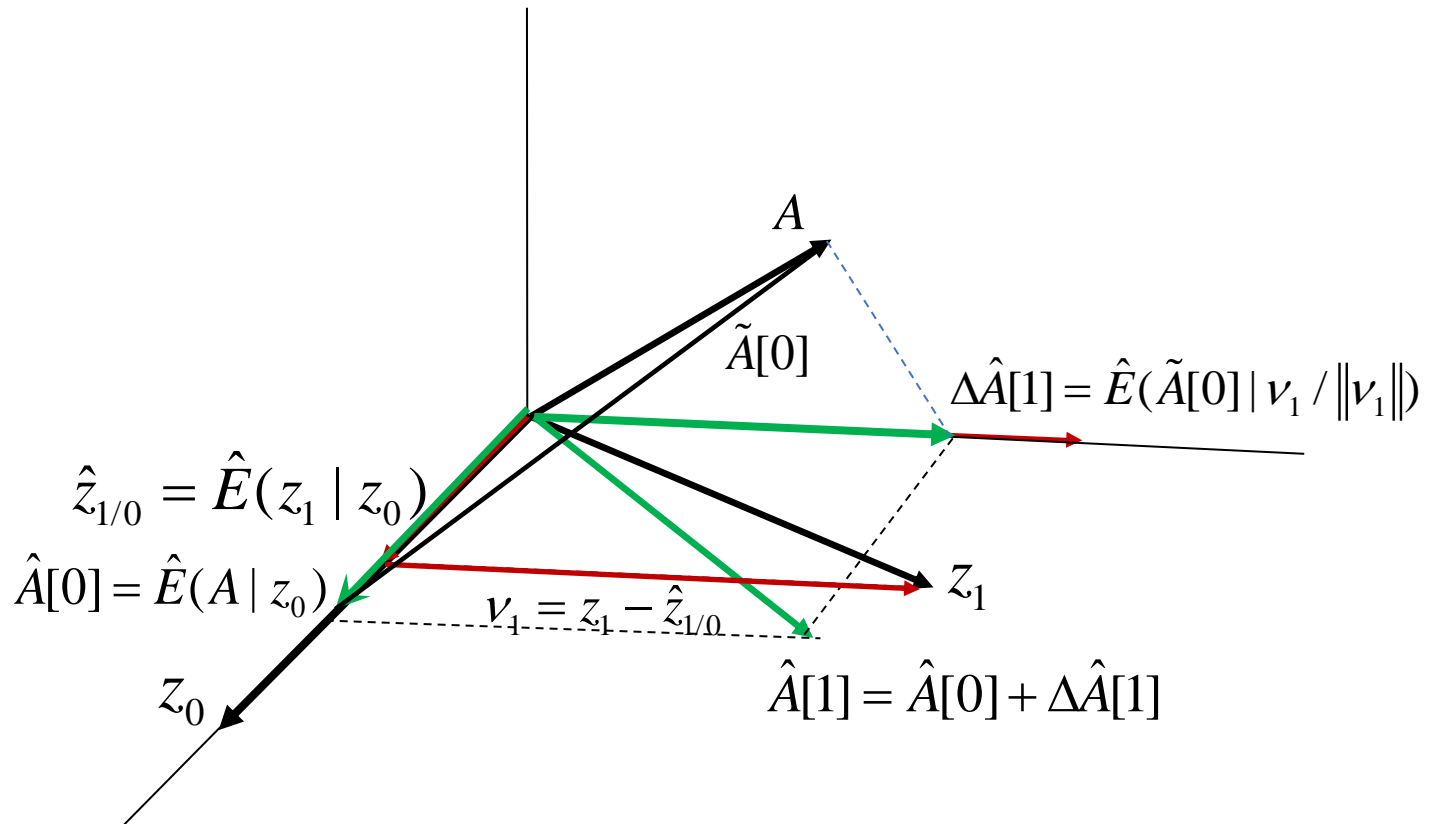




另一种形式

$$\Delta \hat{A}[1] = \hat{E}(A | \nu_1 / \|\nu_1\|) = \hat{E}[(A - \hat{A}[0]) | \nu_1 / \|\nu_1\|] = \hat{E}(\tilde{A}[0] | \nu_1 / \|\nu_1\|)$$

$$\hat{E}[\hat{A}[0] | \nu_1 / \|\nu_1\|] = \frac{E(\hat{A}[0] \nu_1) \nu_1}{\|\nu_1\|^2} = 0$$





4. 拓展：正交投影的性质 (6)

$$(6) \text{ 设 } \mathbf{z}^k = \begin{bmatrix} \mathbf{z}^{k-1} \\ \mathbf{z}_k \end{bmatrix} = [\mathbf{z}_0 \quad \mathbf{z}_1 \quad \dots \quad \mathbf{z}_k]^T$$

$$\begin{aligned} \hat{E}(\boldsymbol{\theta} | \mathbf{z}^k) &= \hat{E}(\boldsymbol{\theta} | \mathbf{z}^{k-1}) + \hat{E}(\tilde{\boldsymbol{\theta}}[k-1] | \mathbf{v}[k]) \\ &= \hat{E}(\boldsymbol{\theta} | \mathbf{z}^{k-1}) + E(\tilde{\boldsymbol{\theta}}[k-1] \mathbf{v}^T[k]) \{E(\mathbf{v}[k] \mathbf{v}^T[k])\}^{-1} \mathbf{v}[k] \end{aligned}$$

$$\text{其中 } \tilde{\boldsymbol{\theta}}[k-1] = \boldsymbol{\theta} - \hat{E}(\boldsymbol{\theta} | \mathbf{z}^{k-1})$$

$$\mathbf{v}[k] = \mathbf{z}_k - \hat{E}(\mathbf{z}_k | \mathbf{z}^{k-1})$$



称为新息(Innovation)



5. 推导过程总结

$$\hat{A}[1] = \hat{A}[0] + \Delta\hat{A}[1]$$

$$\hat{A}[0] = \frac{E(Az_0)}{E(z_0^2)} z_0 = \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0$$

$$\hat{z}_{1/0} = \frac{E(z_1 z_0)}{E(z_0^2)} z_0 = \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0$$

$$v_1 = z_1 - \hat{z}_{1/0}$$

$$\Delta\hat{A}[1] = \frac{E(Av_1)}{E(v_1^2)} v_1$$

或

$$\Delta\hat{A}[1] = \frac{E(\tilde{A}[0]v_1)}{E(v_1^2)} v_1$$

$$K[1] = \frac{E(Av_1)}{E(v_1^2)} = \frac{E(\tilde{A}[0]v_1)}{E(v_1^2)} = \frac{\sigma_A^2}{2\sigma_A^2 + \sigma^2}$$

$$\hat{A}[1] = \hat{A}[0] + K[1](z_1 - \hat{z}_{1/0})$$

按这个过程继续求 $\hat{A}[2]$

$$\hat{A}[2] = \hat{A}[1] + K[2](z_2 - \hat{z}_{2/1})$$



5. 推导过程总结

在这个过程中，我们获得一组相互正交的数据

$$z_0, z_1 - \hat{z}_{1/0}, z_2 - \hat{z}_{2/1}, \dots$$

$$v_0, v_1, v_2, \dots$$

根据LMMSE对于正交数据的相加性原理，

$$\hat{A}[N] = \sum_{i=0}^N \left(A, \frac{v_i}{\|v_i\|} \right) \frac{v_i}{\|v_i\|} = \sum_{i=0}^N \frac{(A, v_i)}{\|v_i\|^2} v_i = \sum_{i=0}^N \frac{E(Av_i)}{E(v_i^2)} v_i = \sum_{i=0}^N K[i] v_i$$

$$\hat{A}[N] = \sum_{i=0}^{N-1} K[i] v_i + K[N] v_N = \hat{A}[N-1] + K[N] (z_N - \hat{z}_{N/N-1})$$

$$K[N] = \frac{E[A(z_N - \hat{z}_{N/N-1})]}{E[(z_N - \hat{z}_{N/N-1})^2]} = \frac{E[\tilde{A}[N-1](z_N - \hat{z}_{N/N-1})]}{E[(z_N - \hat{z}_{N/N-1})^2]}$$



5. 推导过程总结

$$\hat{z}_{N/N-1} = \hat{E}((A + w_N) | z_0, \dots, z_{N-1}) = \hat{A}[N-1] + \hat{w}_{N/N-1} = \hat{A}[N-1]$$

$$z_N - \hat{z}_{N/N-1} = A + w_N - \hat{A}[N-1] = \tilde{A}[N-1] + w_N$$

$$E[(z_N - \hat{z}_{N/N-1})^2] = Mse(\hat{A}[N-1]) + \sigma^2$$

$$E[\tilde{A}[N-1](z_N - \hat{z}_{N/N-1})] = E\{\tilde{A}[N-1](\tilde{A}[N-1] + w_N)\}$$



$$Mse(\hat{A}[N-1])$$



5. 推导过程总结

$$K[N] = \frac{E[\tilde{A}[N-1](z_N - \hat{z}_{N/N-1})]}{E[(z_N - \hat{z}_{N/N-1})^2]} = \frac{Mse(\hat{A}[N-1])}{Mse(\hat{A}[N-1]) + \sigma^2}$$

The diagram shows a red dashed box around the term $(z_N - \hat{z}_{N/N-1})$ in the numerator and denominator. A red dashed line connects the top-right corner of the box in the denominator to the $\tilde{A}[N-1]$ term in the numerator, illustrating the substitution of the error term with the prediction error.

接下来讨论 $Mse(\hat{A}[N])$ 的计算：

$$\begin{aligned} A - \hat{A}[N] &= A - \hat{A}[N-1] - K[N](z_N - \hat{z}_{N/N-1}) \\ &= A - \hat{A}[N-1] - K[N](\tilde{A}[N-1] + w_N) \\ &= (1 - K[N])\tilde{A}[N-1] - K[N]w_N \end{aligned}$$

即
$$\tilde{A}[N] = (1 - K[N])\tilde{A}[N-1] - K[N]w_N$$



5. 推导过程总结

$$\tilde{A}[N] = (1 - K(N))\tilde{A}[N-1] - K[N]w_N$$

$$\begin{aligned} Mse(\hat{A}[N]) &= E \left\{ \left[(1 - K(N))\tilde{A}[N-1] - K[N]w_N \right]^2 \right\} \\ &= (1 - K(N))^2 Mse(\hat{A}[N-1]) + K^2[N]\sigma^2 \\ &= (1 - 2K(N))Mse(\hat{A}[N-1]) + K^2(N)Mse(\hat{A}[N-1]) + K^2[N]\sigma^2 \\ &= (1 - 2K(N))Mse(\hat{A}[N-1]) + K^2(N) \underbrace{\left\{ Mse(\hat{A}[N-1]) + \sigma^2 \right\}}_{K[N]Mse(\hat{A}[N-1])} \end{aligned}$$

$$Mse(\hat{A}[N]) = (1 - K[N])Mse(\hat{A}[N-1])$$

$$K[N] = \frac{Mse(\hat{A}[N-1])}{Mse(\hat{A}[N-1]) + \sigma^2}$$



5. 推导过程总结

估计器更新: $\hat{A}[N] = \hat{A}[N-1] + K[N](z_N - \hat{z}_{N/N-1})$

$$\hat{z}_{N/N-1} = \hat{A}[N-1]$$

增益计算: $K[N] = \frac{Mse(\hat{A}[N-1])}{Mse(\hat{A}[N-1]) + \sigma^2}$

均方误差更新: $Mse(\hat{A}[N]) = (1 - K[N])Mse(\hat{A}[N-1])$

起始条件: $\hat{A}[0] = \frac{E(Az_0)}{E(z_0^2)} z_0 = \frac{\sigma_A^2}{\sigma_A^2 + \sigma^2} z_0$

$$Mse(\hat{A}[0]) = \frac{\sigma_A^2 \sigma^2}{\sigma_A^2 + \sigma^2}$$