

# KDL库安装

KDL库安装：

```
1  #选择一个库保存路径，执行
2  git clone https://github.com/orocos/orocos_kinematics_dynamics.git
3  进入orocos_kdl目录
4  mkdir build
5  cd build
6  cmake ..
7  make
8  sudo make install
9  #完成安装
10
11
12  #选择一个库保存路径，执行
13  git clone https://github.com/ros/kdl_parser.git
14  #进入kdl_parser目录：
15  #20.04 切换分支为noetic
16  mkdir build
17  cd build
18  cmake ..
19  make
20  #编译完成后
21  sudo make install
22  #完成安装
23
24
25
26  export LD_LIBRARY_PATH=/usr/local/lib:$LD_LIBRARY_PATH
27
28  echo 'export LD_LIBRARY_PATH=/usr/local/lib:$LD_LIBRARY_PATH' >> ~/.bashrc
29  source ~/.bashrc
30  echo 'export LD_LIBRARY_PATH=/usr/local/lib:$LD_LIBRARY_PATH' >> ~/.zshrc
31  source ~/.bashrc
32
33  sudo ldconfig
34
```