

Let $Ax = b$ be a system of linear equation, where A is an $m \times n$ matrix, x is a $n \times 1$ matrix and b is a $m \times 1$ matrix. Let A has a right inverse B , that is so that $AB = I_m$, then $x = Bb$ is a solution of the system $Ax = b$.

For example:

$$Ax = ABb = I_m b = b$$

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In particular, if A is invertible square matrix, then it has only inverse A^{-1} , and $x = A^{-1}b$ is the only solution of the system.

Defn: An elementary matrix is a matrix obtained from the identity matrix I_n by executing only one elementary row operation.

Example:

(1) $\begin{bmatrix} 1 & 0 \\ 0 & -5 \end{bmatrix}$ (2) $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$

(3) $\begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Intrestingly, If E is an elementary matrix obtained by executing a certain elementary row operation on the identity matrix I_m , then for any $m \times n$ matrix, A the product EA is exactly the matrix that is obtained when the same elementary row operation in E is executed on A .

Illustration:

Let $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ be a 3×1 column matrix.

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \rightarrow -2R_1 + R_2} E = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$Eb = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 - 2b_1 \\ b_3 \end{bmatrix}$$

$$E = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} b_3 \\ b_2 \\ b_1 \end{bmatrix}$$

Example:

$$E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}, E_3 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{bmatrix}, E_2^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}, E_3^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

So, Each elementary matrix is invertible.

Theorem: For a square matrix A of order ' n ', the following statements are equivalent:

- (1) A is invertible.
- (2) A has rank n .
- (3) A is row-equivalent to identity matrix.
- (4) A is product of elementary matrix.

Theorem: The following statements are equivalent for a square matrix A of order ' n '.

- (1) A is invertible.
- (2) $Ax=0$ has only trivial solution
- (3) $Ax=b$ has a solution x for every b .

Method of finding A^{-1}

Let $Ax = b$ be a system of linear equations.

Here, A is a square matrix.

Further, assume that A is invertible.

Since: by previous theorem A is now equivalent to the identity matrix.

So, there are k elementary matrices, say

$E_k, E_{k-1}, \dots, E_2, E_1$ such that

$$E_k E_{k-1} \dots E_2 E_1 A = I.$$

We also know that $x = A^{-1}b$ is the unique solution of the system $Ax = b$.

So $Ax = b$

$$Ax = Ib$$

$$\frac{E_k E_{k-1} \dots E_2 E_1 A}{I} x = \frac{E_k \dots E_1 I}{A^{-1}} b$$

$$\underline{\underline{x = A^{-1}b}}$$

This process is called Gauss-Jordan method to compute inverse of a matrix.

Example: Compute A^{-1} by Gauss-Jordan method.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 5 \\ 1 & 0 & 2 \end{bmatrix}$$

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 3 & 5 & 0 & 1 & 0 \\ 1 & 0 & 2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - R_1}}$$

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & -2 & -1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_2}$$

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & 3 & -2 & 1 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 + 2R_2} \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & -3 & 2 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & 3 & -2 & 1 \end{array} \right]$$

$$\begin{array}{l} R_1 \rightarrow R_1 - R_3 \\ R_2 \rightarrow R_2 + R_3 \end{array} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 6 & 4 & -1 \\ 0 & -1 & 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & 3 & -2 & 1 \end{array} \right] \xrightarrow{R_2 \rightarrow (-1)R_2}$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 6 & 4 & -1 \\ 0 & 1 & 0 & -1 & 1 & -1 \\ 0 & 0 & 1 & 3 & -2 & 1 \end{array} \right] \quad \text{So, } A^{-1} = \underline{\underline{\begin{bmatrix} 6 & 4 & -1 \\ -1 & 1 & -1 \\ 3 & -2 & 1 \end{bmatrix}}}$$

Example: Write the system linear equations

$$x + 2y + 2z = 10$$

$$2x - 2y + 3z = 1$$

$$4x - 3y + 5z = 4$$

in matrix form $Ax = b$ and solve it by finding A^{-1} .

$$\begin{bmatrix} 1 & 2 & 2 \\ 2 & -2 & 3 \\ 4 & -3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 10 \\ 1 \\ 4 \end{bmatrix}$$

A^{-1}

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 2 & -2 & 3 & 0 & 1 & 0 \\ 4 & -3 & 5 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 4R_1}} \left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & -6 & -1 & -2 & 1 & 0 \\ 0 & -11 & -3 & -4 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{R_3 \rightarrow R_3 + \frac{-11}{6}R_2} \left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & -6 & -1 & -2 & 1 & 0 \\ 0 & 0 & -\frac{2}{6} & -\frac{2}{6} & -\frac{11}{6} & 1 \end{array} \right] \xrightarrow{R_2 \rightarrow -\frac{1}{6}R_2}$$

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & 1 & \frac{1}{6} & \frac{2}{6} & -\frac{1}{6} & 0 \\ 0 & 0 & -\frac{2}{6} & -\frac{2}{6} & -\frac{11}{6} & 1 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - 2R_2} \left[\begin{array}{ccc|ccc} 1 & 0 & \frac{5}{3} & \frac{2}{6} & \frac{2}{6} & 0 \\ 0 & 1 & \frac{1}{6} & \frac{2}{6} & -\frac{1}{6} & 0 \\ 0 & 0 & -\frac{2}{6} & -\frac{2}{6} & -\frac{11}{6} & 1 \end{array} \right]$$

$$\xrightarrow{R_2 \rightarrow R_2 + \frac{1}{6}R_3} \xrightarrow{R_3 \rightarrow -\frac{6}{2}R_3} \left[\begin{array}{ccc|ccc} 1 & 0 & \frac{5}{3} & \frac{2}{6} & \frac{2}{6} & 0 \\ 0 & 1 & \frac{1}{6} & \frac{2}{6} & -\frac{1}{6} & 0 \\ 0 & 0 & 1 & \frac{2}{2} & \frac{11}{2} & -\frac{6}{2} \end{array} \right]$$

$$R_2 \rightarrow R_2 - \frac{1}{6}R_3$$

$$R_1 \rightarrow R_1 - \frac{5}{3}R_3$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{3} & -\frac{11}{3} & 3 \\ 0 & 1 & 0 & \frac{1}{3} & -\frac{13}{3} & -1 \\ 0 & 0 & 1 & 1 & 11 & -6 \end{array} \right] A^{-1} \quad \underline{x = A^{-1}b}$$

Example : compute A^{-1}

$$A = \begin{bmatrix} 0 & 2 & 1 \\ 3 & 1 & 4 \\ 2 & 4 & 6 \end{bmatrix}$$